THOMSON INDUSTRIES, INC. LINE AND ADDITIONAL ADDITICO ADD

#### LINEAR GUIDES

- Ball, roller, and sliding friction bearing technology
- ProfileRail<sup>™</sup> and RoundRail<sup>™</sup> linear guides

#### MOTION CONTROL

- Easy to Specify; Complete Solutions
- Easy to Install; Plug & Play

#### SYSTEMS, SLIDES & STAGES

- Pre-engineered, pre-assembled, ready to install
- The most complete product line available

To place an order call:

North America: **1-800-554-THOMSON** Europe: **(44) 1271 334 500** Elsewhere: **516-883-8000** 

www.thomsonindustries.com



#### PART NUMBER INDEX

Number Prefix	Description	Page Number
1AA	Single Race Unsupported Linear Guide	98
1AB	Double Race Unsupported Linear Guide	100
1AC	Unsupported Linear Guide with Carriage	102
1BA	Single Race End Supported Linear Guide	110
1BB	Double Race End Supported Linear Guide	112
1BC	End Supported Linear Guide with Carriage	114
1CA	Single Race Continuously Supported Linear Guide	62
1CB	Double Race Continuously Supported Linear Guide	64
1CC	Continuously Supported Linear Guide with Carriage	66
IDA	Single Race Side Mounted Linear Guide	76
1DB	Double Race Side Mounted Linear Guide	78
1DC	Side Mounted Linear Guide with Carriage	80
1FA	Single Race Smart Rail* Linear Guide	124
1FB	Double Race Smart Rail Linear Guide	126
1FC	Smart Rail Linear Guide with Carriage	128
1GA	Single Race Bolt from Bottom Linear Guide	84
1GB	Double Race Bolt from Bottom Linear Guide	86
1GC	Bolt from Bottom Linear Guide with Carriage	88
1MA	Single Race Unsupported Linear Guide (metric)	104
1MB	Double Race Unsupported Linear Guide (metric)	106
1MC	Unsupported Linear Guide with Carriage (metric)	108
1NA	Single Race End Supported Linear Guide (metric)	116
1NB	Double Race End Supported Linear Guide (metric)	118
1NC	End Supported Linear Guide with Carriage (metric)	120
1PA	Single Race Continuously Supported Linear Guide (metric)	68
1PB	Double Race Continuously Supported Linear Guide (metric)	70
1PC	Continuously Supported Linear Guide with Carriage (metric)	72
1QA	Single Race Smart Rail Linear Guide (metric)	130
1QB	Double Race Smart Rail Linear Guide (metric)	132
1QC	Smart Rail Linear Guide with Carriage (metric)	134
1RA	Single Race Bolt from Bottom Linear Guide (metric)	90
1RB	Double Race Bolt from Bottom Linear Guide (metric)	92
1RC	Bolt from Bottom Linear Guide with Carriage (metric)	94
1VA	Single Race Unsupported Corrosion Resistant Linear Guide	42
1VA	Single Race End Supported Corrosion Resistant Linear Guide	48
1VA	Single Race Continuously Supported Corrosion Resistant Linear Guide	54
1VB	Double Race Unsupported Corrosion Resistant Linear Guide	44
1VB	Double Race End Supported Corrosion Resistant Linear Guide	50
1VB	Double Race Continuously Supported Corrosion Resistant Linear Guide	56
IVC	Unsupported Corrosion Resistant Linear Guide with Carriage	46
1VC	End Supported Corrosion Resistant Linear Guide with Carriage	52
1VC	Continuously Supported Corrosion Resistant Linear Guide with Carriage	58
IWA	RoundWay* Bolt from Bottom Linear Guide-Single Type	138
IWA	RoundWay Bolt from Bottom Linear Guide-Dual Type	140

Part Numbe	r Index	(Alphabetical)

i art ivani		
Part Number Prefix	Description	Page Number
2BA	Twin Shaft Quickslide* Linear Guide	154
2BB	Twin Shaft Superslide* Linear Motion System	226
2CA	Twin Shaft Web QuickSlide Linear Guide	160
2CB	Twin Shaft Web Superslide Linear Motion System	228
2DA	Dual Shaft Rail QuickSlide Linear Guide	146
2DA	Dual Shaft Rail QuickSlide with Manual Brake	294
2DB	Dual Shaft Rail SuperSlide Linear Motion System	230
2DB	Dual Shaft Rail SuperSlide Linear Motion System (metric)	258
2EA	Double Race Continuous Support Linear Guide	172
2EB	Double Race Continuous Support SuperSlide Linear Motion System	234
2GE	Turbo Module* Belt Driven Linear Motion System	284
2HB	AccuSlide Ball Screw Driven Linear Motion System	260
2HE	AccuSlide Belt Driven Linear Motion System	274
2NB	End Supported SuperSlide Ball Screw Driven Linear Motion System	256
2NE	End Supported SuperSlide Belt Driven Linear Motion System	272
2RB	Continuous Support SuperSlide Ball Screw Driven Linear Motion System	262
2RE	Continuous Support SuperSlide Belt Driven Linear Motion System	276
AT	AccuGlide* T-Series* Linear Guide	35
AP	AXI-PAK* Motion Control Package	397
APi	AXI-PAK* Motion Control Package with Indexing	401
ASC	Aluminum Shroud Cover	302
BEL	Bellows Way Covers 74,122, 152, 166, 7	170, 174, 291
BLX	Brushless Servo Motors	431
BSA	Ball Screw Assemblies	236
CD	AccuGlide* Linear Guide (Miniature Series Carriage)	29
CG	AccuGlide Linear Guide (Standard Carriage)	17
СМ	AccuMax* Linear Guide (Carriage)	11
HW	Handwheels	308
LSP	Limit Switch Package (for Metric Size Systems)	296
MAB	Motor Adaptor Blocks	289
MC	Motor Couplings	288
MS	MicroStage* Linear Guide	175
MS	Micro Stage Actuated Linear Motion System	245
OD	OMNIDRIVE* Digital Servo Drive (Full Size)	417
ODM	OMNIDRIVE Digital Servo Drive (Mini Size)	416
RADMO	Radial Mount Ball Screw Shaft Extenders	292
RD	AccuGlide Linear Guide (Miniature Series Rail)	29
RG	AccuGlide Linear Guide (Standard Rail)	17
RM	AccuMax Linear Guide (Rail)	11
RMC	Radial Mount Couplings	293
TBC7	Electric Brake Controller	306
TEB	Spring Set Electric Brakes	304
TMC	TMC 2000 Motion Controller	385
TNUT	Tee Nut Mounting Hardware	308
TP	Touch Pad	411



Double Race End Supported Quickslide\* Linear Guide with Carriage

Ball Screw Actuated Double Race End Supported Superslide\* System

2AA

2AB

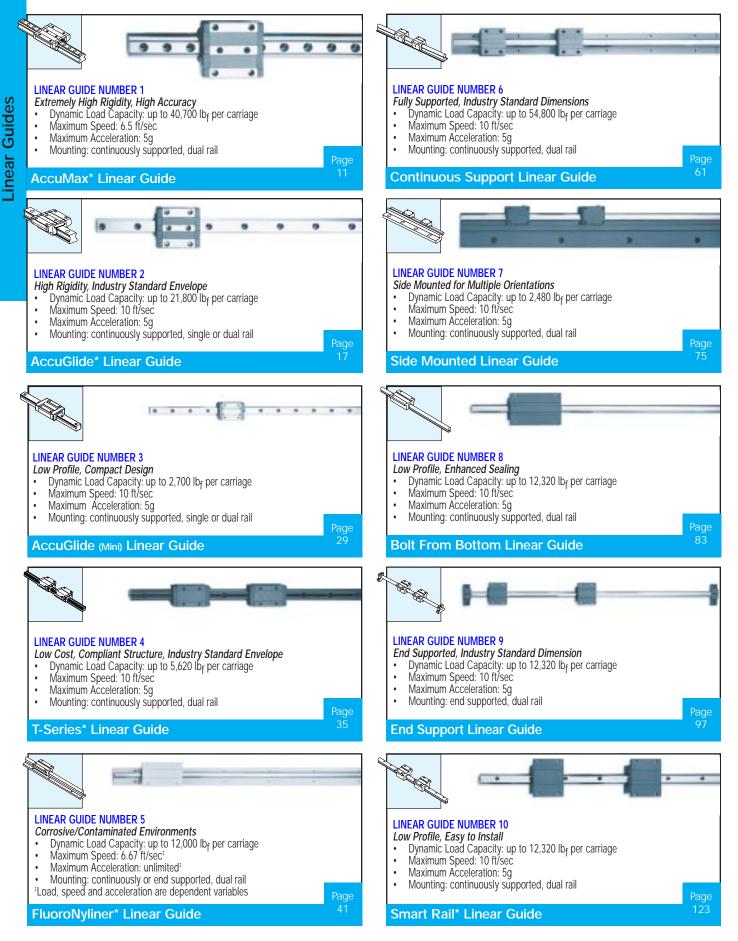
For Application Engineering assistance contact the Thomson Technical HelpLine at 1-800-554-8466. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

168

224

Page 1

#### LINEAR GUIDES PRODUCT SELECTOR

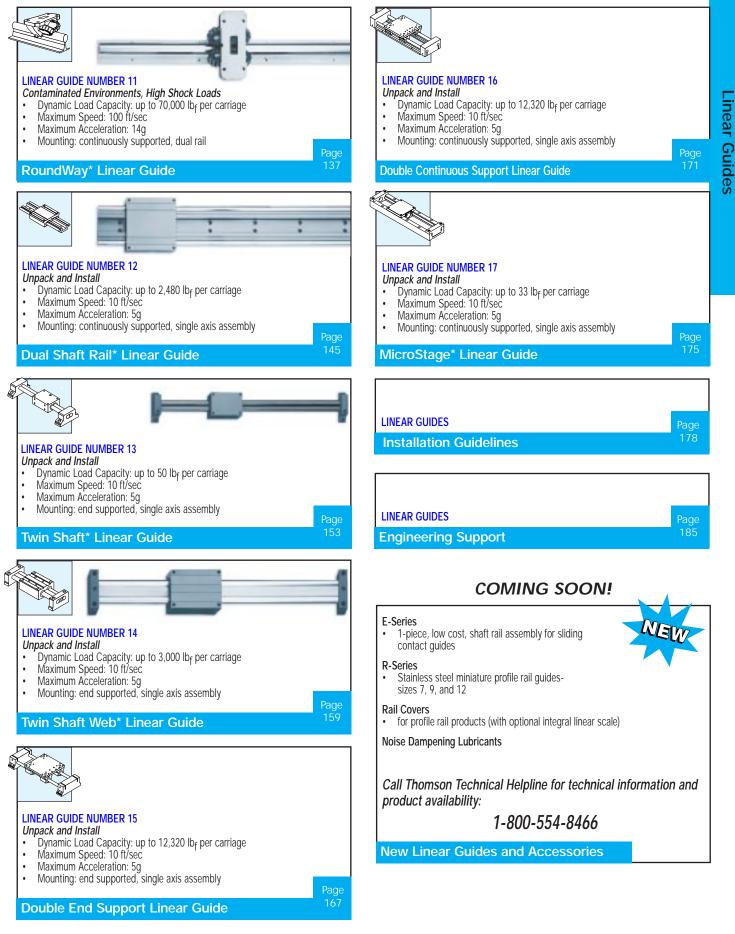




For Application Engineering assistance contact the Thomson Technical HelpLine at 1-800-554-8466. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



#### LINEAR GUIDES PRODUCT SELECTOR

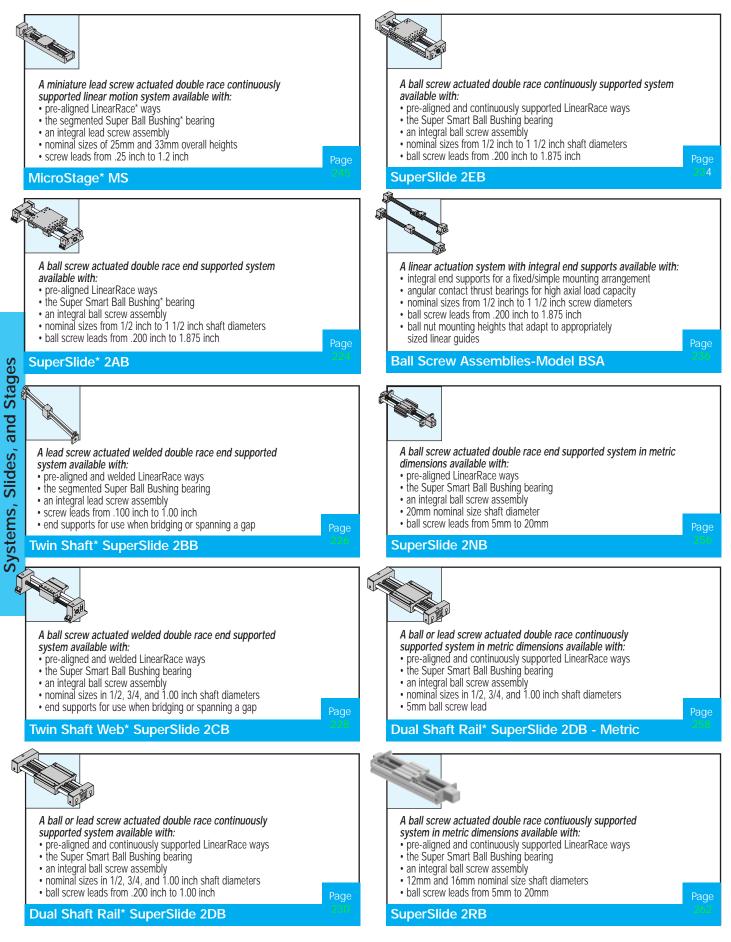




For Application Engineering assistance contact the Thomson Technical HelpLine at 1-800-554-8466. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Page 3

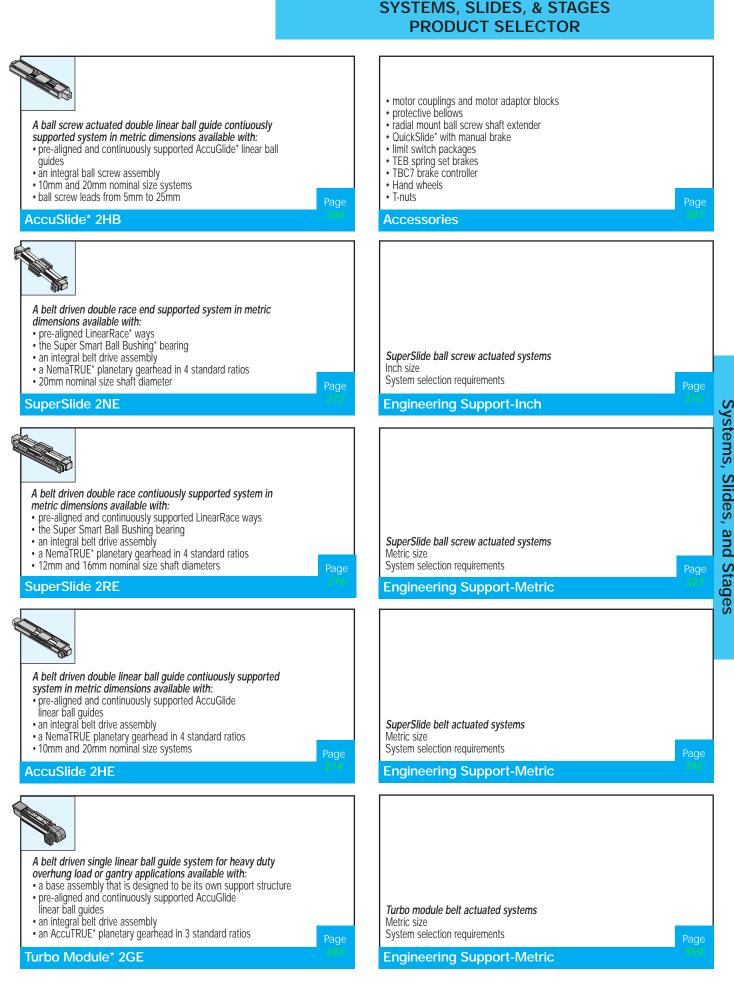
#### SYSTEMS, SLIDES, & STAGES PRODUCT SELECTOR



Page 4

For Application Engineering assistance contact the Thomson Technical HelpLine at 1-800-554-8466. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.





First in Linear Motion and Control Technology

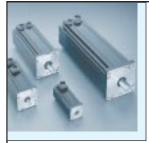
For Application Engineering assistance contact the Thomson Technical HelpLine at 1-800-554-8466. <sup>1</sup> Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Page 5

#### MOTION CONTROL SOLUTION SELECTOR



#### **OMNIDRIVE Digital Servo Drives**



- Superior magnetic and thermal design gives exceptional performance and the highest torque per frame size Standard IP65 sealing, MS style fluid tight connectors, oversize bearings, and thermal switch ensure a long and worry free service life
- · A variety of frame sizes and winding configurations are available to suit your precise application needs
- Internal bearing mounted commutating encoder provides precision and reliability
   Available with planetary gearheads and internal brakes

#### **BLX Brushless Servo Motors**

# www.thomsoncontrol.com Call: 1-800-554-THOMSON







# THOMSON INDUSTRIES, INC. **LINEAR GUIDE SOLUTION** Engineering Guide for Linear Guides



Ball, roller, and sliding friction bearing technology
ProfileRail\* and RoundRail\* linear guides

First in Linear Motion and Control Technology

www.linearguides.com

For Application Engineering assistance contact the Thomson Technical HelpLine at 1-800-554-8466. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

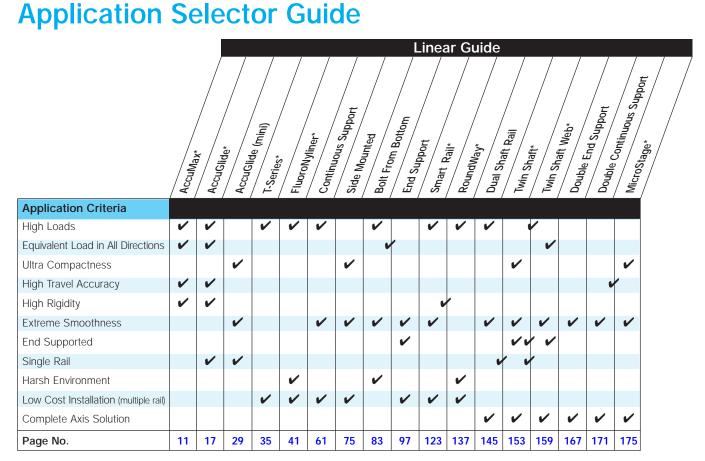


# Linear Guide Selection Criteria:

- Load/Life
- Travel Accuracy
- Rigidity
- Smoothness of Travel
- Speed & Acceleration
- Envelope
- Environment

- Cost of Product
- Cost of Installation
- Cost of Replacement

Linear Guides



# **Application Examples:**

- Machine Tools
- Packaging Machinery
- Automotive Assembly Equipment
- Semiconductor Equipment
- Medical Equipment
- Food Processing Equipment







# **Linear Guide Selection Process:**

The selection of a type of linear guide will greatly effect machine performance and overall cost.

For example, selecting a guide with too much rigidity will decrease the allowable installation tolerances, therefore greatly increasing surface preparation costs. If the costs are not incurred by properly preparing the mounting surface, the guide will run rough and need to be replaced more frequently due to a reduced life.

In order to meet the widely varying demands of today's applications, proper selection from a broad product range will optimize performance and reduce costs. The following selection process will assist you in choosing the appropriate linear guide for your application. **See Engineering Section for more details**. (page 185)

- Review the Linear Guide Selection Criteria on page 8, considering all criteria for the application.
- Using the Application Selection Guide on page 8, select the appropriate type of guide.
- Determine the load on the most heavily loaded carriage or bearing.
- Calculate the minimum required dynamic load rating, Cmin, for the bearing life required between replacements.
- Select the size which offers the load rating, C, equal to or greater than the minimum required dynamic load rating, Cmin.
- If the guide selected offers various preload levels, select a preload based upon the allowable bearing deflection.
- If the guide selected offers various accuracy classes, select an accuracy class based upon the required travel accuracy.
- Determine the need for accessories/options.
- Select the appropriate part number.

If you require any assistance selecting the appropriate linear guide for your application, please contact Thomson's Application Engineering Group: In North America: In Europe: Elsewhere: (516) 883-8937



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



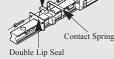
# Maintenance-Free

The new LL Option can provide maintenance-free operation and enhanced protection for a broad range of applications.

- · Only Thomson offers both RoundRail\* and ProfileRail\* self-lubricating linear guides
- Reduces system cost by eliminating the need for expensive lubrication systems
- Clean, self-lubricating applicator eliminates oil-related contamination
- Increases bearing life by offering enhanced protection

#### PATENT PENDING

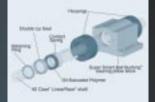
# Oil-saturated Polymer



DESIGN The LL option consists of a section of oil-saturated polymer, custom made to fit the rail. These sections are installed on each end, inside the double lip seal. A proprietary spring assembly assures continuous contact with the rail, releasing oil as the carriage moves. This ensures a film of lubricant between the balls and bearing races, and provides enhanced protection, maintaining long-term running efficiency.

#### PERFORMANCE

Thomson has incorporated a proven oil-saturated polymer used for over 10 years to lubricate radial bearings. This product has a successful track record in applications ranging from food processing to automotive assembly.



H0M50

#### See Page 210 for technical data

All Thomson Industries Manufacturing Locations are ISO 9000 Certified and Automotive Facilities Operate to QS-9000 Standards Three-time Winner General Motors Supplier of the Year

#### ISO 9000

\* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries. ©1999 Thomson Industries, Inc. Printed in the U.S.A. 8-12-99 HAP 9906-08.QXD

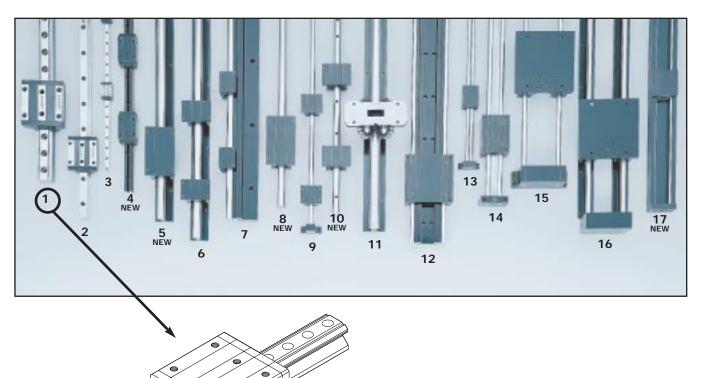


The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.

Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries



# AccuMax Linear Roller Guides



# HIGH LOADS, EXTREME PRECISION, HIGH RIGIDITY

# Thomson AccuMax\* Linear Roller Guides Offer:

- Approximately twice the load capacity of equally-sized linear ball guides. This improvement in bearing capacity provides 10X increase in bearing life; costly service and maintenance is reduced
- Approximately twice the rigidity of equally-sized linear ball guides for a dramatic improvement in machine tool accuracy
- The Arcuate Advantage\*, a patented design which utilize cylindrical roller elements on continuously crowned races, ensuring reliable bearing performance

- Four easily accessible lubrication points
- An industry-standard envelope for drop-in replacement of most linear ball guide systems... the added performance benefits are realized immediately

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



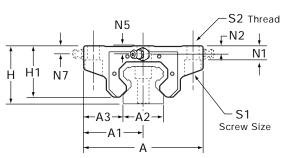
#1

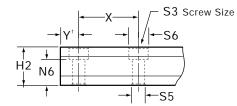
# AccuMax Linear Guide #1 Extremely High Rigidity, High Accuracy

冾

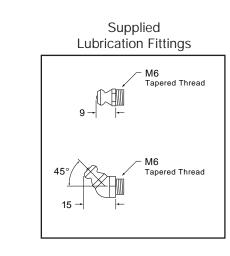
E3 E2

B





† "Y" dimension will be equal on both ends unless specified by customer.



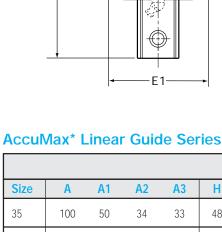
NOTE: AccuMax linear guides are normally not recommended for single rail applications. Contact the Thomson Technical Helpline at 1-800-554-THOMSON for immediate application assistance.

								(mm)								
Size	Α	A1	<b>A</b> 2	<b>A3</b>	Н	H1	H2	В	E1	E2	<b>E</b> 3	<b>S1</b>	<b>S2</b>	<b>S</b> 3	<b>S</b> 5	<b>S6</b>
35	100	50	34	33	48	42,5	31	109	82	62	52	M8	M10	M8	9	15
45	120	60	45	37,5	60	53	38,5	137	100	80	60	M10	M12	M12	14	20
55	140	70	53	43,5	70	62,5	45,5	163	116	95	70	M12	M14	M14	16	24
65**	170	85	63	53,5	90	80	56,5	200	142	110	82	M14	M16	M16	18	26

\*\*Note: Contact Factory for availability.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.





- N8





#### **Dynamic Load and Moment Ratings**

C = Dynamic load rating

Mp = Dynamic pitch moment rating

M<sub>r</sub> = Dynamic roll moment rating

 $M_v$  = Dynamic yaw moment rating

The dynamic load and moment ratings are based upon a 100 km travel life. In order to compare with bearings rated for 50 km, divide the dynamic capacity of the bearing rated for 50 km by 1.26.

#### **Static Load and Moment Capacities**

Co = Static load capacity, N

Mpo = Static pitch moment capacity, Nm

Mro = Static roll moment capacity, Nm

Mvo = Static yaw moment capacity, Nm

The static load and moment capacities are the maximum radial load and moment load that should be applied to the bearing while there is no relative motion between the carriage and rail.

#### **Bearing Travel Life Calculation**

 $L = (C/F)^{10/3} \times 100 \text{ km}$ where:

L = travel life, km

 $C_{\min} = F\left(\frac{L}{100}\right)^{1/3}$ 

where:

C<sub>min</sub> = minimum required dynamic load rating, N C = dynamic load rating, N

F = applied dynamic load, N

F = applied dynamic load, N L = required travel life, km

#### **Operating Parameters**

Maximum Velocity = 2 m/s Maximum Acceleration = 50 m/s<sup>2</sup> Maximum Temperature = 80 °C

			(	(mm)					Load Rating	N (lbf)		oment ating	Nm (lbf-ft	:)	MA Carriag	ISS e Rail
Size	N1	N2	N5	N6	N7	N8	X	L <sub>max<sup>‡</sup></sub>	C(@100km	) C <sub>o</sub>	M <sub>p</sub> ,M <sub>y</sub>	M <sub>po</sub> , M <sub>yo</sub>	M <sub>r</sub>	M <sub>ro</sub>	kg	kg/m
35	12	7	7	21	7	7	40	3 000	46 600 (10,500)	79 500 (17,850)	195 (145)	480 (355)	590 (435)	1 010 (745)	1,5	7,5
45	16	9,5	7	24,5	7	8,5	52,5	3 000	80 000 (18,000)	132 400 (29,750)	425 (315)	935 (690)	990 (730)	1 690 (1,250)	2,8	11,2
55	21	10,5	8	29,5	8	10,25	60	3 000	115 700 (26,000)	191 100 (42,950)	770 (570)	1 615 (1,190)	1 470 (1,080)	2 510 (1,850)	4,7	16,3
65**	23	15	9,5	34,5	9,5	10,5	75	3 000	181 000 (47,000)	281 000 (63,150)	1 530 (1,130)	3 150 (2,320)		5 970 (4,400)	7,2	22,5

#### AccuMax\* Linear Guide Series

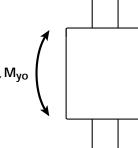
‡ Maximum rail length in one section. Multiple sections can be butted for longer lengths.

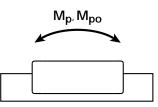
\*\*Note: Contact Factory for availability.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



Page 13



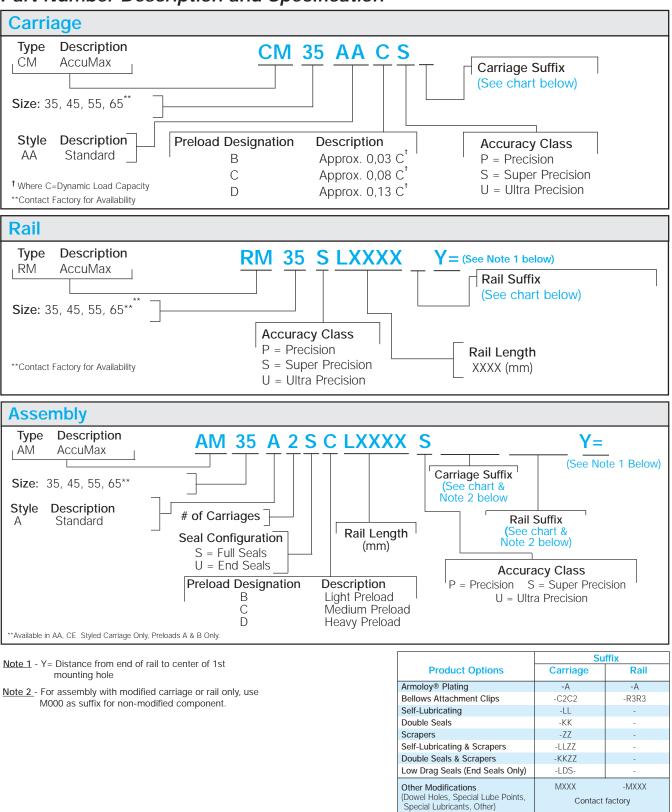


Mr, Mro



# AccuMax\* Linear Guide #1

#### Part Number Description and Specification



For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.

Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries



#### Figure 1 - Dimensions H and A3

#### Figure 2 - Running Parallelism

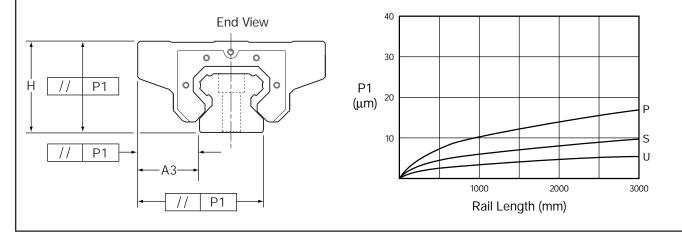


Table 1 - Tolerance	es (µm)		
	Αςςι	uracy Cla	ISSES
	P Precision	S Super Precision	U Ultra Precision
<ol> <li>Assembly Accuracy Dim. H and A3 (measured at middle of carriage at any point along rail)</li> </ol>	±20	±10	±5
2. Pair Variation Max variation in dimensions H and A3 measured on multiple carriages mounted on the same rail (measured at middle of carriage at same position on rail)	7	5	3
3. Running Parallelism (applies to the system)	See	e Figures 1 and	12

#### Table 2 - Preload/Accuracy Combinations

		Preload	
Accuracy Class	approx. 0,03 C <sup>†</sup>	approx. 0,08 C <sup>⁺</sup>	approx. 0,13 C <sup>†</sup>
P, S, U	В	С	D

<sup>†</sup>Where C=Dynamic Load Capacity

#### **Table 3 - Calculations** To determine proper carriage size:

 $C_{min} = F \cdot \left(\frac{L}{100}\right)^{3/10}$ 

L

C<sub>min</sub> = minimum required dynamic load capacity of carriage (N) = equivalent load on carriage (N)

= required travel life (km)

To determine travel life:

$$L = \left(\frac{C}{F}\right)^{10/3} \cdot 100$$

L = normal travel life (km)

- C = rated dynamic load capacity of carriage (N)
- F = equivalent load on carriage (N)

#### Table 4 - Conversions

 $1 \text{ lb}_{f} = 4,448 \text{ N}$  $1 \text{ kg}_{f} = 9,8 \text{ N}$ **1 km =** 39,370 inches  $1 \text{ Nm} = 0.7376 \text{ lb}_{f}\text{-ft}$ 

#### **Operating Parameters**

Maximum Velocity = 2 m/s Maximum Acceleration = 50 m/s<sup>2</sup> Maximum Temperature = 80 °C

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



\* The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.
\* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



# AccuMax Linear Roller Guide Accessories

Full Seal Double Lip

-LL Self-Lubricating Self-Lubricating Material & Spring (both ends) Option

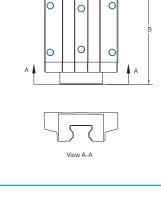
The new LL Option provides maintenancefree operation and enhanced bearing protection.

- · Eliminates the need for expensive lubrication system in most applications
- Increases effective bearing life by increasing protection from contamination
- Environmentally friendly
- Carriage drag with the -LL option will be NOTE: approximately 2x the seal drag.



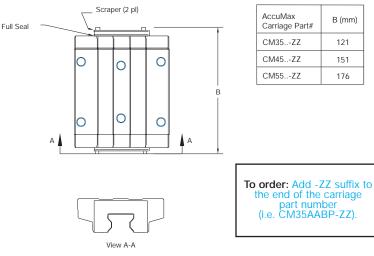
Scraper Option

Scrapers for AccuMax\* linear guidecarriages are manufactured from hardened steel, approximately 1mm thick, and match the profile of the rail within 0.080mm. A scraper is attached to each end of the carriage outside the standard double lip seal.

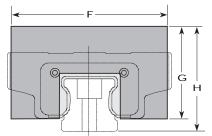


AccuMax Carriage Part#	B (mm)
CM35LL	Contact Factory
CM45LL	Contact Factory
CM55LL	Contact Factory

To order: Add -LL suffix to the end of the carriage
part number (i.e. CM35AACP-LL).



#### **Bellows (Way Covers) Option**



#### Materials Specifications

Type B = Polyurethane coated polyester, maximum ambient temperature = 80 °C (175 °F)

- Type C = Teflon<sup>®</sup> coated fiberglass, maximum ambient temperature = 260 °C (500 °F)
- Type W = Silcone coated Aramid<sup>®</sup>, maximum ambient temperature = 149 °C (300 °F)

To Order: Add -C2C2 Suffix to carriage for attachment clips Add -R3R3 Suffix to rail for end machining and attachment clips

										NEV	0		
		Lo	w Profil Typ		VS	High	Compres Type		llows	-	WS		
Part Number	Rail Size	F	G	Н	CR	F	G	H	CR	F	G	Н	CR
BM35  LXXXX BM45  LXXXX BM55  LXXXX	35 45 55	64 76.8 92.5	41.3 51 60	47.5 58 68	0.15 0.15 0.10	84 96.8 112.5	49.5 58 65	57.5 68 78	0.07 0.07 0.06	77 101 111	42 53 60	48 61 70	0.19 0.15 0.15
	55	72.0		00	0.10	112.0	05	70	0.00		00	70	0.15

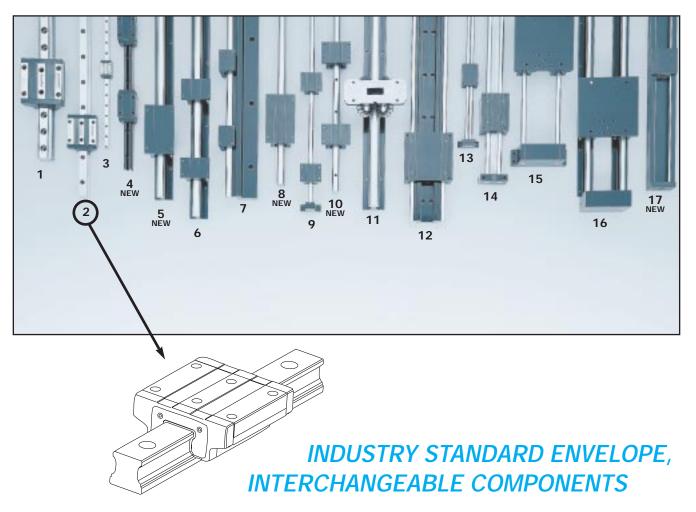
Bellows Type XXXX = Bellows Extended Length (mm)

NOTE: Type B (Low Profile Bellows) is below the carriage top, Type C and Type W are above the carriage top. CR = Compression Ratio (bellows compressed length divided by the bellows extended length).





# AccuGlide Linear Ball Guides



# Thomson AccuGlide\* Linear Ball Guides Offer:

- Interchangeability in all accuracy classes and preloads, eliminating the need to prematch carriages and rails —ordering is simplified and downtime is minimized
- Four easily accessible lubrication points
- A continuous full length wiper mounted on the carriage to exclude contaminants and retain lubrication
- A reduced lead time for all accuracy classes and preloads
- Product availability from over 1800 authorized distributor locations, worldwide
- An industry-standard envelope for interchangeability with existing ball guide systems. This provides a U.S. manufactured source, with off-the-shelf availability

# FOR ACTUATED SYSTEMS CONTAINING THIS TYPE OF LINEAR GUIDE, SEE PAGES 260, 274, and 284

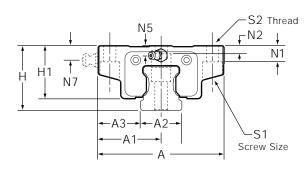
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

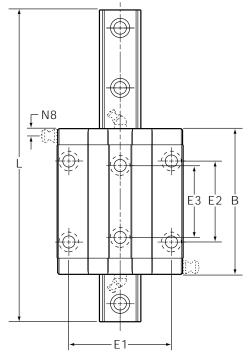


Page 17

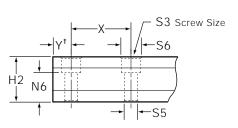
**#2** 

# AccuGlide Linear Guide #2 (Standard) High Rigidity, Industry Standard Envelope

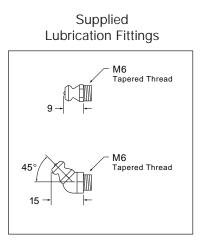




AccuGlide\* Linear Guide Series "AA" - Standard



 $^{\dagger}\,$  "Y" dimension will be equal on both ends unless specified by customer.



Drop-in replacement for type HSR A, B, CA, & CB style guides manufactured by THK Co., LTD. (Japan)

								(mm)								
Size	Α	A1	A2	<b>A3</b>	Н	H1	H2	В	E1	E2	E3	<b>S1</b>	<b>S2</b>	<b>S</b> 3	<b>S</b> 5	<b>S</b> 6
15**	47	23,5	15	16	24	20,9	15	57	38	30	26	M4	M5	M4	4,5	7,5
20	63	31,5	20	21,5	30	25	18	80	53	40	35	M5	M6	M5	6	9,5
25	70	35	23	23,5	36	29,5	24,5	86	57	45	40	M6	M8	M6	7	10,7
30	90	45	28	31	42	35	28,25	100	72	52	44	M8	M10	M8	9	15
35	100	50	34	33	48	40	32	109	82	62	52	M8	M10	M8	9	15
45	120	60	45	37,5	60	50	40	139	100	80	60	M10	M12	M12	14	20
55	140	70	53	43,5	70	57	46	163	116	95	70	M12	M14	M14	16	24

\*\*Note: Contact Factory for availability.





#### **Dynamic Load and Moment Ratings**

C = Dynamic load rating

 $M_{p}$  = Dynamic pitch moment rating

 $M_r$  = Dynamic roll moment rating

M<sub>v</sub> = Dynamic yaw moment rating

The dynamic load and moment capacities are based upon a 100 km travel life. In order to compare with bearings rated for 50 km, divide the dynamic capacity of the bearing rated for 50 km by 1.26.

#### Static Load and Moment Capacities

Co = Static load capacity, N

Mpo = Static pitch moment capacity, Nm

Mro = Static roll moment capacity, Nm

M<sub>vo</sub> = Static yaw moment capacity, Nm

The static load and moment capacities are the maximum radial load and moment load that should be applied to the bearing while there is no relative motion between the carriage and rail.

#### **Bearing Travel Life Calculation**

 $L = (C/F)^3 \times 100 \text{ km}$ where: L = travel life, km C = dynamic load rating, N  $C_{\min} = F \left(\frac{L}{100}\right)^{1/3}$ 

where:

C<sub>min</sub> = minimum required dynamic load rating, N

F = applied dynamic load, N

F = applied dynamic load, N L = required travel life, km

#### **Operating Parameters**

Maximum Velocity = 3 m/s Maximum Acceleration =  $50 \text{ m/s}^2$ Maximum Temperature = 80 °C

#### AccuGlide\* Linear Guide Series "AA" – Standard

			(m	ım)					Load Rating <sup>†</sup>	N (lbf)		oment ating	Nm (lbf-ft	)	MA Carriag	
Size	N1	N2	<b>N5</b>	<b>N6</b>	N7	<b>N8</b>	X	L <sub>max</sub> ‡	C(@100km	) C <sub>o</sub>	$M_p, M_y$	M <sub>po</sub> ,M <sub>yo</sub>	M <sub>r</sub>	M <sub>ro</sub>	kg	kg/m
15**	7,2	3,5	4	9,2	5,8	4	60	3 000	6 000 (1,350)	13 500 (3,030)	31 (23)	71 (53)	57 (43)	130 (98)	0,23	1,4
20	9,75	6,25	5	9,5	7,5	6	60	3 000	13 000 (2,990)	21 000 (4,720)	52 (39)	125 (92)	150 (112)	245 (180)	0,55	2,4
25	9	4,5	5	16	8	5,5	60	3 000	18 200 (4,100)	28 000 (6,290)	86 (65)	195 (145)	260 (190)	400 (295)	0,75	3,2
30	10,75	5	6,3	16,3	8	7,6	80	3 000	24 800 (5,600)	37 000 (8,320)	150 (110)	300 (220)	450 (330)	650 (480)	1,30	5,0
35	14	4,5	6,3	20	10	6,8	80	3 000	32 000 (7,200)	47 000 (10,550)	240 (180)	460 (340)	730 (540)	1 010 (745)	1,85	6,8
45	15	8	7,4	24	14	9,5	105	3 000	52 500 (11,800)	76 000 (17,100)	470 (350)	900 (665)	1 450 (1,090)	2 070 (1,530)	3,40	10,5
55	17,75	10,25	9,3	27	14,5	11,6	120	3 000	77 000 (17,300)	107 000 (24,050)	820 (615)	1 510 (1,110)	2 430 (1,830)	3 385 (2,500)	5,65	16,2

<sup>‡</sup> Maximum rail length in one section. Multiple sections can be butted for longer lengths

\*\*Note: Contact Factory for availability.

<sup>†</sup> Load Ratings per DIN 636

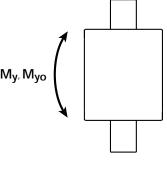
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



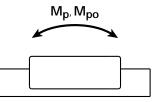
The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



Linear Guides

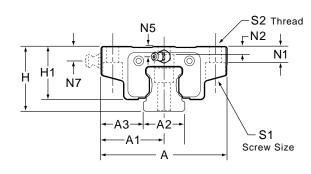


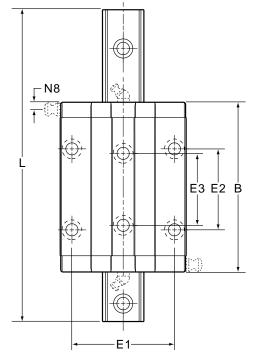
Mr, Mro

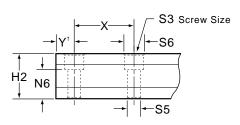




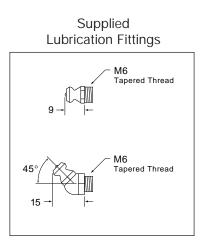
# AccuGlide Linear Guide #2 (Standard Long) High Rigidity, Industry Standard Envelope







† "Y" dimension will be equal on both ends unless specified by customer.



AccuGlide\* Linear Guide Series "BA" – Standard Long

Drop-in replacement for type HSR LA, LB, HA, & HB style guides manufactured by THK Co., LTD. (Japan)

								(mm)								
Size	Α	A1	A2	A3	Н	H1	H2	В	E1	<b>E2</b>	<b>E3</b>	<b>S1</b>	<b>S2</b>	<b>S</b> 3	<b>S</b> 5	<b>S</b> 6
20	63	31,5	20	21,5	30	25	18	102	53	40	35	M5	M6	M5	6	9,5
25	70	35	23	23,5	36	29,5	24,5	105	57	45	40	M6	M8	M6	7	10,7
30	90	45	28	31	42	35	28,25	122	72	52	44	M8	M10	M8	9	15
35	100	50	34	33	48	40	32	134	82	62	52	M8	M10	M8	9	15
45	120	60	45	37,5	60	50	40	171	100	80	60	M10	M12	M12	14	20
55	140	70	53	43,5	70	57	46	201	116	95	70	M12	M14	M14	16	24

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

**Linear Guides** 





#### **Dynamic Load and Moment Ratings**

**C** = Dynamic load rating

M<sub>p</sub> = Dynamic pitch moment rating

 $M_r$  = Dynamic roll moment rating

M<sub>v</sub> = Dynamic yaw moment rating

The dynamic load and moment ratings are based upon a 100 km travel life. In order to compare with bearings rated for 50 km, divide the dynamic capacity of the bearing rated for 50 km by 1.26.

#### Static Load and Moment Capacities

Co = Static load capacity

Mpo = Static pitch moment capacity

 $M_{ro}$  = Static roll moment capacity

 $M_{vo}$  = Static yaw moment capacity

The static load and moment capacities are the maximum radial load and moment load that should be applied to the bearing while there is no relative motion between the carriage and rail.

#### **Bearing Travel Life Calculation**

 $L = (C/F)^3 \times 100 \text{ km}$ where: L = travel life, km C = dynamic load rating, N  $C_{min} = F \left(\frac{L}{100}\right)^{1/3}$ 

where:

C<sub>min</sub> = minimum required dynamic load rating, N

F = applied dynamic load, N

F = applied dynamic load, N L = required travel life, km

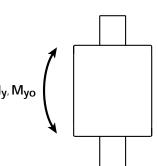
#### **Operating Parameters**

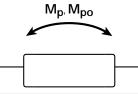
Maximum Velocity = 3 m/s Maximum Acceleration = 50 m/s<sup>2</sup> Maximum Temperature = 80 °C











	٦_

#### AccuGlide\* Linear Guide Series "BA" - Standard Long

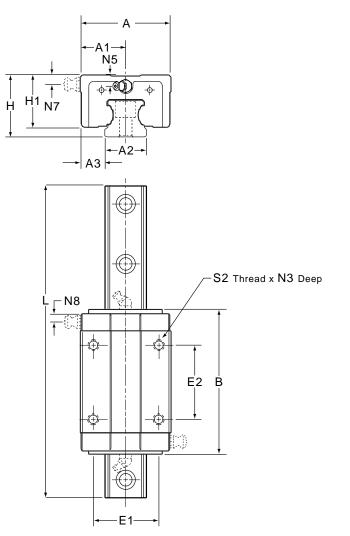
			(m	nm)					Load Rating†	N (lbf)		oment ating	Nm (lbf-f		MAS Carriage	
Size	N1	N2	N5	<b>N6</b>	N7	<b>N8</b>	X	L <sub>maxt</sub>	C(@100km)	Co	M <sub>p</sub> ,M <sub>y</sub>	M <sub>po</sub> , M <sub>yo</sub>	M <sub>r</sub>	M <sub>ro</sub>	kg	kg/m
20	9,75	6,25	5	9,5	7,5	6	60	3 000	17 400 (3,900)	30 000 (6,740)	64 (48)	160 (120)	210 (160)	350 (260)	0,71	2,4
25	9	4,5	5	16	8	5,5	60	3 000	22 700 (5,100)	39 000 (8,770)	102 (77)	255 (190)	320 (240)	550 (405)	1,00	3,2
30	10,75	5	6,3	16,3	8	7,6	80	3 000	31 000 (7,000)	50 000 (11,250)	170 (130)	390 (290)	550 (410)	900 (665)	1,60	5,0
35	14	4,5	6,3	20	10	6,8	80	3 000	40 200 (9,050)	66 000 (14,850)	270 (205)	600 (445)	870 (650)	1 410 (1,040)	2,45	6,8
45	15	8	7,4	24	14	9,5	105	3 000	66 000 (14,800)	106 000 (23,850)	550 (410)	1 180 (870)	1 780 (1,330)	2 850 (2,100)	4,50	10,5
55	17,75	10,25	9,3	27	14,5	11,6	120	3 000	97 000 (21,800)	148 000 (33,250)	965 (710)	1 970 (1,450)	3 050 (2,250)	4 670 (3,440)	7,50	16,2

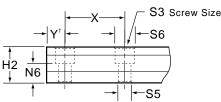
<sup>‡</sup> Maximum rail length in one section. Multiple sections can be butted for longer lengths.

<sup>†</sup> Load Ratings per DIN 636



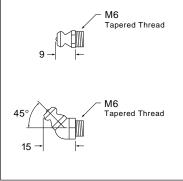
# AccuGlide Linear Guide #2 (Narrow & Narrow High) High Rigidity, Industry Standard Envelope





 $^{\dagger}\,$  "Y" dimension will be equal on both ends unless specified by customer.

Supplied Lubrication Fittings



AccuGlide\* Linear Guide Series "CE" – Narrow AccuGlide Linear Guide Series "EE" – Narrow High

# "EE" style is a drop-in replacement for type HSR R & TR style guides manufactured by THK Co., LTD. (Japan).

								(n	nm)							
					С	E	E	E‡								
Size	Α	<b>A</b> 1	A2	A3	Н	H1	Н	H1	H2	В	E1	E2	<b>S</b> 2	<b>S</b> 3	<b>S</b> 5	<b>S6</b>
15**	34	17	15	9,5	24	20,9	24	20,9	15	57	26	26	M4	M4	4,5	7,5
20	44	22	20	12	30	25	30	25	18	80	32	36	M5	M5	6	9,5
25	48	24	23	12,5	36	29,5	40	33,5	24,5	86	35	35	M6	M6	7	10,7
30	60	30	28	16	42	35	45	38	28,25	100	40	40	M8	M8	9	15
35	70	35	34	18	48	40	55	47	32	109	50	50	M8	M8	9	15
45	86	43	45	20.5	60	50	70	60	40	139	60	60	M10	M12	14	20
55	100	50	53	23,5	70	57	80	67	46	163	75	75	M12	M14	16	24

\*\*Note: Contact Factory for availability.





#### **Dynamic Load and Moment Ratings**

**C** = Dynamic load rating

Mp = Dynamic pitch moment rating

 $M_r$  = Dynamic roll moment rating

 $M_v$  = Dynamic yaw moment rating

The dynamic load and moment ratings are based upon a 100 km travel life. In order to compare with bearings rated for 50 km, divide the dynamic capacity of the bearing rated for 50 km by 1.26.

#### Static Load and Moment Capacities

**Co** = Static load capacity

 $M_{po}$  = Static pitch moment capacity

 $\dot{M_{ro}}$  = Static roll moment capacity

M<sub>vo</sub> = Static yaw moment capacity

The static load and moment capacities are the maximum radial load and moment load that should be applied to the bearing while there is no relative motion between the carriage and rail.

#### **Bearing Travel Life Calculation**

 $L = (C/F)^3 \times 100 \text{ km}$ where: L = travel life, km C = dynamic load rating, N  $C_{min} = F \left(\frac{L}{100}\right)^{1/3}$ 

where:

Cmin = minimum required dynamic load rating, N

F = applied dynamic load, N

F = applied dynamic load, N L = required travel life, km

#### **Operating Parameters**

Maximum Velocity = 3 m/s Maximum Acceleration = 50 m/s Maximum Temperature = 80 °C

#### AccuGlide\* Linear Guide Series "CE" – Narrow AccuGlide Linear Guide Series "EE" - Narrow High

			(mn	n)				Load Rating†	N (lbf)		oment ating	Nm (lbf-ft	)	MAS Carriage	
Size	N3	N5	N6	N7	N8	X	L <sub>max<sup>‡</sup></sub>	C(@100km)	) C <sub>o</sub>	M <sub>p</sub> ,M <sub>y</sub>	M <sub>po</sub> , M <sub>yo</sub>	M <sub>r</sub>	M <sub>ro</sub>	kg	kg/m
15**	4	4	9,2	n/a	n/a	60	3 000	6 000 (1,350)	13 500 (3,030)	31 (23)	71 (53)	57 (43)	130 (98)	0,20	1,4
20	6	5	9,5	n/a	n/a	60	3 000	13 000 (2,990)	21 000 (4,720)	52 (39)	125 (92)	150 (112)	245 (180)	0,40	2,4
25	9	5	16	5,3	5,5	60	3 000	18 200 (4,100)	28 000 (6,290)	86 (65)	195 (145)	260 (190)	400 (295)	0,55	3,2
30	12	6,3	16,3	6,3	7,6	80	3 000	24 800 (5,600)	37 000 (8,320)	150 (110)	300 (220)	450 (330)	650 (480)	0,90	5,0
35	13	6,3	20	6,3	8,2	80	3 000	32 000 (7,200)	47 000 (10,550)	240 (180)	460 (340)	730 (540)	1 010 (745)	1,20	6,8
45	18	7,3	24	7,3	9	105	3 000	52 500 (11,800)	76 000 (17,100)	470 (350)	900 (665)	1 450 (1,090)	2 070 (1,530)	2,30	10,5
55	18,7	9,3	27	9,3	11,6	120	3 000	77 000 (17,300)	107 000 (24,050)	820 (615)	1 510 (1,110)	2 430 (1,830)	3 385 (2,500)	3,80	16,2

<sup>‡</sup> Maximum rail length in one section. Multiple sections can be butted for longer lengths.

\*\*Note: Contact Factory for availability.

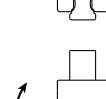
† Load Ratings per DIN 636

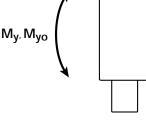


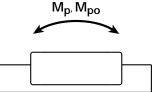




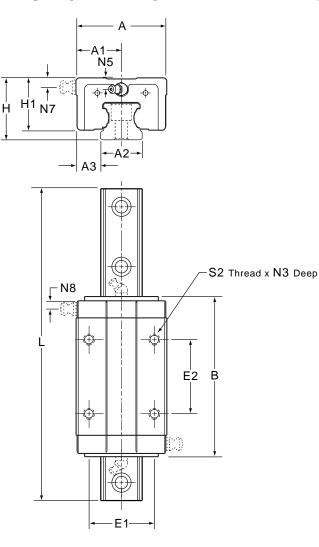


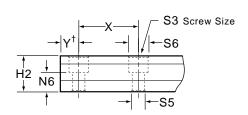






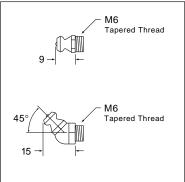
# AccuGlide Linear Guide #2 (Narrow Long) High Rigidity, Industry Standard Envelope





t "Y" dimension will be equal on both ends unless specified by customer.





#### AccuGlide\* Linear Guide Series "DE" – Narrow Long AccuGlide Linear Guide Series "HE" – Narrow Long High

# "HE" style is a drop-in replacement for type HSR LR & HTR style guides manufactured by THK Co., LTD. (Japan).

								(mm)								
					D	E	н	E‡								
Size	Α	<b>A1</b>	A2	A3	Н	H1	Н	H1	H2	В	E1	E2	<b>S</b> 2	<b>S</b> 3	<b>S</b> 5	<b>S6</b>
20	44	22	20	12	30	25	30	25	18	102	32	50	M5	M5	6	9,5
25	48	24	23	12,5	36	29,5	36	29,5	24,5	105	32	50	M6	M6	7	10,7
30	60	30	28	16	42	35	45	38	28,25	122	40	60	M8	M8	9	15
35	70	35	34	18	48	40	55	47	32	134	50	72	M8	M8	9	15
45	86	43	45	20.5	60	50	70	60	40	171	60	80	M10	M12	14	20
55	100	50	53	23,5	70	57	80	67	46	201	75	95	M12	M14	16	24





#### **Dynamic Load and Moment Ratings**

C = Dynamic load rating

M<sub>p</sub> = Dynamic pitch moment rating

 $M_r$  = Dynamic roll moment rating

M<sub>v</sub> = Dynamic yaw moment rating

The dynamic load and moment ratings are based upon a 100 km travel life. In order to compare with bearings rated for 50 km, divide the dynamic capacity of the bearing rated for 50 km by 1.26.

#### Static Load and Moment Capacities

Co = Static load capacity

Mpo = Static pitch moment capacity

Mro = Static roll moment capacity

M<sub>vo</sub> = Static yaw moment capacity

The static load and moment capacities are the maximum radial load and moment load that should be applied to the bearing while there is no relative motion between the carriage and rail.

#### Bearing Travel Life Calculation

 $L = (C/F)^3 \times 100 \text{ km}$ where: L = travel life, km C = dynamic load rating, N $\mathbf{F}$  = applied dynamic load, N  $C_{min} = F \left(\frac{L}{100}\right)^{1/3}$ 

where: C<sub>min</sub> = minimum required dynamic load rating, N

F = applied dynamic load, N L = required travel life, km

#### **Operating Parameters**

Maximum Velocity = 3 m/s Maximum Acceleration = 50 m/s<sup>2</sup> Maximum Temperature = 80 °C



			(mn	n)				Load Rating†	N (lbf)		oment ating	Nm (lbf-ft)		MAS Carriage	
Size	N3	N5	N6	N7	<b>N8</b>	X	L <sub>max‡</sub>	C(@100km)	) C <sub>o</sub>	M <sub>p</sub> , M <sub>y</sub>	M <sub>po</sub> , M <sub>yo</sub>	M <sub>r</sub>	M <sub>ro</sub>	kg	kg/m
20	6	5	9,5	n/a	n/a	60	3 000	17 400 (3,900)	30 000 (6,740)	64 (48)	160 (120)	210 (160)	350 (260)	0,50	2,4
25	9	5	16	5,3	5,5	60	3 000	22 700 (5,100)	39 000 (8,770)	102 (77)	255 (190)	320 (240)	550 (405)	0,70	3,2
30	12	6,3	16,3	6,3	7,6	80	3 000	31 000 (7,000)	50 000 (11,250)	170 (130)	390 (290)	550 (410)	900 (665)	1,10	5,0
35	13	6,3	20	6,3	8,2	80	3 000	40 200 (9,050)	66 000 (14,850)	270 (205)	600 (445)	870 (650)	1 410 (1,040)	1,70	6,8
45	18	7,3	24	7,3	9	105	3 000	66 000 (14,800)	106 000 (23,850)	550 (410)	1 180 (870)	1 780 (1,330)	2 850 (2,100)	3,10	10,5
55	18,7	9,3	27	9,3	11,6	120	3 000	97 000 (21,800)	148 000 (33,250)	965 (710)	1 970 (1,450)	3 050 (2,250)	4 670 (3,440)	4,80	16,2

<sup>‡</sup>Maximum rail length in one section. Multiple sections can be butted for longer lengths.

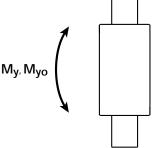
† Load Ratings per DIN 636

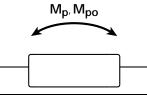
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.





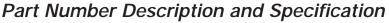
Linear Guides

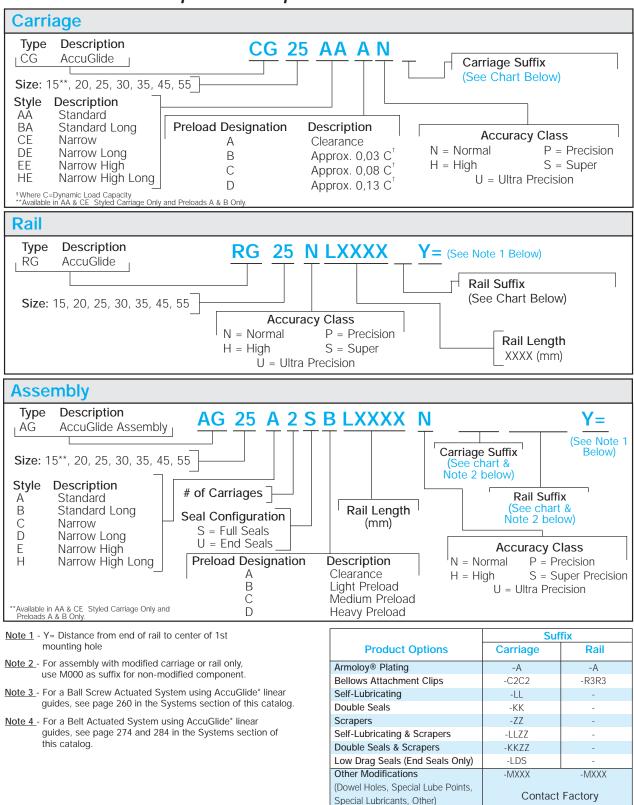






# AccuGlide\* Linear Guide #2









#### Figure 1 - Running Parallelism

Figure 2 - Running Parallelism

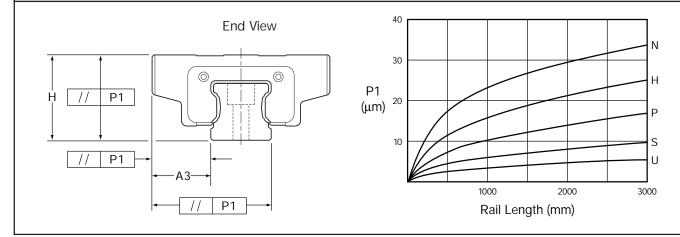


Table 1 - Toler	rances	s (µr	n)		
		Ac	curacy C	Classes	
	N Normal	H High	P Precision	S Super Precision	U Ultra Precision
1. Dim. H and A3 (measured at middle of carriage at any point along rail)	±100	±40	±20	±10	±5
2. Max variation in dimensions H and A3 measured on multiple carriages mounted on the same rail (measured at middle of carriage at same position on rail)	30	15	7	5	3
3. Parallelism (applies to the system)		See	e Figures 1 a	and 2	

# Table 3 - CalculationsTo determine proper carriage size:To determine travel life: $C_{min} = F \cdot \left(\frac{100}{L}\right)^{1/3}$ L = $\left(-\frac{C}{F}\right)^3 \cdot 100$ $C_{min} =$ minimum required dynamic<br/>load capacity of carriage (N)L = normal travel life (km)F = equivalent load on carriage (N)L = normal travel life (km)L = required travel life (km)C = rated dynamic load capacity<br/>of carriage (N)L = required travel life (km)F = equivalent load on carriage (N)Table 4 - Conversions

	4,448 N 9,8 N 39,370 inches 0.7376 lb <sub>f</sub> -ft
--	---

Table 2 - Preload/Accuracy Combinations							
	Clearance		Preload				
Accuracy Class	up to 10 µm	approx. 0,03 C <sup>†</sup>	approx. 0,08 C <sup>⁺</sup>	approx. 0,13 C <sup>⁺</sup>			
P,S,U		В	С	D			
N,H	А	В	С				

<sup>†</sup>Where C=Dynamic Load Rating

#### **Operating Parameters**

Maximum Velocity = 3 m/s Maximum Acceleration = 50 m/s<sup>2</sup> Maximum Temperature = 80 °C

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



\* The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.
\* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



# AccuGlide Linear Ball Guide Accessories

Self-Lubricating

#### -LL Self-Lubricating Option

The new LL Option provides maintenancefree operation and enhanced bearing protection.

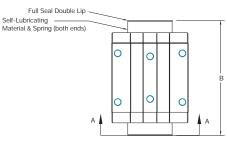
- Eliminates the need for expensive lubrication system in most applications
- Increases effective bearing life by increasing protection from contamination
- Environmentally friendly
- NOTE: Carriage drag with the -LL option will be approximately 2x the seal drag.



## Scraper Option

Scrapers for AccuGlide\* linear guide carriages are manufactured from hardened steel, approximately 1mm thick, and match the profile of the rail within 0.080mm. A scraper is attached to each end of the carriage outside the standard double lip seal.





View A-A

AccuGlide Carriage Part#	B (mm)
CG15LL	75
CG20LL	106
CG25LL	110
CG30LL	128
CG35LL	140
CG45LL	178
CG55LL	208

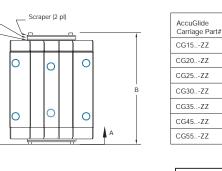
Note: AA style carriage shown. Length (B) for CE style carriages is the same.

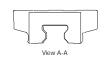
To order: Add -LL suffix to the end of the carriage
part number
(i.e. CG25AAAN-LL).
<ul> <li>-LL option is available on</li> </ul>
AA and CE style
carriages onlý.

B (mm)

& & CE DE

AA BA

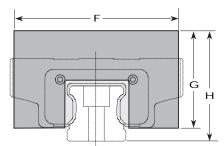




CG15ZZ	68	N/A
CG20ZZ	90	112
CG25ZZ	96	115
CG30ZZ	110	132
CG35ZZ	121	146
CG45ZZ	151	183
CG55ZZ	176	214

To order: Add -ZZ suffix to end of the carriage part number (i.e. CG25AAAN-ZZ).

## **Bellows (Way Covers) Option**



#### Materials Specifications

Spacer (2 pl)

Full Seal

Type B = Polyurethane coated polyester, maximum ambient temperature = 80 °C (175 °F)

- Type C = Teflon<sup>®</sup> coated fiberglass, maximum ambient temperature = 260 °C (500 °F)
- Type W = Silcone coated Aramid<sup>®</sup>, maximum ambient temperature = 149 °C (300 °F)

To Order: Add -C2C2 Suffix to carriage for attachment clips Add -R3R3 Suffix to rail for end machining and attachment clips

× 4

										NEW			
		Low Profile Bellows Type B			High	Compres Type		llows	NISU.	walk-	On Bello ype W	ws	
Part Number	Rail Size	F	G	H	CR	F	G	Н	CR	F	G	Н	CR
BG15 0 LXXXX	15	45	23	26	0.17	59	33	36	0.10	55	30	31	0.19
BG20 👤 LXXXX	20	41.6	24	29	0.17	61.6	34	39	0.10	61	33	34	0.19
BG25 👥 LXXXX	25	43.7	29	35.5	0.17	63.7	39	45.5	0.10	65	36	40.5	0.19
BG30 🔮 LXXXX	30	51.2	33.3	40.25	0.17	71.5	43.3	50.25	0.10	70	39	44.2	0.19
BG35 🔮 LXXXX	35	64	39.5	47.5	0.15	84	49.5	57.5	0.07	77	42	48	0.19
BG45 🔮 LXXXX	45	76.8	48	58	0.15	96.8	58	68	0.07	101	53	61	0.15
BG55 👥 LXXXX	55	92.5	55	68	0.10	112.5	65	78	0.06	111	60	70	0.15

 Bellows Type XXXX = Bellows Extended Length (mm)

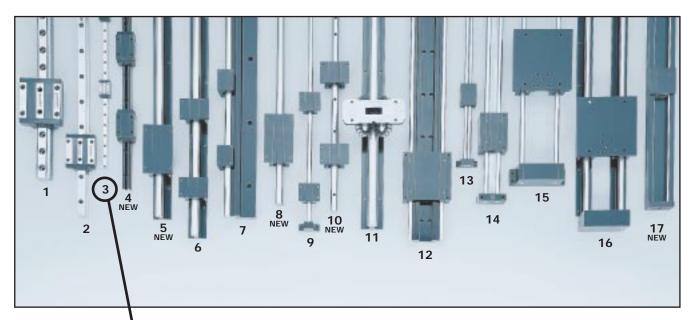
NOTE: Type B (Low Profile Bellows) is below the carriage top, Type C and Type W are above the carriage top. CR = Compression Ratio (bellows compressed length divided by the bellows extended length).

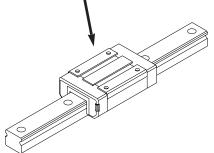


The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.



# AccuGlide Miniature Linear Ball Guides





# ULTRA COMPACT, HIGH ROLL MOMENT CAPACITY

## Thomson AccuGlide\* Miniature Linear Ball Guides offer:

- A superior, patented ball control design for smooth, quiet, low friction linear motion even at high speeds
- A patented full length integral wiper which protects important bearing components from contaminants...effective system life is maximized
- A Gothic Arch design, which provides high roll moment capacity...an important requirement for stand-alone applications

- A wear-resistant, engineered polymer retainer which reduces system inertia and noise
- An American manufacturing source with off-the-shelf availability for all accuracy classes and preload levels
- Worldwide availability from over 1800 authorized distributor locations

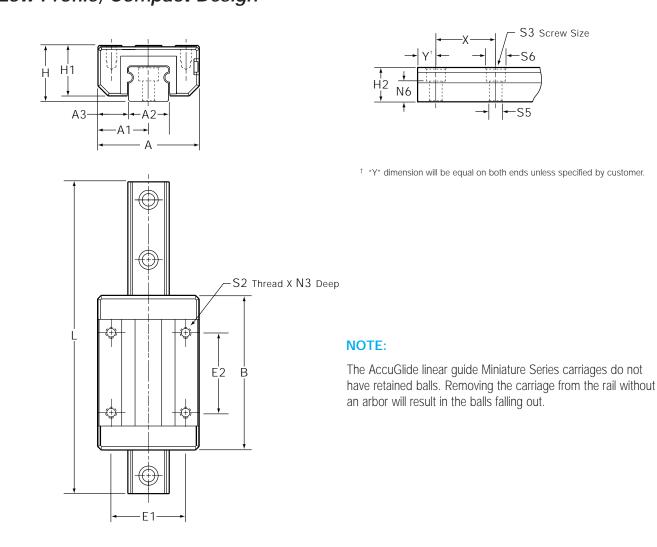
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.





#3

# AccuGlide Linear Guide #3 (Miniature Series) Low Profile, Compact Design



#### AccuGlide\* Linear Guide Miniature Series

	(mm)													
Size	Α	A1	A2	A3	Н	H1	H2	В	E1	E2	<b>S2</b>	<b>S</b> 3	<b>S</b> 5	<b>S6</b>
10	26	13	10	8	15	13	9	40	17	20	M2,5	M2,5	3	5,5
15	38	19	15	11,5	21	19	13	58	28	30	M4	M4	4,5	8
20	50	25	20	15	28	25,6	18	76	37	40	M5	M5	5,5	9,5





#### **Dynamic Load and Moment Ratings**

**C** = Dynamic load rating

 $M_p$  = Dynamic pitch moment rating

 $\dot{M_r}$  = Dynamic roll moment rating

 $M_v$  = Dynamic yaw moment rating

The dynamic load and moment ratings are based upon a 100 km travel life. In order to compare with bearings rated for 50 km, divide the dynamic capacity of the bearing rated for 50 km by 1.26.

#### Static Load and Moment Capacities

**Co** = Static load capacity

Mpo = Static pitch moment capacity

Mro = Static roll moment capacity

M<sub>vo</sub> = Static yaw moment capacity

The static load and moment capacities are the maximum radial load and moment load that should be applied to the bearing while there is no relative motion between the carriage and rail.

#### **Bearing Travel Life Calculation**

 $L = (C/F)^3 \times 100 \text{ km}$ where: L = travel life, km C = dynamic load rating, N  $C_{\min} = F \left(\frac{L}{100}\right)^{1/3}$ 

where:

C<sub>min</sub> = minimum required dynamic load rating, N

F = applied dynamic load, N

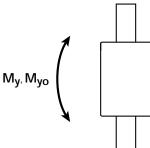
 $\mathbf{F}$  = applied dynamic load, N L = required travel life, km

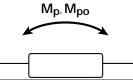
#### **Operating Parameters**

Maximum Velocity = 3 m/s Maximum Acceleration =  $50 \text{ m/s}^2$ Maximum Temperature = 80 °C









	]						

#### AccuGlide\* Linear Guide Miniature Series

		(mm)			Load Rating	N (Ibf)		oment ating	Nm (lbf-f		MA Carriag	ASS e Rail
Size	N3	N6	X	L <sub>max‡</sub>	C(@100km	) C <sub>o</sub>	M <sub>p</sub> , M <sub>y</sub>	M <sub>po</sub> , M <sub>yo</sub>	M <sub>r</sub>	M <sub>ro</sub>	kg	kg/m
10	4,5	5,5	25	1 500	2 820 (635)	5 300 1,190	10 (7)	20 (15)	15 (11)	28 (21)	0,045	0,65
15	6	7,5	40	1 500	6 375 (1,430)	15 200 (3,420)	35 (26)	66 (49)	51 (38)	96 (71)	0,141	1,42
20	8	9,5	60	3 000	11 870 (2,670)	23 000 (5,170)	75 (55)	140 (105)	125 (92)	235 (175)	0,345	2,55

<sup>‡</sup> Maximum rail length in one section. Multiple sections can be butted for longer lengths.

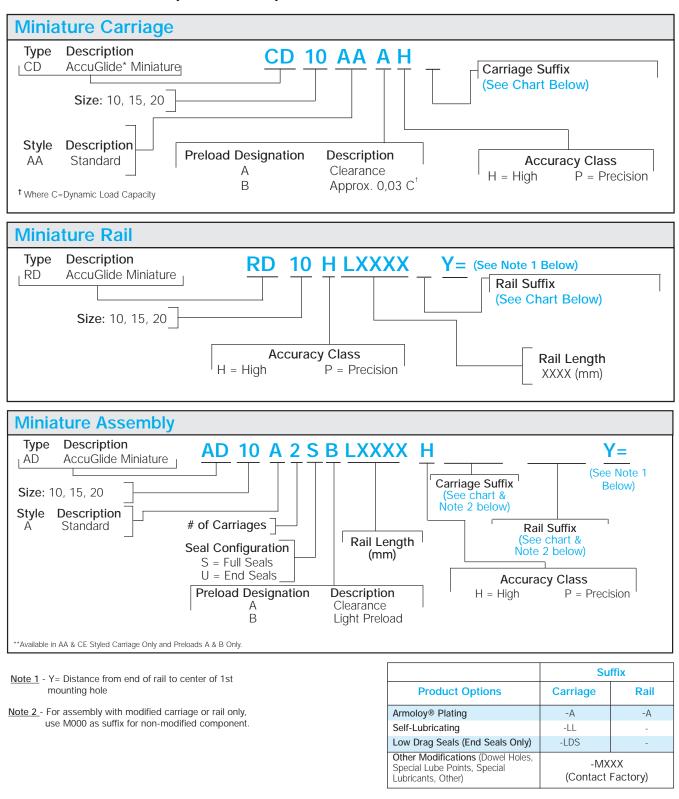
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



#### Linear Guide #3 Part Number Description and Specification







#### Figure 1 - Dimensions H and A3

#### Figure 2 - Running Parallelism

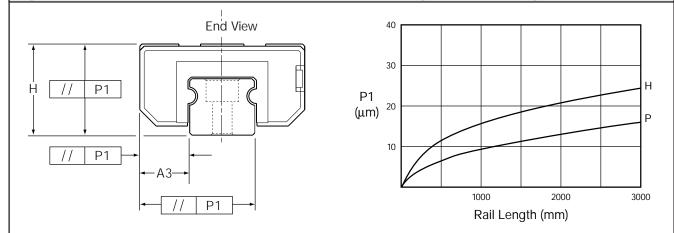


Table 1 - Tolerances (µm)								
	Accurac	y Classes						
	H High	P Precision						
1. Dim. H and A3 (measured at middle of carriage at any point along rail)	±40	±20						
2. Max variation in dimensions H and A3 measured on multiple carriages mounted on the same rail (measured at middle of carriage at same position on rail)	15	7						
3. Parallelism (applies to the system)	See Figures 1 and 2							

Table 2 - Preload/Accuracy Combinations							
	Preload						
Accuracy Class	Clearance up to 10 µm	Light approximately 0,03 C <sup>†</sup>					
Р		В					
Н	А	В					

<sup>†</sup>Where C=Dynamic Load Rating

#### **Table 3 - Calculations** To determine proper carriage size: To determine travel life: $L = \left(\frac{C}{F}\right)^3 \cdot 100$ $C_{\min} = F \cdot \left(\frac{L}{100}\right)^{1/3}$ C<sub>min</sub> = minimum required dynamic L = normal travel life (km) load capacity of carriage (N) C = rated dynamic load capacity = equivalent load on carriage of carriage (N) (N) F = equivalent load on carriage (N)= required travel life (km) L Table 4 - Conversions 1 Ib<sub>f</sub> = 4,448 N

**1** 
$$kg_{f} = 9,8 \text{ N}$$
  
**1**  $km = 39,370 \text{ inches}$   
**1**  $Nm = 0.7376 \text{ lb}_{f}$  ft

#### **Operating Parameters**

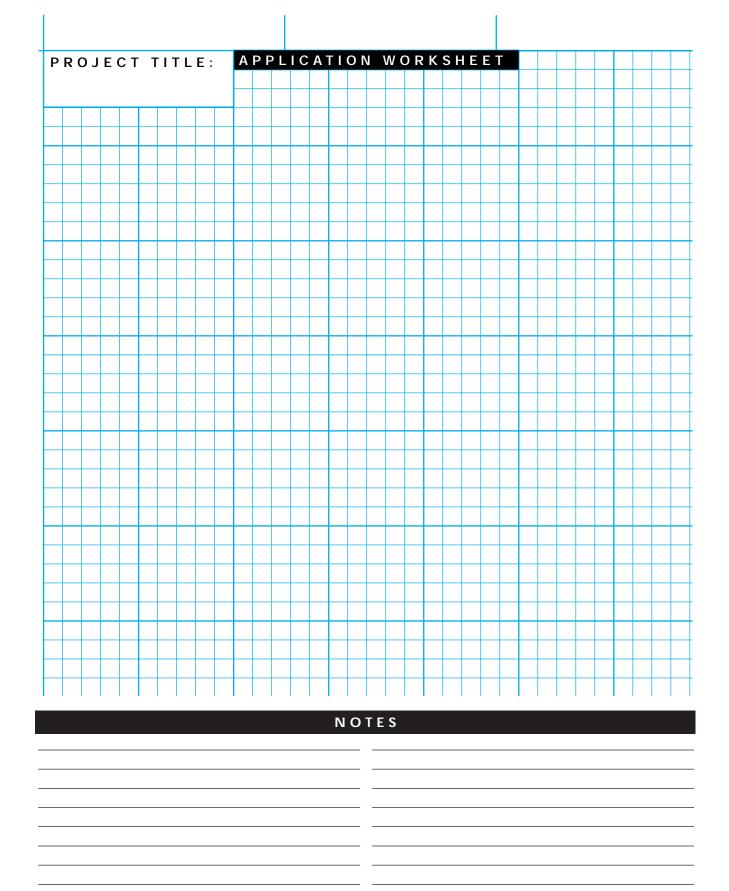
Maximum Velocity = 3 m/s Maximum Acceleration = 50 m/s<sup>2</sup> Maximum Temperature = 80 °C

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



\* The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product sure to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.
\* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Page 33



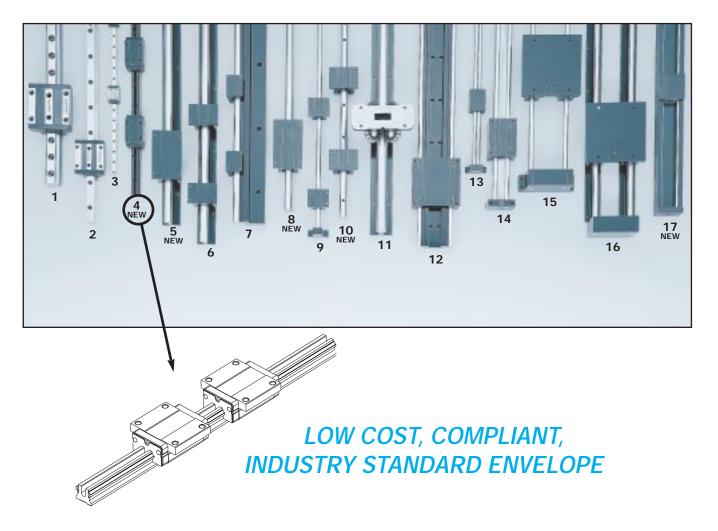
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

- -



Page 34

# AccuGlide\* T-Series\* Linear Ball Guides #4



#### Low Cost, High Loads, Reduced Weight

- Low purchase price
- Easy, low cost installation. T-Series is approx.
   5 times more forgiving of bed preparation errors than all steel profile rail linear guides
- High loads up to 25 000 N (5,620 lbf)
- Longer travel life. Proprietary design decreases induced loads caused by installation errors
- 60% lower inertia of traveling guides in multi-axis systems

- N-grade radial runout accuracy of 33 µm (0.0015 in.) over a 3 m (10 ft) length
- Drop-in replacement with industry-standard envelope and hole pattern
- Long life/easy maintenance with two lubrication ports per carriage and full seals
- Less downtime with quick-turnaround from a U.S. supplier

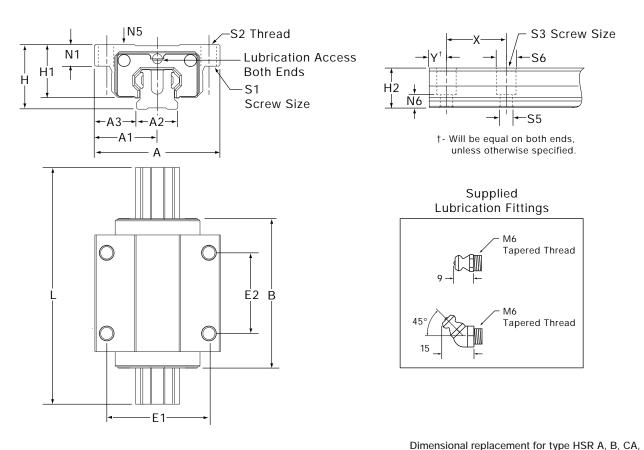


Page 35

## AccuGlide T-Series

AccuGlide\* T-Series\* Linear Guides "A" Style

Linear Guide #4 ("A" Style) Low Cost, Compliant Structure, Industry Standard Envelope



& CB style guides manufactured by THK Co.,LTD. (Japan). Thomson AccuGlide T-Series linear guide is approximately 4x more compliant.

#### (mm) Size Α **A1** A2 **A3** н H1 H2 В **E1 E2 S1 S2 S**3 **S**5 **S6** 15 47 23,5 15 16 24 19.3 15 58 38 30 Μ4 M5 M4 4,5 7,5 20 63 31,5 20 21,5 30 25 18 76 53 40 M5 M6 M5 5,8 9,5 25 70 35 23 23,5 36 29,5 22 88 57 45 M6 M8 M6 7 10,7 30 90 45 28 31 42 35 26 103 72 52 M8 M10 M8 9 14 35 100 50 34 33 48 40 29 117 82 62 M8 M10 M8 9 14

			(mm)	Load Ratings	N (lbf)	MASS Carriage Rail			
Size	Size N1 N5 N6 X					C (@100km)	kg	kg/m	
15	7,7	4,3	7,4	60	5750	5 000 (1,125)	7 050 (1,575)	0,10	0,50
20	10	6,25	7,5	60	5750	9 000 (2,025)	11 000 (2,475)	0,22	0,79
25	12	8	10	60	5750	13 000 (2,925)	15 000 (3,375)	0,30	1,06
30	14	5,8	11	80	5750	20 000 (4,500)	23 000 (5,170)	0,52	1,67
35	15,26	6,6	11	80	5750	25 000 (5,620)	28 000 (6,295)	0,74	2,27

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

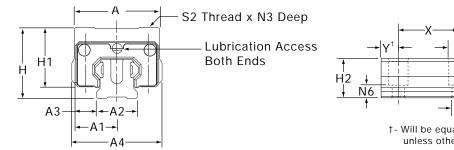
Page 36

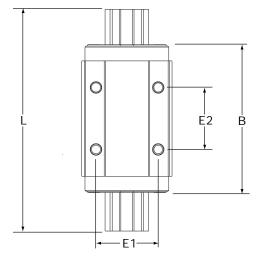
**Linear Guides** 

The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



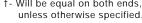
## **AccuGlide T-Series** Linear Guide #4 ("E" Style) Low Cost, Compliant Structure, Industry Standard Envelope

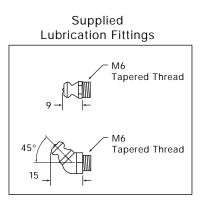




AccuGlide\* T-Series\* Linear Guide "E" Style

S3 Screw Size S6 -S5 t- Will be equal on both ends,





Dimensional replacement for type HSR R & TR style guides manufactured by THK Co., LTD. (Japan). Thomson AccuGlide T-Series linear guide is approximately 4x more compliant.

#### (mm) Size **A4** н H1 H2 **E1 E2 S2 S**3 **S**5 **S6** Α **A1** A2 **A3** В 15 28 14 15 9,5 33,7 28 23,3 15 58 26 26 M4 M4 4,5 7,5 20 44 22 20 12 41,5 30 25 18 76 32 36 M5 M5 5,8 9,5 25 23 12,5 50,9 22 35 35 7 10,7 48 24 40 33,5 88 М6 M6 30 60 30 28 16 61,1 45 38 26 103 40 40 M8 M8 9 14 70 47 29 9 35 35 34 18 68,0 55 117 50 50 M8 M8 14

			(mm)			Load RATINGS	N (lbf)	MASS Carriage Rail		
Size	Size N3 N5 N6 X L <sub>n</sub>				L <sub>max</sub>	C (@100km)	Со	kg	kg/m	
15	5	8,3	7,4	60	5 750	5 000 (1,125)	7 000 (1,575)	0,10	0,50	
20	6	6,25	7,5	60	5 750	9 000 (2,025)	11 000 (2,475)	0,22	0,79	
25	8	12	10	60	5 750	13 000 (2,925)	15 000 (3,375)	0,30	1,06	
30	10	8,8	11	80	5 750	20 000 (4,500)	23 000 (5,170)	0,52	1,67	
35	12	13,6	11	80	5 750	25 000 (5,620)	28 000 (6,295)	0,74	2,27	

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

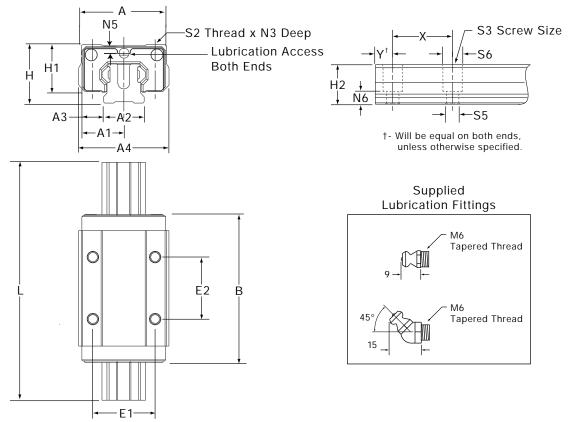


The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



## AccuGlide T-Series

Linear Guide #4 ("F" Style) Low Cost, Compliant Structure, Industry Standard Envelope



### AccuGlide\* T-Series\* Linear Guide "F" Style

Dimensional replacement for type SR W style guides manufactured by THK Co., LTD. (Japan). Thomson AccuGlide T-Series linear guide is approximately 4x more compliant.

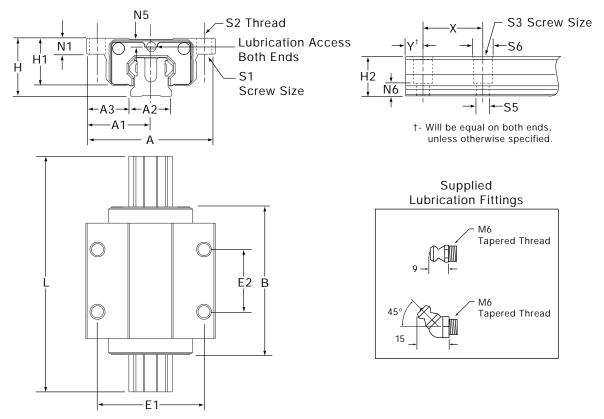
							(	mm)							
Size	Α	A1	A2	<b>A3</b>	<b>A</b> 4	Н	H1	H2	В	E1	<b>E2</b>	<b>S2</b>	<b>S</b> 3	<b>S</b> 5	<b>S6</b>
15	34	17	15	16	33,7	24	19,3	15	58	26	26	M4	M4	4,5	7,5
20	42	21	20	11	41,5	28	23	18	76	32	32	M5	M5	5,8	9,5
25	48	24	23	12,5	51,0	33	26,5	22	88	35	35	M6	M6	7	10,7
30	60	30	28	16	61,1	42	35	26	103	40	40	M8	M8	9	14
35	70	35	34	18	68,0	48	40	29	117	50	50	M8	M8	9	14

		(	(mm)				Ratings (lbf)	Mass Carriage Rail		
Size	N3	N5	N6 X L <sub>max</sub>		L <sub>max</sub>	C (@100km)	Co	kg	kg/m	
15	7	4,3	7,4	60	5 750	5 000 (1,125)	7 050 (1,575)	0,10	0,50	
20	6	4,25	7,5	60	5 750	9 000 (2,025)	11 000 (2,475)	0,22	0,79	
25	8	5	10	60	5 750	13 000 (2,925)	15 000 (3,375)	0,30	1,06	
30	8	5,8	11	80	5 750	20 000 (4,500)	23 000 (5,170)	0,52	1,67	
35	12	6,6	11	80	5 750	25 000 (5,620)	28 000 (6,295)	0,74	2,27	





## AccuGlide T-Series Linear Guide #4 ("G" Style) Low Cost, Compliant Structure, Industry Standard Envelope



Dimensional Replacement for type SR TB style guides manufactured by THK Co., LTD. (Japan). Thomson AccuGlide T-Series linear guide is approximately 4x more compliant.

### AccuGlide\* T-Series\* Linear Guide "G" Style

								(mm)								
Size	Α	<b>A1</b>	A2	<b>A</b> 3	Н	H1	H2	В	E	E1	E2	<b>S1</b>	<b>S2</b>	<b>S</b> 3	<b>S</b> 5	<b>S6</b>
15	52	26	15	16	24	19,3	15	58		41	26	M4	M5	M4	4,5	7,5
20	59	29,5	20	19,5	28	23	18	76		49	32	M5	M6	M5	5,8	9,5
25	73	36,5	23	25	33	26,5	22	88	(	60	35	M6	M8	M6	7	10,7
30	90	45	28	31	42	35	26	103		72	40	M8	M10	M8	9	14
35	100	50	34	33	48	40	29	117	1	82	50	M8	M10	M8	9	14

			(mm)			Load N	Ratings (lbf)	Mass Carriage Rail	
Size	N1	N5	N6	X	L <sub>max</sub>	C (@100km)	Co	kg	kg/m
15	7,7	4,3	7,4	60	5 750	5 000 (1,125)	7 050 (1,575)	0,10	0,50
20	8	4,25	7,5	60	5 750	9 000 (2,025)	11 000 (2,475)	0,22	0,79
25	9	5	10	60	5 750	13 000 (2,925)	15 000 (3,375)	0,30	1,06
30	14	5,8	11	80	5 750	20 000 (4,500)	23 000 (5,170)	0,52	1,67
35	15,26	6,6	11	80	5 750	25 000 (5,620)	28 000 (6,295)	0,74	2,27

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

\* The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.
\* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



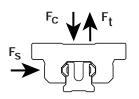


### **Dynamic Load Rating**

**C** = Dynamic load rating The dynamic load rating is based upon a 100 km travel life. In order to compare with bearings rated for 50 km, divide the dynamic rating of the bearing rated for 50 km by 1.26.

### Static Load Capacity

 $C_0$  = Static load capacity The static load capacity is the maximum radial load that should be applied to the bearing while there is no relative motion between the carriage and rail.



Dynamic

Load Rating

С

С

С

F<sub>C</sub>

Ft

 $F_{S}$ 

Load

Limit

С

0.6C

0.6C

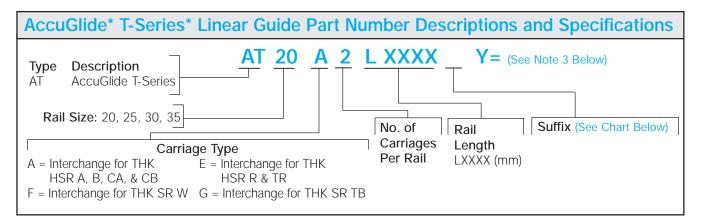
### **Operating Parameters**

Maximum Velocity = 3 m/s Maximum Acceleration = 50 m/s<sup>2</sup> Maximum Temperature = 80 °C

### **Bearing Travel Life Calculation**

<b>L</b> = (C/F) <sup>3</sup> x 100 km
where:
L = travel life, km
C = dynamic load rating, N

 $\mathbf{F}$  = applied dynamic load, N



### How to determine AccuGlide T-Series Linear Guide Part Number:

- Based on load calculations and life requirements, determine the proper AccuGlide T-Series linear guide size.
- 2. Select the assembly part number.
- **3.** The "Y" dimension (distance from rail end to first mounting hole) will be equal on both ends, unless otherwise specified.

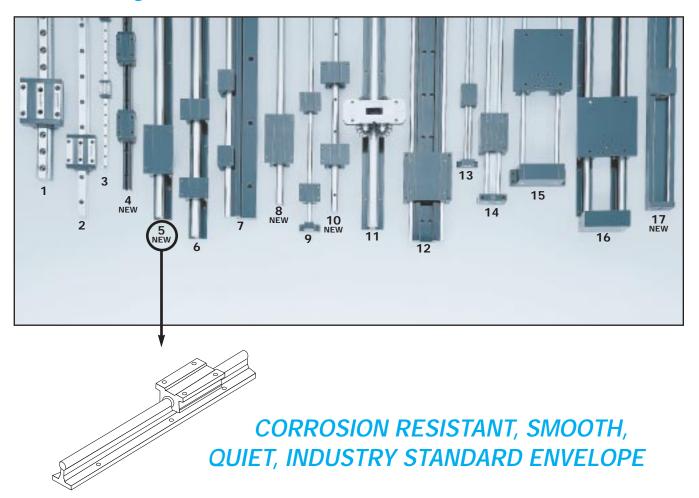
Product Options	Part Number Suffix
Armoloy <sup>®</sup> Plating	А
Low Drag Seals	LDS
Other Modifications (Dowel Holes, Special Lube Points, Special Lubricants,	SXXX
Other)	(Contact Factory)

NOTE: Carriages are dimensionally matched to rails during assembly.





## FluoroNyliner Linear Guides



### FluoroNyliner\* Linear Guides Offer:

- Thomson's new FluoroNyliner Bushing bearings that are made from the most advanced polymer components to achieve maximum performance levels
- Contamination resistance. The FluoroNyliner Linear Guides are practically immune to adverse environments, such as water washdown conditions and magnetic interference
- Self-Aligning Pillow Blocks for ease of use
- Increased bearing load capacities (or 'PV' ratings) and obtainable travel life, when used with Thomson stainless steel, 60 Case\* Linear Race\* shaft, when compared to competitive assemblies
- Specification conformance with FDA and non-lubricated applications
- Use in linear and rotary motion applications
- Operates in temperatures from -400 °F (-240 °C) to 550 °F (270 °C).

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

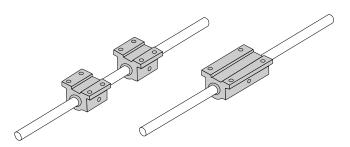


Page 41

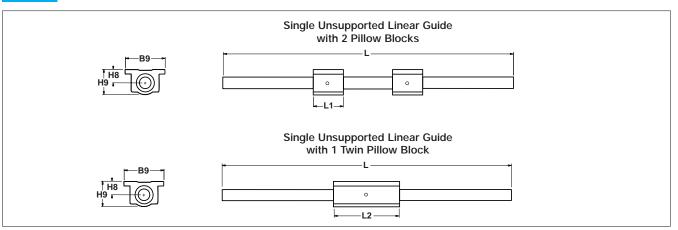
#5

# FluoroNyliner 1VA

Linear Guide #5 Corrosive/Contaminated Environments



### INCH



FluoroNyliner* L	FluoroNyliner* Linear Guide 1VA Single Unsupported with 2 Pillow Blocks         (Dimensions in inches)										
Part Number	Nominal Diameter	L1	H8	H9	В9	Pillow Block					
1VA-06-AOO	.375	1.31	.500	.94	1.75	FNYBUPB06A-XS					
1VA-08-AOO	.500	1.69	.687	1.25	2.00	FNYBUPB08A-XS					
1VA-10-AOO	.625	1.94	.875	1.63	2.50	FNYBUPB10A-XS					
1VA-12-AOO	.750	2.06	.937	1.75	2.75	FNYBUPB12A-XS					
1VA-16-AOO	1.000	2.81	1.187	2.19	3.25	FNYBUPB16A-XS					
1VA-20-AOO	1.250	3.63	1.500	2.81	4.00	FNYBUPB20A-XS					
1VA-24-AOO	1.500	4.00	1.750	3.25	4.75	FNYBUPB24A-XS					

FluoroNyliner Lir	near Guide 1VA S	ingle Unsupported	d with 1 Twin Pillow	v Block	(D	imensions in inches)
Part	Nominal	L2	H8	H9	B9	Pillow
Number	Diameter					Block
1VA-06-BOO	.375	2.75	.500	.94	1.75	FNYBUTWN06A-XS
1VA-08-BOO	.500	3.50	.687	1.25	2.00	FNYBUTWN08A-XS
1VA-10-BOO	.625	4.00	.875	1.63	2.50	FNYBUTWN10A-XS
1VA-12-BOO	.750	4.50	.937	1.75	2.75	FNYBUTWN12A-XS
1VA-16-BOO	1.000	6.00	1.187	2.19	3.25	FNYBUTWN16A-XS
1VA-20-BOO	1.250	7.50	1.500	2.81	4.00	FNYBUTWN20A-XS
1VA-24-BOO	1.500	9.00	1.750	3.25	4.75	FNYBUTWN24A-XS

#### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for deflection calculations.

#### Maximum Operating Parameters per Bearing

Characteristic	Limit
Liner Temperature Range	-240 °C to 288 °C (-400 °F to 550 °F)
Velocity, dry	42.7 m/min. Continuous
Velocity, dry	122 m/min. Intermittent
Velocity, lubricated	122 m/min. Continuous
Pressure	10.35 MPa
PV	21 MPa/m/min





## FluoroNyliner\* Linear Guide 1VA Benefits:

- Requires only one part number to specify entire Linear Guide.
- Design flexibility with custom end supports.
- Used in end supported applications
   when spanning or bridging a gap.

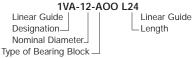
## FluoroNyliner Linear Guide 1VA Components:

- 2 self-aligning FluoroNyliner
   Bushing bearing pillow blocks or
   1 self-aligning FluoroNyliner
   bushing bearing Twin Pillow block.
  - 1 Stainless Steel 60 Case\* LinearRace\* shaft.

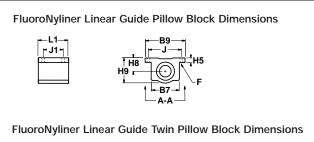
#### Specifying a Thomson Linear Guide:

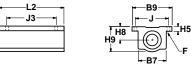
1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System

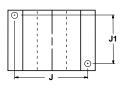


(Dimonsions in inchos)









View A-A

#### Self-Aligning Pillow Blocks

Part	Nom.	L1	H9	H8	H5	B9	B7	J	J1		F	Wt.
Number	Dia.									Bolt	Hole	lb
FNYBUPB06A-XS	.375	.131	.94	.500	.19	1.75	1.12	1.44	.88(2)	#6	.16	.13
FNYBUPB08A-XS	.500	1.69	1.25	.687	.25	2.00	1.38	1.69	1.00	#6	.16	.20
FNYBUPB10A-XS	.625	1.94	1.63	.875	.28	2.50	1.75	2.125	1.125	#8	.19	.50
FNYBUPB12A-XS	.750	2.06	1.75	.937	.31	2.75	1.88	2.38	1.25	#8	.19	.62
FNYBUPB16A-XS	1.000	2.81	2.19	1.187	.38	3.25	2.38	2.88	1.75	#10	.22	1.24
FNYBUPB20A-XS	1.250	3.63	2.81	1.500	.43	4.00	3.00	3.50	2.00	#10	.22	2.57
FNYBUPB24A-XS	1.500	4.00	3.25	1.750	.50	4.75	3.50	4.12	2.50	1/4	.28	3.94
Linustra NAstanial Alum	lousing Material: Aluminum Allou Diagle Anodized											

Housing Material: Aluminum Alloy Black Anodized

 $^{\scriptscriptstyle (2)}\mbox{Two}$  mounting holes as shown in view A-A for size .375

Self-Aligning Twin Pillow Blocks									
Part Number	Nom. Dia.	L2	J3	Wt. Ib					
FNYBUTWN06A-XS	.375	2.75	2.25	.25					
FNYBUTWN08A-XS	.500	3.50	2.50	.40					
FNYBUTWN10A-XS	.625	4.00	3.00	1.00					
FNYBUTWN12A-XS	.750	4.50	3.50	1.24					
FNYBUTWN16A-XS	1.000	6.00	4.50	2.48					
FNYBUTWN20A-XS	1.250	7.50	5.50	5.14					
FNYBUTWN24A-XS	1.500	9.00	6.50	8.08					

Housing Material: Aluminum Alloy Black Anodized

Performance Note: For detailed explanations of FluoroNyliner Linear Guide Dynamic and Static Load Capacities, Frictional Characteristics, Wear Rates, Speeds, and Life Expectancy please contact Thomson Linear Guides Applications Engineering department.

**Product Note:** FluoroNyliner linear guides are shipped free of all lubricants. It is the responsibility of the product user to determine lubricant compatibility with the FluoroNyliner bearing material.

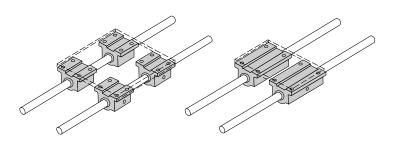
**Product Options:** FluoroNyliner linear guides are available with various inner race materials and platings to accommodate different environments.



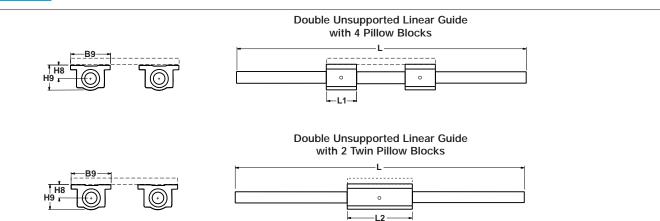


# FluoroNyliner 1VB

Linear Guide #5 Corrosive/Contaminated Environments



INCH



FluoroNyliner* Li	FluoroNyliner* Linear Guide 1VB Double Unsupported with 4 Pillow Blocks									
Part Number	Nominal Diameter	L1	H8	H9	B9	Pillow Block				
1VB-06-AOO	.375	1.31	.500	.94	1.75	FNYBUPB06A-XS				
1VB-08-AOO	.500	1.69	.687	1.25	2.00	FNYBUPB08A-XS				
1VB-10-AOO	.625	1.94	.875	1.63	2.50	FNYBUPB10A-XS				
1VB-12-AOO	.750	2.06	.937	1.75	2.75	FNYBUPB12A-XS				
1VB-16-AOO	1.000	2.81	1.187	2.19	3.25	FNYBUPB16A-XS				
1VB-20-AOO	1.250	3.63	1.500	2.81	4.00	FNYBUPB20A-XS				
1VB-24-AOO	1.500	4.00	1.750	3.25	4.75	FNYBUPB24A-XS				

FluoroNyliner Lir	FluoroNyliner Linear Guide 1VB Double Unsupported with 2 TWIN Pillow Blocks (Dimensions in inches)										
Part Number	Nominal Diameter	L2	H8	H9	B9	Pillow Block					
1VB-06-BOO	.375	2.75	.500	.94	1.75	FNYBUTWN06A-XS					
1VB-08-BOO	.500	3.50	.687	1.25	2.00	FNYBUTWN08A-XS					
1VB-10-BOO	.625	4.00	.875	1.63	2.50	FNYBUTWN10A-XS					
1VB-12-BOO	.750	4.50	.937	1.75	2.75	FNYBUTWN12A-XS					
1VB-16-BOO	1.000	6.00	1.187	2.19	3.25	FNYBUTWN16A-XS					
1VB-20-BOO	1.250	7.50	1.500	2.81	4.00	FNYBUTWN20A-XS					
1VB-24-BOO	1.500	9.00	1.750	3.25	4.75	FNYBUTWN24A-XS					

#### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for deflection calculations.

#### Maximum Operating Parameters per Bearing

Characteristic	Limit
Liner Temperature Range	-240° C to 288° C (-400° F to 550° F)
Velocity, dry	42.7 m/min. Continuous
Velocity, dry	122 m/min. Intermittent
Velocity, lubricated	122 m/min. Continuous
Pressure	10.35 MPa
PV	21 MPa/m/min





#### FluoroNyliner\* Linear Guide **1VB Benefits:**

- Allows for custom table mounting.
- Design flexibility for custom end supports.
- Double LinearRace\* shaft configuration resists torque.
- Used in end supported applications when spanning or bridging a gap.

#### FluoroNyliner Linear Guide **1VB Components:**

- 4 self-aligning FluoroNyliner Bushing bearing pillow blocks or 2 self-aligning FluoroNyliner Bushing bearing Twin Pillow blocks.
- 2 Stainless Steel 60 Case\* LinearRace shafts.

#### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System

Designation -

#### 1VB-12-AOO L24 Linear Guide

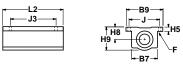
Linear Guide Length

Nominal Diameter -Type of Bearing Block

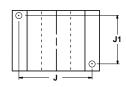
FluoroNyliner Linear Guide Pillow Block Dimensions

FluoroNyliner Linear Guide Twin Pillow Block Dimensions

B7



#### **Pillow Block** Mounting Hole Position for Size .375



View A-A

Self-Aligning Pillow Blocks (Dimensions in inches)												
Part	Nom.	L1	H9	H8	H5	B9	B7	J	J1		F	Wt.
Number	Dia.									Bolt	Hole	lb.
FNYBUPB06A-XS	.375	.131	.94	.500	.19	1.75	1.12	1.44	.88(2)	#6	.16	.13
FNYBUPB08A-XS	.500	1.69	1.25	.687	.25	2.00	1.38	1.69	1.00	#6	.16	.20
FNYBUPB10A-XS	.625	1.94	1.63	.875	.28	2.50	1.75	2.125	1.125	#8	.19	.50
FNYBUPB12A-XS	.750	2.06	1.75	.937	.31	2.75	1.88	2.38	1.25	#8	.19	.62
FNYBUPB16A-XS	1.000	2.81	2.19	1.187	.38	3.25	2.38	2.88	1.75	#10	.22	1.24
FNYBUPB20A-XS	1.250	3.63	2.81	1.500	.43	4.00	3.00	3.50	2.00	#10	.22	2.57
FNYBUPB24A-XS	1.500	4.00	3.25	1.750	.50	4.75	3.50	4.12	2.50	1/4	.28	3.94

Housing Material: Aluminum Alloy Black Anodized

<sup>(2)</sup>Two mounting holes as shown in view A-A for size .375

Self-Aligning Twin Pillow Blocks									
Part Number	Nom. Dia.	L2	J3	Wt. Ib					
FNYBUTWN06A-XS	.375	2.75	2.25	.25					
FNYBUTWN08A-XS	.500	3.50	2.50	.40					
FNYBUTWN10A-XS	.625	4.00	3.00	1.00					
FNYBUTWN12A-XS	.750	4.50	3.50	1.24					
FNYBUTWN16A-XS	1.000	6.00	4.50	2.48					
FNYBUTWN20A-XS	1.250	7.50	5.50	5.14					
FNYBUTWN24A-XS	1.500	9.00	6.50	8.08					

Housing Material: Aluminum Alloy Black Anodized

Performance Note: For detailed explanations of FluoroNyliner Linear Guide Dynamic and Static Load Capacities, Frictional Characteristics, Wear Rates, Speeds, and Life Expectancy please contact Thomson Linear Guides Applications Engineering department.

Product Note: FluoroNyliner linear guides are shipped free of all lubricants. It is the responsibility of the product user to determine lubricant compatibility with the FluoroNyliner bearing material.

Product Options: FluoroNyliner linear guides are available with various inner race materials and platings to accommodate different environments.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



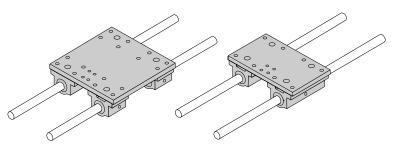
The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



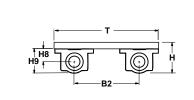
## FluoroNyliner 1VC

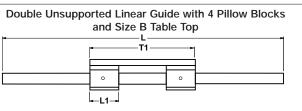
## Linear Guide #5

with Table Top Corrosive/Contaminated Environments

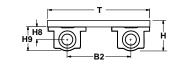


INCH





Double Unsupported Linear Guide with 2 Twin Pillow Blocks and Size A Table Top



L	-
0	
T2	

FluoroNyliner* I	Linear Guide	e 1VC Double	e Unsupport	ed with 4 Pi	llow Blocks	and Table	e Top (Size	e <b>B)</b> (Dii	mensions in inches)
Part Number	Nom. Dia.	L1	Н	B2	H8	H9	Т	T1	Pillow Block
1VC-06-AOB	.375	1.31	1.19	2.50	.500	.94	4.50	4.50	FNYBUPB06A-XS
1VC-08-AOB	.500	1.69	1.63	3.25	.687	1.25	5.50	5.50	FNYBUPB08A-XS
1VC-10-AOB	.625	N\A	N\A	N\A	N\A	N\A	N\A	N\A	FNYBUPB10A-XS
1VC-12-AOB	.750	2.06	2.25	4.50	.937	1.75	7.50	7.50	FNYBUPB12A-XS
1VC-16-AOB	1.000	2.81	2.69	5.50	1.187	2.19	9.00	9.00	FNYBUPB16A-XS
1VC-20-AOB	1.250	3.63	3.56	6.75	1.500	2.81	11.00	11.00	FNYBUPB20A-XS
1VC-24-AOB	1.500	4.00	4.00	8.00	1.750	3.25	13.00	13.00	FNYBUPB24A-XS

FluoroNyliner L	inear Guide	1VC Double Ur	nsupported wi	th 2 Twin Pillo	w Blocks and	I Table Top	(Size A)	(Dimensions in inches)
Part	Nom.	Н	B2	H8	H9	Т	T2	Pillow
Number	Dia.							Block
1VC-06-BOA	.375	1.19	2.50	.500	.94	4.50	2.75	FNYBUTWN06A-XS
1VC-08-BOA	.500	1.63	3.25	.687	1.25	5.50	3.50	FNYBUTWN08A-XS
1VC-10-BOA	.625	N\A	N\A	N\A	N\A	N\A	N\A	FNYBUTWN10A-XS
1VC-12-BOA	.750	2.25	4.50	.937	1.75	7.50	4.50	FNYBUTWN12A-XS
1VC-16-BOA	1.000	2.69	5.50	1.187	2.19	9.00	6.00	FNYBUTWN26A-XS
1VC-20-BOA	1.250	3.56	6.75	1.500	2.81	11.00	7.50	FNYBUTWN20A-XS
1VC-24-BOA	1.500	4.00	8.00	1.750	3.25	13.00	9.00	FNYBUTWN24A-XS

#### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for deflection calculations.

#### Maximum Operating Parameters per Bearing

Characteristic	Limit
Liner Temperature Range	-240° C to 288° C (-400° F to 550° F)
Velocity, dry	42.7 m/min. Continuous
Velocity, dry	122 m/min. Intermittent
Velocity, lubricated	122 m/min. Continuous
Pressure	10.35 MPa
PV	21 MPa/m/min







## FluoroNyliner\* Linear Guide 1VC Benefits:

- Includes table top with standard tapped holes for quick and easy mounting of the work piece.
- Includes Ball Screw Assembly attachment holes for ease of assembly and actuation.
- Used in end supported applications
   when spanning or bridging a gap.

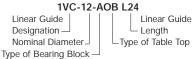
## FluoroNyliner Linear Guide 1VC Components:

- 4 self-aligning FluoroNyliner Bushing bearing pillow blocks or 2 self-aligning FluoroNyliner Bushing bearing Twin Pillow blocks.
- 2 stainless steel 60 Case\* LinearRace\* shafts.
- 1 mounting table top with work piece and Ball Screw Assembly attachment holes.

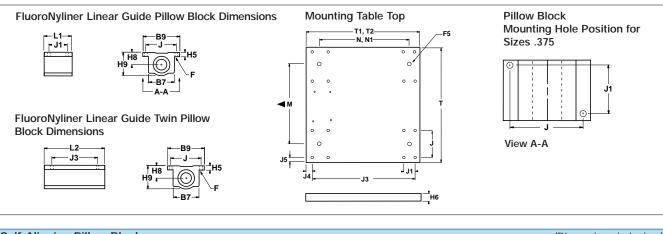
#### Specifying a Thomson Linear Guide

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System



Linear Guides



Self-Aligning Pillow Blocks (Dimensions in inches)												
Part	Nom.	L1	H9	H8	H5	B9	B7	J	J1		F	Wt.
Number	Dia.									Bolt	Hole	lb.
FNYBUPB06A-XS	.375	.131	.94	.500	.19	1.75	1.12	1.44	.88(2)	#6	.16	.13
FNYBUPB08A-XS	.500	1.69	1.25	.687	.25	2.00	1.38	1.69	1.00	#6	.16	.20
FNYBUPB10A-XS	.625	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
FNYBUPB12A-XS	.750	2.06	1.75	.937	.31	2.75	1.88	2.38	1.25	#8	.19	.62
FNYBUPB16A-XS	1.000	2.81	2.19	1.187	.38	3.25	2.38	2.88	1.75	#10	.22	1.24
FNYBUPB20A-XS	1.250	3.63	2.81	1.500	.43	4.00	3.00	3.50	2.00	#10	.22	2.57
FNYBUPB24A-XS	1.500	4.00	3.25	1.750	.50	4.75	3.50	4.12	2.50	1/4	.28	3.94
I I NA-towiel Alive												

Housing Material: Aluminum Alloy Black Anodized

<sup>(2)</sup>Two mounting holes as shown in view A-A for size .375

#### Self-Aligning Twin Pillow Blocks

• •				
Part	Nom.	L2	J3	Wt.
Number	Dia.			lb.
FNYBUTWN06A-XS	.375	2.75	2.25	.25
FNYBUTWN08A-XS	.500	3.50	2.50	.40
FNYBUTWN10A-XS	.625	4.00	3.00	1.00
FNYBUTWN12A-XS	.750	4.50	3.50	1.24
FNYBUTWN16A-XS	1.000	6.00	4.50	2.48
FNYBUTWN20A-XS	1.250	7.50	5.50	5.14
FNYBUTWN24A-XS	1.500	9.00	6.50	8.08

Performance Note: For detailed explanations of FluoroNyliner Linear Guide Dynamic and Static Load Capacities, Frictional Characteristics, Wear Rates, Speeds, and Life Expectancy please contact Thomson Linear Guides Applications Engineering department.

**Product Note:** FluoroNyliner linear guides are shipped free of all lubricants. It is the responsibility of the product user to determine lubricant compatibility with the FluoroNyliner bearing material.

**Product Options:** FluoroNyliner linear guides are available with various inner race materials and platings to accommodate different environments.

Housing Material: Aluminum Alloy Black Anodized

#### Mounting Table Top (Dimensions in inches) Nominal All Table Tops Table Top Size B Table Top Size A Diameter Т Μ F5 Τ1 J1 J4 Ν Τ2 J3 J4 J5 N1 J H6 J5 .375 22 .28 .25 .28 4.5 2.50 1.44 .250 #10-32 4.5 .88(2) 3.75 2.75 2.25 2.0 .500 5.5 3.25 1.69 .375 1/4-20 5.5 1 00 34 .28 4 50 3.50 2.50 .50 31 2.5 N/A N/A N/A .625 N/A 750 7.5 4.50 2.38 500 5/16-18 7.5 1.25 .41 31 6.00 4.50 3.50 50 .31 3.0 1.000 9.0 5.50 2.88 .500 3/8-16 9.0 1.75 .53 .31 7.00 6.00 4.50 .75 .31 4.0 1.250 11.0 6.75 3.50 .750 1/2-13 11.0 2.00 .82 .38 8.50 7.50 5.50 1.00 .38 5.0 1.500 8.00 13.0 4.12 .750 1/2-13 13.0 2.50 .75 44 10.00 9.00 6.50 1.25 .44 6.0

Carriage Material: Aluminum Alloy Black Anodized

 $^{\mbox{\tiny (2)}}\mbox{Two mounting holes as shown in view A-A for size .375}$ 

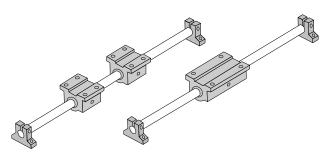
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



\* The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond subt replacement.
\* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

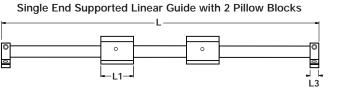


### FluoroNyliner 1VA Linear Guide #5 Corrosive/Contaminated Environments



### INCH





HS	Jol
	-Bb-

Single End Supported Linear Guide with 1 Twin Pillow Block

Linear Guide 1VA with Type SB End Support Block

•	L	
0 <u></u>	○ ►L2►	

FluoroNyline	uoroNyliner* Linear Guide 1VA Single End Supported with 2 Pillow Blocks (Dimensions in inches)												
		1	<u> </u>		1	1	r	1			1	,	
Part N	umber	Nominal	L1	L3	H	HS	В	Bb	B9	Pillow	Shaft Si	upport	
W/ Type ASB	W/ Type SB	Diameter								Block	Туре	Туре	
Shaft	Shaft										ASB	SB	
Support	Support												
1VA-06-AHO	-	.375	1.31	.56	1.062	-	1.63	-	1.75	FNYBUPB06A-XS	ASB-6-XS	-	
1VA-08-AHO	1VA-08-AJO	.500	1.69	.63	1.562	1.687	2.00	2.00	2.00	FNYBUPB08A-XS	ASB-8-XS	SB-8-XS	
-	1VA-10-AJO	.625	1.94	.67	-	1.875	-	2.50	2.50	FNYBUPB10A-XS		SB-10-XS	
1VA-12-AHO	1VA-12-AJO	.750	2.06	.75	2.062	2.187	2.50	2.75	2.75	FNYBUPB12A-XS	ASB-12-XS	SB-12-XS	
1VA-16-AHO	1VA-16-AJO	1.000	2.81	1.00	2.562	2.687	3.25	3.25	3.25	FNYBUPB16A-XS	ASB-16-XS	SB-16-XS	
-	1VA-20-AJO	1.250	3.63	1.13	-	3.250	-	-	4.00	FNYBUPB20A-XS	-	SB-20-XS	
1VA-24-AHO	1VA-24-AJO	1.500	4.00	1.25	3.750	3.750	4.75	4.75	4.75	FNYBUPB24A-XS	ASB-24-XS	SB-24-XS	

FluoroNyliner	luoroNyliner Linear Guide 1VA Single End Supported with 1 Twin Pillow Block (Dimensions in inches													
Part N	lumber	Nom.	L2	L3	Н	HS	В	Bb	B9	Max.	Pillow	Shaft S	upport	
W/ Type ASB	W/ Type SB	Dia.								Stroke	Block	Туре	Туре	
Shaft	Shaft									Length		ASB	SB	
Support	Support													
1VA-06-BHO	_	.375	2.75	.56	1.062	-	1.63	-	1.75	L-(3.88)	FNYBUTWN06A-XS	ASB-6-XS	-	
1VA-08-BHO	1VA-08-BJO	.500	3.50	.63	1.562	1.687	2.00	2.00	2.00	L-(4.75)	FNYBUTWN08A-XS	ASB-8-XS	SB-8-XS	
-	1VA-10-BJO	.625	4.00	.69	-	1.875	-	2.50	2.50	L-(5.38)	FNYBUTWN10A-XS	-	SB-10-XS	
1VA-12-BHO	1VA-12-BJO	.750	4.50	.75	2.062	2.187	2.50	2.75	2.75	L-(6.00)	FNYBUTWN12A-XS	ASB-12-XS	SB-12-XS	
1VA-16-BHO	1VA-16-BJO	1.000	6.00	1.00	2.562	2.687	3.25	3.25	3.25	L-(8.00)	FNYBUTWN16A-XS	ASB-16-XS	SB-16-XS	
-	1VA-20-BJO	1.250	7.50	1.13	-	3.250	-	4.00	4.00	L-(9.75)	FNYBUTWN20A-XS	-	SB-20-XS	
1VA-24-BHO	1VA-24-BJO	1.500	9.00	1.25	3.750	3.750	4.75	4.75	4.75	L-(11.50)	FNYBUTWN24A-XS	ASB-24-XS	SB-24-XS	

#### Shaft Deflection Note:

Page 48

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for deflection calculations.

#### Maximum Operating Parameters per Bearing

Characteristic	Limit
Liner Temperature Range	-240 <sup>°</sup> C to 288 <sup>°</sup> C (-400 <sup>°</sup> F to 550 <sup>°</sup> F)
Velocity, dry	42.7 m/min. Continuous
Velocity, dry	122 m/min. Intermittent
Velocity, lubricated	122 m/min. Continuous
Pressure	10.35 MPa
PV	21 MPa/m/min

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.

Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



#### FluoroNyliner Linear Guide **1VA Benefits:**

- Requires only one part number to specify entire linear guide.
- Available with 60 Case\* LinearRace\* shaft end support blocks in either light weight aluminum or rigid iron materials.
- Used to provide increased stability or torque resistance in linear system applications.

FluoroNyliner Linear Guide

**Pillow Block Dimensions** 

#### FluoroNvliner Linear Guide **1VA Components:**

- 2 self-aligning FluoroNyliner Bushing bearing pillow blocks or 1 self-aligning FluoroNyliner Bushing bearing twin pillow block.
- 1 stainless steel 60 Case LinearRace shaft
- 2 shaft end support blocks.

#### Specifying a Thomson Linear Guide

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System

1VA-12-AHO L24 Linear Guide Linear Guide Designation\_

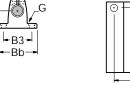
Nominal Diameter Type of Bearing Block

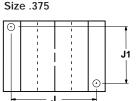
-Length

Type of Support

Type ASB LinearRace Type SB LinearRace **Pillow Block** Mounting Hole Position for Shaft End Support Block Shaft End Support Block H<sub>3</sub> -B3

R

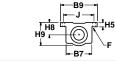




(Dimensions in inches)



FluoroNyliner Linear Guide Twin Pillow Block Dimensions



.B7

#### Self-Aligning Pillow Blocks

12

J3

Scil-Angring I in														
Part	Nom.	L1	H9	H8	H5	B9	B7	J	J1		F			
Number	Dia.									Bolt	Hole	lb		
FNYBUPB06A-XS	.375	.131	.94	.500	.19	1.75	1.12	1.44	.88(2)	#6	.16	.13		
FNYBUPB08A-XS	.500	1.69	1.25	.687	.25	2.00	1.38	1.69	1.00	#6	.16	.20		
FNYBUPB10A-XS	.625	1.94	1.63	.875	.28	2.50	1.75	2.125	1.125	#8	.19	.50		
FNYBUPB12A-XS	.750	2.06	1.75	.937	.31	2.75	1.88	2.38	1.25	#8	.19	.62		
FNYBUPB16A-XS	1.000	2.81	2.19	1.187	.38	3.25	2.38	2.88	1.75	#10	.22	1.24		
FNYBUPB20A-XS	1.250	3.63	2.81	1.500	.43	4.00	3.00	3.50	2.00	#10	.22	2.57		
FNYBUPB24A-XS	1.500	4.00	3.25	1.750	.50	4.75	3.50	4.12	2.50	1/4	.28	3.94		
Linuate a Masterial Alue														

Housing Material: Aluminum Alloy Black Anodized

<sup>(2)</sup>Two mounting holes as shown in view A-A for size .375

Self-Aligning Twin P	illow Blo	ocks						
Part	Nom.	L2	J3	Wt.				
Number	Dia.			lb.				
FNYBUTWN06A-XS .375 2.75 2.25 .25								
FNYBUTWN08A-XS	.500	3.50	2.50	.40				
FNYBUTWN10A-XS	.625	4.00	3.00	1.00				
FNYBUTWN12A-XS	.750	4.50	3.50	1.24				
FNYBUTWN16A-XS	1.000	6.00	4.50	2.48				
FNYBUTWN20A-XS	1.250	7.50	5.50	5.14				
FNYBUTWN24A-XS	1.500	9.00	6.50	8.08				
Housing Material: Aluminum	n Alloy Bla	ck Anodiz	zed					

Performance Note: For detailed explanations of FluoroNyliner Linear Guide Dynamic and Static Load Capacities, Frictional Characteristics, Wear Rates, Speeds, and Life Expectancy please contact Thomson Linear Guides Applications Engineering department.

Product Note: FluoroNyliner linear guides are shipped free of all lubricants. It is the responsibility of the product user to determine lubricant compatibility with the FluoroNyliner bearing material.

Product Options: FluoroNyliner linear guides are available with various inner race materials and platings to accommodate different environments.

Type ASB LinearRace Shaft End Support Block Type SB LinearRace Shaft End Support Block Nom. В Part L3 Ηh Hc Bb B3 G Part Nom. L3 H3 H1 Β3 G Wt. Bolt Hole Number Number Dia. Dia. Bolt Hole lb ASB-06-XS .375 .56 1.00 .562 1.62 1.25 #6 .16 .08 SB-8-XS .500 .63 1.62 1.000 2.00 1.50 #8 .19 SB-10-XS .625 .69 1.75 1.00 2.50 1.875 #10 .22 ASB-08-XS .500 .63 1.48 .875 2.00 1.50 #8 .19 .11 SB-12-XS .750 .75 2.12 1.250 2.75 2.00 #10 .22 ASB-10-XS .625 \_ \_ \_ \_ \_ \_ SB-16-XS 1.000 1.00 2.56 1.500 3.25 2.50 1/4 .28 ASB-12-XS .750 .75 1.95 1.125 2.50 2.00 #10 .22 .22 **SB-20-XS** 1.250 1.13 3.00 1.750 4.00 3.00 <sup>5</sup>/16 .34 ASB-16-XS 1.000 1.00 2.48 1.375 3.25 2.50 1/4 .28 .44 **SB-24-XS** 1.500 1.25 3.50 2.000 4.75 3.50 5/16 .34 <sup>5</sup>/16 ASB-24-XS 1.500 1.250 3.50 2.000 4.75 3.50 .34 1.16

End Support Material: Aluminum Alloy Black Anodized

Material: Iron

#### For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



\//t

lb

.3

.4

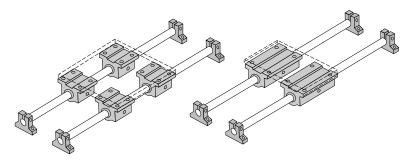
.5

1.0

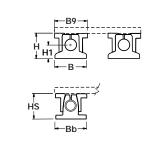
2.0

2.6

### FluoroNyliner 1VB Linear Guide #5 Corrosive/Contaminated Environments

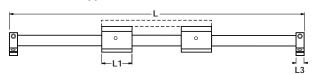


### INCH



Linear Guide 1VB

with Type SB End Support Block



Double End Supported Linear Guide with 4 Pillow Blocks

Double End Supported Linear Guide with 2 Twin Pillow Blocks

		•
Ľ	0	
Ħ	•l 2•	
		·

FluoroNyline	luoroNyliner* Linear Guide 1VB Double End Supported with 4 Pillow Blocks (Dimensions in inches												
Part N	umber	Nominal	L1	L3	Н	HS	В	Bb	B9	Pillow	Shaft S	upport	
W/ Type ASB	W/ Type SB	Diameter								Block	Туре	Туре	
Shaft	Shaft										ASB	SB	
Support	Support												
1VB-06-AHO	-	.375	1.31	.56	1.062	-	1.63	-	1.75	FNYBUPB06A-XS	ASB-6-XS	-	
1VB-08-AHO	1VB-08-AJO	.500	1.69	.63	1.562	1.687	2.00	2.00	2.00	FNYBUPB08A-XS	ASB-8-XS	SB-8-XS	
-	1VB-10-AJO	.625	1.94	.69	-	1.875	-	2.50	2.50	FNYBUPB10A-XS	-	SB-10-XS	
1VB-12-AHO	1VB-12-AJO	.750	2.06	.75	2.062	2.187	2.50	2.75	2.75	FNYBUPB12A-XS	ASB-12-XS	SB-12-XS	
1VB-16-AHO	1VB-16-AJO	1.000	2.81	1.00	2.562	2.687	3.25	3.25	3.25	FNYBUPB16A-XS	ASB-16-XS	SB-16-XS	
-	1VB-20-AJO	1.250	3.63	1.13	-	3.250	-	-	4.00	FNYBUPB20A-XS	-	SB-20-XS	
1VB-24-AHO	1VB-24-AJO	1.500	4.00	1.25	3.750	3.750	4.75	4.75	4.75	FNYBUPB24A-XS	ASB-24-XS	SB-24-XS	

FluoroNyliner	IuoroNyliner Linear Guide 1VB Double End Supported with 2 Twin Pillow Blocks (Dimensions in inches												
Part N	lumber	Nom.	L2	L3	Н	HS	В	Bb	B9	Max.	Pillow	Shaft S	upport
W/ Type ASB	W/ Type SB	Dia.								Stroke	Block	Туре	Туре
Shaft	Shaft									Length		ASB	SB
Support	Support												
1VB-06-BHO	-	.375	2.75	.56	1.062	-	1.63	-	1.75	L-(3.88)	FNYBUTWN06A-XS	ASB-6-XS	-
1VB-08-BHO	1VB-08-BJO	.500	3.50	.63	1.562	1.687	2.00	2.00	2.00	L-(4.75)	FNYBUTWN08A-XS	ASB-8-XS	SB-8-XS
-	1VB-10-BJO	.625	4.00	.69	-	1.875	-	2.50	2.50	L-(5.38)	FNYBUTWN10A-XS	-	SB-10-XS
1VB-12-BHO	1VB-12-BJO	.750	4.50	.75	2.062	2.187	2.50	2.75	2.75	L-(6.00)	FNYBUTWN12A-XS	ASB-12-XS	SB-12-XS
1VB-16-BHO	1VB-16-BJO	1.000	6.00	1.00	2.562	2.687	3.25	3.25	3.25	L-(8.00)	FNYBUTWN16A-XS	ASB-16-XS	SB-16-XS
-	1VB-20-BJO	1.250	7.50	1.13	-	3.250	-	4.00	4.00	L-(9.75)	FNYBUTWN20A-XS	-	SB-20-XS
1VB-24-BHO	1VB-24-BJO	1.500	9.00	1.25	3.750	3.750	4.75	4.75	4.75	L-(11.50)	FNYBUTWN24A-XS	ASB-24-XS	SB-24-XS

#### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for deflection calculations.

#### Maximum Operating Parameters per Bearing

Characteristic	Limit
Liner Temperature Range	-240° C to 288° C (-400° F to 550° F)
Velocity, dry	42.7 m/min. Continuous
Velocity, dry	122 m/min. Intermittent
Velocity, lubricated	122 m/min. Continuous
Pressure	10.35 MPa
PV	21 MPa/m/min

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.

Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



#### FluoroNyliner\* Linear Guide **1VB Benefits:**

- Requires only one part number to specify entire linear guide.
- Available with 60 Case\* LinearRace\* shaft end support blocks in either light weight aluminum or rigid iron materials.
- Used in end supported applications when spanning or bridging a gap.

#### FluoroNyliner Linear Guide **1VB** Components:

- 4 self-aligning FluoroNyliner Bushing bearing pillow blocks or 2 self-aligning FluoroNyliner Bushing bearing twin pillow blocks.
- 2 stainless steel 60 Case LinearRace shafts.
- 4 shaft end support blocks.

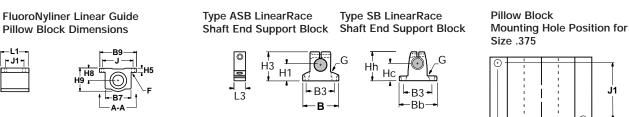
#### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System

1VB-12-AHO L24 Linear Guide Linear Guide Designation--Length Nominal Diameter Type of Support

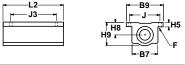
Type of Bearing Block -





FluoroNyliner Linear Guide Twin Pillow Block Dimensions

- J1 -



-R7

Self-Aligning Pill	elf-Aligning Pillow Blocks (Dimensions in inches												
Part	Nom.	L1	H9	H8	H5	B9	B7	J	J1		F		
Number	Dia.									Bolt	Hole	lb	
FNYBUPB06A-XS	.375	.131	.94	.500	.19	1.75	1.12	1.44	.88(2)	#6	.16	.13	
FNYBUPB08A-XS	.500	1.69	1.25	.687	.25	2.00	1.38	1.69	1.00	#6	.16	.20	
FNYBUPB10A-XS	.625	1.94	1.63	.875	.28	2.50	1.75	2.125	1.125	#8	.19	.50	
FNYBUPB12A-XS	.750	2.06	1.75	.937	.31	2.75	1.88	2.38	1.25	#8	.19	.62	
FNYBUPB16A-XS	1.000	2.81	2.19	1.187	.38	3.25	2.38	2.88	1.75	#10	.22	1.24	
FNYBUPB20A-XS	1.250	3.63	2.81	1.500	.43	4.00	3.00	3.50	2.00	#10	.22	2.57	
FNYBUPB24A-XS	1.500	4.00	3.25	1.750	.50	4.75	3.50	4.12	2.50	1/4	.28	3.94	

Housing Material: Aluminum Allov Black Anodized

<sup>(2)</sup>Two mounting holes as shown in view A-A for size .375

Self-Aligning Twin P	illow Bl	ocks		
Part Number	Nom. Dia.	L2	73	Wt. Ib
FNYBUTWN06A-XS	.375	2.75	2.25	.25
FNYBUTWN08A-XS	.500	3.50	2.50	.40
FNYBUTWN10A-XS FNYBUTWN12A-XS	.625 .750	4.00 4.50	3.00 3.50	1.00 1.24
FNYBUTWN16A-XS	1.000	6.00	4.50	2.48
FNYBUTWN20A-XS	1.250	7.50	5.50	5.14
FNYBUTWN24A-XS	1.500	9.00	6.50	8.08

Housing Material: Aluminum Alloy Black Anodized

Performance Note: For detailed explanations of FluoroNyliner Linear Guide Dynamic and Static Load Capacities, Frictional Characteristics, Wear Rates, Speeds, and Life Expectancy please contact Thomson Linear Guides Applications Engineering department.

Product Note: FluoroNyliner linear guides are shipped free of all lubricants. It is the responsibility of the product user to determine lubricant compatibility with the FluoroNyliner bearing material.

Product Options: FluoroNyliner linear guides are available with various inner race materials and platings to accommodate different environments.

Type ASB Li	inearR	ace Sł	naft E	nd Sup	port B	lock				Type SB	Linear	Race	e Sha	ft End	d Sup	port	Bloc	k	
Part	Nom.	L3	H3	H1	В	B3	(	G V		Part	Nom.	L3	Hh	Hc	Bb	B3		G	Wt.
Number	Dia.						Bolt	Hole	lb	Number	Dia.						Bolt	Hole	lb
ASB-06-XS	.375	.56	1.00	.562	1.62	1.25	#6	.16	.08	SB-8-XS	.500	.63	1.62	1.000	2.00	1.50	#8	.19	.3
ASB-08-XS	.500	.63	1.48	.875	2.00	1.50	#8	.19	.11	SB-10-XS	.625	.69	1.75	1.00	2.50	1.875	#10	.22	.4
ASB-10-XS	.625	-	-	-	-	-	-	-	-	SB-12-XS	.750	.75	2.12	1.250	2.75	2.00	#10	.22	.5
ASB-12-XS	.750	.75	1.95	1.125	2.50	2.00	#10	.22	.22	SB-16-XS	1.000	1.00	2.56	1.500	3.25	2.50	1/4	.28	1.0
ASB-16-XS	1.000	1.00	2.48	1.375	3.25	2.50	<sup>1</sup> /4	.28	.44	SB-20-XS	1.250	1.13	3.00	1.750	4.00	3.00	<sup>5</sup> /16	.34	2.0
ASB-24-XS	1.500	1.250	3.50	2.000	4.75	3.50	<sup>5</sup> /16	.34	1.16	SB-24-XS	1.500	1.25	3.50	2.000	4.75	3.50	<sup>5</sup> /16	.34	2.6

End Support Material: Aluminum Alloy Black Anodized

Material: Iron

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

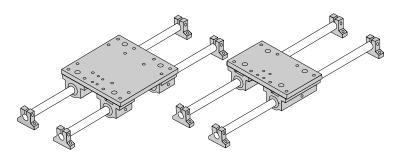


The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed by the product specific application. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

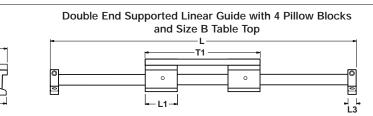
Page 51

# FluoroNyliner 1VC

Linear Guide #5 with Table Top Corrosive/Contaminated Environments



INCH



HS JOF

Double End Supported Linear Guide with 2 Twin Pillow Blocks and Size A Table Top

Linear Guide 1VC with Type SB End Support Block

•	L	•
0	0	Ø
	T2•	

FluoroNyliner* Linear Guide 1VC Double End Supported with 4 Pillow Blocks and Table Top (Size B) (Dimensions in inches)														
Part N	umber	Nom.	L1	L3	Н	HS	В	B2	Т	T1	Max.	Pillow	Shaft S	upport
W/Type ASB	W/Type SB	Dia.									Stroke	Block	Туре	Туре
Shaft	Shaft										Length		ASB	SB
Support	Support													
1VC-06-AHB	-	.375	1.31	.56	1.312	-	4.13	2.50	4.50	4.50	L-(5.62)	FNYBUPB06A-XS	ASB-6-XS	-
1VC-08-AHB	1VC-08-AJB	.500	1.69	.63	1.937	2.062	5.25	3.25	5.50	5.50	L-(6.76)	FNYBUPB08A-XS	ASB-8-XS	SB-8-XS
-	1VC-10-AJB	.625	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	FNYBUPB10A-XS	N/A	N/A
1VC-12-AHB	1VC-12-AJB	.750	2.06	.75	2.562	2.687	7.00	4.50	7.50	7.50	L-(9.0)	FNYBUPB12A-XS	ASB-12-XS	SB-12-XS
1VC-16-AHB	1VC-16-AJB	1.000	2.81	1.00	3.062	3.187	8.75	5.50	9.00	9.00	L-(11.0)	FNYBUPB16A-XS	ASB-16-XS	SB-16-XS
-	1VC-20-AJB	1.250	3.63	1.13	-	4.000	-	6.75	11.00	11.00	L-(13.26)	FNYBUPB20A-XS	-	SB-20-XS
1VC-24-AHB	1VC-24-AJB	1.500	4.00	1.25	4.500	4.500	12.75	8.00	13.00	13.00	L-(15.5)	FNYBUPB24A-XS	ASB-24-XS	SB-24-XS

FluoroNyline	r Linear Guid	le 1VC	Double	e End S	Supporte	ed with	2 Twin	Pillow	Blocks	s and Ta	ble Top (Size A)	(Dimension	ns in inch)
Part N	umber	Nom.	T2	L3	Н	HS	В	B2	Т	Max.	Pillow	Shaft S	upport
W/ Type ASB	W/ Type SB	Dia.								Stroke	Block	Туре	Туре
Shaft	Shaft									Length		ASB	SB
Support	Support												
1VC-06-BHA	-	.375	2.75	.56	1.132	-	4.13	2.50	4.50	L-(3.88)	FNYBUTWN06A-XS	ASB-6-XS	-
1VC-08-BHA	1VC-08-BJA	.500	3.50	.63	1.937	2.062	5.25	3.25	5.50	L-(4.75)	FNYBUTWN08A-XS	ASB-8-XS	SB-8-XS
-	1VC-10-BJA	.625	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	FNYBUTWN10A-XS	N/A	N/A
1VC-12-BHA	1VC-12-BJA	.750	4.50	.75	2.562	2.687	7.00	4.50	7.50	L-(6.00)	FNYBUTWN12A-XS	ASB-12-XS	SB-12-XS
1VC-16-BHA	1VC-16-BJA	1.000	6.00	1.00	3.062	3.187	8.75	5.50	9.00	L-(8.00)	FNYBUTWN16A-XS	ASB-16-XS	SB-16-XS
-	1VC-20-BJA	1.250	7.50	1.13	-	4.000	-	6.75	11.00	L-(9.75)	FNYBUTWN20A-XS	-	SB-20-XS
1VC-24-BHA	1VC-24-BJA	1.500	9.00	1.25	4.500	4.500	12.75	8.00	13.00	L-(11.50)	FNYBUTWN24A-XS	ASB-24-XS	SB-24-XS

#### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for deflection calculations.

Performance Note: For detailed explanations of FluoroNyliner Linear Guide Dynamic and Static Load Capacities, Frictional Characteristics, Wear Rates, Speeds, and Life Expectancy please contact Thomson Linear Guides Applications Engineering department. **Product Note:** FluoroNyliner linear guides are shipped free of all lubricants. It is the responsibility of the product user to determine lubricant compatibility with the FluoroNyliner bearing material.

**Product Options:** FluoroNyliner linear guides are available with various inner race materials and platings to accommodate different environments.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.

Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



#### FluoroNyliner\* Linear Guide **1VC Benefits:**

- Includes table top with standard tapped holes for quick and easy mounting of the work piece.
- Includes Ball Screw Assembly attachment holes for ease of assembly and actuation.
- Available with 60 Case\* LinearRace\* shaft end support blocks in either light weight aluminum or rigid iron materials.

#### FluoroNyliner Linear Guide **1VC Components:**

- 4 self-aligning FluoroNyliner Bushing bearing pillow blocks or 2 self-aligning FluoroNyliner Bushing bearing twin pillow blocks.
- 2 Stainless Steel 60 Case LinearRace shafts.
- 4 Shaft End Support Blocks.
- 1 mounting table top with work piece and Ball Screw Assembly attachment holes.

#### Specifying a Thomson Linear Guide:

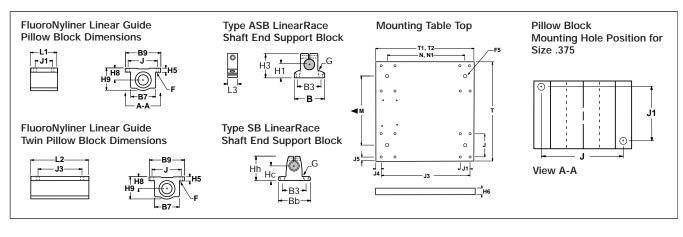
1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System

#### 1VC-12-AHB L24

Linear Guide Designation . Nominal Diameter Type of Bearing Block

Linear Guide Length Type of Table Top Type of Support



Self-Aligning P	illow	Block	s						(Dim	ensior	ns in ir	nches)	Self-Aligning Twin F	Pillow	Block	S	
Part	Nom.	L1	H9	H8	H5	B9	B7	J	J1		-	Wt.	Part	Nom.	L2	J3	Wt.
Number	Dia.									Bolt Hole Ib		lb	Number	Dia.			lb.
FNYBUPB06A-XS										FNYBUTWN06A-XS	.375	2.75	2.25	.25			
FNYBUPB08A-XS	.500	1.69	1.25	.687	.25	2.00	1.38	1.69	1.00	#6	.16	.20	FNYBUTWN08A-XS	.500	3.50	2.50	.40
FNYBUPB10A-XS	.625	-	-	-	-	-	-	-	-	-	-	-	FNYBUTWN10A-XS	.625	-	-	-
FNYBUPB12A-XS	.750	2.06	1.75	.937	.31	2.75	1.88	2.38	1.25	#8	.19	.62	FNYBUTWN12A-XS	.750	4.50	3.50	1.24
FNYBUPB16A-XS	1.000	2.81	2.19	1.187	.38	3.25	2.38	2.88	1.75	#10	.22	1.24	FNYBUTWN16A-XS	1.000	6.00	4.50	2.48
FNYBUPB20A-XS	1.250	3.63	2.81	1.500	.43	4.00	3.00	3.50	2.00	#10	.22	2.57	FNYBUTWN20A-XS	1.250	7.50	5.50	5.14
FNYBUPB24A-XS	1.500	4.00	3.25	1.750	.50	4.75	3.50	4.12	2.50	1/4	.28	3.94	FNYBUTWN24A-XS	1.500	9.00	6.50	8.08
Housing Material: Al	uminum	Allov I	Black A	nodized									Housing Material: Aluminu	n Allov	Black A	nodizec	4

<sup>(2)</sup>Two mounting holes as shown in view A-A for size .375

ng Material: Aluminum Alloy Black Ano

Type ASB Li	inearR	ace SI	naft E	nd Sup	port B	lock				Type SB	Linear	Race	sha	ft Enc	l Sup	port	Bloc	k	
Part	Nom.	L3	H3	H1	В	B3	(	G		Part	Nom.	L3	Hh	Нс	Bb	B3		G	Wt.
Number	Dia.						Bolt			Number	Dia.						Bolt	Hole	lb
ASB-06-XS	.375	.56	1.00	.562	1.62				SB-8-XS	.500	.63	1.62	1.000	2.00	1.50	#8	.19	.3	
ASB-08-XS	.500	.63	1.48	.875	2.00	1.50	#8	.19	.11	SB-10-XS	.625	.69	1.75	1.00	2.50	1.875	#10	.22	.4
ASB-10-XS	.625	-	-	-	-	-	-	-	-	SB-12-XS	.750	.75	2.12	1.250	2.75	2.00	#10	.22	.5
ASB-12-XS	.750	.75	1.95	1.125	2.50	2.00	#10	.22	.22	SB-16-XS	1.000	1.00	2.56	1.500	3.25	2.50	<sup>1</sup> /4	.28	1.0
ASB-16-XS	1.000	1.00	2.48	1.375	3.25	2.50	1/4	.28	.44	SB-20-XS	1.250	1.13	3.00	1.750	4.00	3.00	<sup>5</sup> /16	.34	2.0
ASB-24-XS	1.500	1.250	3.50	2.000	4.75	3.50	3.50 <sup>5</sup> /16 .34 1.16		SB-24-XS	1.500	1.25	3.50	2.000	4.75	3.50	<sup>5</sup> /16	.34	2.6	
End Support Ma	Support Material: Aluminum Alloy Black Anodized																		

End Support Material: Aluminum Alloy Black Anodized

Mountin	g Table	Тор											(Dimens	sions in	inches)
Nominal		All	Table To	ps			Tabl	e Top Siz	e B			Tabl	le Top Siz	e A	
Diameter	Т	М	J	H6	F5	T1	J1	J4	J5	Ν	T2	J3	J4	J5	N1
.375	4.5	2.50	1.44	.250	#10-32	4.5	.88(2)	.22	.28	3.75	2.75	2.25	.25	.28	2.0
.500	5.5	3.25	1.69	.375	1/4-20	5.5	1.00	.34	.28	4.50	3.50	2.50	.50	.31	2.5
.625	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
.750	7.5	4.50	2.38	.500	<sup>5</sup> /16-18	7.5	1.25	.41	.31	6.00	4.50	3.50	.50	.31	3.0
1.000	9.0	5.50	2.88	.500	<sup>3</sup> /8-16	9.0	1.75	.53	.31	7.00	6.00	4.50	.75	.31	4.0
1.250	11.0	6.75	3.50	.750	1/2-13	11.0	2.00	.82	.38	8.50	7.50	5.50	1.00	.38	5.0
1.500	13.0	8.00	4.12	.750	1/2-13	13.0	2.50	.75	.44	10.00	9.00	6.50	1.25	.44	6.0

Carriage Material: Aluminum Alloy Black Anodized.

<sup>(2)</sup>Two mounting holes as shown in view A-A for size .375

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

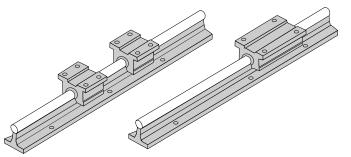


The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

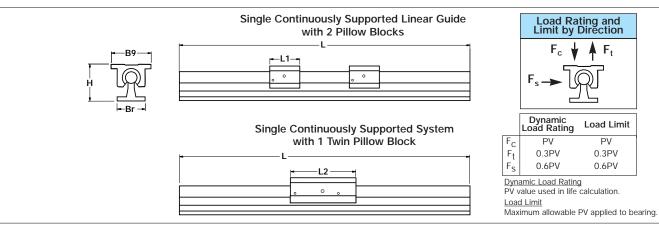


## FluoroNyliner 1VA Linear Guide #5

Corrosive/Contaminated Environments



### INCH



FluoroNyliner* L	inear Guide 1V	A Single Conti	inuously Supp	orted with 2 F	Pillow Blocks	(Dimen	sions in inches)
Part	Nominal	L1	Н	Br	B9	Pillow	Shaft
Number	Diameter					Block	Support
							Rail
							Assembly
1VA-08-FAO	.50	1.50	1.812	1.50	2.00	FNYBUPBO08A-XS	SRA-8-XS-SS
1VA-12-FAO	.75	1.88	2.437	1.75	2.75	FNYBUPBO12A-XS	SRA-12-XS-SS
1VA-16-FAO	1.00	2.63	2.937	2.13	3.25	FNYBUPBO16A-XS	SRA-16-XS-SS
1VA-20-FAO	1.25	3.38	3.625	2.50	4.00	FNYBUPBO20A-XS	SRA-20-XS-SS
1VA-24-FAO	1.50	3.75	4.250	3.00	4.75	FNYBUPBO24A-XS	SRA-24-XS-SS

FluoroNyliner Lin	near Guide 1V	A Single Co	ontinuously S	Supported v	with 1 Twin	Pillow Blog	<b>ck</b> (Dimens	ions in inches)
Part	Nominal	L2	Н	Br	B9	Maximum	Pillow	Shaft
Number	Diameter					Stroke	Block	Support
						Length		Rail
								Assembly
1VA-08-HAO	.50	3.5	1.812	1.50	2.00	L-(3.5)	FNYBUTWNO08A-XS	SRA-8-XS-SS
1VA-12-HAO	.75	4.5	2.437	1.75	2.75	L-(4.5)	FNYBUTWNO10A-XS	SRA-12-XS-SS
1VA-16-HAO	1.00	6.0	2.937	2.13	3.25	L-(6.0)	FNYBUTWNO16A-XS	SRA-16-XS-SS
1VA-20-HAO	1.25	7.5	3.625	2.50	4.00	L-(7.5)	FNYBUTWNO20A-XS	SRA-20-XS-SS
1VA-24-HAO	1.50	9.0	4.250	3.00	4.75	L-(9.0)	FNYBUTWNO24A-XS	SRA-24-XS-SS

#### Maximum Operating Parameters per Bearing

1 0	1 0
Characteristic	Limit
Liner Temperature Range	-240° C to 288° C (-400° F to 550° F)
Velocity, dry	42.7 m/min. Continuous
Velocity, dry	122 m/min. Intermittent
Velocity, lubricated	122 m/min. Continuous
Pressure	10.35 MPa
PV	21 MPa/m/min





#### FluoroNyliner\* Linear Guide **1VA Benefits:**

- Requires only one part number to specify the entire linear guide.
- Used as a load support, transport, and guidance solution.
- Used in continuously supported applications when rigidity is required.

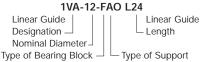
#### FluoroNyliner Linear Guide **1VA Components:**

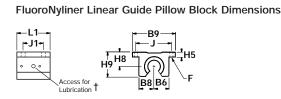
- 2 self-aligning FluoroNyliner\* Bushing bearing open pillow blocks or 1 self-aligning FluoroNyliner Bushing bearing open twin pillow block.
- 1 stainless steel 60 Case\* linearRace\* shaft support rail assembly.

#### Specifying this Thomson Linear Guide:

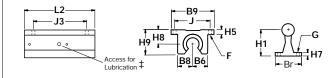
1. Determine the proper Linear Guide for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System





#### FluoroNyliner Linear Guide Twin Pillow Block Dimensions



Self-Aligning Pillo	w Bloc	ks									(Dime	ensions ir	i inches)
Part	Nom.	L1	H9	H8	H5	B9	B8	B7	J	J1		-	Wt.
Number	Dia.										Bolt	Hole	lb
FNYBUPBO08A-XS	.50	1.50	1.12	.687	.25	2.00	.75	.69	1.69	1.00	#6	.16	.20
FNYBUPBO12A-XS	.75	1.88	1.56	.937	.31	2.75	1.00	.94	2.38	1.25	#8	.19	.51
FNYBUPBO16A-XS	1.00	2.63	2.00	1.187	.38	3.25	1.25	1.19	2.88	1.75	#10	.22	1.03
FNYBUPBO20A-XS	1.25	3.38	2.56	1.500	.43	4.00	1.63	1.50	3.50	2.00	#10	.22	2.15
FNYBUPBO24A-XS	1.50	3.75	2.94	1.750	.50	4.75	1.88	1.75	4.12	2.50	/4	.28	3.29

Housing Material: Aluminum Alloy Black Anodized

Self-Aligning Twin Pill	ow Blo	ocks									
Part	Nom.	L2	J3	Wt.							
Number	Number Dia. Ib.										
FNYBUTWNO08A-XS	.500	3.50	2.50	.40							
FNYBUTWNO12A-XS	.750	4.50	3.50	1.02							
FNYBUTWNO16A-XS	1.00	6.00	4.50	2.06							
FNYBUTWNO20A-XS	1.25	7.50	5.50	4.30							
FNYBUTWNO24A-XS 1.50 9.00 6.50 6.88											
Housing Material: Aluminum	Alloy Blac	k Anodiz	ed								



Type SRA LinearRace Shaft Support Rail Assembly

Performance Note: For detailed explanations of FluoroNyliner Linear Guide Dynamic and Static Load Capacities, Frictional Characteristics, Wear Rates, Speeds, and Life Expectancy please contact Thomson Linear Guides Applications Engineering department.

Product Note: FluoroNyliner linear guides are shipped free of all lubricants. It is the responsibility of the product user to determine lubricant compatibility with the FluoroNyliner bearing material.

Product Options: FluoroNyliner linear guides are available with various inner race materials and platings to accommodate different environments.

Type SRA Line	arRace S	Shaft Suppo	ort Rail Ass	embly					(Dimensions	in Inches)
Part	Nom.	H1	H7	Br	K	Х	Y	(	G	Wt.
Number	Dia.							Bolt	Hole	lb/ft
SRA-8-XS-SS	.50	1.125	.19	1.50	1.00	4	2	#6	.17	1.26
SRA-12-XS-SS	.75	1.500	.25	1.75	1.25	6	3	#10	.22	2.50
SRA-16-XS-SS	1.00	1.750	.25	2.13	1.50	6	3	1/4	.28	4.06
SRA-20-XS-SS	1.25	2.125	.31	2.50	1.88	6	3	<sup>5</sup> /16	.34	6.30
SRA-24-XS-SS	1.50	2.500	.38	3.00	2.25	8	4	<sup>5</sup> /16	.34	8.60

LinearRace Support Rail Material: Aluminum Alloy Black Anodized

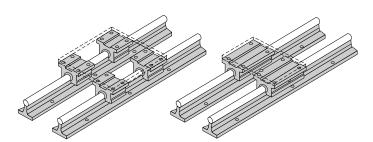
Maximum length of LinearRace Shaft Support Rail is 72 inches. If longer continuous one-piece LinearRace Shaft Support Rails are required, contact the Thomson Linear Guide Application Engineering department.



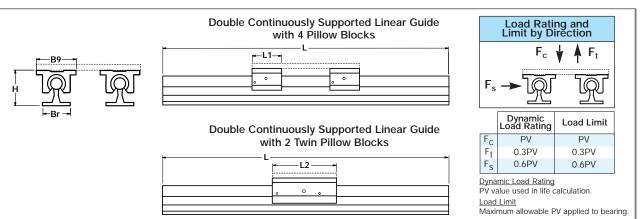
Page 55

# FluoroNyliner 1VB

Linear Guide #5 Corrosive/Contaminated Environments



### INCH



FluoroNyliner* L	inear Guide 1V	B Double Con	tinuously Sup	ported with 4	Pillow Blocks	(Dimen	sions in inches)
Part	Nominal	L1	Н	Br	B9	Pillow	Shaft
Number	Diameter					Block	Support
							Rail
							Assembly
1VB-08-FAO	.50	1.50	1.812	1.50	2.00	FNYBUPBO08A-XS	SRA-8-XS-SS
1VB-12-FAO	.75	1.88	2.437	1.75	2.75	FNYBUPBO12A-XS	SRA-12-XS-SS
1VB-16-FAO	1.00	2.63	2.937	2.13	3.25	FNYBUPBO16A-XS	SRA-16-XS-SS
1VB-20-FAO	1.25	3.38	3.625	2.50	4.00	FNYBUPBO20A-XS	SRA-20-XS-SS
1VB-24-FAO	1.50	3.75	4.250	3.00	4.75	FNYBUPBO24A-XS	SRA-24-XS-SS

FluoroNyliner Lin	near Guide 1V	/B Double (	Continuous	y Supported	d with 2 Tw	in Pillow Blo	ocks (Dimens	ions in inches)
Part	Nominal	L2	Н	Br	B9	Maximum	Pillow	Shaft
Number	Diameter					Stroke	Block	Support
						Length		Rail
								Assembly
1VB-08-HAO	.50	3.5	1.812	1.50	2.00	L-(3.5)	FNYBUTWNO08A-XS	SRA-8-XS-SS
1VB-12-HAO	.75	4.5	2.437	1.75	2.75	L-(4.5)	FNYBUTWNO12A-XS	SRA-12-XS-SS
1VB-16-HAO	1.00	6.0	2.937	2.13	3.25	L-(6.0)	FNYBUTWNO16A-XS	SRA-16-XS-SS
1VB-20-HAO	1.25	7.5	3.625	2.50	4.00	L-(7.5)	FNYBUTWNO20A-XS	SRA-20-XS-SS
1VB-24-HAO	1.50	9.0	4.250	3.00	4.75	L-(9.0)	FNYBUTWNO24A-XS	SRA-24-XS-SS

Maximum Operating Parameters per Bearing

1 0	1 0
Characteristic	Limit
Liner Temperature Range	-240° C to 288° C (-400° F to 550° F)
Velocity, dry	42.7 m/min. Continuous
Velocity, dry	122 m/min. Intermittent
Velocity, lubricated	122 m/min. Continuous
Pressure	10.35 MPa
PV	21 MPa/m/min





## FluoroNyliner\* Linear Guide 1VB Benefits:

- Requires only one part number to specify the entire linear guide.
- Allows for custom table mounting.
- Used in continuously supported applications when rigidity is required.

## FluoroNyliner Linear Guide 1VB Components:

- 4 self-aligning FluoroNyliner\* Bushing bearing open pillow blocks or 2 self-aligning FluoroNyliner Bushing bearing open twin pillow blocks.
- 2 Stainless Steel 60 Case\* LinearRace\* Shaft Support Rail Assemblies.

#### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System

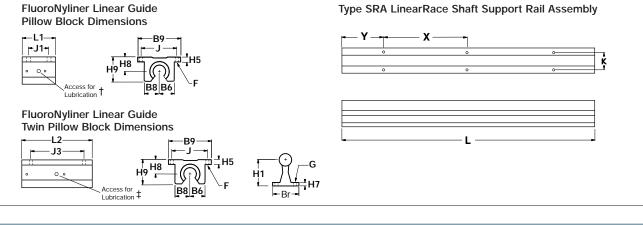
 1VB-12-FAO L24

 Linear guide

 Designation

 Nominal Diameter

 Type of Bearing Block



Self-Aligning Pillo	w Bloc	ks									(Dime	ensions ir	inches)
Part	Nom.	L1	H9	H8	H5	B9	B8	B7	J	J1		F	Wt.
Number	Dia.										Bolt	Hole	lb
FNYBUPBO08A-XS	.50	1.50	1.12	.687	.25	2.00	.75	.69	1.69	1.00	#6	.16	.20
FNYBUPBO12A-XS	.75	1.88	1.56	.937	.31	2.75	1.00	.94	2.38	1.25	#8	.19	.51
FNYBUPBO16A-XS	1.00	2.63	2.00	1.187	.38	3.25	1.25	1.19	2.88	1.75	#10	.22	1.03
FNYBUPBO20A-XS	1.25	3.38	2.56	1.500	.43	4.00	1.63	1.50	3.50	2.00	#10	.22	2.15
FNYBUPBO24A-XS	1.50	3.75	2.94	1.750	.50	4.75	1.88	1.75	4.12	2.50	/4	.28	3.29

Housing Material: Aluminum Alloy Black Anodized

Self-Aligning Twin Pill	ow Blo	ocks							
Part	Nom.	L2	J3	Wt.					
Number	Dia.			lb.					
FNYBUTWNO08A-XS	.500	3.50	2.50	.40					
FNYBUTWNO12A-XS	.750	4.50	3.50	1.02					
FNYBUTWNO16A-XS	1.00	6.00	4.50	2.06					
FNYBUTWNO20A-XS	1.25	7.50	5.50	4.30					
FNYBUTWNO24A-XS 1.50 9.00 6.50 6.88									
Housing Material: Aluminum A	Alloy Blac	k Anodiz	ed						

Performance Note: For detailed explanations of FluoroNyliner Linear Guide Dynamic and Static Load Capacities, Frictional Characteristics, Wear Rates, Speeds, and Life Expectancy please contact Thomson Linear Guides Applications Engineering department.

**Product Note:** FluoroNyliner linear guides are shipped free of all lubricants. It is the responsibility of the product user to determine lubricant compatibility with the FluoroNyliner bearing material.

Product Options: FluoroNyliner linear guides are available with various inner race materials and platings to accommodate different environments.

Type SRA Line	earRace S	Shaft Suppo	ort Rail Ass	embly					(Dimensions	s in Inches)
Part Number	Nom. Dia.	H1	H7	Br	K	Х	Y	Bolt	G Hole	Wt. Ib/ft
SRA-8-XS-SS	.50	1.125	.19	1.50	1.00	4	2	#6	.17	1.26
SRA-12-XS-SS	.75	1.500	.25	1.75	1.25	6	3	#10	.22	2.50
SRA-16-XS-SS	1.00	1.750	.25	2.13	1.50	6	3	1/4	.28	4.06
SRA-20-XS-SS	1.25	2.125	.31	2.50	1.88	6	3	<sup>5</sup> /16	.34	6.30
SRA-24-XS-SS	1.50	2.500	.38	3.00	2.25	8	4	<sup>5</sup> /16	.34	8.60

LinearRace Support Rail Material: Aluminum Alloy Black Anodized

Maximum length of LinearRace shaft support rail is 72 inches. If longer continuous one-piece LinearRace Support Rails are required, contact the Thomson Linear Guide Application Engineering department.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



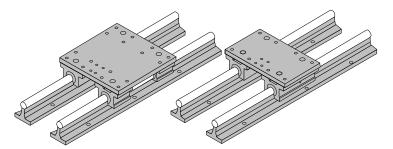
The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.
Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Page 52

# FluoroNyliner 1VC

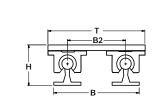
Linear Guide #5

with Table Top Corrosive/Contaminated Environments

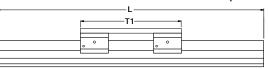


INCH

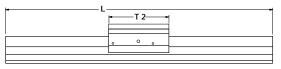
Page 58

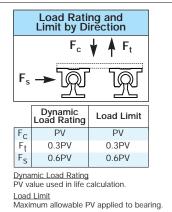


Double Continuously Supported Linear Guide with 4 Pillow Blocks and Size B Table Top



Double Continuously Supported Linear Guide with 2 Twin Pillow Blocks and Size A Table Top





FluoroNyliner* Lin	ear Guide 1	VC Double	Continuou	sly Support	ed with 4 Pi	llow Blocks	and Table T	op (size B) (Dime	nsions in inches)
Part	Nominal	T1	Т	Н	В	B2	Maximum	Pillow	Shaft
Number	Diameter						Stroke	Block	Support
							Length		Rail
									Assembly
1VC-08-FAB	.50	5.5	5.5	2.187	4.75	3.25	L-(5.5)	FNYBUPBO08A-XS	SRA-8-XS-SS
1VC-12-FAB	.75	7.5	7.5	2.937	6.25	4.50	L-(7.5)	FNYBUPBO12A-XS	SRA-12-XS-SS
1VC-16-FAB	1.00	9.0	9.0	3.437	7.63	5.50	L-(9.0)	FNYBUPBO16A-XS	SRA-16-XS-SS
1VC-20-FAB	1.25	11.0	11.0	4.375	9.25	6.75	L-(11.0)	FNYBUPBO20A-XS	SRA-20-XS-SS
1VC-24-FAB	1.50	13.0	13.0	5.000	11.00	8.00	L-(13.0)	FNYBUPBO24A-XS	SRA-24-XS-SS

FluoroNyliner Line	ar Guide 1V	C Double C	Continuously	y Supported	l with 2 Twin	Pillow Bloc	cks and Tabl	e Top (size A) (Dime	ensions in inches)
Part	Nom.	T2	Т	Н	В	B2	Maximum	Pillow	Shaft
Number	Dia.						Stroke	Block	Support
							Length		Rail
									Assembly
1VC-08-HAA	.50	3.5	5.5	2.187	4.75	3.25	L-(3.5)	FNYBUTWNO08A-XS	SRA-8-XS-SS
1VC-12-HAA	.75	4.5	7.5	2.937	6.25	4.50	L-(4.5)	FNYBUTWNO12A-XS	SRA-12-XS-SS
1VC-16-HAA	1.00	6.0	9.0	3.437	7.63	5.50	L-(6.0)	FNYBUTWNO16A-XS	SRA-16-XS-SS
1VC-20-HAA	1.25	7.5	11.0	4.375	9.25	6.75	L-(7.5)	FNYBUTWNO20A-XS	SRA-20-XS-SS
1VC-24-HAA	1.50	9.0	13.0	5.000	11.00	8.00	L-(9.0)	FNYBUTWNO24A-XS	SRA-24-XS-SS

#### Maximum Operating Parameters per Bearing

Characteristic	Limit
Liner Temperature Range	-240° C to 288° C (-400° F to 550° F)
Velocity, dry	42.7 m/min. Continuous
Velocity, dry	122 m/min. Intermittent
Velocity, lubricated	122 m/min. Continuous
Pressure	10.35 MPa
PV	21 MPa/m/min

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.





#### FluoroNyliner\* Linear Guide **1VC Benefits:**

- Requires only one part number to specify the entire linear guide.
- Includes table top with standard tapped holes for quick and easy mounting of the work piece.
- Includes Ball Screw Assembly attachment holes for ease of assembly and actuation.
- Used in continuously supported applications when rigidity is required.

-L1

ŀ•J1•∣

0,0

L2

J3

0.0

#### FluoroNyliner Linear Guide **1VC Components:**

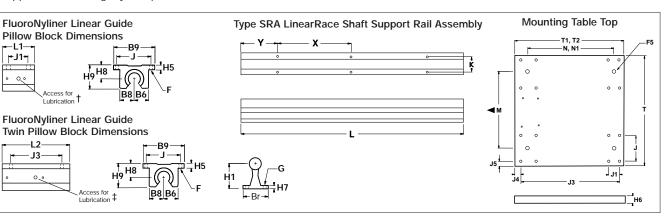
- 4 self-aligning FluoroNyliner polymer linear guides open type pillow blocks or 2 self-aligning FluoroNyliner open twin pillow blocks.
- 2 stainless steel 60 Case\* LinearRace\* Shaft Support Rail Assemblies.
- 1 mounting table top with work piece and Ball Screw Assembly attachment holes.

#### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System

1VC-12-FAB L24 Linear Guide Linear Guide – Length Designation -LType of Table Top Nominal Diameter -Type of Bearing Block -Type of Support



Self-Aligning Pillow Blocks         (Dimensions in inches)													
Part	Nom.	L1	H9	H8	H5	B9	B8	B6	J	J1		F	Wt.
Number	Dia.										Bolt	Hole	lb
FNYBUPBO08A-XS	.50	1.50	1.12	.687	.25	2.00	.75	.69	1.69	1.00	#6	.16	.20
FNYBUPBO12A-XS	.75	1.88	1.56	.937	.31	2.75	1.00	.94	2.38	1.25	#8	.19	.51
FNYBUPBO16A-XS	1.00	2.63	2.00	1.187	.38	3.25	1.25	1.19	2.88	1.75	#10	.22	1.03
FNYBUPBO20A-XS	1.25	3.38	2.56	1.500	.43	4.00	1.63	1.50	3.50	2.00	#10	.22	2.15
FNYBUPBO24A-XS	1.50	3.75	2.94	1.750	.50	4.75	1.88	1.75	4.12	2.50	1/4	.28	3.29

Self-Aligning Twin	Pillov	v Blo	cks									
Part Nom. L2 J3 Wt.												
Number Dia. Ib												
<b>FNYBUTWN008A-XS</b> .50 3.5 2.5 .40												
FNYBUTWNO12A-XS	.75	4.5	3.5	1.02								
FNYBUTWNO16A-XS	1.00	6.0	4.5	2.06								
FNYBUTWNO20A-XS	1.25	7.5	5.5	4.30								
FNYBUTWNO24A-XS 1.50 9.0 6.5 6.88												
Housing Material: Aluminu	um Alloy	y Black	Anodi	zed								

Housing Material: Aluminum Alloy Black Anodized

Type SRA Line	earRace S	Shaft Suppo	ort Rail Ass	embly					(Dimensions	s in inches)
Part Number	Nom. Dia.	H1	H7	Br	K	Х	Y	Bolt	G Hole	Wt. Ib/ft
SRA- 8-XS-SS	.50	1.125	.19	1.50	1.00	4	2	#6	.17	1.26
SRA-12-XS-SS	.75	1.500	.25	1.75	1.25	6	3	#10	.22	2.50
SRA-16-XS-SS	1.00	1.750	.25	2.13	1.50	6	3	1/4	.28	4.06
SRA-20-XS-SS	1.25	2.125	.31	2.50	1.88	6	3	<sup>5</sup> /16	.34	6.30
SRA-24-XS-SS	1.50	2.500	.38	3.00	2.25	8	4	<sup>5</sup> /16	.34	8.60

LinearRace Shaft Support Rail Material: Aluminum Alloy Black Anodized

Maximum length of LinearRace Shaft Support Rail is 72 inches. If longer continuous one-piece LinearRace Shaft Support Rails are required, contact the Thomson Linear Guides application engineering department

Mountin	g Table	Тор											(Dimer	nsions in	inches)
Nominal		All	Table To	ps			Tabl	e Top Siz	e B			Tabl	le Top Siz	e A	
Diameter	Т	М	J	H6	F5	T1	J1	J4	J5	Ν	T2	J3	J4	J5	N1
.50	5.5	3.25	1.69	.375	1/4-20	0 5.5 1.00 .34 .28 4.5 3.5 2.5 .50 .31								2.5	
.75	7.5	4.50	2.38	.500	<sup>5</sup> /16-18	7.5	1.25	.41	.31	6.0	4.5	3.5	.50	.31	3.0
1.00	9.0	5.50	2.88	.500	<sup>3</sup> /8-16	9.0	1.75	.53	.31	7.0	6.0	4.5	.75	.31	4.0
1.25	11.0	6.75	3.50	.750	1/2-13	11.0 2.00 .82 .38 8.5 7						5.5	1.00	.38	5.0
1.50	13.0	8.00	4.12	.750	1/2-13	13.0	2.50	.75	.44	10.0	9.0	6.5	1.25	.44	6.0

Material: Aluminum Alloy Black Anodized

Performance Note: For detailed explanations of FluoroNyliner Linear Guide Dynamic and Static Load Capacities, Frictional Characteristics, Wear Rates, Speeds, and Life Expectancy please contact Thomson Linear Guides Applications Engineering department.

Product Note: FluoroNyliner linear guides are shipped free of all lubricants. It is the responsibility of the product user to determine lubricant compatibility with the FluoroNyliner bearing material.

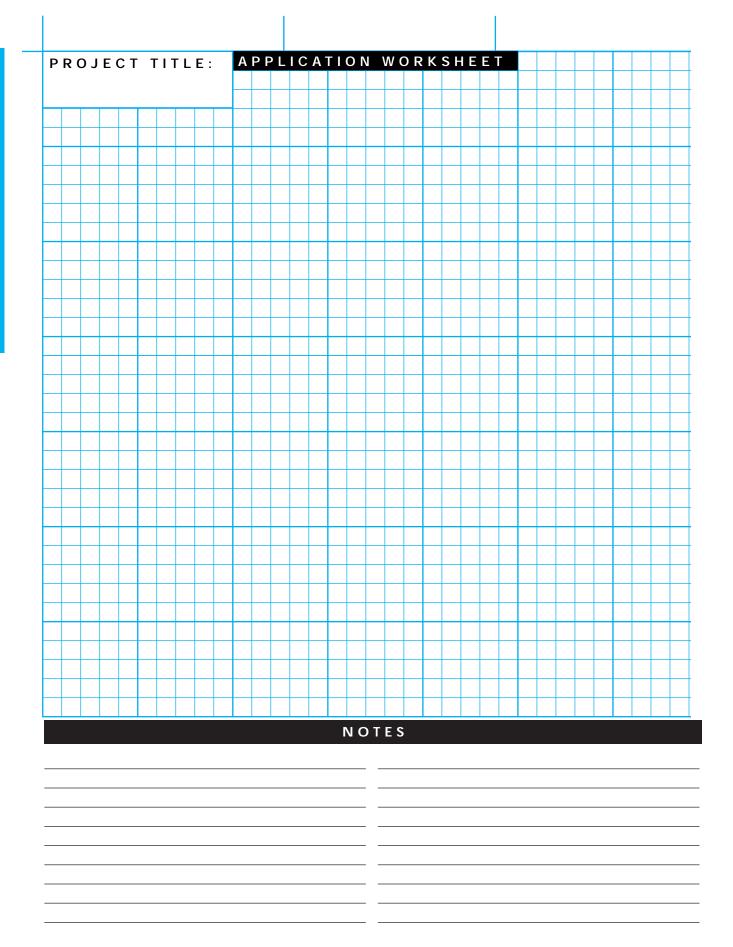
Product Options: FluoroNyliner linear guides are available with various inner race materials and platings to accommodate different environments.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.





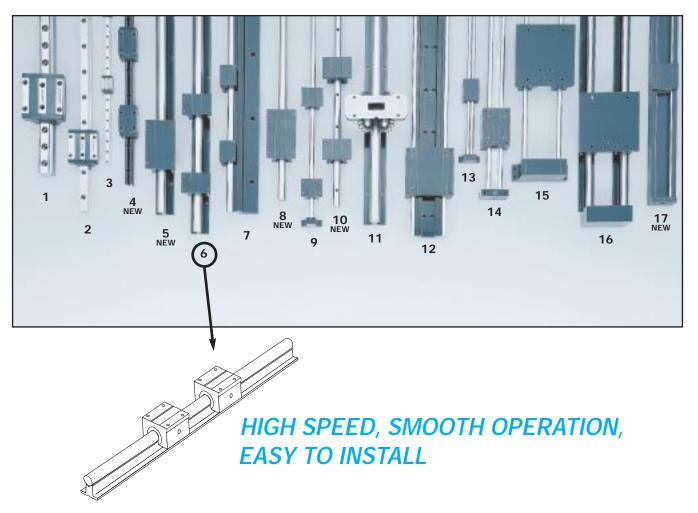
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



First in Linear Motion and Control Technology

Page 60

# Continuous Support Linear Ball Guides



### Continuous Support Linear Ball Guides Offer:

- Increased life within the same envelope. RoundRail\* linear guides feature the new patented Super Smart Ball Bushing\* bearings for up to 216X the life or 6X the load capacity of conventional bearings
- Cost savings: save time and money preparing your mounting surfaces before bolting down RoundRail linear guides
- Superior performance. Continuously supported for maximum (down- & side-) load applications without concerns for shaft deflection
- The RoundRail Advantage\*. The inherent self-aligning-in-all-directions design of the Super Smart Ball Bushing bearing allows for ultra smooth travel when mounted to wider toleranced prepared surfaces
- Unlimited travel lengths without concerns for machined reference edges or butt joint alignment
- The Super Smart Ball Bushing bearing...the most technologically advanced and most robust linear bearing in the world
- Corrosion resistant versions for maximum performance in harsh environments.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



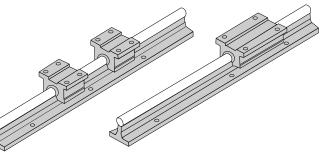
Page 61

#6

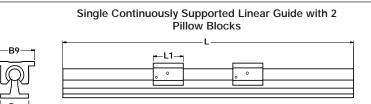
Linear Guides

## **Continuous Support 1CA**

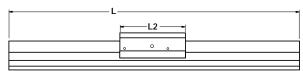
Linear Guide #6 Fully Supported, Highest Performance Industry Standard Dimensions

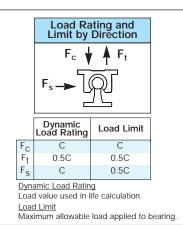


### INCH



Single Continuously Supported Linear Guide with 1 Twin Pillow Block





Continuously Su	pported Linea	r Guide 1CA Si	ingle with 2 P	illow Blocks		(Dimen:	sions in inches)
Part	Nominal	L1	Н	Br	B9	Pillow	Shaft
Number	Diameter					Block	Support
							Rail
							Assembly
1CA-08-FAO	.50	1.50	1.812	1.50	2.00	SPB-8-OPN-XS	SRA-8-XS
1CA-12-FAO	.75	1.88	2.437	1.75	2.75	SSUPBO-12-XS	SRA-12-XS
1CA-16-FAO	1.00	2.63	2.937	2.13	3.25	SSUPBO-16-XS	SRA-16-XS
1CA-20-FAO	1.25	3.38	3.625	2.50	4.00	SSUPBO-20-XS	SRA-20-XS
1CA-24-FAO	1.50	3.75	4.250	3.00	4.75	SSUPBO-24-XS	SRA-24-XS

Continuously Su	pported Linea	ar Guide 10	A Single wit	h 1 Twin Pil	low Block		(Dimens	ions in inches)
Part	Nominal	L2	Н	Br	B9	Maximum	Pillow	Shaft
Number	Diameter					Stroke	Block	Support
						Length		Rail
								Assembly
1CA-08-HAO	.50	3.5	1.812	1.50	2.00	L-(3.5)	TWN-8-OPN-XS	SRA-8-XS
1CA-12-HAO	.75	4.5	2.437	1.75	2.75	L-(4.5)	SSUTWNO-12-XS	SRA-12-XS
1CA-16-HAO	1.00	6.0	2.937	2.13	3.25	L-(6.0)	SSUTWNO-16-XS	SRA-16-XS
1CA-20-HAO	1.25	7.5	3.625	2.50	4.00	L-(7.5)	SSUTWNO-20-XS	SRA-20-XS
1CA-24-HAO	1.50	9.0	4.250	3.00	4.75	L-(9.0)	SSUTWNO-24-XS	SRA-24-XS





#### Continuously Supported Linear Guide 1CA Benefits:

- Requires only one part number to specify the entire linear guide.
- Used as a load support, transport, and guidance solution.
- Used in continuously supported applications when rigidity is required.

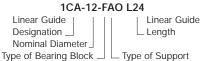
### Continuously Supported Linear Guides 1CA Components:<sup>†</sup>

- 2 Super Smart Ball Bushing\* open type pillow blocks or 1 Super Smart Ball Bushing open twin pillow blocks.
- 1 60 Case\* LinearRace\* shaft Support Rail Assembly.

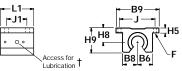
#### Specifying this Thomson Linear Guide:

 Determine the proper Linear Guide for your load and life requirements.
 Select the part number.
 Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

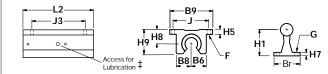
#### Part Numbering System



Type SSUPBO Open Type Super Smart Ball Bushing Pillow Block Type SPB-OPN Open Type Ball Bushing Pillow Block



Type SSUTWN Open Type Super Smart Ball Bushing Twin Pillow Block Type TWN-OPN Open Type Ball Bushing Twin Pillow Block



Type SRA LinearRace Shaft Support Rail Assembly



<sup>\$</sup> Size .500 inch has oil lubricant fitting. Sizes .625 and above have <sup>1</sup>/<sub>4</sub>-28 access for lubrication.

Type SPB-OP	N and	d SSL	JPBO	Pillow	/ Bloc	:ks				(Dimen	sions	in Inc	hes)	Type TWN-OPN a	ind SSU	TWNO	Pillow E	Blocks
Part	Nom.	L1	H9	H8	H5	B9	B8	B6	J	J1	F	-	Wt.	Part	Nom.	L2	J3	Wt.
Number	Dia.										Bolt	Hole	lb	Number	Dia.			lb
SPB-8-OPN-XS	.50	1.50	1.12	.687	.25	2.00	.75	.69	1.69	1.00	#6	.16	.20	TWN-8-OPN-XS	.50	3.5	2.5	.40
SSUPBO-12-XS	.75	1.88	1.56	.937	.31	2.75	1.00	.94	2.38	1.25	#8	.19	.51	SSUTWNO-12-XS	.75	4.5	3.5	1.02
SSUPBO-16-XS	1.00	2.63	2.00	1.187	.38	3.25	1.25	1.19	2.88	1.75	#10	.22	1.03	SSUTWNO-16-XS	1.00	6.0	4.5	2.06
SSUPBO-20-XS	1.25	3.38	2.56	1.500	.43	4.00	1.63	1.50	3.50	2.00	#10	.22	2.15	SSUTWNO-20-XS	1.25	7.5	5.5	4.30
SSUPBO-24-XS	1.50	3.75	2.94	1.750	.50	4.75	1.88	1.75	4.12	2.50	1/4	.28	3.29	SSUTWNO-24-XS	1.50	9.0	6.5	6.88

Housing Material: Aluminum Alloy Black Anodized

Housing Material: Aluminum Alloy Black Anodized

Type SRA Li	nearRace S	Shaft Suppo	ort Rail Ass	embly					(Dimensions	in Inches)
Part Number	Nom. Dia.	H1	H7	Br	K	Х	Y	Bolt	G Hole	Wt. Ib/ft
SRA-8-XS	.50	1.125	.19	1.50	1.00	4	2	#6	.17	1.26
SRA-12-XS	.75	1.500	.25	1.75	1.25	6	3	#10	.22	2.50
SRA-16-XS	1.00	1.750	.25	2.13	1.50	6	3	1/4	.28	4.06
SRA-20-XS	1.25	2.125	.31	2.50	1.88	6	3	<sup>5</sup> /16	.34	6.30
SRA-24-XS	1.50	2.500	.38	3.00	2.25	8	4	<sup>5</sup> /16	.34	8.60

LinearRace Shaft Support Rail Material: Aluminum Alloy Black Anodized Maximum length of LinearRace Shaft Support Rail is 72 inches. If longer continuous one-piece LinearRace Shaft Support Rails are required, contact the Thomson Linear Guides Application Engineering department.

Dynamic Lo	ad Rating (C) M	atrix (4 millio	on inches travel)	Dynamic Lo	ad Rating (C) N	<b>latrix</b> (4 millio	on inches travel)
Linear Guide	Dynamic Load	Pillow Block	Pillow Block	Linear Guide	Dynamic Load	Pillow Block	Pillow Block
Assembly	Rating, C (lb <sub>f</sub> )	Part No.	Dynamic Load	Assembly	Rating, C (lb <sub>f</sub> )	Part No.	Dynamic Load
Part No.	(Even Distribution)		Rating, C (lb <sub>f</sub> )	Part No.	(Even Distribution)		Rating, C (lb <sub>f</sub> )
1CA-08-FAO	290	SPB-8-OPN-XS	145	1CA-08-HAO	290	TWN-8-OPN-XS	290
1CA-12-FAO	1800	SSUPBO-12-XS	900	1CA-12-HAO	1800	SSUTWNO-12-XS	1800
1CA-16-FAO	3000	SSUPBO-16-XS	1500	1CA-16-HAO	3000	SSUTWNO-16-XS	3000
1CA-20-FAO	3730	SSUPBO-20-XS	1865	1CA-20-HAO	3730	SSUTWNO-20-XS	3730
1CA-24-FAO	6160	SSUPBO-24-XS	3080	1CA-24-HAO	6160	SSUTWNO-24-XS	6160

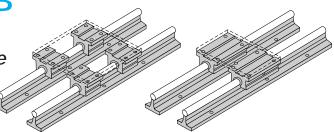
<sup>†</sup> Super Ball Bushing<sup>\*</sup> bearings are used in .500 inch size pillow blocks.





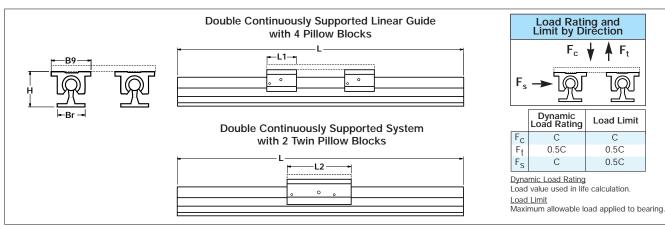
## **Continuous Support 1CB**

Linear Guide #6 Fully Supported, Highest Performance Industry Standard Dimensions



### INCH

Page 64



Continuously Su	pported Linea	r Guide 1CB D	ouble with 4 I	Pillow Blocks		(Dimens	sions in inches)
Part	Nominal	L1	Н	Br	B9	Pillow	Shaft
Number	Diameter					Block	Support
							Rail
							Assembly
1CB-08-FAO	.50	1.50	1.812	1.50	2.00	SPB-8-OPN-XS	SRA-8-XS
1CB-12-FAO	.75	1.88	2.437	1.75	2.75	SSUPBO-12-XS	SRA-12-XS
1CB-16-FAO	1.00	2.63	2.937	2.13	3.25	SSUPBO-16-XS	SRA-16-XS
1CB-20-FAO	1.25	3.38	3.625	2.50	4.00	SSUPBO-20-XS	SRA-20-XS
1CB-24-FAO	1.50	3.75	4.250	3.00	4.75	SSUPBO-24-XS	SRA-24-XS

Continuously Su	pported Linea	ar Guide 10	B Double wi	th 2 Twin P	illow Blocks		(Dimens	ions in inches)
Part Number	Nominal Diameter	L2	Н	Br	В9	Maximum Stroke Length	Pillow Block	Shaft Support Rail Assembly
1CB-08-HAO	.50	3.5	1.812	1.50	2.00	L-(3.5)	TWN-8-OPN-XS	SRA-8-XS
1CB-12-HAO	.75	4.5	2.437	1.75	2.75	L-(4.5)	SSUTWNO-12-XS	SRA-12-XS
1CB-16-HAO	1.00	6.0	2.937	2.13	3.25	L-(6.0)	SSUTWNO-16-XS	SRA-16-XS
1CB-20-HAO	1.25	7.5	3.625	2.50	4.00	L-(7.5)	SSUTWNO-20-XS	SRA-20-XS
1CB-24-HAO	1.50	9.0	4.250	3.00	4.75	L-(9.0)	SSUTWNO-24-XS	SRA-24-XS



#### Continuously Supported Linear Guide 1CB Benefits:

- Requires only one part number to specify the entire linear guide.
- Allows for custom table mounting.
- Used in continuously supported applications when rigidity is required.

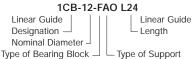
### Continuously Supported Linear Guide 1CB Components: <sup>†</sup>

- 4 Super Smart Ball Bushing\* open type pillow blocks or 2 Super Smart Ball Bushing open type twin pillow blocks.
- 2 60 Case\* LinearRace\* shaft Support Rail Assemblies.

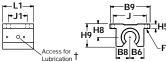
#### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

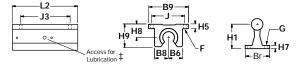
#### Part Numbering System

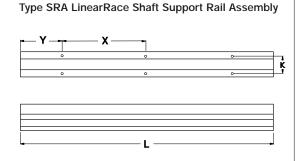


Type SSUPBO Open Type Super Smart Ball Bushing Pillow Block Type SPB-OPN Open Type Ball Bushing Pillow Block



Type SSUTWN Open Type Super Smart Ball Bushing Twin Pillow Block Type TWN-OPN Open Type Ball Bushing Twin Pillow Block





<sup>‡</sup> Size .500 inch has oil lubricant fitting.

Sizes .625 and above have  $\ensuremath{^{1}\!\!/}\xspace$  access for lubrication.

Type SPB-OP	N and	d SSL	JPBO	Pillow	Bloc	:ks				(Dimen	sions	in Inc	hes)	Type TWN-OPN a	ind SSU	TWNO	Pillow E	Blocks
Part Number	Nom. Dia.	L1	H9	H8	H5	B9	B8	B6	J	J1	F Bolt	Hole	Wt. Ib	Part Number	Nom. Dia.	L2	J3	Wt. Ib
SPB-8-OPN-XS	.50	1.50	1.12	.687	.25	2.00	.75	.69	1.69	1.00	#6	.16	.20	TWN-8-OPN-XS	.50	3.5	2.5	.40
SSUPBO-12-XS	.75	1.88	1.56	.937	.31	2.75	1.00	.94	2.38	1.25	#8	.19	.51	SSUTWNO-12-XS	.75	4.5	3.5	1.02
SSUPBO-16-XS	1.00	2.63	2.00	1.187	.38	3.25	1.25	1.19	2.88	1.75	#10	.22	1.03	SSUTWNO-16-XS	1.00	6.0	4.5	2.06
SSUPBO-20-XS	1.25	3.38	2.56	1.500	.43	4.00	1.63	1.50	3.50	2.00	#10	.22	2.15	SSUTWNO-20-XS	1.25	7.5	5.5	4.30
SSUPBO-24-XS	1.50	3.75	2.94	1.750	.50	4.75	1.88	1.75	4.12	2.50	1/4	.28	3.29	SSUTWNO-24-XS	1.50	9.0	6.5	6.88

Housing Material: Aluminum Alloy Black Anodized

Housing Material: Aluminum Alloy Black Anodized

Type SRA Li	nearRace S	Shaft Suppo	ort Rail Ass	sembly					(Dimensions	in Inches)
Part	Nom.	H1	H7	Br	K	Х	Y		G	Wt.
Number	Dia.							Bolt	Hole	lb/ft
SRA-8-XS	.50	1.125	.19	1.50	1.00	4	2	#6	.17	1.26
SRA-12-XS	.75	1.500	.25	1.75	1.25	6	3	#10	.22	2.50
SRA-16-XS	1.00	1.750	.25	2.13	1.50	6	3	1/4	.28	4.06
SRA-20-XS	1.25	2.125	.31	2.50	1.88	6	3	<sup>5</sup> /16	.34	6.30
SRA-24-XS	1.50	2.500	.38	3.00	2.25	8	4	<sup>5</sup> /16	.34	8.60

LinearRace Shaft Support Rail Material: Aluminum Alloy Black Anodized Maximum length of LinearRace Shaft Support Rail is 72 inches. If longer continuous one-piece LinearRace Shaft Support Rails are required, contact the Thomson Linear Guide Application Engineering department.

Dynamic Lo	ad Rating (C) M	atrix (4 millio	on inches travel)	Dynamic Lo	ad Rating (C) N	latrix (4 millio	on inches travel)
Linear Guide Assembly Part No.	Dynamic Load Rating, C (lb <sub>f</sub> ) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (lb <sub>f</sub> )	Linear Guide Assembly Part No.	Dynamic Load Rating, C (Ib <sub>f</sub> ) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (lb <sub>f</sub> )
1CB-08-FAO	580	SPB-8-OPN-XS	145	1CB-08-HAO	580	TWN-8-OPN-XS	290
1CB-12-FAO	3600	SSUPBO-12-XS	900	1CB-12-HAO	3600	SSUTWNO-12-XS	1800
1CB-16-FAO	6000	SSUPBO-16-XS	1500	1CB-16-HAO	6040	SSUTWNO-16-XS	3020
1CB-20-FAO	7460	SSUPBO-20-XS	1865	1CB-20-HAO	7460	SSUTWNO-20-XS	3730
1CB-24-FAO	12320	SSUPBO-24-XS	3080	1CB-24-HAO	12320	SSUTWNO-24-XS	6160

<sup>†</sup> Super Ball Bushing<sup>\*</sup> bearings are used in .500 inch size pillow blocks.

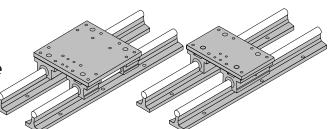


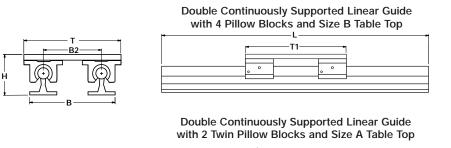


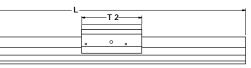
## **Continuous Support 1CC**

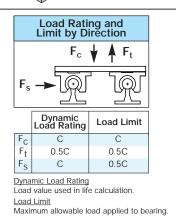
Linear Guide #6

with Table Top *Fully Supported, Highest Performance Industry Standard Dimensions* INCH









Continuously Sup	ported Line	ar Guide 10	CC Double	with 4 Pillow	v Blocks an	d Table Top	(Size B)	(Dim	ensions in inches)
Part	Nominal	T1	Т	Н	В	B2	Maximum	Pillow	Shaft
Number	Diameter						Stroke	Block	Support
							Length		Rail
									Assembly
1CC-08-FAB	.50	5.5	5.5	2.187	4.75	3.25	L-(5.5)	SPB-8-OPN-XS	SRA-8-XS
1CC-12-FAB	.75	7.5	7.5	2.937	6.25	4.50	L-(7.5)	SSUPBO-12-XS	SRA-12-XS
1CC-16-FAB	1.00	9.0	9.0	3.437	7.63	5.50	L-(9.0)	SSUPBO-16-XS	SRA-16-XS
1CC-20-FAB	1.25	11.0	11.0	4.375	9.25	6.75	L-(11.0)	SSUPBO-20-XS	SRA-20-XS
1CC-24-FAB	1.50	13.0	13.0	5.000	11.00	8.00	L-(13.0)	SSUPBO-24-XS	SRA-24-XS

Continuously Supp	orted Linea	ar Guide 1C	C Double w	ith 2 Twin P	illow Blocks	and Table T	op (Size A)	(Din	nensions in inches)
Part	Nom.	T2	Т	Н	В	B2	Maximum	Pillow	Shaft
Number	Dia.						Stroke	Block	Support
							Length		Rail
									Assembly
1CC-08-HAA	.50	3.5	5.5	2.187	4.75	3.25	L-(3.5)	TWN-8-OPN-XS	SRA-8-XS
1CC-12-HAA	.75	4.5	7.5	2.937	6.25	4.50	L-(4.5)	SSUTWNO-12-XS	SRA-12-XS
1CC-16-HAA	1.00	6.0	9.0	3.437	7.63	5.50	L-(6.0)	SSUTWNO-16-XS	SRA-16-XS
1CC-20-HAA	1.25	7.5	11.0	4.375	9.25	6.75	L-(7.5)	SSUTWNO-20-XS	SRA-20-XS
1CC-24-HAA	1.50	9.0	13.0	5.000	11.00	8.00	L-(9.0)	SSUTWNO-24-XS	SRA-24-XS

Dynamic Loa	ad Rating (C) M	atrix (4 millio	on inches travel)	Dynamic Lo	ad Rating (C) N	latrix (4 millio	on inches travel)
Linear Guide Assembly Part No.	Dynamic Load Rating, C (lb <sub>f</sub> ) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (lb <sub>f</sub> )	Linear Guide Assembly Part No.	Dynamic Load Rating, C (Ib <sub>f</sub> ) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (lb <sub>f</sub> )
1CC-08-FAB	580	SPB-8-OPN-XS	145	1CC-08-HAA	580	TWN-8-OPN-XS	290
1CC-12-FAB	3600	SSUPBO-12-XS	900	1CC-12-HAA	3600	SSUTWNO-12-XS	1800
1CC-16-FAB	6000	SSUPBO-16-XS	1500	1CC-16-HAA	6040	SSUTWNO-16-XS	3020
1CC-20-FAB	7460	SSUPBO-20-XS	1865	1CC-20-HAA	7460	SSUTWNO-20-XS	3730
1CC-24-FAB	12320	SSUPBO-24-XS	3080	1CC-24-HAA	12320	SSUTWNO-24-XS	6160





#### **Continuously Supported** Linear Guide 1CC Benefits:

- Requires only one part number to specify the entire linear guide.
- Includes table top with standard tapped holes for quick and easy mounting of the work piece.
- Includes Ball Screw Assembly attachment holes for ease of assembly and actuation
- Used in continuously supported applications when rigidity is required.

Pillow Block

**≁J1**+

0,0

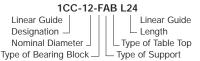
#### **Continuously Supported** Linear Guide 1CC Components:\*

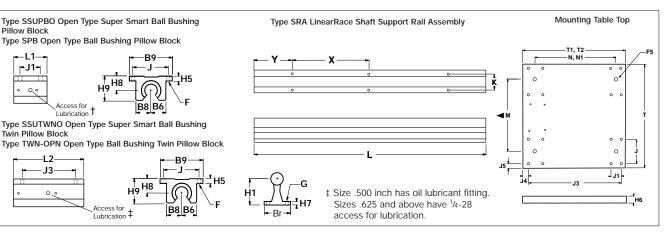
- 4 Super Smart Ball Bushing\* open type pillow blocks or 2 Super Smart Ball Bushing open type twin pillow blocks.
- 2 60 Case\* LinearRace\* shaft Support Rail Assemblies.
  - 1 mounting table top with work piece and Ball Screw Assembly attachment holes

#### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System





Type SPB-OP	N and	I SSL	JPBO	Pillow	Bloc	:ks				(Dimen	sions	in Inc	:hes)	Type TWN-OPN a	nd SSU	TWNO	Pillow E	Blocks
Part	Nom.	L1	H9	H8	H5	B9	B8	B6	J	J1	F	-	Wt.	Part	Nom.	L2	J3	Wt.
Number	Dia.										Bolt	Hole	lb	Number	Dia.			lb
SPB-8-OPN-XS	.50	1.50	1.12	.687	.25	2.00	.75	.69	1.69	1.00	#6	.16	.20	TWN-8-OPN-XS	.50	3.5	2.5	.40
SSUPBO-12-XS	.75	1.88	1.56	.937	.31	2.75	1.00	.94	2.38	1.25	#8	.19	.51	SSUTWNO-12-XS	.75	4.5	3.5	1.02
SSUPBO-16-XS	1.00	2.63	2.00	1.187	.38	3.25	1.25	1.19	2.88	1.75	#10	.22	1.03	SSUTWNO-16-XS	1.00	6.0	4.5	2.06
SSUPBO-20-XS	1.25	3.38	2.56	1.500	.43	4.00	1.63	1.50	3.50	2.00	#10	.22	2.15	SSUTWNO-20-XS	1.25	7.5	5.5	4.30
SSUPBO-24-XS	1.50	3.75	2.94	1.750	.50	4.75	1.88	1.75	4.12	2.50	1/4	.28	3.29	SSUTWNO-24-XS	1.50	9.0	6.5	6.88

Housing Material: Aluminum Alloy Black Anodized

Housing Material: Aluminum Alloy Black Anodized

Type SRA Li	nearRace S	Shaft Suppo	ort Rail Ass	sembly					(Dimensions	s in Inches)
Part	Nom.	H1	H7	Br	K	Х	Y	(	G	Wt.
Number	Dia.							Bolt	Hole	lb/ft
SRA-8-XS	.50	1.125	.19	1.50	1.00	4	2	#6	.17	1.26
SRA-12-XS	.75	1.500	.25	1.75	1.25	6	3	#10	.22	2.50
SRA-16-XS	1.00	1.750	.25	2.13	1.50	6	3	1/4	.28	4.06
SRA-20-XS	1.25	2.125	.31	2.50	1.88	6	3	<sup>5</sup> /16	.34	6.30
SRA-24-XS	1.50	2.500	.38	3.00	2.25	8	4	<sup>5</sup> /16	.34	8.60

LinearRace Shaft Support Rail Material: Aluminum Alloy Black Anodized

Maximum length of LinearRace Shaft Support Rail is 72 inches. If longer continuous one-piece LinearRace Shaft Support Rails are required, contact the Thomson Linear Guide Application Engineering department.

Mountin	g Table	Тор											(Dime	nsions in	inches)
Nominal		All	Table To	ps			Table	e Top Siz	e <b>B</b>			Tab	le Top Si	ze A	
Diameter	Т	М	J	H6	F5	T1	J1	J4	J5	N	T2	J3	J4	J5	N1
.50	5.5	3.25	1.69	.375	1/4-20	5.5	1.00	.34	.28	4.5	3.5	2.5	.50	.31	2.5
.75	7.5	4.50	2.38	.500	<sup>5</sup> /16-18	7.5	1.25	.41	.31	6.0	4.5	3.5	.50	.31	3.0
1.00	9.0	5.50	2.88	.500	<sup>3</sup> /8-16	9.0	1.75	.53	.31	7.0	6.0	4.5	.75	.31	4.0
1.25	11.0	6.75	3.50	.750	1/2-13	11.0	2.00	.82	.38	8.5	7.5	5.5	1.00	.38	5.0
1.50	13.0	8.00	4.12	.750	1/2-13	13.0	2.50	.75	.44	10.0	9.0	6.5	1.25	.44	6.0

Material: Aluminum Alloy Black Anodized

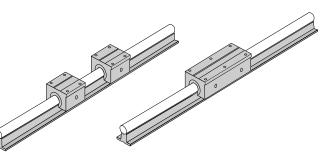
<sup>†</sup> Super Ball Bushing<sup>\*</sup> bearings are used in .500 inch size pillow blocks.



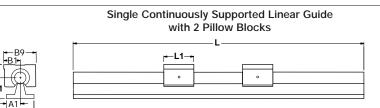


## **Continuous Support 1PA**

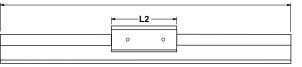
Linear Guide #6 Fully Supported, Highest Performance Industry Standard Dimensions

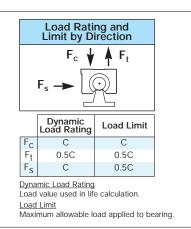


### METRIC



Single Continuously Supported Linear Guide with 1 Twin Pillow Block





Continuously S	upported Li	near Gui	de 1PA	Single \	with 2 P	illow Blo	ocks			(Dimensions in mm)
Part Number	Nominal Diameter	L1	H	H1	A	A1	B1	B9	Pillow Block	Shaft Support Rail Assembly
1PA-M12-LWO	12	39	46	28	43	21,5	21,5	43	SPPBO-M12-XS	SRA-M12-XS
1PA-M16-LWO	16	43	52	30	48	24,0	26,5	53	SSEPBO-M16-XS	SRA-M16-XS
1PA-M20-LWO	20	54	63	38	56	28,0	30,0	60	SSEPBO-M20-XS	SRA-M20-XS
1PA-M25-LWO	25	67	72	42	60	30,0	39,0	78	SSEPBO-M25-XS	SRA-M25-XS
1PA-M30-LWO	30	79	88	53	74	37,0	43,5	87	SSEPBO-M30-XS	SRA-M30-XS
1PA-M40-LWO	40	91	105	60	78	39,0	54,0	108	SSEPBO-M40-XS	SRA-M40-XS

Continuously Su	upported Li	inear Gu	ide 1P/	A Single	with 1	Twin Pi	llow Bl	ock		(Dim	ensions in mm)
Part	Nominal	L2	Н	H1	А	A1	B1	B9	Maximum	Pillow	Shaft
Number	Diameter								Stroke	Block	Support
									Length		Rail
											Assembly
1PA-M12-MWO	12	76	46	28	43	21,5	21,5	43	L-(76)	SPTWNO-M12-XS	SRA-M12-XS
1PA-M16-MWO	16	84	52	30	48	24,0	26,5	53	L-(84)	SSETWNO-M16-XS	SRA-M16-XS
1PA-M20-MWO	20	104	63	38	56	28,0	30,0	60	L-(104)	SSETWNO-M20-XS	SRA-M20-XS
1PA-M25-MWO	25	130	72	42	60	30,0	39,0	78	L-(130)	SSETWNO-M25-XS	SRA-M25-XS
1PA-M30-MWO	30	152	88	53	74	37,0	43,5	87	L-(152)	SSETWNO-M30-XS	SRA-M30-XS
1PA-M40-MWO	40	176	105	60	78	39,0	54,0	108	L-(176)	SSETWNO-M40-XS	SRA-M40-XS





**Continuously Supported** Linear Guide 1PA Benefits:

- Requires only one part number to specify the entire linear guide.
- Used as load support, transport and guidance solution.
- Used in continuously supported applications when rigidity is required.

#### **Continuously Supported** Linear Guide 1PA Components:\*

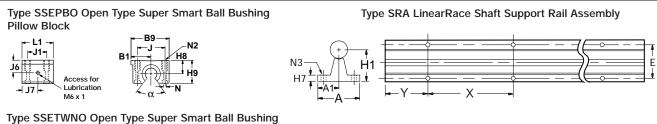
- 2 Super Smart Ball Bushing\* open type pillow blocks or 1 Super Smart Ball Bushing open type twin pillow block.
- 1 60 Case\* LinearRace\* shaft Support Rail Assembly.

#### Specifying this Thomson Linear Guide:

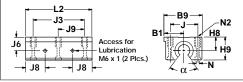
1. Determine the proper Linear Guide for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number.

#### Part Numbering System

1PA-M12-I	_WO L600
Linear Guide	Linear Guide
Designation	Length
Nominal Diameter 🚽	
Type of Bearing Block -	Type of Support



Type SSETWNO Open Type Super Smart Ball Bushing **Twin Pillow Block** 



illow	Bloc	:ks								(Din	nensio	ons in	ı mm)	Type SSETWNO F	Pillow	Bloc	ks			
Nom.	L1	H8	H9	B1	B9	J6	J7	J	J1	N	N2	α	Mass	Part	Nom.	L2	J3	J8	J9	Mass
Dia.										Dia.		Deg	kg	Number	Dia.					kg
12	39	18	28	21,5	43	16,7	19,5	32	23	4,3	M5	66	0,11	SPTWNO-M12-XS	12	76	56	19,5	28	0,22
16	43	22	35	26,5	53	22,0	21,5	40	26	5,3	M6	66	0,17	SSETWNO-M16-XS	16	84	64	21,5	32	0,34
20	54	25	41	30,0	60	25,0	27,0	45	32	6,6	M8	60	0,30	SSETWNO-M20-XS	20	104	76	27,0	38	0,63
25	67	30	50	39,0	78	31,5	33,5	60	40	8,4	M10	60	0,57	SSETWNO-M25-XS	25	130	94	33,6	47	1,18
30	79	35	60	43,5	87	33,0	39,5	68	45	8,4	M10	60	0,87	SSETWNO-M30-XS	30	152	106	39,5	53	1,70
40	91	45	77	54,0	108	43,5	45,5	86	58	10,5	M12	60	1,62	SSETWNO-M40-XS	40	176	124	45,5	62	3,18
	Nom. Dia. 12 16 20 25 30	Nom. Dia.L112391643205425673079	Dia.         Image: Provide state state           12         39         18           16         43         22           20         54         25           25         67         30           30         79         35	Nom. Dia.         L1         H8         H9           12         39         18         28           16         43         22         35           20         54         25         41           25         67         30         50           30         79         35         60	Nom. Dia.         L1         H8         H9         B1           12         39         18         28         21,5           16         43         22         35         26,5           20         54         25         41         30,0           25         67         30         50         39,0           30         79         35         60         43,5	Nom. Dia.         L1         H8         H9         B1         B9           12         39         18         28         21,5         43           16         43         22         35         26,5         53           20         54         25         41         30,0         60           25         67         30         50         39,0         78           30         79         35         60         43,5         87	Nom. Dia.         L1         H8         H9         B1         B9         J6           12         39         18         28         21,5         43         16,7           16         43         22         35         26,5         53         22,0           20         54         25         41         30,0         60         25,0           25         67         30         50         39,0         78         31,5           30         79         35         60         43,5         87         33,0	Nom. Dia.         L1         H8         H9         B1         B9         J6         J7           12         39         18         28         21,5         43         16,7         19,5           16         43         22         35         26,5         53         22,0         21,5           20         54         25         41         30,0         60         25,0         27,0           25         67         30         50         39,0         78         31,5         33,5           300         79         35         60         43,5         87         30,0         39,5	Nom. Dia.         L1         H8         H9         B1         B9         J6         J7         J           12         39         18         28         21,5         43         16,7         19,5         32           16         43         22         35         26,5         53         22,0         21,5         40           20         54         25         41         30,0         60         25,0         27,0         45           25         67         30         50         39,0         78         31,5         33,5         60           30         79         35         60         43,5         87         33,0         39,5         68	Nom. Dia.         L1         H8         H9         B1         B9         J6         J7         J         J1           12         39         18         28         21,5         43         16,7         19,5         32         23           16         43         22         35         26,5         53         22,0         21,5         40         26           20         54         25         41         30,0         60         25,0         27,0         45         32           25         67         30         50         39,0         78         31,5         33,5         60         40           300         79         35         60         43,5         87         33,0         39,5         68         45	Nom. Dia.         L1         H8         H9         B1         B9         J6         J7         J         J1         N Dia.           12         39         18         28         21,5         43         16,7         19,5         32         23         4,3           16         43         22         35         26,5         53         22,0         21,5         40         26         5,3           20         54         25         41         30,0         60         25,0         27,0         45         32         6,6           25         67         30         50         39,0         78         31,5         33,5         60         40         8,4           300         79         35         60         43,5         87         33,0         39,5         68         45         8,4	Nom. Dia.         L1         H8         H9         B1         B9         J6         J7         J1         N         N2           12         39         18         28         21,5         43         16,7         19,5         32         23         4,3         M5           16         43         22         35         26,5         53         22,0         21,5         40         26         5,3         M6           20         54         25         41         30,0         60         25,0         27,0         45         32         6,6         M8           25         67         30         50         39,0         78         31,5         33,5         60         40         8,4         M10           300         79         35         60         43,5         87         33,0         39,5         68         45         8,4         M10	Nom. Dia.         L1         H8         H9         B1         B9         J6         J7         J         J1         N Dia.         N2         Δ Deg           12         39         18         28         21,5         43         16,7         19,5         32         23         4,3         M5         66           16         43         22         35         26,5         53         22,0         21,5         40         26         5,3         M6         66           20         54         25         41         30,0         60         25,0         27,0         45         32         6,6         M8         60           25         67         30         50         39,0         78         31,5         33,5         60         40         8,4         M10         60           30         79         35         60         43,5         87         33,0         39,5         68         45         8,4         M10         60	Nom. Dia.         L1         H8         H9         B1         B9         J6         J7         J1         N         N2         α         Mass Deg         Mass kg           12         39         18         28         21,5         43         16,7         19,5         32         2.3         4.3         M5         66         0,11           16         43         22         35         26,5         53         22,0         21,5         40         26         5,3         M6         66         0,17           20         54         25         41         30,0         60         25,0         27,0         45         32         6,6         M8         60         0,30           25         67         30         50         39,0         78         31,5         33,5         60         40         8,4         M10         60         0,57           30         79         35         60         43,5         87         33,0         39,5         68         45         8,4         M10         60         0,87	Nom. Dia.         L1         H8         H9         B1         B9         J6         J7         J         J1         N         N2         α         Mass Deg         Part Number           12         39         18         28         21,5         43         16,7         19,5         32         23         4,3         M5         66         0,11         SPTWNO-M12-XS           16         43         22         35         26,5         53         22,0         21,5         40         26         5,3         M6         66         0,17         SSETWNO-M16-XS           20         54         25         41         30,0         60         25,0         27,0         45         32         6,6         M8         60         0,30         SSETWNO-M20-XS           20         54         25         41         30,0         78         31,5         33,5         60         40         8,4         M10         60         0,57         SSETWNO-M20-XS           25         67         30         50         37,0         37,5         68         45         8,4         M10         60         0,87         SSETWNO-M30-XS           300         79 </td <td>Nom. Dia.         L1         H8         H9         B1         B9         J6         J7         J         J1         N         N2         α         Mass Deg         Mass Kg         Part Number         Nom. Dia.           12         39         18         28         21,5         43         16,7         19,5         32         23         4,3         M5         66         0,11         SPTWNO-M12-XS         12           16         43         22         35         26,5         53         22,0         21,5         40         26         5,3         M6         66         0,17         SSETWNO-M16-XS         16           20         54         25         41         30,0         60         25,0         27,0         45         32         6,6         M8         60         0,30         SSETWNO-M16-XS         16           20         54         25         41         30,0         60         25,0         27,0         45         32         6,6         M8         60         0,30         SSETWNO-M20-XS         20           25         67         30         50         39,0         78         31,5         33,5         60         40</td> <td>Nom. Dia.         L1         H8         H9         B1         B9         J6         J7         J         J1         N         N2         α         Mass Deg         Mass Kg         Part Number         Nom. Dia.         L2           12         39         18         28         21,5         43         16,7         19,5         32         23         4,3         M5         66         0,11         SPTWNO-M12-XS         12         76           16         43         22         35         26,5         53         22,0         21,5         40         26         5,3         M6         66         0,11         SSETWNO-M12-XS         16         84           20         54         25         41         30,0         60         25,0         27,0         45         32         6,6         M8         60         0,30         SSETWNO-M20-XS         20         104           25         67         30         50         39,0         78         31,5         33,5         60         40         8,4         M10         60         0,57         SSETWNO-M30-XS         30         152           30         79         35         60         43,5</td> <td>Nom. Dia.         L1         H8         H9         B1         B9         J6         J7         J         J1         N         Dia.         Ca         Mass Deg         Mass Deg         Part Number         Part Number         Nom. Dia.         L2         J3           12         39         18         28         21,5         43         16,7         19,5         32         23         4,3         M5         66         0,11         SPTWNO-M12-XS         12         76         56           16         43         22         35         26,5         53         20,0         21,5         40         26         5,3         M6         66         0,17         SETWNO-M16-XS         16         84         64           20         54         25         41         30,0         60         25,0         27,0         45         32         6,6         M8         60         0,30         SETWNO-M16-XS         16         84         64           20         54         25         41         30,0         60         25,0         27,0         45         32         6,6         M8         60         0,30         SETWNO-M26-XS         20         104         7</td> <td>Nom. Dia.         L1         H8         H9         B1         B9         J6         J7         J         J1         N         N2         α         Mass Deg         Part Number         Nom. Dia.         L2         J3         J8           12         39         18         28         21,5         43         16,7         19,5         32         23         4,3         M5         66         0,11         SPTWNO-M12-XS         12         76         56         19,5           16         43         22         35         26,5         53         22,0         21,5         40         26         5,3         M6         66         0,17         SSETWNO-M16-XS         16         84         64         21,5           20         54         25         41         30,0         60         25,0         27,0         45         32         6,6         M8         60         0,30         SSETWNO-M16-XS         16         84         64         21,5           20         54         25         41         30,0         60         40         8,4         M10         60         0,57         SSETWNO-M25-XS         25         130         94         3,6</td> <td>Nom. Dia.         L1         H8         H9         B1         B9         J6         J7         J         J1         N         Dia.         Ca         Mass Deg         Part Number         Part Number         Nom. Dia.         L2         J3         J8         J9           12         39         18         28         21.5         43         16.7         19.5         32         23         4.3         M5         66         0.11         SPTWNO-M12-XS         12         76         56         19.5         28           16         43         22         35         26.5         53         20         21.5         40         26         5.3         M6         66         0.11         SETWNO-M12-XS         10         84         64         21.5         32         23         4.3         M6         60         0.30         SETWNO-M16-XS         16         84         64         21.5         32         26         6.6         M8         60         0.30         SETWNO-M26-XS         20         104         76         27.0         38           25         67         30         50         39.0         78         31.5         33.5         60         40</td>	Nom. Dia.         L1         H8         H9         B1         B9         J6         J7         J         J1         N         N2         α         Mass Deg         Mass Kg         Part Number         Nom. Dia.           12         39         18         28         21,5         43         16,7         19,5         32         23         4,3         M5         66         0,11         SPTWNO-M12-XS         12           16         43         22         35         26,5         53         22,0         21,5         40         26         5,3         M6         66         0,17         SSETWNO-M16-XS         16           20         54         25         41         30,0         60         25,0         27,0         45         32         6,6         M8         60         0,30         SSETWNO-M16-XS         16           20         54         25         41         30,0         60         25,0         27,0         45         32         6,6         M8         60         0,30         SSETWNO-M20-XS         20           25         67         30         50         39,0         78         31,5         33,5         60         40	Nom. Dia.         L1         H8         H9         B1         B9         J6         J7         J         J1         N         N2         α         Mass Deg         Mass Kg         Part Number         Nom. Dia.         L2           12         39         18         28         21,5         43         16,7         19,5         32         23         4,3         M5         66         0,11         SPTWNO-M12-XS         12         76           16         43         22         35         26,5         53         22,0         21,5         40         26         5,3         M6         66         0,11         SSETWNO-M12-XS         16         84           20         54         25         41         30,0         60         25,0         27,0         45         32         6,6         M8         60         0,30         SSETWNO-M20-XS         20         104           25         67         30         50         39,0         78         31,5         33,5         60         40         8,4         M10         60         0,57         SSETWNO-M30-XS         30         152           30         79         35         60         43,5	Nom. Dia.         L1         H8         H9         B1         B9         J6         J7         J         J1         N         Dia.         Ca         Mass Deg         Mass Deg         Part Number         Part Number         Nom. Dia.         L2         J3           12         39         18         28         21,5         43         16,7         19,5         32         23         4,3         M5         66         0,11         SPTWNO-M12-XS         12         76         56           16         43         22         35         26,5         53         20,0         21,5         40         26         5,3         M6         66         0,17         SETWNO-M16-XS         16         84         64           20         54         25         41         30,0         60         25,0         27,0         45         32         6,6         M8         60         0,30         SETWNO-M16-XS         16         84         64           20         54         25         41         30,0         60         25,0         27,0         45         32         6,6         M8         60         0,30         SETWNO-M26-XS         20         104         7	Nom. Dia.         L1         H8         H9         B1         B9         J6         J7         J         J1         N         N2         α         Mass Deg         Part Number         Nom. Dia.         L2         J3         J8           12         39         18         28         21,5         43         16,7         19,5         32         23         4,3         M5         66         0,11         SPTWNO-M12-XS         12         76         56         19,5           16         43         22         35         26,5         53         22,0         21,5         40         26         5,3         M6         66         0,17         SSETWNO-M16-XS         16         84         64         21,5           20         54         25         41         30,0         60         25,0         27,0         45         32         6,6         M8         60         0,30         SSETWNO-M16-XS         16         84         64         21,5           20         54         25         41         30,0         60         40         8,4         M10         60         0,57         SSETWNO-M25-XS         25         130         94         3,6	Nom. Dia.         L1         H8         H9         B1         B9         J6         J7         J         J1         N         Dia.         Ca         Mass Deg         Part Number         Part Number         Nom. Dia.         L2         J3         J8         J9           12         39         18         28         21.5         43         16.7         19.5         32         23         4.3         M5         66         0.11         SPTWNO-M12-XS         12         76         56         19.5         28           16         43         22         35         26.5         53         20         21.5         40         26         5.3         M6         66         0.11         SETWNO-M12-XS         10         84         64         21.5         32         23         4.3         M6         60         0.30         SETWNO-M16-XS         16         84         64         21.5         32         26         6.6         M8         60         0.30         SETWNO-M26-XS         20         104         76         27.0         38           25         67         30         50         39.0         78         31.5         33.5         60         40

Housing Material: Aluminum Alloy Grey Anodized

Housing Material: Aluminum Alloy Grey Anodized

Type SRA Li	nearRace	Shaft Supp	oort Rail As	sembly					(Dimensio	ons in mm)
Part Number	Nom. Dia.	H1	H7	A	A1	E	Х	Y	N3 Dia.	Mass kg/m
SRA-M12-XS	12	28	5	43	21,5	29	75	37,5	4,5	4,1
SRA-M16-XS	16	30	5	48	24,0	33	100	50	5,5	6,2
SRA-M20-XS	20	38	6	56	28,0	37	100	50	6,6	9,5
SRA-M25-XS	25	42	6	60	30,0	42	120	60	6,6	13,7
SRA-M30-XS	30	53	8	74	37,0	51	150	75	8,6	20,0
SRA-M40-XS	40	60	8	78	39,0	55	200	100	8,6	32,5

LinearRace Shaft Support Rail Material:

Aluminum Alloy Grey Anodized

Maximum length of LinearRace Shaft Support Rail is 600 mm. If longer continuous one-piece LinearRace Shaft Support Rails are required, contact the Thomson Linear Guides application engineering department.

Dynamic Load Rating (C) Matrix			(100 km travel)	Dynamic Loa	atrix	(100 km travel)	
Linear Guide Assembly Part No.	Dynamic Load Rating, C (N) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (N)	Linear Guide Assembly Part No.	Dynamic Load Rating, C (N) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (N)
1PA-M12-LWO	1500	SPPBO-M12-XS	750	1PA-M12-MWO	1220	SPTWNO-M12-XS	1500
1PA-M16-LWO	4400	SSEPBO-M16-XS	2200	1PA-M16-MWO	4400	SSETWNO-M16-XS	4400
1PA-M20-LWO	8000	SSEPBO-M20-XS	4000	1PA-M20-MWO	8000	SSETWNO-M20-XS	8000
1PA-M25-LWO	13400	SSEPBO-M25-XS	6700	1PA-M25-MWO	13400	SSETWNO-M25-XS	13400
1PA-M30-LWO	16600	SSEPBO-M30-XS	8300	1PA-M30-MWO	16600	SSETWNO-M30-XS	16600
1PA-M40-LWO	27400	SSEPBO-M40-XS	13700	1PA-M40-MWO	27400	SSETWNO-M40-XS	27400

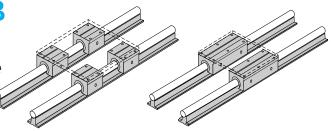
<sup>†</sup> Super Plus Ball Bushing<sup>\*</sup> bearings are used in 12 mm size pillow blocks.





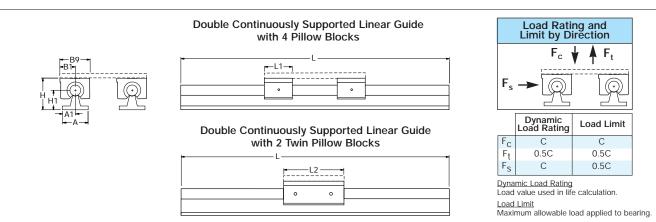
## **Continuous Support 1PB**

Linear Guide #6 Fully Supported, Highest Performance Industry Standard Dimensions



### METRIC

Page 70



Continuously S	ontinuously Supported Linear Guide 1PB Double with 4 Pillow Blocks														
Part Number	Nominal Diameter	L1	H	H1	A	A1	B1	В9	Pillow Block	Shaft Support Rail Assembly					
1PB-M12-LWO	12	39	46	28	43	21,5	21,5	43	SPPBO-M12-XS	SRA-M12-XS					
1PB-M16-LWO	16	43	52	30	48	24,0	26,5	53	SSEPBO-M16-XS	SRA-M16-XS					
1PB-M20-LWO	20	54	63	38	56	28,0	30,0	60	SSEPBO-M20-XS	SRA-M20-XS					
1PB-M25-LWO	25	67	72	42	60	30,0	39,0	78	SSEPBO-M25-XS	SRA-M25-XS					
1PB-M30-LWO	30	79	88	53	74	37,0	43,5	87	SSEPBO-M30-XS	SRA-M30-XS					
1PB-M40-LWO	40	91	105	60	78	39,0	54,0	108	SSEPBO-M40-XS	SRA-M40-XS					

Continuously Su	ontinuously Supported Linear Guide 1PB Double with 2 Twin Pillow Blocks														
Part	Nominal	L2	Н	H1	А	A1	B1	B9	Maximum	Pillow	Shaft				
Number	Diameter								Stroke	Block	Support				
									Length		Rail				
											Assembly				
1PB-M12-MWO	12	76	46	28	43	21,5	21,5	43	L-(76)	SPTWNO-M12-XS	SRA-M12-XS				
1PB-M16-MWO	16	84	52	30	48	24,0	26,5	53	L-(84)	SSETWNO-M16-XS	SRA-M16-XS				
1PB-M20-MWO	20	104	63	38	56	28,0	30,0	60	L-(104)	SSETWNO-M20-XS	SRA-M20-XS				
1PB-M25-MWO	25	130	72	42	60	30,0	39,0	78	L-(130)	SSETWNO-M25-XS	SRA-M25-XS				
1PB-M30-MWO	30	152	88	53	74	37,0	43,5	87	L-(152)	SSETWNO-M30-XS	SRA-M30-XS				
1PB-M40-MWO	40	176	105	60	78	39,0	54,0	108	L-(176)	SSETWNO-M40-XS	SRA-M40-XS				





Continuously Supported Linear Guide 1PB Benefits:

- Requires only one part number to specify the entire linear guide.
- Allows for custom table mounting
- Used in continuously supported applications when rigidity is required.

#### Continuously Supported Linear Guide 1PB Components:<sup>†</sup>

- 4 Super Smart Ball Bushing\* open type pillow blocks or 2 Super Smart Ball Bushing open type twin pillow blocks.
- 2 60 Case\* LinearRace\* shaft Support Rail Assemblies.

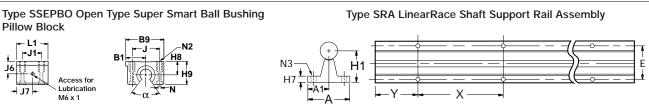
#### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number.

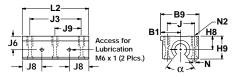
#### Part Numbering System

#### 1PB-M12-LWO L600

Linear Guide Designation J Nominal Diameter J Type of Bearing Block J Type of Support



Type SSETWNO Open Type Super Smart Ball Bushing Twin Pillow Block



ype SSEPBO Pillow Blocks         (Dimensions in mm)														Type SSETWNO F	Pillow l	Bloc	ks				
Part	Nom.	L1	H8	H9	B1	B9	J6	J7	J	J1	Ν	N2	α	Mass	Part	Nom.	L2	J3	J8	J9	Mass
Number	Dia.										Dia.		Deg	kg	Number	Dia.					kg
SPPBO-M12-XS	12	39	18	28	21,5	43	16,7	19,5	32	23	4,3	M5	66	0,11	SPTWNO-M12-XS	12	76	56	19,5	28	0,22
SSEPBO-M16-XS	16	43	22	35	26,5	53	22,0	21,5	40	26	5,3	M6	66	0,17	SSETWNO-M16-XS	16	84	64	21,5	32	0,34
SSEPBO-M20-XS	20	54	25	41	30,0	60	25,0	27,0	45	32	6,6	M8	60	0,30	SSETWNO-M20-XS	20	104	76	27,0	38	0,63
SSEPBO-M25-XS	25	67	30	50	39,0	78	31,5	33,5	60	40	8,4	M10	60	0,57	SSETWNO-M25-XS	25	130	94	33,6	47	1,18
SSEPBO-M30-XS	30	79	35	60	43,5	87	33,0	39,5	68	45	8,4	M10	60	0,87	SSETWNO-M30-XS	30	152	106	39,5	53	1,70
SSEPBO-M40-XS	40	91	45	77	54,0	108	43,5	45,5	86	58	10,5	M12	60	1,62	SSETWNO-M40-XS	40	176	124	45,5	62	3,18

Housing Material: Aluminum Alloy Grey Anodized

Type SRA Li	pe SRA LinearRace Shaft Support Rail Assembly														
Part Number	Nom. Dia.	H1	H7	A	A1	E	Х	Y	N3 Dia.	Mass kg/m					
SRA-M12-XS	12	28	5	43	21,5	29	75	37,5	4,5	4,1					
SRA-M16-XS	16	30	5	48	24,0	33	100	50	5,5	6,2					
SRA-M20-XS	20	38	6	56	28,0	37	100	50	6,6	9,5					
SRA-M25-XS	25	42	6	60	30,0	42	120	60	6,6	13,7					
SRA-M30-XS	30	53	8	74	37,0	51	150	75	8,6	20,0					
SRA-M40-XS	40	60	8	78	39,0	55	200	100	8,6	32,5					

LinearRace Shaft Support Rail Material: Aluminum Alloy Grey Anodized Maximum length of LinearRace Shaft Support Rail is 600 mm. If longer continuous one-piece LinearRace Shaft Support Rails are required, contact the Thomson Linear Guide application engineering department.

Dynamic Loa	(100 km travel)	Dynamic Loa	atrix	(100 km travel)			
Linear Guide Assembly Part No.	Dynamic Load Rating, C (N) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (N)	Linear Guide Assembly Part No.	Dynamic Load Rating, C (N) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (N)
1PB-M12-LWO	3000	SPPBO-M12-XS	750	1PB-M12-MWO	2440	SPTWNO-M12-XS	1500
1PB-M16-LWO	8800	SSEPBO-M16-XS	2200	1PB-M16-MWO	8800	SSETWNO-M16-XS	4400
1PB-M20-LWO	16000	SSEPBO-M20-XS	4000	1PB-M20-MWO	16000	SSETWNO-M20-XS	8000
1PB-M25-LWO	26800	SSEPBO-M25-XS	6700	1PB-M25-MWO	26800	SSETWNO-M25-XS	13400
1PB-M30-LWO	33200	SSEPBO-M30-XS	8300	1PB-M30-MWO	33200	SSETWNO-M30-XS	16600
1PB-M40-LWO	54800	SSEPBO-M40-XS	13700	1PB-M40-MWO	54800	SSETWNO-M40-XS	27400

<sup>†</sup> Super Plus Ball Bushing<sup>\*</sup> bearings are used in 12 mm size pillow blocks.

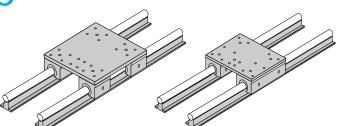




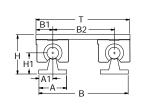


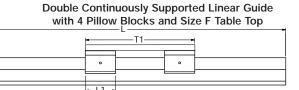
## **Continuous Support 1PC**

### Linear Guide #6 with Table Top Fully Supported, Industry Standard Dimensions

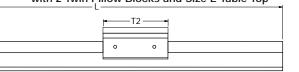


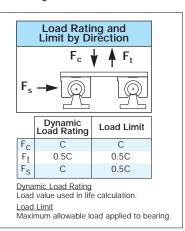
METRIC





Double Continuously Supported Linear Guide with 2 Twin Pillow Blocks and Size E Table Top





Continuously S	upport	ed Lin	ear Gui	de 1PC	Doub	le with	4 Pillo	w Bloc	ks an	d Table	e Top (S	Size F)	[]	Dimensions in mm)		
Part	Nom.	L1	Н	H1	A	A1	В	B1	B2	Т	T1	Maximum	Pillow	Shaft		
Number	Dia.											Stroke	Block	Support		
												Length		Rail		
													Assembly			
1PC-M12-LWF	12	39	56	28	43	21,5	98	22,5	55	100	100	L-(100)	SPPBO-M12-XS	SRA-M12-XS		
1PC-M16-LWF	16	43	65	30	48	24,0	118	27,5	70	125	125	L-(125)	SSEPBO-M16-XS	SRA-M16-XS		
1PC-M20-LWF	20	54	79	38	56	28,0	166	32,0	110	175	175	L-(175)	SSEPBO-M20-XS	SRA-M20-XS		
1PC-M25-LWF	25	67	92	42	60	30,0	203	42,5	140	225	225	L-(225)	SSEPBO-M25-XS	SRA-M25-XS		
1PC-M30-LWF	30	79	108	53	74	37,0	254	47,5	180	275	275	L-(275)	SSEPBO-M30-XS	SRA-M30-XS		
1PC-M40-LWF	40	91	130	60	78	39,0	288	57,5	210	325	325	L-(325)	SSEPBO-M40-XS	SRA-M40-XS		

Continuously Sup	ported Li	inear Gu	uide 1P	C Dou	ble with	n 2 Twin	Pillow	Blocks	and Ta	able Top	o (Size E)	([	Dimensions in mm)
Part	Nom.	Н	H1	Α	A1	В	B1	B2	Т	T2	Maximum	Pillow	Shaft
Number	Dia.										Stroke	Block	Support
											Length		Rail
													Assembly
1PC-M12-MWE	12	56	28	43	21,5	98	22,5	55	100	76	L-(76)	SPTWNO-M12-XS	SRA-M12-XS
1PC-M16-MWE	16	65	30	48	24,0	118	27,5	70	125	84	L-(84)	SSETWNO-M16-XS	SRA-M16-XS
1PC-M20-MWE	20	79	38	56	28,0	166	32,5	110	175	104	L-(104)	SSETWNO-M20-XS	SRA-M20-XS
1PC-M25-MWE	25	92	42	60	30,0	203	42,5	140	225	130	L-(130)	SSETWNO-M25-XS	SRA-M25-XS
1PC-M30-MWE	30	108	53	74	37,0	254	47,5	180	275	152	L-(152)	SSETWNO-M30-XS	SRA-M30-XS
1PC-M40-MWE	40	130	60	78	39,0	288	57,5	210	325	176	L-(176)	SSETWNO-M40-XS	SRA-M40-XS

Dynamic Lo	ad Rating (C) M	atrix	(100 km travel)	Dynamic Loa	ad Rating (C) M	latrix	(1
Linear Guide	Dynamic Load	Pillow Block	Pillow Block	Linear Guide	Dynamic Load	Pillow Block	
Assembly Part No.	Rating, C (N) (Even Distribution)	Part No.	Dynamic Load Rating, C (N)	Assembly Part No.	Rating, C (N) (Even Distribution)	Part No.	
1PC-M12-LWF	3000	SPPBO-M12-XS	750	1PC-M12-MWE	2440	SPTWNO-M12-XS	ſ
1PC-M16-LWF	8800	SSEPBO-M16-XS	2200	1PC-M16-MWE	8800	SSETWNO-M16-XS	
1PC-M20-LWF	16000	SSEPBO-M20-XS	4000	1PC-M20-MWE	16000	SSETWNO-M20-XS	
1PC-M25-LWF	26800	SSEPBO-M25-XS	6700	1PC-M25-MWE	26800	SSETWNO-M25-XS	
1PC-M30-LWF	33200	SSEPBO-M30-XS	8300	1PC-M30-MWE	33200	SSETWNO-M30-XS	
IPC-M40-LWF	54800	SSEPBO-M40-XS	13700	1PC-M40-MWE	54800	SSETWNO-M40-XS	







**Continuously Supported** Linear Guide 1PC Benefits:

- Requires only one part number to specify the entire linear guide.
- Includes table top with standard tapped holes for quick and easy mounting of the work piece.
- Includes Ball Screw Assembly attachment holes for ease of assembly and actuation.
- Used in continuously supported applications when rigidity is required.

17

J6

Ŧ

J8

#### **Continuously Supported** Linear Guide 1PC Components:\*

- 4 Super Smart Ball Bushing\* open type pillow blocks or 2 Super Smart Ball Bushing open type twin pillow blocks.
- 2 60 Case\* LinearRace\* shaft Support Rail Assemblies.
  - 1 mounting table top with work piece and Ball Screw Assembly attachment holes.

#### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number.

#### Part Numbering System

1PC-M12-LWF L600



Type SSEPBO Open Type Super Smart Ball Type SRA LinearRace Shaft Support Rail Assembly Mounting Table Top **Bushing Pillow Block** R9 M1, M2 N2 r+J1+ F 0 0 H9 Access for 0 Lubrication Х M6 x 1 Type SSETWNO Open Type Super Smart Ball **Bushing Twin Pillow Block** 0 J3 N2 - J9-B1 J<sub>J1</sub> Access for .13 Lubrication \_\_\_\_Н6 M6 x 1 (2 Plcs.) -+ J8

Type SSEPBO F	Pillow	Bloc	ks								(Din	nensio	ons in	n mm)	Type SSETWNO F	Pillow I	Bloc	ks			
Part	Nom.	L1	H8	H9	B1	B9	J6	J7	J	J1	Ν	N2	α	Mass	Part	Nom.	L2	J3	J8	J9	Mass
Number	Dia.										Dia.		Deg	kg	Number	Dia.					kg
SPPBO-M12-XS	12	39	18	28	21,5	43	16,7	19,5	32	23	4,3	M5	66	0,11	SPTWNO-M12-XS	12	76	56	19,5	28	0,22
SSEPBO-M16-XS	16	43	22	35	26,5	53	22,0	21,5	40	26	5,3	M6	66	0,17	SSETWNO-M16-XS	16	84	64	21,5	32	0,34
SSEPBO-M20-XS	20	54	25	41	30,0	60	25,0	27,0	45	32	6,6	M8	60	0,30	SSETWNO-M20-XS	20	104	76	27,0	38	0,63
SSEPBO-M25-XS	25	67	30	50	39,0	78	31,5	33,5	60	40	8,4	M10	60	0,57	SSETWNO-M25-XS	25	130	94	33,6	47	1,18
SSEPBO-M30-XS	30	79	35	60	43,5	87	33,0	39,5	68	45	8,4	M10	60	0,87	SSETWNO-M30-XS	30	152	106	39,5	53	1,70
SSEPBO-M40-XS	40	91	45	77	54,0	108	43,5	45,5	86	58	10,5	M12	60	1,62	SSETWNO-M40-XS	40	176	124	45,5	62	3,18
Housing Material: Alu	minum		Grev A	nodiz	ed										Housing Material: Alu	iminum	Allov	Grev	Anod	ized	

lousing Material: Aluminum Alloy Grey Anodized

ng Material: Aluminum Alloy Grey Anodi

Type SRA Li	nearRace	Shaft Supp	ort Rail As	sembly					(Dimensio	ons in mm)
Part Number	Nom. Dia.	H1	H7	A	A1	E	Х	Y	N3 Dia.	Mass kg/m
SRA-M12-XS	12	28	5	43	21,5	29	75	37,5	4,5	4,1
SRA-M16-XS	16	30	5	48	24,0	33	100	50	5,5	6,2
SRA-M20-XS	20	38	6	56	28,0	37	100	50	6,6	9,5
SRA-M25-XS	25	42	6	60	30,0	42	120	60	6,6	13,7
SRA-M30-XS	30	53	8	74	37,0	51	150	75	8,6	20,0
SRA-M40-XS	40	60	8	78	39,0	55	200	100	8,6	32,5

LinearRace Shaft Support Rail Material: Aluminum Alloy Grey Anodized

Maximum length of LinearRace Shaft Support Rail is 600 mm. If longer continuous one-piece LinearRace Shaft Support Rails are required, contact the Thomson Linear Guide application engineering department.

Mounting	g Table	Тор												(Dimen	isions i	n mm)
System		All	Table To	ps			Tab	le Top Siz	e F			Т	able To	p Size <b>E</b>	-	
	Т	M	J	H6	F5 <sup>(2)</sup>	T1	J1	J4	J5	M1	T2	J3	J4	J5	J9	M2
1PC-M12	100	55	32	10	M6	100	23	8,0	6,5	55	76	56	10	6,5	28	40
1PC-M16	125	70	40	13	M6	125	26	10,0	7,5	70	84	64	10	7,5	32	45
1PC-M20	175	110	45	16	M8	175	32	11,0	10,0	110	104	76	14	10,0	38	55
1PC-M25	225	140	60	20	M8	225	40	13,5	12,5	140	130	94	18	12,5	47	65
1PC-M30	275	180	68	20	M8	275	45	17,0	13,5	180	152	106	23	13,5	53	75
1PC-M40	325	210	86	25	M10	325	58	16,5	14,5	210	176	124	26	14,5	62	85

Material: Aluminum Alloy Grey Anodized

<sup>(2)</sup> Customer Mounting hole.

<sup>†</sup> Super Plus Ball Bushing<sup>\*</sup> bearings are used in 12 mm size pillow blocks.





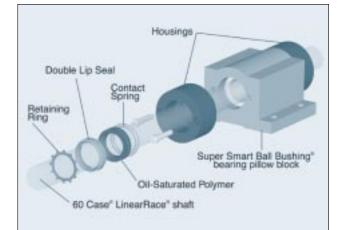
### **Continuous Support Ball Guide Accessories**



### -LL Self-Lubricating Option<sup>‡</sup>

The new LL Option provides maintenancefree operation and enhanced bearing protection.

- Eliminates the need for expensive lubrication system in most applications
- Increases effective bearing life by increasing protection from contamination
- Environmentally friendly
- NOTE: Carriage drag with the -LL option will be approximately 2x the seal drag.
- <sup>+</sup> See page 210 for technical data.

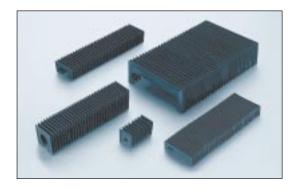


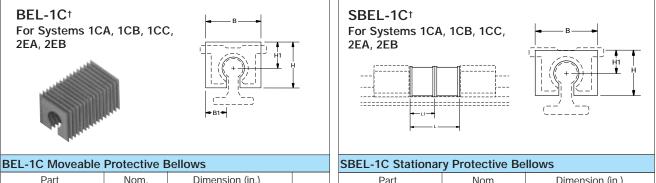
### **Bellows (Way Covers) Option**



This illustration describes the proper usage for stationary and moveable bellows for System 1CA.

Stationary Protective Bellows are designed to fit between two fixed pillow blocks and underneath the profile of the carrriage mounting top.





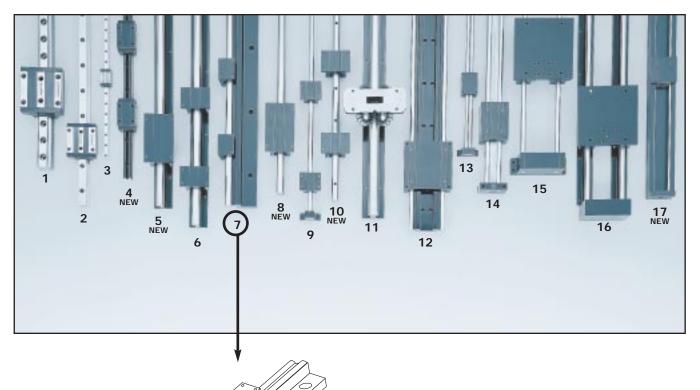
							· <b>,</b> · · · · · · · · · · · · · · · · · · ·			(
Part	Nom.	Dime	Dimension (in.)		CR	Part	Nom.	Di	mension (	in.)
Number	Shaft Dia.	Н	H1	В	CK	Number	Shaft Dia.	Н	H1	В
BEL-1C-08	1/2	1.375	.968	2.062	.088	SBEL-1C-08	1/2	1.125	0.656	2.062
BEL-1C-12	3/4	1.812	1.062	2.312	.120	SBEL-1C-12	3/4	1.625	0.843	2.281
BEL-1C-16	1	2.375	1.218	2.625	.088	SBEL-1C-16	1	2.250	1.031	2.625
BEL-1C-24	<b>1</b> <sup>1</sup> / <sub>2</sub>	3.125	1.531	3.125	.088	SBEL-1C-24	<b>1</b> <sup>1</sup> / <sub>2</sub>	3.062	1.531	3.125

<sup>†</sup> Each moveable bellows comes with 1 section of bellows and 2 pairs of Velcro® Fasteners.





## Side Mounted Linear Ball Guides



## LOW PROFILE, HIGH LOADS IN ALL DIRECTIONS, EASY TO INSTALL

### Side Mounted Linear Ball Guides Offer:

- Increased life within the same envelope. RoundRail\* linear guides feature the new patented Super Smart Ball Bushing\* bearings for up to 216X the life or 6X the load capacity of conventional bearings
- Cost savings: save time and money preparing your mounting surfaces before bolting down RoundRail linear guides
- Side mounted geometry for increased mounting flexibility
- Superior performance. Continuously supported for maximum (down- & side-) load applications without concerns for shaft deflection

- The RoundRail Advantage\*. The inherent self-aligning-in-all-directions design of the Super Smart Ball Bushing bearing allows for ultra smooth travel when mounted to wider toleranced prepared surfaces
- Unlimited travel lengths without concerns for machined reference edges or butt joint alignment
- The Super Smart Ball Bushing bearing... the most technologically advanced and most robust linear bearing in the world
- Corrosion resistant versions for maximum performance in harsh environments.

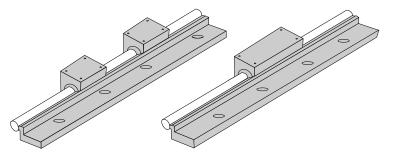
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



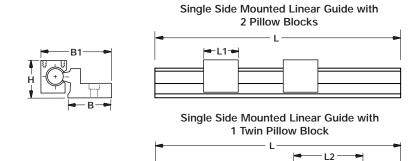
#7

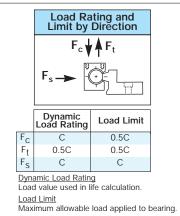
## Side Mounted 1DA

Linear Guide #7 Side Mounted for Low Profile



### INCH





Side Mounted L	inear Guide 1D	A Single Side I	Mounted with 2	Pillow Blocks	5	(Dimensio	ons in inches)
Part Number	Nominal Diameter	Н	В	B1	L1	Pillow Block	Shaft Support Rail Assembly
1DA-08-JOO	.50	1.562	1.44	2.61	1.50	SPB-8-OPN-MOD	SSRA-8
1DA-12-JOO	.75	2.062	1.94	3.55	1.88	SSUPBO-12-MOD	SSRA-12
1DA-16-JOO	1.00	2.562	2.44	4.49	2.63	SSUPBO-16-MOD	SSRA-16

Side Mounted	Linear Guide	1DA Single	Side Mount	ted with 1 T	win Pillow Bl	ock	(Dimensio	ns in inches)
Part	Nominal	Н	В	B1	L2	Maximum	Pillow	Shaft
Number	Diameter					Stroke	Block	Support
						Length		Rail
								Assembly
1DA-08-KOO	.50	1.562	1.44	2.61	3.5	L-(3.5)	TWN-8-OPN-MOD	SSRA-8
1DA-12-KOO	.75	2.062	1.94	3.55	4.5	L-(4.5)	SSUTWNO-12-MOD	SSRA-12
1DA-16-KOO	1.00	2.562	2.44	4.49	6.0	L-(6.0)	SSUTWNO-16-MOD	SSRA-16





#### Side Mounted Linear Guide 1DA Benefits:

- Continuously supported design increases rigidity and provides for unlimited linear guide travel lengths.
- Versatile Side Support Rail Assembly geometry for optimizing mounting ability.
- Side mounted design provides an increase in pull-off load capacity.

#### Side Mounted Linear Guide 1DA Components: †

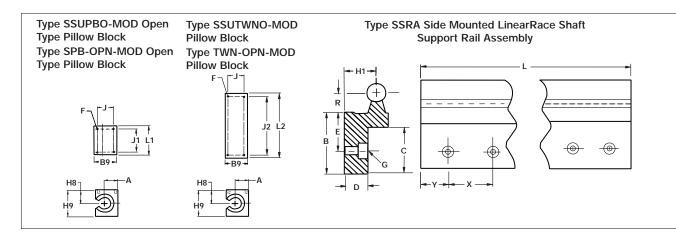
- 2 Super Smart Ball Bushing\* modified open type pillow blocks or 1 Super Smart Ball Bushing modified open type twin pillow block.
- 1 60 Case\* LinearRace\* shaft Side Mounted Support Rail Assembly.

#### Specifying this Thomson Linear Guide:

1. Determine the proper Linear Guide for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System

1DA-12-JOO L24 Linear Guide Linear Guide Designation Length Nominal Diameter. Type of Bearing Block → Type of Support



Type SPB-OPN-	MOD	and SS	UPBO-	MOD P	illow Bl	ock	(	Dimensi	ons in in	ches)	Type TWN-OPN-MOD an	d SSUTW	NO-MOE	) Pillow B	locks
Part	Nom.	H8	H9	А	B9	L1	J	J1	F	Wt.	Part	Nom.	L2	J2	Wt.
Number	Dia.									lb	Number	Dia.			lb
SPB-08-OPN-MOD	.50	.687	1.44	.67	1.12	1.50	.812	1.250	#8-32	.18	TWN-8-OPN-MOD	.50	3.5	3.00	.39
SSUPBO-12-MOD	.75	.937	1.94	.92	1.56	1.88	1.187	1.562	#10-32	.45	SSUTWNO-12-MOD	.75	4.5	4.00	1.00
SSUPBO-16-MOD	1.00	1.187	2.44	1.17	2.00	2.63	1.438	2.250	1/4-20	.98	SSUTWNO-16-MOD	1.00	6.0	5.25	2.11
Housing Material: Alu	lousing Material: Aluminum Alloy Black Anodized Housing Material: Aluminum Alloy Black														

Housing Material: Aluminum Alloy Black Anodized

enal. Alumnum Alloy Diach Anodized

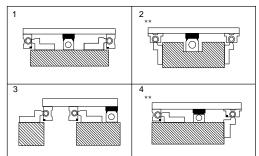
Type SSRA S	Side Moun	ted Linear	Race Sha	aft Suppor	t Rail Asse	embly				(Dimen	sions in	Inches)
Part	Nom.	H1	В	R	E	D	С	Х	Y <sup>(1)</sup>	(	<u>.</u>	Wt.
Number	Dia.									Bolt	Hole	lb/ft
SSRA-08	.500	.875	1.44	.500	1.00	.49	1.06	4	2	1/4	.28	2.05
SSRA-12	.750	1.125	1.94	.688	1.31	.75	1.44	6	3	<sup>5</sup> /16	.34	4.00
SSRA-16	1.000	1.375	2.44	.875	1.63	.88	1.81	6	3	<sup>3</sup> /8	.41	6.25
<sup>(1)</sup> For standard le	or standard lengths Maximum length of LinearRace Shaft Support Rail is 72 inches. If longer continuous one-piece											

<sup>(1)</sup> For standard lengths

LinearRace Shaft Support Rail Material: Aluminum Black Anodized

#### **Mounting Configurations**

The following mounting configurations depict ideas for combining the Side Mounted Continuously Supported Linear Guides into your linear motion application. If you need further information, contact the Thomson Application Engineering Department.



\*\*Pillow blocks shown are the standard SSUPBO or SPB-OPN style. To order System 1DA with standard pillow blocks, order the Side Mounted

Shaft Rail Assembly (SSRA) and the SSUPBO or SPB-OPN separately.



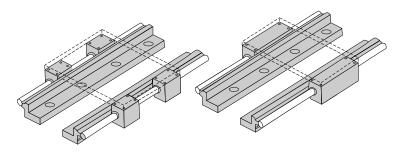
LinearRace Shaft Support Rails are required, contact the Thomson Linear Guides Application Engineering department.

Dynamic Load	Rating (C) Matrix	(4 mi	llion inches travel)
Linear Guide Assembly Part No.	Dynamic Load Rating, C (Ib <sub>f</sub> ) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (lb <sub>f</sub> )
1DA-08-JOO	240	SPB-8-OPN-MOD	120
1DA-12-JOO	1600	SSUPBO-12-MOD	800
1DA-16-JOO	2700	SSUPBO-16-MOD	1350
1DA-08-KOO	240	TWN-8-OPN-MOD	240
1DA-12-KOO 1600		SSUTWNO-12-MOD	1600
1DA-16-KOO	2700	SSUTWNO-16-MOD	2700

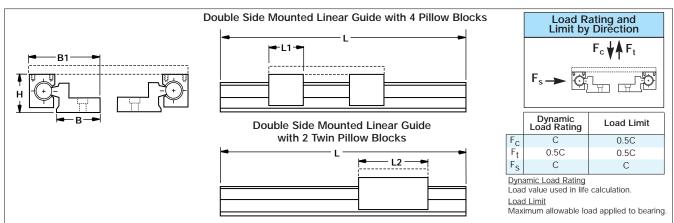
† Super Ball Bushing\* bearings are used in .500 inch size pillow blocks.

Page 7

### Side Mounted 1DB Linear Guide #7 Side Mounted for Low Profile



INCH



Side Mounted	Linear Guide 1	IDB Double Si	de Mounted wi	ith 4 Pillow Blo	ocks	(Dimensio	(Dimensions in inches)		
Part Number	Nominal Diameter	Н	В	B1	L1	Pillow Block	Shaft Support Rail Assembly		
1DB-08-JOO	.50	1.562	1.44	2.61	1.50	SPB-8-OPN-MOD	SSRA-8		
1DB-12-JOO	.75	2.062	1.94	3.55	1.88	SSUPBO-12-MOD	SSRA-12		
1DB-16-JOO	1.00	2.562	2.44	4.49	2.63	SSUPBO-16-MOD	SSRA-16		

Side Mounted	Side Mounted Linear Guide 1DB Double Side Mounted with 2 Twin Pillow Blocks (Dimension												
Part Number	Nominal Diameter	Н	В	B1	L2	Maximum Stroke Length	Pillow Block	Shaft Support Rail Assembly					
1DB-08-KOO	.50	1.562	1.44	2.61	3.5	L-(3.5)	TWN-8-OPN-MOD	SSRA-8					
1DB-12-KOO	.75	2.062	1.94	3.55	4.5	L-(4.5)	SSUTWNO-12-MOD	SSRA-12					
1DB-16-KOO	1.00	2.562	2.44	4.49	6.0	L-(6.0)	SSUTWNO-16-MOD	SSRA-16					

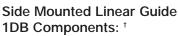
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

Page 78



### Side Mounted Linear Guide 1DB Benefits:

- Requires only one part number to order the entire Linear Guide.
- Continuously supported design increases rigidity and provides for unlimited system travel lengths.
- Low profile, side mounted design allows for compact machines.
- Side mounted design provides an increase in pull off load capacity.
- Allows for custom table mounting.



- 4 Super Smart Ball Bushing\* modified open type pillow blocks or 2 Super Smart Ball Bushing modified open type twin pillow blocks.
- 2 60 Case\* LinearRace\* shaft Side Mounted Support Rail Assemblies.

#### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System

Designation-

1C	B-1	2-J(	DO L2	24
Linear Guide				LЦ

Linear Guide

Nominal Diameter Type of Bearing Block Type of Support

Type SSUPBO-MOD Open Type Pillow Block Type SPB-OPN-MOD Open Type Pillow Block Type TWN-OPN-MOD Pillow Block

Type SPB-OPN-	MOD	and SS	UPBO-	MOD P	illow Bl	ock	(Dimensions in Inches)				Type TWN-OPN-MOD and SSUTWNO-MOD Pillow Blocks				
Part	Nom.	H8	H9	Α	B9	L1	J	J1	F	Wt.	Part	Nom.	L2	J2	Wt.
Number	Dia.									lb	Number	Dia.			lb
SPB-8-OPN-MOD	.50	.687	1.44	.67	1.12	1.50	.812	1.250	#8-32	.18	TWN-8-OPN-MOD	.50	3.5	3.00	.39
SSUPBO-12-MOD	.75	.937	1.94	.92	1.56	1.88	1.187	1.562	#10-32	.45	SSUTWNO-12-MOD	.75	4.5	4.00	1.00
SSUPBO-16-MOD	1.00	1.187	2.44	1.17	2.00	2.63	1.438	2.250	1/4-20	.98	SSUTWNO-16-MOD	1.00	6.0	5.25	2.11

Housing Material: Aluminum Alloy Black Anodized

Housing Material: Aluminum Alloy Black Anodized

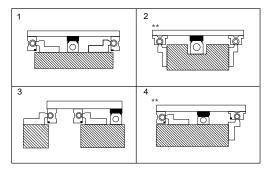
Type SSRA S	Side Moun	ted Linear	Race Sha	aft Suppor	t Rail Asse	embly				(Dimens	sions in	Inches)
Part	Nom.	H1	В	R	E	D	С	Х	Y <sup>(1)</sup>	(	3	Wt.
Number	Dia.									Bolt	Hole	lb/ft
SSRA-08	.50	.875	1.44	.500	1.00	.49	1.06	4	2	1/4	.28	2.05
SSRA-12	.75	1.125	1.94	.688	1.31	.75	1.44	6	3	<sup>5</sup> /16	.34	4.00
SSRA-16	1.00	1.375	2.44	.875	1.63	.88	1.81	6	3	<sup>3</sup> /8	.41	6.25

<sup>(1)</sup> For standard lengths

LinearRace Shaft Support Rail Material: Aluminum Black Anodized

#### **Mounting Configurations**

The following mounting configurations depict ideas for combining the Side Mounted Continuously Supported linear guides into your linear motion application. If you need further information, contact the Thomson Application Engineering Department.



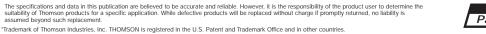
\*\*Pillow blocks shown are the standard SSUPBO or SPB-OPN style. To order System 1DA with standard pillow blocks, order the Side Mounted Shaft Rail Assembly (SSRA) and the SSUPBO or SPB-OPN separately.

First in Linear Motion and Control Technology

Maximum length of LinearRace Shaft Support Rail is 72 inches. If longer continuous onepiece LinearRace Shaft Support Rails are required, contact the Thomson Linear Guides Application Engineering department.

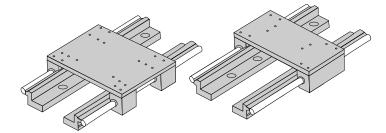
Dynamic Load	Rating (C) Matrix	(4 mi	llion inches travel)
Linear Guide Assembly Part No.	Dynamic Load Rating, C (Ib <sub>f</sub> ) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (lbf)
1DB-08-JOO	480	SPB-8-OPN-MOD	120
1DB-12-JOO	3200	SSUPBO-12-MOD	800
1DB-16-JOO	5400	SSUPBO-16-MOD	1350
1DB-08-KOO	480	TWN-8-OPN-MOD	240
1DB-12-KOO	3200	SSUTWNO-12-MOD	1600
1DB-16-KOO	5400	SSUTWNO-16-MOD	2700

<sup>†</sup> Super Ball Bushing<sup>\*</sup> bearings are used in .500 inch size pillow blocks.

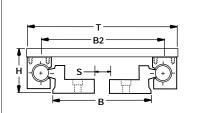


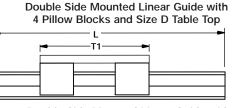
### Side Mounted 1DC Linear Guide #7

with Table Top Side Mounted for Low Profile

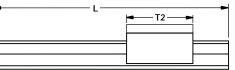


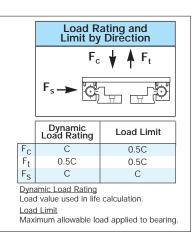
INCH





Double Side Mounted Linear Guide with 2 Twin Pillow Blocks and Size C Table Top





Side Mounted Linear Guide 1DC Double Side Mounted with 4 Pillow Blocks and Table Top (Size D) (Dimensions											
Part Number	Nominal Diameter	Н	Т	T1	В	B2	S	Maximum Stroke Length	Pillow Block	Shaft Support Rail Assembly	
1DC-08-JOD	.50	2.062	7.25	5.50	4.63	5.63	1.75	L-(5.5)	SPB-8-OPN-MOD	SSRA-8	
1DC-12-JOD	.75	2.562	9.75	7.50	6.13	7.50	2.25	L-(7.5)	SSUTWNO-12-MOD	SSRA-12	
1DC-16-JOD	1.00	3.062	12.00	9.00	7.63	9.38	2.75	L-(9.0)	SSUTWNO-16-MOD	SSRA-16	

Side Mounted L	inear Guide	1DC Doubl	e Side Mo	unted with	2 Twin Pil	low Block	ks and Table	Top (Size C) (Dimensio	ons in inches)
Part Number	Nominal Diameter	Н	Т	T2	В	B2	Maximum Stroke Length	Pillow Block	Shaft Support Rail Assembly
1DC-08-KOC	.50	2.062	7.25	3.5	4.63	5.63	L-(3.5)	TWN-8-OPN-MOD	SSRA-8
1DC-12-KOC	.75	2.562	9.75	4.5	6.13	7.50	L-(4.5)	SSUTWNO-12-MOD	SSRA-12
1DC-16-KOC	1.00	3.062	12.00	6.0	7.63	9.38	L-(6.0)	SSUTWNO-16-MOD	SSRA-16





### Side Mounted Linear Guide 1DC Benefits:

- Requires only one part number to order the entire linear guide.
- Continuously supported design increases rigidity and provides for unlimited system travel lengths.
- Low profile, side mounted design allows for compact machines.
- Side mounted design provides an increase in pull-off load capacity.
- Includes table top with standard tapped holes for quick and easy mounting of the work piece.

### Side Mounted Linear Guide 1DC Components:

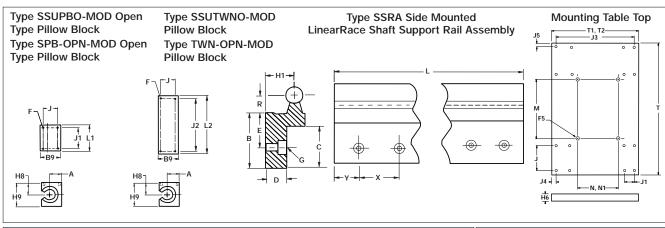
- 4 Super Smart Ball Bushing\* modified open type pillow blocks or 2 Super Smart Ball Bushing modified open type twin pillow blocks.
- 2 60 Case\* LinearRace\* shaft Side Mounted Support Rail Assemblies.
- 1 mounting table top with work piece attachment holes.

#### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System

1DC-12-JOD L24 Linear Guide Designation Linear Guide Designation Linear Guide Designation Linear Guide Type of Table Top Type of Support



Type SPB-OPN-	MOD	and SS	UPBO-	MOD Pi	llow Blo	ock	(Di	mensior	ns in Inc	hes)	Type TWN-OPN-MOD and SSUTWNO-MOD Pillow Blocks				Blocks
Part	Nom.	H8	H9	А	B9	L1	J	J1	F	Wt.	Part	Nom.	L2	J2	Wt.
Number	Dia.									lb	Number	Dia.			lb
SPB-08-OPN-MOD	.50	.687	1.44	.67	1.12	1.50	.812	1.250	#8-32	.18	TWN-8-OPN-MOD	.50	3.5	3.00	.39
SSUPBO-12-MOD	.75	.937	1.94	.92	1.56	1.88	1.187	1.562	#10-32	.45	SSUTWNO-12-MOD	.75	4.5	4.00	1.00
SSUPBO-16-MOD	1.00	1.187	2.44	1.17	2.00	2.63	1.438	2.250	1/4-20	.98	SSUTWNO-16MOD	1.00	6.0	5.25	2.11

Type SSRA Side Mounted LinearRace Shaft Support Rail Assembly         (Dimensions in Inches)												Inches)
Part	Nom.	H1	В	R	E	D	С	Х	Y <sup>(1)</sup>	0		Wt.
Number	Dia.									Bolt	Hole	lb/ft
SSRA-08	.500	.875	1.44	.500	1.00	.49	1.06	4	2	1/4	.28	2.05
SSRA-12	.750	1.125	1.94	.688	1.31	.75	1.44	6	3	<sup>5</sup> /16	.34	4.00
SSRA-16	<b>SSRA-16</b> 1.000 1.375 2.44 .875 1.63 .88 1.81 6 3 <sup>3</sup> / <sub>8</sub> .41 6.25											
The standard lengths Maximum length of LinearDace Shaft Support Pail is 72 inches. If longer continuous												

<sup>1)</sup> For standard lengths

LinearRace Shaft Support Rail Material: Aluminum Black Anodized

Maximum length of LinearRace Shaft Support Rail is 72 inches. If longer continuous one-piece LinearRace Shaft Support Rails are required, contact the Thomson Linear Guide Application Engineering department.

Mountin	founting Table Top (Dimensions in inche										inches)					
Nominal	ninal All Table Tops						Table Top Size <b>D</b>						Table Top Size C			
Diameter	Т	M J H6 F5 T1					J1	J4	J5	N	T2	J3	J4	J5	N1 <sup>(2)</sup>	
.50	7.25	4.0	.81	.50	1/4-20	5.5	1.25	.25	.28	2.63	3.5	3.00	.25	.28	.75	
.75	9.75	6.0	1.19	.50	<sup>5</sup> /16-18	7.5	1.56	.25	.38	3.50	4.5	4.00	.25	.38	1.00	
1.00	12.00	12.00 6.0 1.44 .50 3/8-16 9.0 2.25 .34 .40 4.38 6.0 5.25 .38 .40 1.25														

<sup>(2)</sup> Mounting hole spacing facilitates attachment of Dual Shaft Rail 2DA Linear Guide in an X-Y orientation.

Dynamic Load	Rating (C) Matrix	(4 mi	llion inches travel)
Linear Guide Assembly Part No.	Dynamic Load Rating, C (lb <sub>f</sub> ) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (lbf)
1DC-08-JOD	480	SPB-8-OPN-MOD	120
1DC-12-JOD	3200	SSUTWNO-12-MOD	800
1DC-16-JOD	5400	SSUTWNO-16-MOD	1350
1DC-08-KOC	480	TWN-8-OPN-MOD	240
1DC-12-KOC	3200	SSUTWNO-12-MOD	1600
1DC-16-KOC	5400	SSUTWNO-16-MOD	2700

† Super Ball Bushing\* bearings are used in .500 inch size pillow blocks.



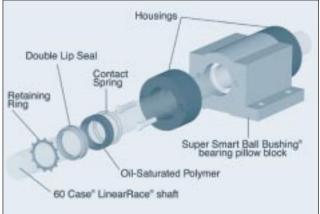
The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.
\* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Page 81



The new LL Option provides maintenancefree operation and enhanced bearing protection.

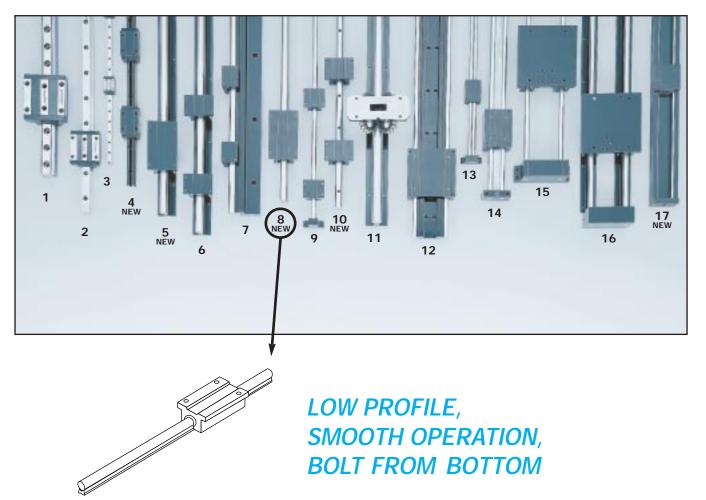
- Eliminates the need for expensive lubrication system in most applications
- Increases effective bearing life by increasing protection from contamination
- Environmentally friendly
- NOTE: Carriage drag with the -LL option will be approximately 2x the seal drag.
- <sup>‡</sup> See page 210 for technical data.







## **Bolt From Bottom Linear Ball Guides**



### Bolt From Bottom Linear Ball Guides Offer:

- Bolt from bottom design to ensure maximum sealing area between the Super Smart Ball Bushing\* bearing and the 60 Case\* LinearRace\* shaft
- Increased life within the same envelope. RoundRail\* linear guides feature the new patented Super Smart Ball Bushing bearings for up to 216X the life or 6X the load capacity of conventional bearings
- The RoundRail Advantage\*. The inherent self-aligning-in-all-directions design of the Super Smart Ball Bushing bearing allows for ultra smooth travel when mounted to wider toleranced prepared surfaces

- Cost savings: save time and money preparing your mounting surfaces before bolting down RoundRail linear guides
- Superior performance. Continuously supported for maximum down load applications without concerns for shaft deflection
- Unlimited travel lengths without concerns for machined reference edges or butt joint alignment
- The Super Smart Ball Bushing bearing...the most technologically advanced and most robust linear bearing in the world
- Corrosion resistant versions for maximum performance in harsh environments.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

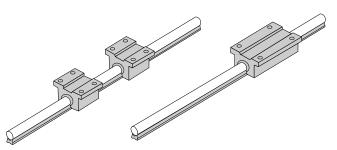


Page 83

#8

## **Bolt From Bottom 1GA**

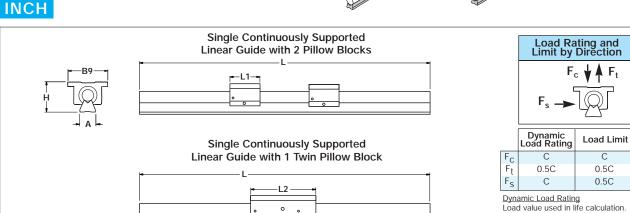
Linear Guide #8 Low Profile, Enhanced Sealing



Load Limit

F.

С



			,			Maximum allowable	load applied to bearing.
			Quality	C			
BOIT FROM BOTT	om Linear G	uide 1GA Single	Continuousiy	Supported with	1 2 PIIIOW BIOCK	s (Dime	nsions in inches)
Part Number	Nom. Dia.	L1	Η	A	В9	Pillow Block	Shaft Support Rail Assembly
1GA-12-FBO	.75	1.88	1.687	.51	2.75	SSUPBO-12-XS	ULSRA-12-XS
1GA-16-FBO	1.00	2.63	2.187	.69	3.25	SSUPBO-16-XS	ULSRA-16-XS
1GA-20-FBO	1.25	3.38	2.687	.78	4.00	SSUPBO-20-XS	ULSRA-20-XS
1GA-24-FBO	1.50	3.75	3.125	.93	4.75	SSUPBO-24-XS	ULSRA-24-XS

Bolt From Bott	Bolt From Bottom Linear Guide 1GA Single Continuously Supported with 1 Twin Pillow Block(Dimensions in inches)											
Part	Nom.	L2	Н	А	B9	Maximum	Pillow	Shaft				
Number	Dia.					Stroke	Block	Support				
						Length		Rail				
								Assembly				
1GA-12-HBO	.75	4.5	1.687	.51	2.75	L-(4.5)	SSUTWNO-12-XS	ULSRA-12-XS				
1GA-16-HBO	1.00	6.0	2.287	.69	3.25	L-(6.0)	SSUTWNO-16-XS	ULSRA-16-XS				
1GA-20-HBO	1.25	7.5	2.687	.78	4.00	L-(7.5)	SSUTWNO-12-XS	ULSRA-20-XS				
1GA-24-HBO	1.50	9.0	3.125	.93	4.75	L-(9.0)	SSUTWNO-24-XS	ULSRA-24-XS				



#### **Bolt From Bottom Linear Guide 1GA Benefits:**

- Requires only one part number to specify the linear guide system.
- More mounting flexibility through bolt up from the bottom access.
- Used in continuously supported applications when rigidity is required.
- Lower overall linear guide height.

-J1-

#### **Bolt From Bottom Linear Guide 1GA** Components:

- 2 Super Smart Ball Bushing\* open type pillow blocks or 1 Super Smart Ball Bushing open twin pillow block.
- 1 60 Case\* LinearRace\* shaft Support Rail Assembly.

#### Specifying this Thomson Linear Guide:

1. Determine the proper Linear Guide for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length n inches, as a suffix to the part number.

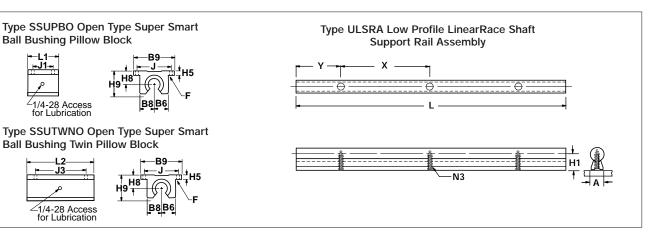
#### Part Numbering System

Designation .

1GA-12-FBO L24 Linear Guide

Linear Guide Length

Nominal Diameter Type of Bearing Block \_ Type of Support



Type SSUPBC	pe SSUPBO Pillow Blocks (Dimensions in Inches)											hes)	Type SSUTWNO Pillow Blocks					
Part Number	Nom. Dia.	L1	H9	H8	H5	B9	B8	B6	J	J1	F Bolt	- Hole	Wt. Ib	Part Number	Nom. Dia.	L2	J3	Wt. Ib
SSUPBO-12-XS	.75	1.88	1.56	.937	.31	2.75	1.00	.94	2.38	1.25	#8	.19	.51	SSUTWNO-12-XS	.75	4.5	3.5	1.02
SSUPBO-16-XS	1.00	2.63	2.00	1.187	.38	3.25	1.25	1.19	2.88	1.75	#10	.22	1.03	SSUTWNO-16-XS	1.00	6.0	4.5	2.06
SSUPBO-20-XS	1.25	3.38	2.56	1.500	.43	4.00	1.63	1.50	3.50	2.00	#10	.22	2.15	SSUTWNO-20-XS	1.25	7.5	5.5	4.30
SSUPBO-24-XS	1.50	3.75	2.94	1.750	.50	4.75	1.88	1.75	4.12	2.50	<sup>1</sup> /4	.25	3.29	SSUTWNO-24-XS	1.50	9.0	6.5	6.88
Ausing Material: Aluminum Alloy Black Apodized																		

Housing Material: Aluminum Alloy Black Anodized

Housing Material: Aluminum Alloy Black Anodized

Type ULSRA L	Type ULSRA Low Profile LinearRace Shaft Support Rail Assembly         (Dimensions in Inches)											
Part Number	Nom. Dia.	H1	A	Х	Y	N3	Wt. Ib/ft					
ULSRA-12-XS	.75	.750	.51	6	3	#10 - 32	2.09					
ULSRA-16-XS	1.00	1.000	.69	6	3	1/4 - 20	3.67					
ULSRA-20-XS	1.25	1.187	.78	6	3	<sup>5</sup> / <sub>16</sub> -18	5.86					
ULSRA-24-XS	1.50	1.375	.93	8	4	³/ <sub>8</sub> -16	7.68					

LinearRace Shaft Support Rail Material: Black Oxided Steel

Dynamic Load Rating (C) Matrix (4 million inches travel) Linear Guide Dynamic Load **Pillow Block Pillow Block** Assembly Rating, C (lb<sub>f</sub>) Dynamic Load Part No. Part No. (Even Distribution) Rating, C (lbf) 1GA-12-FBO 1800 SSUPBO-12-XS 900 1GA-16-FBO 3000 SSUPBO-16-XS 1500 1GA-20-FBO 3730 SSUPBO-20-XS 1865 1GA-24-FBO SSUPBO-24-XS 3080 6160 1GA-12-HBO 1800 SSUTWNO-12-XS 1800 1GA-16-HBO 3020 SSUTWNO-16-XS 3020 1GA-20-HBO 3730 SSUTWNO-12-XS 3730 1GA-24-HBO 6160 SSUTWNO-24-XS 6160

Maximum length of LinearRace Shaft Support Rail is 144 inches. If longer continuous one-piece LinearRace Shaft Support Rails are required, contact the Thomson Linear Guides Application Engineering department.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

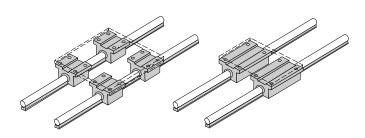




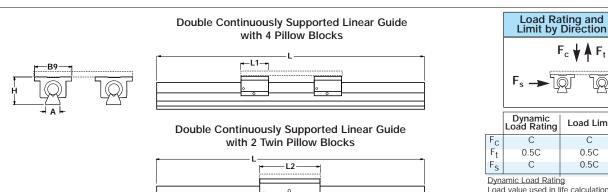
Linear Guides

## **Bolt From Bottom 1GB**

Linear Guide #8 Low Profile, Enhanced Sealing



### INCH



Dynamic Load Rating Load Limit С 0.5C 0.5C Dynamic Load Rating Load value used in life calculation Load Limit

F

Maximum allowable load applied to bearing.

Bolt From Bott	Bolt From Bottom Linear Guide 1GB Double Continuously Supported with 4 Pillow Blocks (Dimensions in inches)										
Part Number	Nom. Dia.	L1	Н	A	В9	Pillow Block	Shaft Support Rail Assembly				
1GB-12-FBO	.75	1.88	1.687	.51	2.75	SSUPBO-12-XS	ULSRA-12-XS				
1GB-16-FBO	1.00	2.63	2.187	.69	3.25	SSUPBO-16-XS	ULSRA-16-XS				
1GB-20-FBO	1.25	3.38	2.687	.78	4.00	SSUPBO-20-XS	ULSRA-20-XS				
1GB-24-FBO	1.50	3.75	3.125	.93	4.75	SSUPBO-24-XS	ULSRA-24-XS				

Bolt From Bott	om Linear G	Guide 1GB Do	ouble Contin	uously Supp	orted with 2	2 Twin Pillow	Blocks (Dimensi	ions in inches)
Part	Nom.	L2	Н	A	B9	Maximum	Pillow	Shaft
Number	Dia.					Stroke	Block	Support
						Length		Rail
								Assembly
1GB-12-HBO	.75	4.5	1.687	.51	2.75	L-(4.5)	SSUTWNO-12-XS	ULSRA-12-XS
1GB-16-HBO	1.00	6.0	2.287	.69	3.25	L-(6.0)	SSUTWNO-16-XS	ULSRA-16-XS
1GB-20-HBO	1.25	7.5	2.687	.78	4.00	L-(7.5)	SSUTWNO-20-XS	ULSRA-20-XS
1GB-24-HBO	1.50	9.0	3.125	.93	4.75	L-(9.0)	SSUTWNO-24-XS	ULSRA-24-XS



#### **Bolt From Bottom Linear Guide 1GB Benefits:**

- Requires only one part number to specify the entire linear guide.
- More mounting flexibility through bolt up from the bottom access.
- Used in continuously supported applications when rigidity is required.
- Lower overall linear guide height.

<u>⊢J1</u>

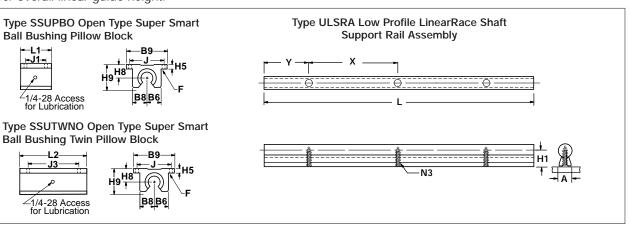
#### **Bolt From Bottom Linear Guide 1GB** Components:

- 4 Super Smart Ball Bushing\* bearing open type pillow blocks or 2 Super Smart Ball Bushing open Part Numbering System type twin pillow blocks.
- 2 60 Case\* LinearRace\* shaft Support Rail Assemblies.

#### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

1GB-12-FBO L24 Linear Guide Linear Guide Designation --Lenath Nominal Diameter -Type of Bearing Block Type of Support



Type SSUPBC	) Pillo	w Blo	ocks							(Dimen	sions	in Inc	hes)	Type SSUTWNO Pillow Blocks				
Part	Nom.	L1	H9	H8	H5	B9	B8	B6	J	J1	F	-	Wt.	Part	Nom.	L2	J3	Wt.
Number	Dia.										Bolt	Hole	lb	Number	Dia.			lb
SSUPBO-12-XS	.75	1.88	1.56	.937	.31	2.75	1.00	.94	2.38	1.25	#8	.19	.51	SSUTWNO-12-XS	.75	4.5	3.5	1.02
SSUPBO-16-XS	1.00	2.63	2.00	1.187	.38	3.25	1.25	1.19	2.88	1.75	#10	.22	1.03	SSUTWNO-16-XS	1.00	6.0	4.5	2.06
SSUPBO-20-XS	1.25	3.38	2.56	1.500	.43	4.00	1.63	1.50	3.50	2.00	#10	.23	2.15	SSUTWNO-20-XS	1.25	7.5	5.5	4.30
SSUPBO-24-XS	1.50	3.75	2.94	1.750	.50	4.75	1.88	1.75	4.12	2.50	<sup>1</sup> /4	.25	3.20	SSUTWNO-24-XS	1.50	9.0	6.5	6.88
Lausing Materials Aluminum Allow Deak Angeliad																		

Housing Material: Aluminum Alloy Black Anodized

Housing Material: Aluminum Alloy Black Anodized

Type ULSRA L	Type ULSRA Low Profile LinearRace Shaft Support Rail Assembly         (Dimensions in Inches)											
Part Number	Nom. Dia.	H1	A	Х	Y	N3	Wt. Ib/ft					
ULSRA-12-XS	.75	.750	.51	6	3	#10 - 32	2.09					
ULSRA-16-XS	1.00	1.000	.69	6	3	1/4 - 20	3.67					
ULSRA-20-XS	1.25	1.187	.78	6	3	<sup>5</sup> / <sub>16</sub> -18	5.86					
ULSRA-24-XS	1.50	1.375	.93	8	4	<sup>3</sup> / <sub>8</sub> -16	7.68					

LinearRace Shaft Support Rail Material: Black Oxidized Steel

Maximum length of LinearRace Shaft Support Rail is 144 inches. If longer continuous one-piece LinearRace Shaft Support Rails are required, contact the Thomson Linear Guide Application Engineering department.

Dynamic Load	Rating (C) Matrix	(4 m	(4 million inches travel)				
Linear Guide Assembly Part No.	Dynamic Load Rating, C (Ib <sub>f</sub> ) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (lbf)				
1GB-12-FBO	3600	SSUPBO-12-XS	900				
1GB-16-FBO	6000	SSUPBO-16-XS	1500				
1GB-20-FBO	7460	SSUPBO-20-XS	1865				
1GB-24-FBO	12320	SSUPBO-24-XS	3080				
1GB-12-HBO	3600	SSUTWNO-12-XS	1800				
1GB-16-HBO	6040	SSUTWNO-16-XS	3020				
1GB-20-HBO	7460	SSUTWNO-12-XS	3730				
1GB-24-HBO	12320	SSUTWNO-24-XS	6160				

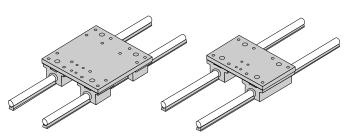




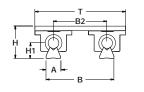
## **Bolt From Bottom 1GC**

### Linear Guide #8

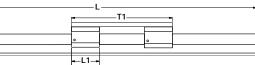
with Table Top *Low Profile, Enhanced Sealing* 



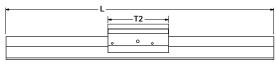
### INCH

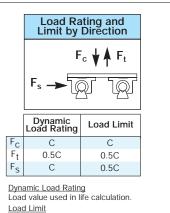


Double Continuously Supported Linear Guide with 4 Pillow Blocks and Size B Table Top



Double Continuously Supported Linear Guide with 2 Twin Pillow Blocks and Size A Table Top





Maximum allowable load applied to bearing.

Bolt From Bot	tom Lin	ear Guic	le 1GC D	ouble C	ontinuou	isly Supj	ported w	ith 4 Pill	ow Bloc	ks and Tab	le Top (Size B) (Di	mensions in inches)
Part	Nom.	А	T1	Т	Н	H1	В	B2	L1	Maximum	Pillow	Shaft
Number	Dia.									Stroke	Block	Support
										Length		Rail
												Assembly
1GC-12-FBB	.75	.51	7.5	7.5	2.187	.750	5.01	4.50	1.88	L-(7.5)	SSUPBO-12-XS	ULSRA-12-XS
1GC-16-FBB	1.00	.69	9.0	9.0	2.687	1.000	6.19	5.50	2.63	L-(9.0)	SSUPBO-16-XS	ULSRA-16-XS
1GC-20-FBB	1.25	.78	11.0	11.0	3.437	1.187	7.53	6.75	3.38	L-(11.0)	SSUPBO-20-XS	ULSRA-20-XS
1GC-24-FBB	1.50	.93	13.0	13.0	3.875	1.375	8.93	8.00	3.75	L-(13.0)	SSUPBO-24-XS	ULSRA-24-XS

Bolt From Bott	tom Line	ear Guide	1FC Doul	ole Contin	uously Su	pported w	/ith 2 Twin	n Pillow B	locks and Ta	able Top (Size A) (D	imensions in inches)
Part	Nom.	А	T2	Т	Н	H1	В	B2	Maximum	Pillow	Shaft
Number	Dia.								Stroke	Block	Support
									Length		Rail
											Assembly
1GC-12-HBA	.75	.51	4.5	7.5	2.187	.750	5.01	4.50	L-(4.5)	SSUTWNO-12-XS	ULSRA-12-XS
1GC-16-HBA	1.00	.69	6.0	9.0	2.687	1.000	6.19	5.50	L-(6.0)	SSUTWNO-16-XS	ULSRA-16-XS
1GC-20-HBA	1.25	.78	7.5	11.0	3.437	1.187	7.53	6.75	L-(7.5)	SSUTWNO-20-XS	ULSRA-20-XS
1GC-24-HBA	1.50	.93	9.0	13.0	3.875	1.375	8.93	8.00	L-(9.0)	SSUTWNO-24-XS	ULSRA-24-XS

Dynamic Load	Rating (C) Matrix	(4 mil	llion inches travel)
Linear Guide Assembly Part No.	Dynamic Load Rating, C (lb <sub>f</sub> ) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (lb <sub>f</sub> )
1GC-12-FBB	3600	SSUPBO-12-XS	900
1GC-16-FBB	6000	SSUPBO-16-XS	1500
1GC-20-FBB	7460	SSUPBO-20-XS	1865
1GC-24-FBB	12320	SSUPBO-24-XS	3080
1GC-12-HBA	3600	SSUTWNO-12-XS	1800
1GC-16-HBA	6040	SSUTWNO-16-XS	3020
1GC-20-HBA	7460	SSUTWNO-12-XS	3730
1GC-24-HBA	12320	SSUTWNO-24-XS	6160

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

Page 88

The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



## Bolt From Bottom Linear Guide 1GC Benefits:

- Requires only one part number to specify the entire linear guide.
- Includes table top with standard tapped holes for quick and easy mounting of the work piece.
- More mounting flexibility through bolt up from the bottom access.
- Used in continuously supported applications when rigidity is required.
- Lower overall linear guide height.

### Bolt From Bottom Linear Guide 1GC Components:

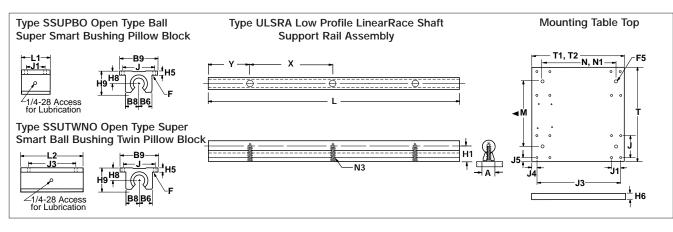
- 4 Super Smart Ball Bushing\* open type pillow blocks or 2 Super Smart Ball Bushing open type twin pillow blocks.
- 2 60 Case\* LinearRace\* shaft Support Rail Assemblies.
- 1 mounting table top with work piece attachment holes.

#### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System

IGC-12-FBB L24 Linear Guide Designation \_\_\_\_\_\_ Nominal Diameter \_\_\_\_\_\_ Type of Table Top Type of Bearing Block \_\_\_\_\_ Type of Support



Type SSUPBC	) Pillo	w Blo	ocks							(Dimen	sions	in Inc	hes)	Type SSUTWN	O Pillo	w Bloc	:ks	
Part	Nom.	L1	H9	H8	H5	B9	B8	B6	J	J1	F	:	Wt.	Part	Nom.	L2	J3	Wt.
Number	Dia.	1.00	1 5 (	0.07	01	0.75	1.00	0.4	0.00	1.05	Bolt	Hole	lb	Number	Dia.		0.5	lb
SSUPBO-12-XS		1.88	1.56		.31	2.75	1.00	.94	2.38	1.25	#8	.19	.51	SSUTWNO-12-XS		4.5	3.5	1.02
SSUPBO-16-XS		2.63	2.00		.38	3.25	1.25	1.19	2.88	1.75	#10	.22		SSUTWNO-16-XS		6.0	4.5	2.06
SSUPBO-20-XS	1.25	3.38	2.56		.43	4.00	1.63	1.50	3.50	2.00	#10	.23	2.15	SSUTWNO-20-XS	1.25	7.5	5.5	4.30
SSUPBO-24-XS	1.50	3.75	2.94	1.750	.50	4.75	1.88	1.75	4.12	2.50	1/4	.25	3.20	SSUTWNO-24-XS	1.50	9.0	6.5	6.88

Housing Material: Aluminum Alloy Black Anodized

Housing Material: Aluminum Alloy Black Anodized

Type ULSRA L	ow Profile Line	arRace Shaft S	upport Rail Ass	embly		(Dimen	sions in Inches)
Part Number	Nom. Dia.	H1	A	Х	Y	N3	Wt. Ib/ft
ULSRA-12-XS	.75	.750	.51	6	3	#10 - 32	2.09
ULSRA-16-XS	1.00	1.000	.69	6	3	1/4 - 20	3.67
ULSRA-20-XS	1.25	1.187	.78	6	3	<sup>5</sup> / <sub>16</sub> -18	5.86
ULSRA-24-XS	1.50	1.375	.93	8	4	³⁄₁₀ -16	7.68

LinearRace Shaft Support Rail Material: Black Oxidized Steel

Maximum length of LinearRace Shaft Support Rail is 144 inches. If longer continuous one-piece LinearRace Shaft Support Rails are required, contact the Thomson Linear Guide Application Engineering department.

Mountin	g Table	Тор											(Dimen	isions in	inches)
Nominal		All	Table To	ps			Tabl	e Top Siz	e <b>B</b>			Tab	le Top Siz	e <b>A</b>	
Diameter	Т	Μ	J	H6	F5 <sup>(2)</sup>	T1	J1	J4	J5	N	T2	J3	J4	J5	N1
.75	7.5	4.50	2.38	.500	<sup>5</sup> /16-18	7.5	1.25	.41	.31	6.0	4.5	3.5	.50	.31	3.0
1.00	9.0	5.50	2.88	.500	<sup>3</sup> /8-16	9.0	1.75	.53	.31	7.0	6.0	4.5	.75	.31	4.0
1.25	11.0	6.75	3.50	.750	1/2-13	11.0	2.00	.82	.38	8.5	7.5	5.5	1.00	.38	5.0
1.50	13.0	8.00	4.12	.750	1/2-13	13.0	2.50	.75	.44	10.0	9.0	6.5	1.25	.44	6.0

Material: Aluminum Alloy Black Anodized (2) Customer Mounting Hole

NOTE: To determine the proper Linear Guide size for your application refer to the Dynamic Load Rating (C) Matrix and substitute 1GB with 1GC for Linear Guide assembly part number.

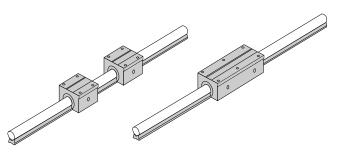




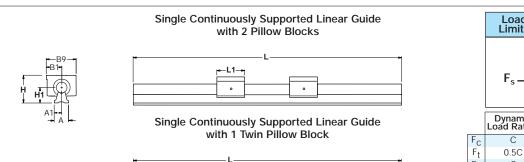
## **Bolt From Bottom 1RA**

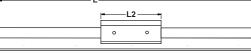
Linear Guide #8

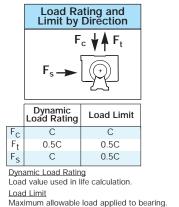
Low Profile, Enhanced Sealing



#### METRIC







Bolt From Bott	om Linear (	Guide 1F	RA Single	e Contir	nuously	Support	ed with	2 Pillow	Blocks	(Dimensions in mm)
Part Number	Nominal Diameter	L1	Η	H1	A	A1	B1	B9	Pillow Block	Shaft Support Rail Assembly
1RA-M16-LLO	16	43	40	18	14	7,0	26,5	53	SSEPBO-M16-XS	ULSRA-M16-XS
1RA-M20-LLO	20	54	47	22	17	8,5	30,0	60	SSEPBO-M20-XS	ULSRA-M20-XS
1RA-M25-LLO	25	67	56	26	21	10,5	39,0	78	SSEPBO-M25-XS	ULSRA-M25-XS
1RA-M30-LLO	30	79	65	30	23	11,5	43,5	87	SSEPBO-M30-XS	ULSRA-M30-XS
1RA-M40-LLO	40	91	84	39	30	15,0	54,0	108	SSEPBO-M40-XS	ULSRA-M40-XS

Bolt From Botto	m Linear C	Guide 1F	RA Sing	le Conti	nuously	/ Suppo	rted wi	th 1 Tw	vin Pillow B	Block (Dir	mensions in mm)
Part	Nominal	L2	Н	H1	А	A1	B1	B9	Maximum	Pillow	Shaft
Number	Diameter								Stroke	Block	Support
									Length		Rail
											Assembly
1RA-M16-MLO	16	84	40	18	14	7,0	26,5	53	L-(84)	SSETWNO-M16-XS	ULSRA-M16-XS
1RA-M20-MLO	20	104	47	22	17	8,5	30,0	60	L-(104)	SSETWNO-M20-XS	ULSRA-M20-XS
1RA-M25-MLO	25	130	56	26	21	10,5	39,0	78	L-(130)	SSETWNO-M25-XS	ULSRA-M25-XS
1RA-M30-MLO	30	152	65	30	23	11,5	43,5	87	L-(152)	SSETWNO-M30-XS	ULSRA-M30-XS
1RA-M40-MLO	40	176	84	39	30	15,0	54,0	108	L-(176)	SSETWNO-M40-XS	ULSRA-M40-XS





## Bolt From Bottom Linear Guide 1RA Benefits:

- Requires only one part number to specify the entire linear guide.
- Used to provide increased stability or torque resistance in linear system applications.
- Used in continuously supported applications when rigidity is required.
- Lower overall linear guide height.

### Bolt From Bottom Linear Guide 1RA Components:

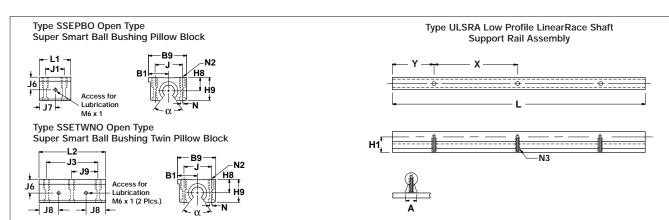
- 2 Super Smart Ball Bushing\* open type pillow blocks or 1 Super Smart Ball Bushing open type twin pillow block.
- 1 60 Case\* LinearRace\* shaft Support Rail Assembly.

#### Specifying a Thomson Linear Guide:

 Determine the proper system for your load and life requirements.
 Select the part number.
 Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number.

#### Part Numbering System

1RA-M16-	LLO L600
Linear Guide	Linear Guide
Designation	Length
Nominal Diameter	
Type of Bearing Block —	Type of Support



Type SSEPBO P	llow	Bloc	ks								(Dim	nensio	ons ir	ı mm)	Type SSETWNO	Pillow	I Blo	cks			
Part Number	Nom. Dia.	L1	H8	H9	B1	B9	J6	J7	J	J1	N Dia.	N2	α Deg	Mass kg	Part Number	Nom. Dia.	L2	J3	J8	J9	Mass kg
SSEPBO-M16-XS	16	43	22	35	26,5	53	22,0	21,5	40	26	5,3	M6	66	0,17	SSETWNO-M16-XS	16	84	64	21,5	32	0,34
SSEPBO-M20-XS	20	54	25	41	30,0	60	25,0	27,0	45	32	6,6	M8	60	0,30	SSETWNO-M20-XS	20	104	76	27,0	38	0,63
SSEPBO-M25-XS	25	67	30	50	39,0	78	31,5	33,5	60	40	8,4	M10	60	0,57	SSETWNO-M25-XS	25	130	94	33,6	47	1,18
SSEPBO-M30-XS	30	79	35	60	43,5	87	33,0	39,5	68	45	8,4	M10	60	0,87	SSETWNO-M30-XS	30	152	106	39,5	53	1,70
SSEPBO-M40-XS	40	91	45	77	54,0	108	43,5	45,5	86	58	10,5	M12	60	1,62	SSETWNO-M40-XS	40	176	124	45,5	62	3,18

Housing Material: Aluminum Alloy Grey Anodized

Housing Material: Aluminum Alloy Grey Anodized

Type ULSRA Lov	v Profile Linea	arRace Shaft	Support Rail A	ssembly			(Dimens	ions in mm)
Part Number	Nominal Diameter	H1	А	A1	Х	Υ†	N3 <sup>(1)</sup>	Mass kg/m
ULSRA-M16-XS	16	18	14	7,0	100	20	M3 x 30	3,6
ULSRA-M20-XS	20	22	17	8,5	100	30	M4 x 35	5,5
ULSRA-M25-XS	25	26	21	10,5	120	30	M5 x 45	8,5
ULSRA-M30-XS	30	30	23	11,5	150	40	M6 x 50	13,0
ULSRA-M40-XS	40	39	30	15,0	200	52,5	M10 x 65	21,0

LinearRace Shaft Support Rail Material: Black Oxided Steel

Maximum continuous length of LinearRace Shaft Support Rail is 3650 mm. If longer continuous one-piece LinearRace Shaft Support Rails are required, contact the Thomson Linear Guides Application Engineering department.

Dynamic Loa	d Rating (C) M	latrix (	100 km travel)		Dynamic Loa	d Rating (C) N	flatrix (
Linear Guide Assembly Part No.	Dynamic Load Rating, C (N) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (N)		Linear Guide Assembly Part No.	Dynamic Load Rating, C (N) (Even Distribution)	Pillow Block Part No.
1RA-M16-LLO	4400	SSEPBO-M16-XS	2200	]	1RA-M16-MLO	4400	SSETWNO-M16-XS
1RA-M20-LLO	8000	SSEPBO-M20-XS	4000		1RA-M20-MLO	8000	SSETWNO-M20-XS
1RA-M25-LLO	13400	SSEPBO-M25-XS	6700		1RA-M25-MLO	13400	SSETWNO-M25-XS
1RA-M30-LLO	16600	SSEPBO-M30-XS	8300		1RA-M30-MLO	16600	SSETWNO-M30-XS
1RA-M40-LLO	27400	SSEPBO-M40-XS	13700		1RA-M40-MLO	27400	SSETWNO-M40-XS

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



Page 91

(100 km travel) Pillow Block Dynamic Load Rating, C (N)

> 4400 8000

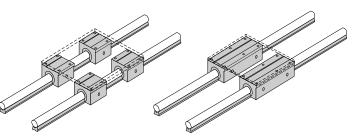
13400

16600

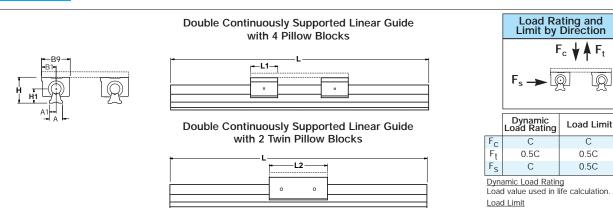
27400

## **Bolt From Bottom 1RB**

### Linear Guide #8 Low Profile, Enhanced Sealing



### METRIC



Maximum allowable load applied to bearing.

Bolt From Bott	om Linear C	Guide 1R	B Doub	le Conti	nuously	Suppor	ted with	1 4 Pillow	v Blocks	(Dimensions in mm)
Part Number	Nominal Diameter	L1	H	H1	A	A1	B1	B9	PillowBlock	Shaft Support Rail Assembly
1RB-M16-LLO	16	43	40	18	14	7,0	26,5	53	SSEPBO-M16-XS	ULSRA-M16-XS
1RB-M20-LLO	20	54	47	22	17	8,5	30,0	60	SSEPBO-M20-XS	ULSRA-M20-XS
1RB-M25-LLO	25	67	56	26	21	10,5	39,0	78	SSEPBO-M25-XS	ULSRA-M25-XS
1RB-M30-LLO	30	79	65	30	23	11,5	43,5	87	SSEPBO-M30-XS	ULSRA-M30-XS
1RB-M40-LLO	40	91	84	39	30	15,0	54,0	108	SSEPBO-M40-XS	ULSRA-M40-XS

Bolt From Botto	m Linear (	Guide 1	RB Doul	ole Cont	inuous	ly Supp	orted w	vith 2 T	win Pillow	Blocks (Dir	mensions in mm)
Part	Nominal	L2	Н	H1	А	A1	B1	B9	Maximum	Pillow	Shaft
Number	Diameter								Stroke	Block	Support
									Length		Rail
											Assembly
1RB-M16-MLO	16	84	40	18	14	7,0	26,5	53	L-(84)	SSETWNO-M16-XS	ULSRA-M16-XS
1RB-M20-MLO	20	104	47	22	17	8,5	30,0	60	L-(104)	SSETWNO-M20-XS	ULSRA-M20-XS
1RB-M25-MLO	25	130	56	26	21	10,5	39,0	78	L-(130)	SSETWNO-M25-XS	ULSRA-M25-XS
1RB-M30-MLO	30	152	65	30	23	11,5	43,5	87	L-(152)	SSETWNO-M30-XS	ULSRA-M30-XS
1RB-M40-MLO	40	176	84	39	30	15,0	54,0	108	L-(176)	SSETWNO-M40-XS	ULSRA-M40-XS

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

Page 92



#### **Bolt From Bottom Linear Guide 1RB Benefits:**

- Requires only one part number to specify the entire linear guide.
- Allows for custom table top mounting.
- Used in continuously supported applications when rigidity is required.
- Lower overall linear guide height.

#### **Bolt From Bottom Linear Guide 1RB** Components:

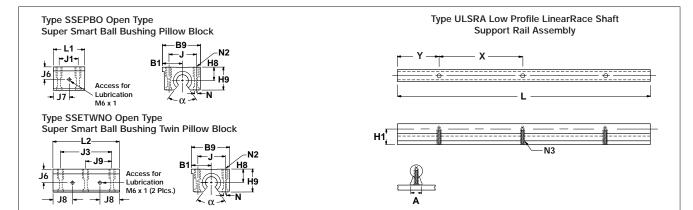
- 4 Super Smart Ball Bushing\* open type pillow blocks or 2 Super Smart Ball Bushing open type twin pillow blocks.
- 2 60 Case\* LinearRace\* shaft Support Rail Assemblies.

#### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number.

#### Part Numbering System

1RB-M16-LLO L600 Linear Guide Linear Guide Designation -- Length Nominal Diameter Type of Bearing Block \_ L Type of Support



Type SSEPBO F	Pillow	Bloc	:ks								(Dim	nensio	ons ir	ı mm)	Type SSETWNO	Pillow	/ Blo	cks			
Part	Nom.	L1	H8	H9	B1	B9	J6	J7	J	J1	Ν	N2	α	Mass	Part	Nom.	L2	J3	J8	J9	Mass
Number	Dia.										Dia.		Deg	kg	Number	Dia.					kg
SSEPBO-M16-XS	16	43	22	35	26,5	53	22,0	21,5	40	26	5,3	M6	66	0,17	SSETWNO-M16-XS	16	84	64	21,5	32	0,34
SSEPBO-M20-XS	20	54	25	41	30,0	60	25,0	27,0	45	32	6,6	M8	60	0,30	SSETWNO-M20-XS	20	104	76	27,0	38	0,63
SSEPBO-M25-XS	25	67	30	50	39,0	78	31,5	33,5	60	40	8,4	M10	60	0,57	SSETWNO-M25-XS	25	130	94	33,6	47	1,18
SSEPBO-M30-XS	30	79	35	60	43,5	87	33,0	39,5	68	45	8,4	M10	60	0,87	SSETWNO-M30-XS	30	152	106	39,5	53	1,70
SSEPBO-M40-XS	40	91	45	77	54,0	108	43,5	45,5	86	58	10,5	M12	60	1,62	SSETWNO-M40-XS	40	176	124	45,5	62	3,18
Housing Material: Alu	minum /	Alloy	Grey A	nodiz	ed										Housing Material: Alu	iminum	Alloy	Grey	Anod	ized	

Type ULSRA Lo	w Profile Line	arRace Shaft	Support Rail	Assembly			(Dimens	ions in mm)
Part Number	Nominal Diameter	H1	А	A1	Х	Υ <sup>†</sup>	N3 <sup>(1)</sup>	Mass kg/m
ULSRA-M16-XS	16	18	14	7,0	100	20	M3 x 30	3,6
ULSRA-M20-XS	20	22	17	8,5	100	30	M4 x 35	5,5
ULSRA-M25-XS	25	26	21	10,5	120	30	M5 x 45	8,5
ULSRA-M30-XS	30	30	23	11,5	150	40	M6 x 50	13,0
ULSRA-M40-XS	40	39	30	15,0	200	52,5	M10 x 65	21,0

LinearRace Shaft Support Rail Material: Black Oxided Steel

Maximum continuous length of LinearRace Shaft Support Rail is 3650 mm. If longer continuous one-piece LinearRace Shaft Support Rails are required, contact the Thomson Linear Guides Application Engineering department.

Dynamic Loa	nd Rating (C) N	flatrix (	100 km travel)
Linear Guide Assembly Part No.	Dynamic Load Rating, C (N) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (N)
1RB-M16-LLO	8800	SSEPBO-M16-XS	2200
1RB-M20-LLO	16000	SSEPBO-M20-XS	4000
1RB-M25-LLO	26800	SSEPBO-M25-XS	6700
1RB-M30-LLO	33200	SSEPBO-M30-XS	8300
1RB-M40-LLO	54800	SSEPBO-M40-XS	13700

Dynamic Loa	d Rating (C) N	Natrix (	100 km travel)
Linear Guide Assembly Part No.	Dynamic Load Rating, C (N) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating C (N)
1RB-M16-MLO	8800	SSETWNO-M16-XS	4400
1RB-M20-MLO	16000	SSETWNO-M20-XS	8000
1RB-M25-MLO	26800	SSETWNO-M25-XS	13400
1RB-M30-MLO	33200	SSETWNO-M30-XS	16600
1RB-M40-MLO	54800	SSETWNO-M40-XS	27400

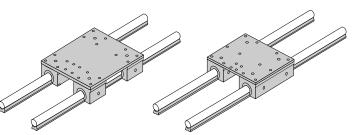


Page 93

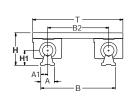
## **Bolt From Bottom 1RC**

Linear Guide #8

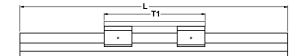
with Table Top *Low Profile*, *Enhanced Sealing* 



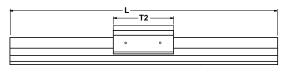
### METRIC

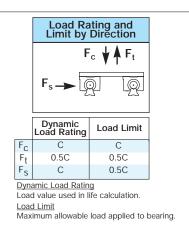


Double Continuously Supported Linear Guide with 4 Pillow Blocks and Size F Table Top



Double Continuously Supported Linear Guide with 2 Twin Pillow Blocks and Size E Table Top





Bolt From Botto	om Line	ar Guide	1RC Do	uble Co	ntinuous	ly Suppo	orted wit	h 4 Pillo	w Block	s and Table	Top (Size F) (D	imensions in mm)
Part	Nom.	T1	Т	Н	H1	A	A1	В	B2	Maximum	Pillow	Shaft
Number	Dia.									Stroke	Block	Support
										Length		Rail
												Assembly
1RC-M16-LLF	16	125	125	53	18	14	7,0	86	70	L-(125)	SSEPBO-M16-XS	ULSRA-M16-XS
1RC-M20-LLF	20	175	175	63	22	17	8,5	132	110	L-(175)	SSEPBO-M20-XS	ULSRA-M20-XS
1RC-M25-LLF	25	225	225	76	26	21	10,5	168	140	L-(225)	SSEPBO-M25-XS	ULSRA-M25-XS
1RC-M30-LLF	30	275	275	85	30	23	11,5	211	180	L-(275)	SSEPBO-M30-XS	ULSRA-M30-XS
1RC-M40-LLF	40	325	325	109	39	30	15,0	247	210	L-(325)	SSEPBO-M40-XS	ULSRA-M40-XS

Bolt From Botto	m Linea	r Guide	1RC Dou	uble Con	tinuously	Suppor	ted with	2 Twin Pi	illow Blo	cks and Ta	ible Top (Size E) (D	imensions in mm)
Part	Nom.	T2	Т	Н	H1	А	A1	В	B2	Maximum	Pillow	Shaft
Number	Dia.									Stroke	Block	Support
										Length		Rail
												Assembly
1RC-M16-MLE	16	84	125	53	18	14	7,0	86	70	L-(84)	SSETWNO-M16-XS	ULSRA-M16-XS
1RC-M20-MLE	20	104	175	63	22	17	8,5	132	110	L-(104)	SSETWNO-M20-XS	ULSRA-M20-XS
1RC-M25-MLE	25	130	225	76	26	21	10,5	168	140	L-(130)	SSETWNO-M25-XS	ULSRA-M25-XS
1RC-M30-MLE	30	152	275	85	30	23	11,5	211	180	L-(152)	SSETWNO-M30-XS	ULSRA-M30-XS
1RC-M40-MLE	40	176	325	109	39	30	15,0	247	210	L-(176)	SSETWNO-M40-XS	ULSRA-M40-XS

Dynamic Loa	d Rating (C) N	latrix (	100 km travel)	Dynamic Loa	d Rating (C) N	latrix (	(100 km travel)
Linear Guide Assembly Part No.	Dynamic Load Rating, C (N) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (N)	Linear Guide Assembly Part No.	Dynamic Load Rating, C (N) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (N)
1RC-M16-LLF	8800	SSEPBO-M16-XS	2200	1RC-M16-MLE	8800	SSETWNO-M16-XS	4400
1RC-M20-LLF	16000	SSEPBO-M20-XS	4000	1RC-M20-MLE	16000	SSETWNO-M20-XS	8000
1RC-M25-LLF	26800	SSEPBO-M25-XS	6700	1RC-M25-MLE	26800	SSETWNO-M25-XS	13400
1RC-M30-LLF	33200	SSEPBO-M30-XS	8300	1RC-M30-MLE	33200	SSETWNO-M30-XS	16600
1RC-M40-LLF	54800	SSEPBO-M40-XS	13700	1RC-M40-MLE	54800	SSETWNO-M40-XS	27400





### Bolt From Bottom Linear Guide 1RC Benefits:

- Requires only one part number to specify the entire linear guide.
- Includes table top with standard tapped holes for quick and easy mounting of the work piece.
- Includes Ball Screw Assembly attachment holes for ease of assembly and actuation.
- Used in continuously supported applications when rigidity is required.

### Bolt From Bottom Linear Guide 1RC Components:

- 4 Super Smart Ball Bushing\* open type pillow blocks or 2 Super Smart Ball Bushing open type twin pillow blocks.
- 2 60 Case\* LinearRace\* shaft Support Rail Assemblies.
- 1 mounting table top with work piece and Ball Screw Assembly attachment holes.

#### Specifying a Thomson Linear Guide:

 Determine the proper system for your load and life requirements.
 Select the part number.
 Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number.

#### Part Numbering System

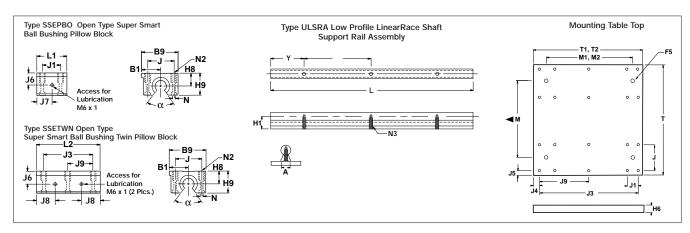
 IRC-M16-MLE L600

 Linear Guide

 Designation

 Nominal Diameter

 Type of Bearing Block



Type SSEPBO P	Pillow	Bloc	:ks								(Din	nensio	ons in	i mm)	Type SSETWNO	Pillow	Blo	cks			
Part	Nom.	L1	H8	H9	B1	B9	J6	J7	J	J1	Ν	N2	α	Mass	Part	Nom.	L2	J3	J8	J9	Mass
Number	Dia.										Dia.		Deg	kg	Number	Dia.					kg
SSEPBO-M16-XS	16	43	22	35	26,5	53	22,0	21,5	40	26	5,3	M6	66	0,17	SSETWNO-M16-XS	16	84	64	21,5	32	0,34
SSEPBO-M20-XS	20	54	25	41	30,0	60	25,0	27,0	45	32	6,6	M8	60	0,30	SSETWNO-M20-XS	20	104	76	27,0	38	0,63
SSEPBO-M25-XS	25	67	30	50	39,0	78	31,5	33,5	60	40	8,4	M10	60	0,57	SSETWNO-M25-XS	25	130	94	33,6	47	1,18
SSEPBO-M30-XS	30	79	35	60	43,5	87	33,0	39,5	68	45	8,4	M10	60	0,87	SSETWNO-M30-XS	30	152	106	39,5	53	1,70
SSEPBO-M40-XS	40	91	45	77	54,0	108	43,5	45,5	86	58	10,5	M12	60	1,62	SSETWNO-M40-XS	40	176	124	45,5	62	3,18

Housing Material: Aluminum Alloy Grey Anodized

Housing Material: Aluminum Alloy Grey Anodized

Type ULSRA Lov	v Profile Linea	arRace Shaft	Support Rail A	ssembly			(Dimens	ions in mm)
Part Number	Nominal Diameter	H1	А	A1	Х	Υ†	N3 <sup>(1)</sup>	Mass kg/m
ULSRA-M16-XS	16	18	14	7,0	100	20	M3 x 30	3,6
ULSRA-M20-XS	20	22	17	8,5	100	30	M4 x 35	5,5
ULSRA-M25-XS	25	26	21	10,5	120	30	M5 x 45	8,5
ULSRA-M30-XS	30	30	23	11,5	150	40	M6 x 50	13,0
ULSRA-M40-XS	40	39	30	15,0	200	52,5	M10 x 65	21,0

LinearRace Shaft Support Rail Material: Black Oxided Steel

Maximum continuous length of LinearRace Shaft Support Rail is 3650 mm. If longer continuous one-piece LinearRace Shaft Support Rails are required, contact the Thomson Linear Guides Application Engineering department.

Mounting	g Table	Тор												(Dimen	sions i	n mm)
System		All	Table To	ps			Tab	e Top Siz	e F			Т	able To	p Size <b>E</b>		
	Т	М	J	H6	F5 <sup>(2)</sup>	T1	J1	J4	J5	M1	T2	J3	J4	J5	J9	M2
1RC-M16	125	70	40	13	M6	125	26	10,0	7,5	70	84	64	10	7,5	32	45
1RC-M20	175	110	45	16	M8	175	32	11,0	10,0	110	104	76	14	10,0	38	55
1RC-M25	225	140	60	20	M8	225	40	13,5	12,5	140	130	94	18	12,5	47	65
1RC-M30	275	180	68	20	M8	275	45	17,0	13,5	180	152	106	23	13,5	53	75
1RC-M40	325	210	86	25	M10	325	58	16,5	14,5	210	176	124	26	14,5	62	85

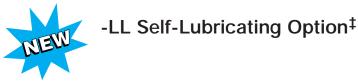
Material: Aluminum Alloy Grey Anodized

(2) Customer Mounting Hole



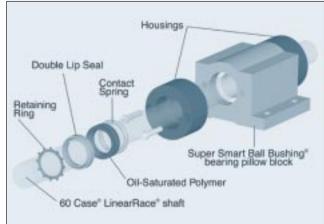


### **Bolt From Bottom Linear Ball Guide Accessories**



The new LL Option provides maintenancefree operation and enhanced bearing protection.

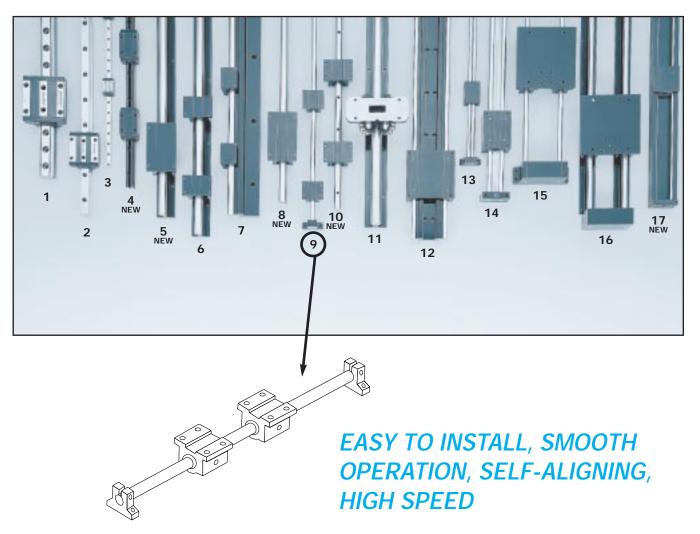
- Eliminates the need for expensive lubrication system in most applications
- Increases effective bearing life by increasing protection from contamination
- Environmentally friendly
- NOTE: Carriage drag with the -LL option will be approximately 2x the seal drag.
- <sup>‡</sup> See page 210 for technical data.







## **End Support Linear Ball Guides**



### End Support Linear Ball Guides Offer:

- Increased life within the same envelope. RoundRail\* linear guides feature the new patented Super Smart Ball Bushing\* bearings for up to 216X the life or 6X the load capacity of conventional bearings
- Cost savings: save time and money preparing your mounting surfaces before bolting down RoundRail linear guides
- End supported for gantry style or 'bridge' applications
- The RoundRail Advantage\*. The inherent self-aligning-in-all-directions design of the Super Smart Ball Bushing bearing allows for ultra smooth travel when mounted to wider toleranced prepared surfaces
- The Super Smart Ball Bushing bearing... the most technologically advanced and most robust linear bearing in the world
- Corrosion resistant versions for maximum performance in harsh environments.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

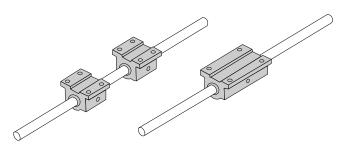


Page 97

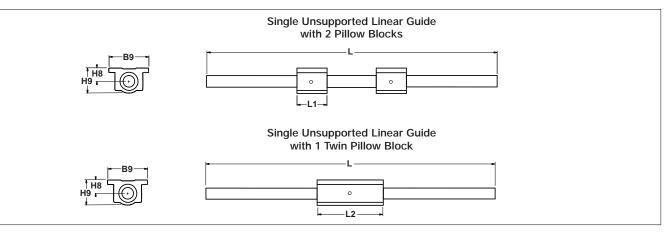
**#9** 

## End Support 1AA

Linear Guide #9 Unsupported, Industry Standard Dimension



### INCH



End Support Line	ar Guide 1AA Sin	gle with 2 Pillow	Blocks		(Dime	nsions in inches)
Part Number	Nominal Diameter	L1	H8	H9	B9	Pillow Block
1AA-04-AOO	.250	1.19	.437	.81	1.63	SPB-4-XS
1AA-06-AOO	.375	1.31	.500	.94	1.75	SPB-6-XS
1AA-08-AOO	.500	1.69	.687	1.25	2.00	SSUPB-8-XS
1AA-12-AOO	.750	2.06	.937	1.75	2.75	SSUPB-12-XS
1AA-16-AOO	1.000	2.81	1.187	2.19	3.25	SSUPB-16-XS
1AA-20-AOO	1.250	3.63	1.500	2.81	4.00	SSUPB-20-XS
1AA-24-AOO	1.500	4.00	1.750	3.25	4.75	SSUPB-24-XS

End Support Line	ear Guide 1AA Sir	ngle with 1 Twin P	illow Block		(Dime	nsions in inches)
Part Number	Nominal Diameter	L2	H8	H9	B9	Pillow Block
1AA-04-BOO	.250	2.50	.437	.81	1.63	TWN-4-XS
1AA-06-BOO	.375	2.75	.500	.94	1.75	TWN-6-XS
1AA-08-BOO	.500	3.50	.687	1.25	2.00	SSUTWN-8-XS
1AA-12-BOO	.750	4.50	.937	1.75	2.75	SSUTWN-12-XS
1AA-16-BOO	1.000	6.00	1.187	2.19	3.25	SSUTWN-16-XS
1AA-20-BOO	1.250	7.50	1.500	2.81	4.00	SSUTWN-20-XS
1AA-24-BOO	1.500	9.00	1.750	3.25	4.75	SSUTWN-24-XS

#### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for Deflection calculations.





### End Support Linear Guide 1AA Benefits:

- Requires only one part number to specify entire linear guide.
- Design flexibility with custom end supports.
- Used in end supported applications when spanning or bridging a gap.

## End Support Linear Guide 1AA Components: <sup>†</sup>

- Super Smart Ball Bushing\* pillow blocks or 1 Super Smart Ball Bushing twin pillow block.
- 1 60 Case\* LinearRace\* shaft.

#### Specifying this Thomson Linear Guide:

 Determine the proper Linear Guide for your load and life requirements. 2. Select the part number.
 Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System

**Pillow Block** 

View A-A

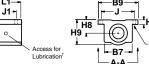


Type SPB Super Ball Bushing

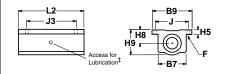
Mounting Hole Position for

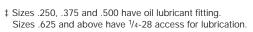
Sizes .250 and .375

Type SSUPB Super Smart Ball Bushing Pillow Block Type SPB Super Ball Bushing Pillow Block



Type SSUTWN Super Smart Ball Bushing Twin Pillow Block Type TWN Super Ball Bushing Twin Pillow Block





Type SPB and	SSUP	B Pillo	ow Blo	ocks					(Din	nensior	ns in in	ches)	Type TWN and	SSUT	WN Pi	llow B	ocks
Part	Nom.	L1	H9	H8	H5	B9	B7	J	J1	ŀ	=	Wt.	Part	Nom.	L2	J3	Wt.
Number	Dia.									Bolt	Hole	lb	Number	Dia.			lb
SPB-4-XS	.250	1.19	.81	.437	.19	1.63	1.00	1.31	.75(2)	#6	.16	.10	TWN-4-XS	.250	2.50	2.00	.19
SPB-6-XS	.375	1.31	.94	.500	.19	1.75	1.12	1.44	.88(2)	#6	.16	.13	TWN-6-XS	.375	2.75	2.25	.25
SSUPB-8-XS	.500	1.69	1.25	.687	.25	2.00	1.38	1.69	1.00	#6	.16	.20	SSUTWN-8-XS	.500	3.50	2.50	.40
SSUPB-12-XS	.750	2.06	1.75	.937	.31	2.75	1.88	2.38	1.25	#8	.19	.62	SSUTWN-12-XS	.750	4.50	3.50	1.24
SSUPB-16-XS	1.000	2.81	2.19	1.187	.38	3.25	2.38	2.88	1.75	#10	.22	1.24	SSUTWN-16-XS	1.000	6.00	4.50	2.48
SSUPB-20-XS	1.250	3.63	2.81	1.500	.43	4.00	3.00	3.50	2.00	#10	.22	2.57	SSUTWN-20-XS	1.250	7.50	5.50	5.14
SSUPB-24-XS	1.500	4.00	3.25	1.750	.50	4.75	3.50	4.12	2.50	1/4	.28	3.94	SSUTWN-24-XS	1.500	9.00	6.50	8.08
Housing Matorial: A	luminum		look An	odizod									Lloucing Material	Alumation			

Housing Material: Aluminum Alloy Black Anodized

 $^{\scriptscriptstyle (2)}\text{Two}$  mounting holes as shown in view A-A for sizes .250 and .375

Dynamic Load	Capacity Matrix	(4 m	nillion inches travel)		
Linear Guide Assembly Part No.	Dynamic Load Capacity (lb <sub>f</sub> ) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Capacity (lb <sub>f</sub> )		
1AA-04-AOO	100	SPB-4-XS	50		
1AA-06-AOO	160	SPB-6-XS	80		
1AA-08-AOO	800	SSUPB-8-XS	400		
1AA-12-AOO	1800	SSUPB-12-XS	900		
1AA-16-AOO	3000	SSUPB-16-XS	1500		
1AA-20-AOO	3730	SSUPB-20-XS	1865		
1AA-24-AOO	6160	SSUPB-24-XS	3080		
1AA-04-BOO	100	TWN-4-XS	100		
1AA-06-BOO	160	TWN-6-XS	160		
1AA-08-BOO	800	SSUTWN-8-XS	800		
1AA-12-BOO	1800	SSUTWN-12-XS	1800		
1AA-16-BOO	3020	SSUTWN-16-XS	3020		
1AA-20-BOO	3730	SSUTWN-20-XS 3730			
1AA-24-BOO	6160	SSUTWN-24-XS	6160		

Housing Material: Aluminum Alloy Black Anodized

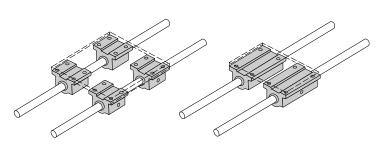
<sup>†</sup> Super Ball Bushing<sup>\*</sup> bearings are used in .250 and .375 inch size pillow blocks.



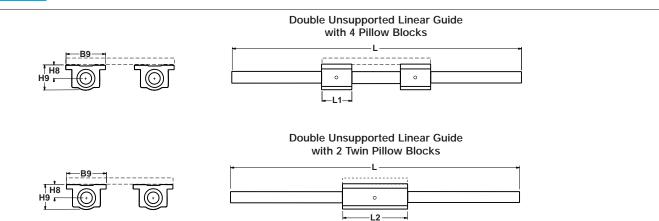


# End Support 1AB

Linear Guide #9 Unsupported, Industry Standard Dimension



INCH



End Support Line	End Support Linear Guide 1AB Double with 4 Pillow Blocks									
Part Number	Nominal Diameter	L1	H8	H9	B9	Pillow Block				
1AB-04-AOO	.250	1.19	.437	.81	1.63	SPB-4-XS				
1AB-06-AOO	.375	1.31	.500	.94	1.75	SPB-6-XS				
1AB-08-AOO	.500	1.69	.687	1.25	2.00	SSUPB-8-XS				
1AB-12-AOO	.750	2.06	.937	1.75	2.75	SSUPB-12-XS				
1AB-16-AOO	1.000	2.81	1.187	2.19	3.25	SSUPB-16-XS				
1AB-20-AOO	1.250	3.63	1.500	2.81	4.00	SSUPB-20-XS				
1AB-24-AOO	1.500	4.00	1.750	3.25	4.75	SSUPB-24-XS				

End Support Line	End Support Linear Guide 1AB Double with 2 TWIN Pillow Blocks (Dimensions in inches									
Part	Nominal	L2	H8	H9	B9	Pillow				
Number	Diameter					Block				
1AB-04-BOO	.250	2.50	.437	.81	1.63	TWN-4-XS				
1AB-06-BOO	.375	2.75	.500	.94	1.75	TWN-6-XS				
1AB-08-BOO	.500	3.50	.687	1.25	2.00	SSUTWN-8-XS				
1AB-12-BOO	.750	4.50	.937	1.75	2.75	SSUTWN-12-XS				
1AB-16-BOO	1.000	6.00	1.187	2.19	3.25	SSUTWN-16-XS				
1AB-20-BOO	1.250	7.50	1.500	2.81	4.00	SSUTWN-20-XS				
1AB-24-BOO	1.500	9.00	1.750	3.25	4.75	SSUTWN-24-XS				

#### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for Deflection calculations.





#### End Support Linear Guide **1AB Benefits:**

- Allows for custom table mounting.
- Design flexibility for custom end supports.
- Double LinearRace\* shaft configuration resists torque.
- Used in end supported applications when spanning or bridging a gap.

### End Support Linear Guide 1AB Components: 1

- 4 Super Smart Ball Bushing\* pillow blocks or 2 Super Smart Ball Bushing twin pillow blocks.
- 2 60 Case\* LinearRace shafts.

#### Specifying a Thomson Linear guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System

#### 1AB-12-AOO L24

Linear Guide Designation \_ Nominal Diameter

Linear Guide - Length

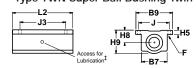
Type of Bearing Block

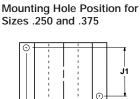
**Pillow Block** 

Type SSUPB Super Smart Ball Bushing Pillow Block Type SPB Super Ball Bushing Pillow Block



Type SSUTWN Super Smart Ball Bushing Twin Pillow Block Type TWN Super Ball Bushing Twin Pillow Block





Type SPB Super Ball Bushing



‡ Sizes .250, .375 and .500 have oil lubricant fitting. Sizes .625 and above have 1/4-28 access for lubrication.

Type SPB and SSUPB Pillow Blocks         (Dimensions in inches)											Type TWN and	I SSUT	WN Pi	llow B	ocks		
Part	Nom.	L1	H9	H8	H5	B9	B7	J	J1		F	Wt.	Part	Nom.	L2	J3	Wt.
Number	Dia.									Bolt	Hole	lb	Number	Dia.			lb
SPB-4-XS	.250	1.19	.81	.437	.19	1.63	1.00	1.31	.75(2)	#6	.16	.10	TWN-4-XS	.250	2.50	2.00	.19
SPB-6-XS	.375	1.31	.94	.500	.19	1.75	1.12	1.44	.88(2)	#6	.16	.13	TWN-6-XS	.375	2.75	2.25	.25
SSUPB-8-XS	.500	1.69	1.25	.687	.25	2.00	1.38	1.69	1.00	#6	.16	.20	SSUTWN-8-XS	.500	3.50	2.50	.40
SSUPB-12-XS	.750	2.06	1.75	.937	.31	2.75	1.88	2.38	1.25	#8	.19	.62	SSUTWN-12-XS	.750	4.50	3.50	1.24
SSUPB-16-XS	1.000	2.81	2.19	1.187	.38	3.25	2.38	2.88	1.75	#10	.22	1.24	SSUTWN-16-XS	1.000	6.00	4.50	2.48
SSUPB-20-XS	1.250	3.63	2.81	1.500	.43	4.00	3.00	3.50	2.00	#10	.22	2.57	SSUTWN-20-XS	1.250	7.50	5.50	5.14
SSUPB-24-XS	1.500	4.00	3.25	1.750	.50	4.75	3.50	4.12	2.50	1/4	.28	3.94	SSUTWN-24-XS	1.500	9.00	6.50	8.08
Joucing Material, /	luminun		المماد الم	o dia o d									Housing Material:	Aluminu			

Housing Material: Aluminum Alloy Black Anodized

<sup>(2)</sup>Two mounting holes as shown in view A-A for sizes .250 and .375

Dynamic Load	Capacity Matrix	(4 n	nillion inches travel)
Linear Guide Assembly Part No.	Dynamic Load Capacity (lb <sub>f</sub> ) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Capacity (Ib <sub>f</sub> )
1AB-04-AOO	200	SPB-4-XS	50
1AB-06-AOO	320	SPB-6-XS	80
1AB-08-AOO	1600	SSUPB-8-XS	400
1AB-12-AOO	2600	SSUPB-12-XS	900
1AB-16-AOO	6000	SSUPB-16-XS	1500
1AB-20-AOO	7460	SSUPB-20-XS	1865
1AB-24-AOO	12320	SSUPB-24-XS	3080
1AB-04-BOO	200	TWN-4-XS	100
1AB-06-BOO	320	TWN-6-XS	160
1AB-08-BOO	1600	SSUTWN-8-XS	800
1AB-12-BOO	3600	SSUTWN-12-XS	1800
1AB-16-BOO	6040	SSUTWN-16-XS	3020
1AB-20-BOO	7460	SSUTWN-20-XS	3730
1AB-24-BOO	12320	SSUTWN-24-XS	6160

Housing Material: Aluminum Alloy Black Anodized

<sup>+</sup> Super Ball Bushing\* bearings are used in .250 and .375 inch size pillow blocks.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

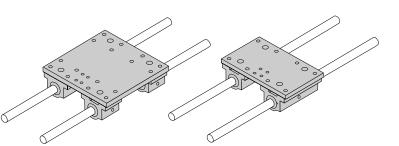


The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

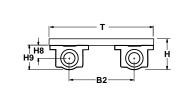


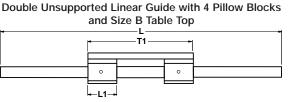
## End Support 1AC

Linear Guide #9 with Table Top Unsupported, Industry Standard Dimension

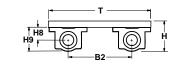


INCH





Double Unsupported Linear Guide with 2 Twin Pillow Blocks and Size A Table Top



L	
0	
•T2•	

End Support Lir	End Support Linear Guide 1AC Double with 4 Pillow Blocks and Table Top (Size B)										
Part	Nom.	L1	Н	B2	H8	H9	Т	T1	Pillow		
Number	Dia.								Block		
1AC-04-AOB	.250	1.19	1.06	2.25	.437	.81	4.00	4.00	SPB-4-XS		
1AC-06-AOB	.375	1.31	1.19	2.50	.500	.94	4.50	4.50	SPB-6-XS		
1AC-08-AOB	.500	1.69	1.63	3.25	.687	1.25	5.50	5.50	SSUPB-8-XS		
1AC-12-AOB	.750	2.06	2.25	4.50	.937	1.75	7.50	7.50	SSUPB-12-XS		
1AC-16-AOB	1.000	2.81	2.69	5.50	1.187	2.19	9.00	9.00	SSUPB-16-XS		
1AC-20-AOB	1.250	3.63	3.56	6.75	1.500	2.81	11.00	11.00	SSUPB-20-XS		
1AC-24-AOB	1.500	4.00	4.00	8.00	1.750	3.25	13.00	13.00	SSUPB-24-XS		

End Support Li	End Support Linear Guide 1AC Double with 2 Twin Pillow Blocks and Table Top (Size A) (Dimensions in inches									
Part	Nom.	Н	B2	H8	H9	Т	T2	Pillow		
Number	Dia.							Block		
1AC-04-BOA	.250	1.06	2.25	.437	.81	4.00	2.50	TWN-4-XS		
1AC-06-BOA	.375	1.19	2.50	.500	.94	4.50	2.75	TWN-6-XS		
1AC-08-BOA	.500	1.63	3.25	.687	1.25	5.50	3.50	SSUTWN-8-XS		
1AC-12-BOA	.750	2.25	4.50	.937	1.75	7.50	4.50	SSUTWN-12-XS		
1AC-16-BOA	1.000	2.69	5.50	1.187	2.19	9.00	6.00	SSUTWN-16-XS		
1AC-20-BOA	1.250	3.56	6.75	1.500	2.81	11.00	7.50	SSUTWN-20-XS		
1AC-24-BOA	1.500	4.00	8.00	1.750	3.25	13.00	9.00	SSUTWN-24-XS		

#### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for Deflection calculations.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



#### End Support Linear Guide 1AC Benefits:

- Includes table top with standard tapped holes for quick and easy mounting of the work piece.
- Includes Ball Screw Assembly and actuation.
- Used in end supported applications when spanning or bridging a gap.

#### End Support Linear Guide 1AC Components: <sup>†</sup>

- 4 Super Smart Ball Bushing\* pillow blocks or 2 Super Smart Ball Bushing twin pillow blocks.
- 2 60 Case\* LinearRace\* shafts.
- attachment holes for ease of assembly 1 mounting table top with work piece and Ball Screw Assembly attachment holes.

#### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

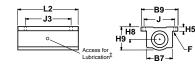
#### Part Numbering System

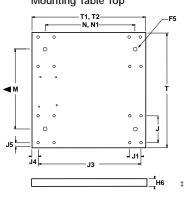
Type of Bearing Block

Linear Guide Designation \_ Nominal Diameter

1AC-12-AOO L24 Linear Guide Length -Type of Table Top

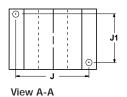
Type SSUPB Super Smart Ball Bushing Pillow Block Mounting Table Top Type SPB Super Ball Bushing Pillow Block - T1, T2-- N, N1-.11 0 0 118 Access for Lubrication Type SSUTWN Super Smart Ball Bushing Twin **Pillow Block** Type TWN Super Ball Bushing Twin Pillow Block 0





**Pillow Block** Mounting Hole Position for Sizes .250 and .375

Type SPB Super Ball Bushing



<sup>‡</sup> Sizes .250, .375 and .500 have oil lubricant fitting. Sizes, .625 and above have 1/4-28 access for lubrication.

Type SPB and	SSUP	B Pillo	ow Blo	ocks					(Din	nensior	ns in in	ches)	Type TWN and	I SSUT	WN Pi	llow B	ocks
Part	Nom.	L1	H9	H8	H5	B9	B7	J	J1	F	-	Wt.	Part	Nom.	L2	J3	Wt.
Number	Dia.									Bolt	Hole	lb	Number	Dia.			lb
SPB-4-XS	.250	1.19	.81	.437	.19	1.63	1.00	1.31	.75(2)	#6	.16	.10	TWN-4-XS	.250	2.50	2.00	.19
SPB-6-XS	.375	1.31	.94	.500	.19	1.75	1.12	1.44	.88(2)	#6	.16	.13	TWN-6-XS	.375	2.75	2.25	.25
SSUPB-8-XS	.500	1.69	1.25	.687	.25	2.00	1.38	1.69	1.00	#6	.16	.20	SSUTWN-8-XS	.500	3.50	2.50	.40
SSUPB-12-XS	.750	2.06	1.75	.937	.31	2.75	1.88	2.38	1.25	#8	.19	.62	SSUTWN-12-XS	.750	4.50	3.50	1.24
SSUPB-16-XS	1.000	2.81	2.19	1.187	.38	3.25	2.38	2.88	1.75	#10	.22	1.24	SSUTWN-16-XS	1.000	6.00	4.50	2.48
SSUPB-20-XS	1.250	3.63	2.81	1.500	.43	4.00	3.00	3.50	2.00	#10	.22	2.57	SSUTWN-20-XS	1.250	7.50	5.50	5.14
SSUPB-24-XS	1.500	4.00	3.25	1.750	.50	4.75	3.50	4.12	2.50	1/4	.28	3.94	SSUTWN-24-XS	1.500	9.00	6.50	8.08
Housing Material: /	Jusing Material: Aluminum Alloy, Black Apodized																

ousing Material: Aluminum Allov Black Anodized

<sup>(2)</sup>Two mounting holes as shown in view A-A for sizes .250 and .375

Housing Material: Aluminum Alloy Black Anodized

Mountin	Mounting Table Top (Dimensions in inches)															
Nominal		All Table Tops					Table Top Size <b>B</b>					Table Top Size <b>A</b>				
Diameter	Т	Μ	J	H6	F5	T1	J1	J4	J5	N	T2	J3	J4	J5	N1	
.250	4.0	2.25	1.31	.250	#8-32	4.0	.75(2)	.22	.22	3.50	2.50	2.00	.25	.22	2.0	
.375	4.5	2.50	1.44	.250	#10-32	4.5	.88(2)	.22	.28	3.75	2.75	2.25	.25	.28	2.0	
.500	5.5	3.25	1.69	.375	1/4-20	5.5	1.00	.34	.28	4.50	3.50	2.50	.50	.31	2.5	
.750	7.5	4.50	2.38	.500	<sup>5</sup> /16-18	7.5	1.25	.41	.31	6.00	4.50	3.50	.50	.31	3.0	
1.000	9.0	5.50	2.88	.500	<sup>3</sup> /8-16	9.0	1.75	.53	.31	7.00	6.00	4.50	.75	.31	4.0	
1.250	11.0	6.75	3.50	.750	1/2-13	11.0	2.00	.82	.38	8.50	7.50	5.50	1.00	.38	5.0	
1.500	13.0	8.00	4.12	.750	1/2-13	13.0	2.50	.75	.44	10.00	9.00	6.50	1.25	.44	6.0	

Carriage Material: Aluminum Alloy Black Anodized.

<sup>(2)</sup>Two mounting holes as shown in view A-A for sizes .250 and .375

Dynamic Lo	Dynamic Load Capacity Matrix (4 mill									
Linear Guide	Dynamic Load	Pillow Block	Pillow Block							
Assembly	Capacity (lb <sub>f</sub> )	Part No.	Dynamic Load							
Part No.	(Even Distribution)		Capacity (lb <sub>f</sub> )							
1AC-04-AOB	200	SPB-4-XS	50							
1AC-06-AOB	320	SPB-6-XS	80							
1AC-08-AOB	1600	SSUPB-8-XS	400							
1AC-12-AOB	3600	SSUPB-12-XS	900							
1AC-16-AOB	6000	SSUPB-16-XS	1500							
1AC-20-AOB	7460	SSUPB-20-XS	1865							
1AC-24-AOB	12320	SSUPB-24-XS	3080							

<sup>†</sup> Super Ball Bushing<sup>\*</sup> bearings are used in .250 and .375 inch size pillow blocks.

Dynamic Lo	ad Capacity Ma	trix (4 milli	on inches travel)
Linear Guide	Dynamic Load	Pillow Block	Pillow Block
Assembly	Capacity (lb <sub>f</sub> )	Part No.	Dynamic Load
Part No.	(Even Distribution)		Capacity (lb <sub>f</sub> )
1AC-04-BOA	200	TWN-4-XS	100
1AC-06-BOA	320	TWN-6-XS	160
1AC-08-BOA	1600	SSUTWN-8-XS	800
1AC-12-BOA	3600	SSUTWN-12-XS	1800
1AC-16-BOA	6040	SSUTWN-16-XS	3020
1AC-20-BOA	7460	SSUTWN-20-XS	3730
1AC-24-BOA	12320	SSUTWN-24-XS	6160

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

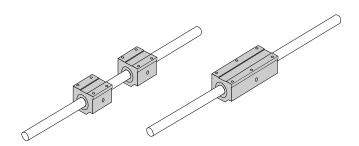


The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

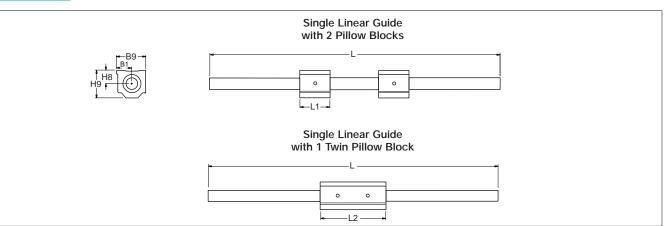


## End Support 1MA

Linear Guide #9 Unsupported, Industry Standard Dimension



### METRIC



End Support Linear Guide 1MA Single with 2 Pillow Blocks (Dimensions in mm)											
Part Number	Nominal Diameter	L1	H8	H9	B1	B9	Pillow Block				
1MA-M08-NOO	8	32	15	28	17,5	35	SPPB-M08-XS				
1MA-M12-NOO	12	39	18	35	21,5	43	SSEPB-M12-XS				
1MA-M16-NOO	16	43	22	42	26,5	53	SSEPB-M16-XS				
1MA-M20-NOO	20	54	25	50	30,0	60	SSEPB-M20-XS				
1MA-M25-NOO	25	67	30	60	39,0	78	SSEPB-M25-XS				
1MA-M30-NOO	30	79	35	70	43,5	87	SSEPB-M30-XS				
1MA-M40-NOO	40	91	45	90	54,0	108	SSEPB-M40-XS				

End Support Line	End Support Linear Guide 1MA Single with 1 Twin Pillow Block (Dimensions in mm												
Part Number	Nominal Diameter	L2	H8	H9	B1	B9	Pillow Block						
1MA-M08-POO	8	62	15	28	17,5	35	SPTWN-M08-XS						
1MA-M12-POO	12	76	18	35	21,5	43	SSETWN-M12-XS						
1MA-M16-POO	16	84	22	42	26,5	53	SSETWN-M16-XS						
1MA-M20-POO	20	104	25	50	30,0	60	SSETWN-M20-XS						
1MA-M25-POO	25	130	30	60	39,0	78	SSETWN-M25-XS						
1MA-M30-POO	30	152	35	70	43,5	87	SSETWN-M30-XS						
1MA-M40-POO	40	176	45	90	54,0	108	SSETWN-M40-XS						

#### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for Deflection calculations.





### End Support Linear Guide 1MA Benefits:

- Requires only one part number to specify entire linear guide.
- Design flexibility with custom end supports.
- Used in end supported applications when spanning or bridging a gap.

## End Support Linear Guide 1MA Components: <sup>†</sup>

- 2 Super Smart Ball Bushing\* pillow blocks or 1 Super Smart Ball Bushing twin pillow block.
- 1 60 Case\* LinearRace\* shaft.

#### Specifying this Thomson Linear Guide:

 Determine the proper Linear Guide for your load and life requirements.
 Select the part number.
 Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number.

#### Part Numbering System

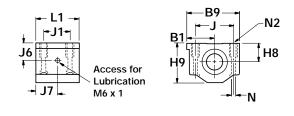
#### 1MA-M12-NOO L600

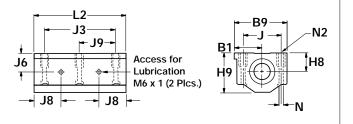
Linear Guide L Designation L Nominal Diameter Type of Bearing Block

Linear Guide Length

Linear Guides

Type SPPB Super Plus Ball Bushing Pillow Block Type SSEPB Super Smart Ball Bushing Pillow Block





Type SPTWN Super Plus Ball Bushing Twin Pillow Block

Type SSETWN Super Smart Ball Bushing Twin Pillow Block

Type SPPB a	Type SPPB and SSEPB Pillow Blocks (Dimensions in mm)										Type SPTWN a	and SS	SETW	/N Pi	illow	Bloc	ks			
Part Number	Nom. Dia.	L1	H8	H9	B1	B9	J	J1	J6	J7	N Dia.	N2	Mass kg	Part Number	Nom. Dia.	L2	J3	J8	J9	Mass kg
SPPB-M08-XS	8	32	15	28	17,5	35	25	20	15	19,5	3,3	M4	0,07	SPTWN-M08-XS	8	62	50	19,5	25	0,15
SSEPB-M12-XS	12	39	18	35	21,5	43	32	23	18	23,0	4,3	M5	0,13	SSETWN-M12-XS	12	76	56	23,0	28	0,27
SSEPB-M16-XS	16	43	22	42	26,5	53	40	26	22	25,0	5,3	M6	0,20	SSETWN-M16-XS	16	84	64	25,0	32	0,41
SSEPB-M20-XS	20	54	25	50	30,0	60	45	32	25	30,5	6,6	M8	0,35	SSETWN-M20-XS	20	104	76	30,5	38	0,73
SSEPB-M25-XS	25	67	30	60	39,0	78	60	40	30	37	8,4	M10	0,66	SSETWN-M25-XS	25	130	94	37,0	47	1,37
SSEPB-M30-XS	30	79	35	70	43,5	87	68	45	35	43	8,4	M10	0,99	SSETWN-M30-XS	30	152	106	43,0	53	2,04
SSEPB-M40-XS	40	91	45	90	54,0	108	86	58	45	49	10,5	M12	1,83	SSETWN-M40-XS	40	176	124	49,0	62	3,73
Housing Material	ausing Material: Aluminum Allov Grev Angelized												Housing Material: A	Iuminur	n Allov	/ Croy	Anoc	hozik		

Housing Material: Aluminum Alloy Grey Anodized

Dynamic Load	Capacity Matrix		(100 km travel)		
Linear Guide Assembly Part No.	Dynamic Load Capacity (N) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Capacity (N)		
1MA-M08-NOO	620	SPPB-M08-XS	310		
1MA-M12-NOO	1300	SSEPB-M12-XS	650		
1MA-M16-NOO	4400	SSEPB-M16-XS	2200		
1MA-M20-NOO	8000	SSEPB-M20-XS	4000		
1MA-M25-NOO	13400	SSEPB-M25-XS	6700		
1MA-M30-NOO	16600	SSEPB-M30-XS	8300		
1MA-M40-NOO	27400	SSEPB-M40-XS	13700		
1MA-M08-POO	500	SPTWN-M08-XS	500		
1MA-M12-POO	1060	SSETWN-M12-XS	1060		
1MA-M16-POO	4400	SSETWN-M16-XS	4400		
1MA-M20-POO	8000	SSETWN-M20-XS	8000		
1MA-M25-POO	13400	SSETWN-M25-XS	13400		
1MA-M30-POO	16600	SSETWN-M30-XS	16600		
1MA-M40-POO	27400	SSETWN-M40-XS	27400		

Housing Material: Aluminum Alloy Grey Anodized

<sup>†</sup> Super Plus Ball Bushing\* bearings are used in 8 mm size pillow blocks.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

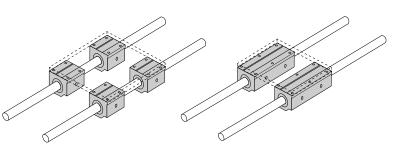


\* The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.
\* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

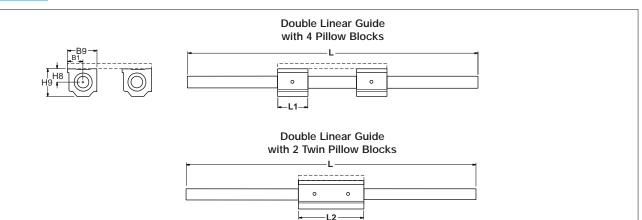


### End Support 1MB

### Linear Guide #9 Unsupported, Industry Standard Dimension



### METRIC



End Support Lin	End Support Linear Guide 1MB Double with 4 Pillow Blocks(Dimensions in mm)											
Part Number	Nominal Diameter	L1	H8	H9	B1	B9	Pillow Block					
1MB-M08-NOO	8	32	15	28	17,5	35	SPPB-M08-XS					
1MB-M12-NOO	12	39	18	35	21,5	43	SSEPB-M12-XS					
1MB-M16-NOO	16	43	22	42	26,5	53	SSEPB-M16-XS					
1MB-M20-NOO	20	54	25	50	30,0	60	SSEPB-M20-XS					
1MB-M25-NOO	25	67	30	60	39,0	78	SSEPB-M25-XS					
1MB-M30-NOO	30	79	35	70	43,5	87	SSEPB-M30-XS					
1MB-M40-NOO	40	91	45	90	54,0	108	SSEPB-M40-XS					

End Support Li	End Support Linear Guide 1MB Double with 2 Twin Pillow Blocks (Dimensions in mm)												
Part Number	Nominal Diameter	L2	H8	H9	B1	B9	Pillow Block						
1MB-M08-POO	8	62	15	28	17,5	35	SPTWN-M08-XS						
1MB-M12-POO	12	76	18	35	21,5	43	SSETWN-M12-XS						
1MB-M16-POO	16	84	22	42	26,5	53	SSETWN-M16-XS						
1MB-M20-POO	20	104	25	50	30,0	60	SSETWN-M20-XS						
1MB-M25-POO	25	130	30	60	39,0	78	SSETWN-M25-XS						
1MB-M30-POO	30	152	35	70	43,5	87	SSETWN-M30-XS						
1MB-M40-POO	40	176	45	90	54,0	108	SSETWN-M40-XS						

#### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for Deflection calculations.

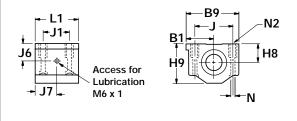




### End Support Linear Guide 1MB Benefits:

- Allows for custom table mounting.
- Design flexibility for custom end supports.
- Double LinearRace\* shaft configuration resists torque.
- Used in end supported applications when spanning or bridging a gap.

#### Type SPPB Super Plus Ball Bushing Pillow Block Type SSEPB Super Smart Ball Bushing Pillow Block



## End Support Linear Guide 1MB Components: <sup>†</sup>

- 4 Super Smart Ball Bushing\* pillow blocks or 2 Super Smart Ball Bushing twin pillow blocks.
- 2 60 Case\* LinearRace shafts.

#### Specifying a Thomson Linear Guide:

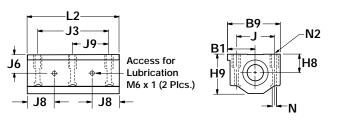
 Determine the proper system for your load and life requirements.
 Select the part number.
 Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number.

#### Part Numbering System

#### 1MB-M12-NOO L600

Linear guide Designation J Nominal Diameter J Type of Bearing Block J

Type SPTWN Super Plus Ball Bushing Twin Pillow Block Type SSETWN Super Smart Ball Bushing Twin Pillow Block



Type SPPB and SSEPB Pillow Blocks         (Dimensions in mm)											Type SPTWN a	and SS	SETW	/N Pi	illow	Bloc	ks			
Part	Nom.	L1	H8	H9	B1	B9	J	J1	J6	J7	Ν	N2	Mass	Part	Nom.	L2	J3	J8	J9	Mass
Number	Dia.										Dia.		kg	Number	Dia.					kg
SPPB-M08-XS	8	32	15	28	17,5	35	25	20	15	19,5	3,3	M4	0,07	SPTWN-M08-XS	8	62	50	19,5	25	0,15
SSEPB-M12-XS	12	39	18	35	21,5	43	32	23	18	23,0	4,3	M5	0,13	SSETWN-M12-XS	12	76	56	23,0	28	0,27
SSEPB-M16-XS	16	43	22	42	26,5	53	40	26	22	25,0	5,3	M6	0,20	SSETWN-M16-XS	16	84	64	25,0	32	0,41
SSEPB-M20-XS	20	54	25	50	30,0	60	45	32	25	30,5	6,6	M8	0,35	SSETWN-M20-XS	20	104	76	30,5	38	0,73
SSEPB-M25-XS	25	67	30	60	39,0	78	60	40	30	37,0	8,4	M10	0,66	SSETWN-M25-XS	25	130	94	37,0	47	1,37
SSEPB-M30-XS	30	79	35	70	43,5	87	68	45	35	43,0	8,4	M10	0,99	SSETWN-M30-XS	30	152	106	43,0	53	2,04
SSEPB-M40-XS	40	91	45	90	54,0	108	86	58	45	49,0	10,5	M12	1,83	SSETWN-M40-XS	40	176	124	49,0	62	3,73

Housing Material: Aluminum Alloy Grey Anodized

Dynamic Load	Capacity Matrix		(100 km travel)		
Linear Guide Assembly Part No.	Dynamic Load Capacity (N) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Capacity (N)		
1MB-M08-NOO	1240	SPPB-M08-XS	310		
1MB-M12-NOO	2600	SSEPB-M12-XS	650		
1MB-M16-NOO	8800	SSEPB-M16-XS	2200		
1MB-M20-NOO	16000	SSEPB-M20-XS	4000		
1MB-M25-NOO	26800	SSEPB-M25-XS	6700		
1MB-M30-NOO	33200	SSEPB-M30-XS	8300		
1MB-M40-NOO	54800	SSEPB-M40-XS	13700		
1MB-M08-POO	1000	SPTWN-M08-XS	500		
1MB-M12-POO	2120	SSETWN-M12-XS	1060		
1MB-M16-POO	8800	SSETWN-M16-XS	4400		
1MB-M20-POO	16000	SSETWN-M20-XS	8000		
1MB-M25-POO	26800	SSETWN-M25-XS	13400		
1MB-M30-POO	33200	SSETWN-M30-XS	16600		
1MB-M40-POO	54800	SSETWN-M40-XS	27400		

Housing Material: Aluminum Alloy Grey Anodized

Super Plus Ball Bushing\* bearings are used in 8 mm size pillow blocks.



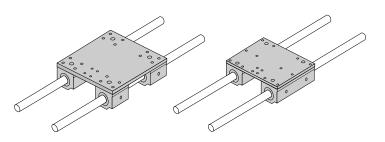


# End Support 1MC

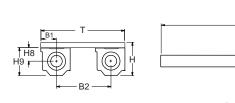
Linear Guide #9

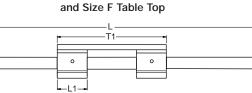
with Table Top

Unsupported, Industry Standard Dimension



METRIC





Double Linear Guide with 4 Pillow Blocks

Double Linear Guide with 2 Twin Pillow Blocks and Size E Table Top

•	−L	
0	o	

End Support Lin	ear Guide	1MC Dou	ble with	4 Pillow E	Blocks and	d Table To	p (Size F)			(Dir	mensions in mm)
Part	Nominal	L1	Н	H8	H9	B1	B2	B9	Т	T1	Pillow
Number	Diameter										Block
1MC-M08-NOF	8	32	38	15	28	17,5	50	35	85	85	SPPB-M08-XS
1MC-M12-NOF	12	39	45	18	35	21,5	57	43	100	100	SSEPB-M12-XS
1MC-M16-NOF	16	43	55	22	42	26,5	70	53	125	125	SSEPB-M16-XS
1MC-M20-NOF	20	54	66	25	50	30,0	110	60	175	175	SSEPB-M20-XS
1MC-M25-NOF	25	67	80	30	60	39,0	147	78	225	225	SSEPB-M25-XS
1MC-M30-NOF	30	79	90	35	70	43,5	188	87	275	275	SSEPB-M30-XS
1MC-M40-NOF	40	91	115	45	90	54,0	217	108	325	325	SSEPB-M40-XS

End Support Line	ar Guide	1MC Doub	le with 2 Tv	vin Pillow B	Blocks and	Table Top	o (Size E)		(	Dimensions in mm)
Part	Nominal	Н	H8	H9	B1	B2	B9	Т	T2	Pillow
Number	Diameter									Block
1MC-M08-POE	8	38	15	28	17,5	50	35	85	62	SPTWN-M08-XS
1MC-M12-POE	12	45	18	35	21,5	55	43	100	76	SSETWN-M12-XS
1MC-M16-POE	16	55	22	42	26,5	70	53	125	84	SSETWN-M16-XS
1MC-M20-POE	20	66	25	50	30,0	110	60	175	104	SSETWN-M20-XS
1MC-M25-POE	25	80	30	60	39,0	140	78	225	130	SSETWN-M25-XS
1MC-M30-POE	30	90	35	70	43,5	180	87	275	152	SSETWN-M30-XS
1MC-M40-POE	40	115	45	90	54,0	210	108	325	176	SSETWN-M40-XS

### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for Deflection calculations.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.





## **End Support Linear Guide** 1MC Benefits:

- Includes table top with standard tapped holes for quick and easy mounting of the work piece.
- Includes Ball Screw Assembly attachment holes for ease of assembly and actuation.
- Used in end supported applications when spanning or bridging a gap.

## End Support Linear Guide 1MC Components: <sup>†</sup>

- 4 Super Smart Ball Bushing\* pillow blocks or 2 Super Smart Ball Bushing twin pillow blocks.
- 2 60 Case\* LinearRace\* shafts.

N2

1 mounting table top with work piece and Ball Screw Assembly attachment holes.

### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number.

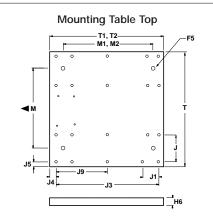
### Part Numbering System

1MC-M12-NOF L600 Linear Guide Linear Guide Designation Length Nominal Diameter\_ Type of Table Top Type of Bearing Block



Type SPTWN Super Plus Ball Bushing Twin Pillow Block Type SSETWN Super Smart Ball Bushing Twin Pillow Block





Type SPPB a	nd SS	SEPB	Pillo	N Blo	cks					(Dii	nensi	ons in	ı mm)	Type SPTWN an	d SSE	TWN	Pillo	ow Bl	ocks	5	
Part Number	Nom. Dia.	L1	H8	H9	B1	B9	J	J1	J6	J7	N Dia.	N2	Mass kg	Part Number	Nom. Dia.	L2	J3	J8	J9	Mass kg	
SPPB-M08-XS	8	32	15	28	17,5	35	25	20	15	19,5	3,3	M4	0,07	SPTWN-M08-XS	8	62	50	19,5	25	0,15	
SSEPB-M12-XS	12	39	18	35	21,5	43	32	23	18	23,0	4,3	M5	0,13	SSETWN-M12-XS	12	76	56	23,0	28	0,27	
SSEPB-M16-XS	16	43	22	42	26,5	53	40	26	22	25,0	5,3	M6	0,20	SSETWN-M16-XS	16	84	64	25,0	32	0,41	
SSEPB-M20-XS	20	54	25	50	30,0	60	45	32	25	30,5	6,6	M8	0,35						38	0,73	
SSEPB-M25-XS	25	67	30	60	39,0	78	60	40	30	37,0	8,4	M10	0,66	SSETWN-M25-XS	25	130	94	37,0	47	1,37	
SSEPB-M30-XS	30	79	35	70	43,5	87	68	45	35	43,0	8,4	M10	0,99	SSETWN-M30-XS	30	152	106	43,0	53	2,04	
SSEPB-M40-XS	40	91	45	90	54,0	108	86	58	45	49,0	10,5	M12	1,83	SSETWN-M40-XS							
Housing Material:	Alumin	num Alle	oy Grey	Anodi	zed									Housing Material: A	luminur	n Alloy	/ Grey	y Anoc	lized		

Mounting Table Top (Dimensions in mm) Nominal All Table Tops Table Top Size F Table Top Size E Diameter Т Μ J H6 E5(2) T1 J1 J4 J5 M1 T2 J3 J4 J5 19 M2 85 50 10 M6 85 20 6,0 50 62 50 25 35 08 25 5,0 6 5,0 100 100 23 8,0 55 12 55 32 10 M6 6,5 76 56 10 6,5 28 40 125 70 40 125 26 10,0 7,5 70 10 7,5 32 16 13 M6 84 64 45 20 175 110 45 16 M8 175 32 11,0 10,0 110 104 76 14 10,0 38 55 25 225 140 60 20 M8 225 40 13,5 12,5 140 130 94 18 12,5 47 65 30 275 180 68 20 M8 275 45 17,0 13,5 180 152 106 23 13,5 53 75 40 325 210 86 25 M10 325 58 16,5 14,5 210 176 124 26 14.5 62 85

Carriage Material: Aluminum Alloy Grey Anodized

Dynamic Lo	ad Capacity Ma	trix	(100 km travel)	Dynamic Lo	ad Capacity Ma	trix	(100 km travel)
Linear Guide Assembly Part No.	Dynamic Load Capacity (N) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Capacity (N)	Linear Guide Assembly Part No.	Dynamic Load Capacity (N) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Capacity (N)
1MC-M08-NOF	1240	SPPB-M08-XS	310	1MC-M08-POE	1000	SPTWN-M08-XS	500
1MC-M12-NOF	2600	SSEPB-M12-XS	650	1MC-M12-POE	2120	SSETWN-M12-XS	1060
1MC-M16-NOF	8800	SSEPB-M16-XS	2200	1MC-M16-POE	8800	SSETWN-M16-XS	4400
1MC-M20-NOF	16000	SSEPB-M20-XS	4000	1MC-M20-POE	16000	SSETWN-M20-XS	8000
1MC-M25-NOF	26800	SSEPB-M25-XS	6700	1MC-M25-POE	26800	SSETWN-M25-XS	13400
1MC-M30-NOF	33200	SSEPB-M30-XS	8300	1MC-M30-POE	33200	SSETWN-M30-XS	16600
1MC-M40-NOF	54800	SSEPB-M40-XS	13700	1MC-M40-POE	54800	SSETWN-M40-XS	27400

<sup>†</sup> Super Plus Ball Bushing<sup>\*</sup> bearings are used in 8 mm size pillow blocks.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



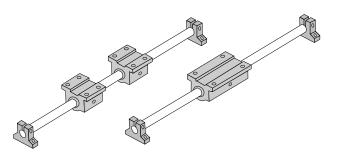
The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

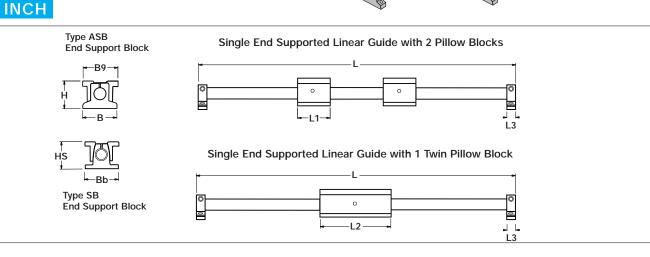


<sup>(2)</sup> Customer Mounting hole.

# End Support 1BA

Linear Guide #9 End Supported, Industry Standard Dimension





End Support	Linear Guid	e 1BA with	2 Pillow	Blocks	5						(Dimensions	in inches)
Part N	umber	Nominal	L1	L3	Н	HS	В	Bb	B9	Pillow	Shaft S	upport
W/ Type ASB Shaft Supports	W/ Type SB Shaft Supports	Diameter								Block	Type ASB	Type SB
1BA-04-AHO	-	.250	1.19	.50	.937	-	1.50	-	1.63	SPB-4-XS	ASB-4-XS	-
1BA-06-AHO	-	.375	1.31	.56	1.062	-	1.63	-	1.75	SPB-6-XS	ASB-6-XS	-
1BA-08-AHO	1BA-08-AJO	.500	1.69	.63	1.562	1.687	2.00	2.00	2.00	SSUPB-8-XS	ASB-8-XS	SB-8-XS
1BA-12-AHO	1BA-12-AJO	.750	2.06	.75	2.062	2.187	2.50	2.75	2.75	SSUPB-12-XS	ASB-12-XS	SB-12-XS
1BA-16-AHO	1BA-16-AJO	1.000	2.81	1.00	2.562	2.687	3.25	3.25	3.25	SSUPB-16-XS	ASB-16-XS	SB-16-XS
-	1BA-20-AJO	1.250	3.63	1.13	-	3.250	-	-	4.00	SSUPB-20-XS	-	SB-20-XS
1BA-24-AHO	1BA-24-AJO	1.500	4.00	1.25	3.750	3.750	4.75	4.75	4.75	SSUPB-24-XS	ASB-24-XS	SB-24-XS

End Support	Linear Guide	1BA wi	th 1 Tw	in Pillo	ow Blo	ck					(Di	mensions i	n inches)
Part N	umber	Nom.	L2	L3	Н	HS	В	Bb	B9	Max.	Pillow	Shaft S	upport
W/ Type ASB	W/ Type SB	Dia.								Stroke	Block	Туре	Туре
Shaft	Shaft									Length		ASB	SB
Supports	Supports												
1BA-04-BHO	-	.250	2.50	.50	.937	-	1.50	-	1.63	L-(3.50)	TWN-4-XS	ASB-4-XS	-
1BA-06-BHO	-	.375	2.75	.56	1.062	-	1.63	-	1.75	L-(3.88)	TWN-6-XS	ASB-6-XS	-
1BA-08-BHO	1BA-08-BJO	.500	3.50	.63	1.562	1.687	2.00	2.00	2.00	L-(4.75)	SSUTWN-8-XS	ASB-8-XS	SB-8-XS
1BA-12-BHO	1BA-12-BJO	.750	4.50	.75	2.062	2.187	2.50	2.75	2.50	L-(6.00)	SSUTWN-12-XS	ASB-12-XS	SB-12-XS
1BA-16-BHO	1BA-16-BJO	1.000	6.00	1.00	2.562	2.687	3.25	3.25	3.25	L-(8.00)	SSUTWN-16-XS	ASB-16-XS	SB-16-XS
-	1BA-20-BJO	1.250	7.50	1.13	-	3.250	-	4.00	4.00	L-(9.75)	SSUTWN-20-XS	-	SB-20-XS
1BA-24-BHO	1BA-24-BJO	1.500	9.00	1.25	3.750	3.750	4.75	4.75	4.75	L-(11.50)	SSUTWN-24-XS	ASB-24-XS	SB-24-XS

### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for Deflection calculations.





## **End Support Linear Guide 1BA Benefits:**

- Requires only one part number to specify entire linear quide.
- Available with 60 Case\* LinearRace\* Shaft end support blocks in either light weight aluminum or rigid iron materials.
- Used to provide increased stability or torque resistance in linear system applications.

## **End Support Linear Guide** 1BA Components: †

- 2 Super Smart Ball Bushing\* pillow blocks or 1 Super Smart Ball Bushing twin pillow block.
- 1 60 Case LinearRace shaft.
- 2 Shaft End Support Blocks.

Type ASB LinearRace

Shaft End Support Block

#### Specifying this Thomson Linear Guide:

1. Determine the proper Linear Guide for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

### Part Numbering System

Type SB LinearRace

Shaft End Support Block

Rh

1BA-12-AHO L24 Linear Guide Linear Guide Designation -Length Nominal Diameter-

Pillow Block

View A-A

Type of Bearing Block

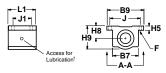
Type of Support

Type SPB Super Ball Bushing

J1

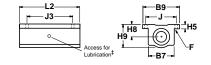
Mounting Hole Position for Sizes .250 and .375

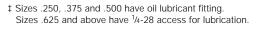
Type SSUPB Super Smart Ball Bushing Pillow Block Type SPB Super Ball Bushing Pillow Block



Type SSUTWN Super Smart Ball Bushing Twin Pillow Block

Type TWN Super Ball Bushing Twin Pillow Block





Type SPB and	SSUP	B Pillo	ow Blo	ocks					(Din	nensior	ns in In	ches)	Type TWN and	I SSUT	WN Pi	llow B	ocks
Part	Nom.	L1	H9	H8	H5	B9	B7	J	J1		-	Wt.	Part	Nom.	L2	J3	Wt.
Number	Dia.									Bolt	Hole	lb	Number	Dia.			lb
SPB-4-XS	.250	1.19	.81	.437	.19	1.63	1.00	1.31	.75(2)	#6	.16	.10	TWN-4-XS	.250	2.50	2.00	.19
SPB-6-XS	.375	1.31	.94	.500	.19	1.75	1.12	1.44	.88(2)	#6	.16	.13	TWN-6-XS	.375	2.75	2.25	.25
SSUPB-8-XS	.500	1.69	1.25	.687	.25	2.00	1.38	1.69	1.00	#6	.16	.20	SSUTWN-8-XS	.500	3.50	2.50	.40
SSUPB-12-XS	.750	2.06	1.75	.937	.31	2.75	1.88	2.38	1.25	#8	.19	.62	SSUTWN-12-XS	.750	4.50	3.50	1.24
SSUPB-16-XS	1.000	2.81	2.19	1.187	.38	3.25	2.38	2.88	1.75	#10	.22	1.24	SSUTWN-16-XS	1.000	6.00	4.50	2.48
SSUPB-20-XS	1.250	3.63	2.81	1.500	.43	4.00	3.00	3.50	2.00	#10	.22	2.57	SSUTWN-20-XS	1.250	7.50	5.50	5.14
SSUPB-24-XS	1.500	4.00	3.25	1.750	.50	4.75	3.50	4.12	2.50	1/4	.28	3.94	SSUTWN-24-XS	1.500	9.00	6.50	8.08
Housing Material: A	luminum	n Alloy E	lack An	odized									Housing Material:	Aluminu	ım Alloy	/ Black	

<sup>(2)</sup>Two mounting holes as shown in view A-A for sizes .250 and .375

Anodized

Type ASB L	inearR	ace Sl	haft E	nd Sup	port B	lock				Type SB	Linear	Race	e Sha	ift End	d Sup	port	Bloc	k	
Part	Nom.	L3	H3	H1	В	B3	(	3	Wt.	Part	Nom.	L3	Hh	Hc	Bb	B3		G	Wt.
Number	Dia.						Bolt	Hole	lb	Number	Dia.						Bolt	Hole	lb
ASB-04-XS	.250	.50	.88	.500	1.50	1.12	#6	.16	.06	SB-8-XS	.500	.63	1.62	1.000	2.00	1.50	#8	.19	.3
ASB-06-XS	.375	.56	1.00	.562	1.62	1.25	#6	.16	.08	SB-12-XS	.750	.75	2.12	1.250	2.75	2.00	#10	.22	.5
ASB-08-XS	.500	.63	1.48	.875	2.00	1.50	#8	.19	.11	SB-16-XS	1.000	1.00	2.56	1.500	3.25	2.50	1/4	.28	1.0
ASB-12-XS	.750	.75	1.95	1.125	2.50	2.00	#10	.22	.22	SB-20-XS	1.250	1.13	3.00	1.750	4.00	3.00	<sup>5</sup> /16	.34	2.0
ASB-16-XS	1.000	1.00	2.48	1.375	3.25	2.50	1/4	.28	.44	SB-24-XS	1.500	1.25	3.50	2.000	4.75	3.50	<sup>5</sup> /16	.34	2.6
ASB-24-XS	1.500	1.250	3.50	2.000	4.75	3.50	<sup>5</sup> /16	.34	1.16	Material: Iroi	n								

End Support Material: Aluminum Alloy Black Anodized

Dynamic Loa	ad Capacity	Matrix	(4 million ind	ches travel)	Dynamic Lo	ad Capacity	Matrix	(4 million inc	hes travel)
Asse	Guide embly t No.	Dynamic Load Capacity (Ib <sub>f</sub> ) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Capacity (Ib <sub>f</sub> )		Guide embly No.	Dynamic Load Capacity (Ib <sub>f</sub> ) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Capacity (lb <sub>f</sub> )
1BA-04-AHO	-	100	SPB-4-XS	50	1BA-04-BHO	-	100	TWN-4-XS	100
1BA-06-AHO	-	160	SPB-6-XS	80	1BA-06-BHO	-	160	TWN-6-XS	160
1BA-08-AHO	1BA-08-AJO	800	SSUPB-8-XS	400	1BA-08-BHO	1BA-08-BJO	800	SSUTWN-8-XS	800
1BA-12-AHO	1BA-12-AJO	1800	SSUPB-12-XS	900	1BA-12-BHO	1BA-12-BJO	1800	SSUTWN-12-XS	1800
1BA-16-AHO	1BA-16-AJO	3000	SPSUB-16-XS	1500	1BA-16-BHO	1BA-16-BJO	3000	SPSTWN-16-XS	3020
-	1BA-20-AJO	3730	SSUPB-20-XS	1865	-	1BA-20-BJO	3730	SSUTWN-20-XS	1865
1BA-24-AHO	1BA-24-AJO	6160	SSUPB-24-XS	3080	1BA-24-BHO	1BA-24-BJO	6160	SSUTWN-24-XS	6160

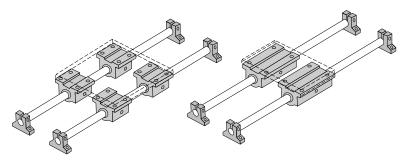
<sup>+</sup> Super Ball Bushing<sup>\*</sup> bearings are used in .250 and .375 inch size pillow blocks.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



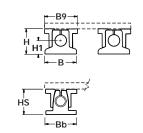


## End Support 1BB Linear Guide #9 End Supported, Industry Standard Dimension



INCH

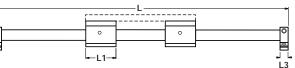
Type ASB End Support Block



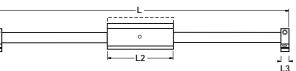
End Support Block

Type SB

Double End Supported Linear Guide with 4 Pillow Blocks



Double End Supported Linear Guide with 2 Twin Pillow Blocks



Maximum Stroke Length is determined by subtracting pillow block length (L2) and 2x support block length (L3) from total Linear Guide length (L).

End Support	Linear Guid	e 1BB with	4 Pillow	Blocks	5						(Dimensions	in inches)
Part N	umber	Nominal	L1	L3	Н	HS	В	Bb	B9	Pillow	Shaft S	upport
W/ Type ASB	W/ Type SB	Diameter								Block	Туре	Туре
Shaft	Shaft										ASB	SB
Supports	Supports											
1BB-04-AHO	-	.250	1.19	.50	.937	-	1.50	-	1.63	SPB-4-XS	ASB-4-XS	-
1BB-06-AHO	-	.375	1.31	.56	1.062	-	1.63	-	1.75	SPB-6-XS	ASB-6-XS	-
1BB-08-AHO	1BB-08-AJO	.500	1.69	.63	1.562	1.687	2.00	2.00	2.00	SSUPB-8-XS	ASB-8-XS	SB-8-XS
1BB-12-AHO	1BB-12-AJO	.750	2.06	.75	2.062	2.187	2.50	2.75	2.75	SSUPB-12-XS	ASB-12-XS	SB-12-XS
1BB-16-AHO	1BB-16-AJO	1.000	2.81	1.00	2.562	2.687	3.25	3.25	3.25	SSUPB-16-XS	ASB-16-XS	SB-16-XS
-	1BB-20-AJO	1.250	3.63	1.13	-	3.250	-	-	4.00	SSUPB-20-XS	-	SB-20-XS
1BB-24-AHO	1BB-24-AJO	1.500	4.00	1.25	3.750	3.750	4.75	4.75	4.75	SSUPB-24-XS	ASB-24-XS	SB-24-XS

End Support	Linear Guide	1BB wi	ith 2 Tw	in Pille	ow Blo	cks					(Di	mensions i	n inches)
Part N	umber	Nom.	L2	L3	Н	HS	В	Bb	B9	Max.	Pillow	Shaft S	upport
W/ Type ASB	W/ Type SB	Dia.								Stroke	Block	Туре	Туре
Shaft	Shaft									Length		ASB	SB
Supports	Supports												
1BB-04-BHO	-	.250	2.50	.50	.937	-	1.50	-	1.63	L-(3.50)	TWN-4-XS	ASB-4-XS	-
1BB-06-BHO	-	.375	2.75	.56	1.062	-	1.63	-	1.75	L-(3.88)	TWN-6-XS	ASB-6-XS	-
1BB-08-BHO	1BB-08-BJO	.500	3.50	.63	1.562	1.687	2.00	2.00	2.00	L-(4.75)	SSUTWN-8-XS	ASB-8-XS	SB-8-XS
1BB-12-BHO	1BB-12-BJO	.750	4.50	.75	2.062	2.187	2.50	2.75	2.50	L-(6.00)	SSUTWN-12-XS	ASB-12-XS	SB-12-XS
1BB-16-BHO	1BB-16-BJO	1.000	6.00	1.00	2.562	2.687	3.25	3.25	3.25	L-(8.00)	SSUTWN-16-XS	ASB-16-XS	SB-16-XS
-	1BB-20-BJO	1.250	7.50	1.13	-	3.250	-	4.00	4.00	L-(9.75)	SSUTWN-20-XS	-	SB-20-XS
1BB-24-BHO	1BB-24-BJO	1.500	9.00	1.25	3.750	3.750	4.75	4.75	4.75	L-(11.50)	SSUTWN-24-XS	ASB-24-XS	SB-24-XS

### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for Deflection calculations.





## End Support Linear Guide 1BB Benefits:

- Requires only one part number to specify entire linear guide.
- Available with 60 Case\* LinearRace\* Shaft end support blocks in either light weight aluminum or rigid iron
- Used in end supported applications when spanning or bridging a gap.

# End Support Linear Guide 1BB Components: <sup>†</sup>

- 4 Super Smart Ball Bushing\* pillow blocks or Super Smart Ball Bushing twin pillow blocks.
- 2 60 Case LinearRace shafts.
- 4 Shaft End Support Blocks.

#### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

## Part Numbering System

 1BB-12-AHO L24

 Linear Guide

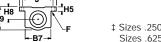
 Designation

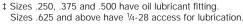
 Nominal Diameter

 Nominal Diameter

Type of Bearing Block → └─ Type of Support

Type SPB Super Ball Bushing Type SSUPB Super Smart Ball Bushing Pillow Block Type ASB LinearRace Type SB LinearRace Type SPB Super Ball Bushing Pillow Block Shaft End Support Block Shaft End Support Block Pillow Block Mounting Hole Position for Sizes .250 and .375 ۰J1 HS -R7 +B3+ Rh J1 Type SSUTWN Super Smart Ball Bushing Twin Pillow Block Type TWN Super Ball Bushing Twin Pillow Block J3 View A-A





Type SPB and	SSUP	B Pillo	ow Blo	ocks					(Din	nensio	ns in In	ches)	Type TWN and	I SSUT	WN Pi	llow B	locks
Part	Nom.	L1	H9	H8	H5	B9	B7	J	J1		F	Wt.	Part	Nom.	L2	J3	Wt.
Number	Dia.									Bolt	Hole	lb	Number	Dia.			lb
SPB-4-XS	.250	1.19	.81	.437	.19	1.63	1.00	1.31	.75(2)	#6	.16	.10	TWN-4-XS	.250	2.50	2.00	.19
SPB-6-XS	.375	1.31	.94	.500	.19	1.75	1.12	1.44	.88(2)	#6	.16	.13	TWN-6-XS	.375	2.75	2.25	.25
SSUPB-8-XS	.500	1.69	1.25	.687	.25	2.00	1.38	1.69	1.00	#6	.16	.20	SSUTWN-8-XS	.500	3.50	2.50	.40
SSUPB-12-XS	.750	2.06	1.75	.937	.31	2.75	1.88	2.38	1.25	#8	.19	.62	SSUTWN-12-XS	.750	4.50	3.50	1.24
SSUPB-16-XS	1.000	2.81	2.19	1.187	.38	3.25	2.38	2.88	1.75	#10	.22	1.24	SSUTWN-16-XS	1.000	6.00	4.50	2.48
SSUPB-20-XS	1.250	3.63	2.81	1.500	.43	4.00	3.00	3.50	2.00	#10	.22	2.57	SSUTWN-20-XS	1.250	7.50	5.50	5.14
SSUPB-24-XS	1.500	4.00	3.25	1.750	.50	4.75	3.50	4.12	2.50	<sup>1</sup> /4	.28	3.94	SSUTWN-24-XS	1.500	9.00	6.50	8.08

Housing Material: Aluminum Alloy Black Anodized

Access for

<sup>(2)</sup>Two mounting holes as shown in view A-A for sizes .250 and .375

Housing Material: Aluminum Alloy Black Anodized

Type ASB Li	nearR	ace Sl	naft Ei	nd Sup	port B	lock				Type SB	Linear	Race	e Sha	ft End	d Sup	port	Bloc	k	
Part	Nom.	L3	H3	H1	В	B3	(	3	Wt.	Part	Nom.	L3	Hh	Hc	Bb	B3	(	3	Wt.
Number	Dia.						Bolt	Hole	lb	Number	Dia.						Bolt	Hole	lb
ASB-04-XS	.250	.50	.88	.500	1.50	1.12	#6	.16	.06	SB-8-XS	.500	.63	1.62	1.000	2.00	1.50	#8	.19	.3
ASB-06-XS	.375	.56	1.00	.562	1.62	1.25	#6	.16	.08	SB-12-XS	.750	.75	2.12	1.250	2.75	2.00	#10	.22	.5
ASB-08-XS	.500	.63	1.48	.875	2.00	1.50	#8	.19	.11	SB-16-XS	1.000	1.00	2.56	1.500	3.25	2.50	<sup>1</sup> /4	.28	1.0
ASB-12-XS	.750	.75	1.95	1.125	2.50	2.00	#10	.22	.22	SB-20-XS	1.250	1.13	3.00	1.750	4.00	3.00	<sup>5</sup> /16	.34	2.0
ASB-16-XS	1.000	1.00	2.48	1.375	3.25	2.50	1/4	.28	.44	SB-24-XS	1.500	1.25	3.50	2.000	4.75	3.50	<sup>5</sup> /16	.34	2.6
ASB-24-XS	1.500	1.250	3.50	2.000	4.75	3.50	<sup>5</sup> /16	.34	1.16	Material: Iro	n								

End Support Material: Aluminum Alloy Black Anodized

Dynamic Lo	ad Capacity	Matrix	(4 million inc	hes travel)	Dynamic Lo	ad Capacity	Matrix	(4 million inc	hes travel)
	Guide embly No.	Dynamic Load Capacity (Ib <sub>f</sub> ) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Capacity (lb <sub>f</sub> )	Asse	<sup>-</sup> Guide embly t No.	Dynamic Load Capacity (Ib <sub>f</sub> ) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Capacity (lbf)
1BB-04-AHO	- 200 SP		SPB-4-XS	50	1BB-04-BHO	-	200	TWN-4-XS	100
1BB-06-AHO	-	320	SPB-6-XS	80	1BB-06-BHO	-	320	TWN-6-XS	160
1BB-08-AHO	1BB-08-AJO	1600	SSUPB-8-XS	400	1BB-08-BHO	1BB-08-BJO	1600	SSUTWN-8-XS	800
1BB-12-AHO	1BB-12-AJO	3600	SSUPB-12-XS	900	1BB-12-BHO	1BB-12-BJO	3600	SSUTWN-12-XS	1800
1BB-16-AHO	1BB-16-AJO	6000	SPSUB-16-XS	1500	1BB-16-BHO	1BB-16-BJO	6040	SPSTWN-16-XS	3020
-	1BB-20-AJO	7460	SSUPB-20-XS	1865	-	1BB-20-BJO	7460	SSUTWN-20-XS	3730
1BB-24-AHO	1BB-24-AJO	12320	SSUPB-24-XS	3080	1BB-24-BHO	1BB-24-BJO	12320	SSUTWN-24-XS	6160

<sup>†</sup> Super Ball Bushing<sup>\*</sup> bearings are used in .250 and .375 inch pillow blocks.

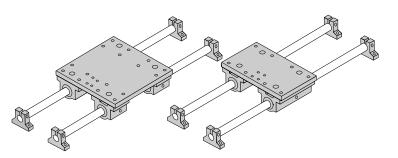




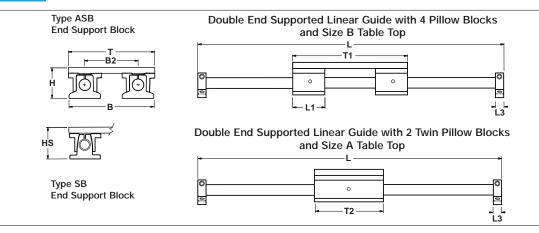
## End Support 1BC Linear Guide #9

with Table Top

End Supported, Industry Standard Dimension



INCH



End Suppor	rt Linear Gu	ide 1B	C with	4 Pillo	w Bloc	cks and	d Table	Top (S	ize B)			])	Dimensions	in inch)
Part N	umber	Nom.	L1	L3	Н	HS	В	B2	Т	T1	Max.	Pillow	Shaft Su	ipport
W/Type ASB	W/Type SB	Dia.									Stroke	Block	Туре	Туре
Shaft	Shaft										Length		ASB	SB
Supports	Supports													
1BC-04-AHB	-	.250	1.19	.50	1.187	-	3.75	2.25	4.00	4.00	L-(5.0)	SPB-4-XS	ASB-4-XS	-
1BC-06-AHB	-	.375	1.31	.56	1.312	-	4.13	2.50	4.50	4.50	L-(5.62)	SPB-6-XS	ASB-6-XS	-
1BC-08-AHB	1BC-08-AJB	.500	1.69	.63	1.937	2.062	5.25	3.25	5.50	5.50	L-(6.76)	SSUPB-8-XS	ASB-8-XS	SB-8-XS
1BC-12-AHB	1BC-12-AJB	.750	2.06	.75	2.562	2.687	7.00	4.50	7.50	7.50	L-(9.0)	SSUPB-12-XS	ASB-12-XS	SB-12-XS
1BC-16-AHB	1BC-16-AJB	1.000	2.81	1.00	3.062	3.187	8.75	5.50	9.00	9.00	L-(11.0)	SSUPB-16-XS	ASB-16-XS	SB-16-XS
-	1BC-20-AJB	1.250	3.63	1.13	-	4.000	-	6.75	11.00	11.00	L-(13.26)	SSUPB-20-XS	-	SB-20-XS
1BC-24-AHB	1BC-24-AJB	1.500	4.00	1.25	4.500	4.500	12.75	8.00	13.00	13.00	L-(15.5)	SSUPB-24-XS	ASB-24-XS	SB-24-XS

End Support	Linear Guide	e 1BC \	with 2	Twin Pi	llow Blo	cks and	Table T	op (Siz	e <b>A)</b>			(Dimension	is in inch)
Part N	umber	Nom.	T2	L3	Н	HS	В	B2	Т	Max.	Pillow	Shaft S	upport
W/ Type ASB	W/ Type SB	Dia.								Stroke	Block	Туре	Туре
Shaft	Shaft									Length		ASB	SB
Supports	Supports												
1BC-04-BHA	-	.250	2.50	.50	1.187	-	3.75	2.25	4.00	L-(3.50)	TWN-4-XS	ASB-4-XS	-
1BC-06-BHA	-	.375	2.75	.56	1.132	-	4.13	2.50	4.50	L-(3.88)	TWN-6-XS	ASB-6-XS	-
1BC-08-BHA	1BC-08-BJA	.500	3.50	.63	1.937	2.062	5.25	3.25	5.50	L-(4.75)	SSUTWN-8-XS	ASB-8-XS	SB-8-XS
1BC-12-BHA	1BC-12-BJA	.750	4.50	.75	2.562	2.687	7.00	4.50	7.50	L-(6.00)	SSUTWN-12-XS	ASB-12-XS	SB-12-XS
1BC-16-BHA	1BC-16-BJA	1.000	6.00	1.00	3.062	3.187	8.75	5.50	9.00	L-(8.00)	SSUTWN-16-XS	ASB-16-XS	SB-16-XS
-	1BC-20-BJA	1.250	7.50	1.13	-	4.000	-	6.75	11.00	L-(9.75)	SSUTWN-20-XS	-	SB-20-XS
1BC-24-BHA	1BC-24-BJA	1.500	9.00	1.25	4.500	4.500	12.75	8.00	13.00	L-(11.50)	SSUTWN-24-XS	ASB-24-XS	SB-24-XS

### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for Deflection calculations.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.





## **End Support Linear Guide 1BC Benefits:**

۳J1۹

12

J3-

- Includes table top with standard tapped holes for quick and easy mounting of the work piece.
- Includes Ball Screw Assembly attachment holes for ease of assembly and actuation.
- Available with 60 Case\* LinearRace\* shaft end support blocks in either light weight aluminum or rigid iron materials.

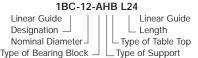
## End Support Linear Guide 1BC Components: <sup>†</sup>

- 4 Super Smart Ball Bushing\* pillow blocks or 2 Super Smart Ball Bushing twin pillow blocks.
- 2 60 Case LinearRace shafts.
- 4 Shaft End Support Blocks.
- 1 mounting table top with work piece and Ball Screw Assembly attachment holes.

#### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System



Type SSUPB Super Smart Ball Bushing Pillow Block Type ASB LinearRace Mounting Table Top Type SPB Super Ball Bushing Shaft End Support Block Pillow Block Type SPB Super Ball Bushing Pillow Block Mounting Hole Position for Sizes .250 and .375 B3 -B7 ·B A-A Ĵ1 Type SB LinearRace Type SSUTWN Super Smart Ball Bushing Shaft End Support Block Twin Pillow Block Type TWN Super Ball Bushing Twin Pillow Block 0 0 .RO /iew A-A \_\_\_\_\_\_ •B3 • \* Sizes .250, .375 and .500 have oil Bb ]\_\_не lubricant fitting. Sizes, .625 and above have 1/4-28 access for lubrication.

Type SPB and	SSUP	B Pillo	ow Blo	ocks					(Din	nensio	ns in In	ches)	Type TWN and	I SSUT	WN Pi	llow B	locks
Part	Nom.	L1	H9	H8	H5	B9	B7	J	J1		F	Wt.	Part	Nom.	L2	J3	Wt.
Number	Dia.									Bolt	Hole	lb	Number	Dia.			lb
SPB-4-XS	.250	1.19	.81	.437	.19	1.63	1.00	1.31	.75(2)	#6	.16	.10	TWN-4-XS	.250	2.50	2.00	.19
SPB-6-XS	.375	1.31	.94	.500	.19	1.75	1.12	1.44	.88(2)	#6	.16	.13	TWN-6-XS	.375	2.75	2.25	.25
SSUPB-8-XS	.500	1.69	1.25	.687	.25	2.00	1.38	1.69	1.00	#6	.16	.20	SSUTWN-8-XS	.500	3.50	2.50	.40
SSUPB-12-XS	.750	2.06	1.75	.937	.31	2.75	1.88	2.38	1.25	#8	.19	.62	SSUTWN-12-XS	.750	4.50	3.50	1.24
SSUPB-16-XS	1.000	2.81	2.19	1.187	.38	3.25	2.38	2.88	1.75	#10	.22	1.24	SSUTWN-16-XS	1.000	6.00	4.50	2.48
SSUPB-20-XS	1.250	3.63	2.81	1.500	.43	4.00	3.00	3.50	2.00	#10	.22	2.57	SSUTWN-20-XS	1.250	7.50	5.50	5.14
SSUPB-24-XS	1.500	4.00	3.25	1.750	.50	4.75	3.50	4.12	2.50	<sup>1</sup> /4	.28	3.94	SSUTWN-24-XS	1.500	9.00	6.50	8.08
Housing Material: A	Aluminun	n Alloy E	lack An	odized									Housing Material:	Aluminu	um Alloy	Black	

<sup>(2)</sup>Two mounting holes as shown in view A-A for sizes .250 and .375

Anodized

Type ASB Li	nearR	ace SI	naft E	nd Sup	port B	lock				Type SB	Linear	Race	e Sha	ft End	d Sup	port	Bloc	k	
Part	Nom.	L3	H3	H1	В	B3	(	3	Wt.	Part	Nom.	L3	Hh	Hc	Bb	B3		G	Wt.
Number	Dia.						Bolt	Hole	lb	Number	Dia.						Bolt	Hole	lb
ASB-04-XS	.250	.50	.88	.500	1.50	1.12	#6	.16	.06	SB-8-XS	.500	.63	1.62	1.000	2.00	1.50	#8	.19	.3
ASB-06-XS	.375	.56	1.00	.562	1.62	1.25	#6	.16	.08	SB-12-XS	.750	.75	2.12	1.250	2.75	2.00	#10	.22	.5
ASB-08-XS	.500	.63	1.48	.875	2.00	1.50	#8	.19	.11	SB-16-XS	1.000	1.00	2.56	1.500	3.25	2.50	1/4	.28	1.0
ASB-12-XS	.750	.75	1.95	1.125	2.50	2.00	#10	.22	.22	SB-20-XS	1.250	1.13	3.00	1.750	4.00	3.00	<sup>5</sup> /16	.34	2.0
ASB-16-XS	1.000	1.00	2.48	1.375	3.25	2.50	<sup>1</sup> /4	.28	.44	SB-24-XS	1.500	1.25	3.50	2.000	4.75	3.50	<sup>5</sup> /16	.34	2.6
ASB-24-XS	1.500	1.250	3.50	2.000	4.75	3.50	<sup>5</sup> /16	.34	1.16	Material: Iro	n								

End Support Material: Aluminum Alloy Black Anodized

Mountin	g Table	Тор											(Dimens	sions in i	nches)
Nominal		All	Table To	ps			Tabl	e Top Siz	e B			Tabl	e Top Siz	e A	
Diameter	Т	М	J	H6	F5	T1	J1	J4	J5	N	T2	J3	J4	J5	N1
.250	4.0	2.25	1.31	.250	#8-32	4.0	.75(2)	.22	.22	3.50	2.50	2.00	.25	.22	2.0
.375	4.5	2.50	1.44	.250	#10-32	4.5	.88(2)	.22	.28	3.75	2.75	2.25	.25	.28	2.0
.500	5.5	3.25	1.69	.375	1/4-20	5.5	1.00	.34	.28	4.50	3.50	2.50	.50	.31	2.5
.750	7.5	4.50	2.38	.500	<sup>5</sup> /16-18	7.5	1.25	.41	.31	6.00	4.50	3.50	.50	.31	3.0
1.000	9.0	5.50	2.88	.500	<sup>3</sup> /8-16	9.0	1.75	.53	.31	7.00	6.00	4.50	.75	.31	4.0
1.250	11.0	6.75	3.50	.750	1/2-13	11.0	2.00	.82	.38	8.50	7.50	5.50	1.00	.38	5.0
1.500	13.0	8.00	4.12	.750	1/2-13	13.0	2.50	.75	.44	10.00	9.00	6.50	1.25	.44	6.0

Carriage Material: Aluminum Alloy Black Anodized

<sup>(2)</sup>Two mounting holes as shown in view A-A for sizes .250 and .375

\* Super Ball Bushing\* bearings are used in .250 and .375 inch size pillow blocks.

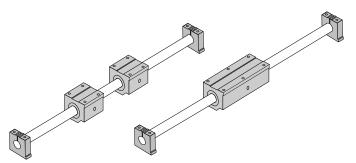
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



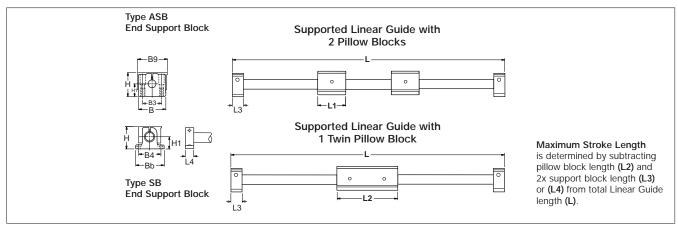


# End Support 1NA

Linear Guide #9 End Supported, Industry Standard Dimension



## METRIC



End Support	t Linear Guid	le 1NA	with 2 I	Pillow	Blocks							(Dimensio	ons in mm)
Part Nu	umber	Nom.	L1	L3	L4	Н	H1	В	Bb	B9	Pillow	Shaft S	Support
W/ Type ASB	W/ Type SB	Dia.									Block	Туре	Туре
Shaft	Shaft											ASB	SB
Supports	Supports												
1NA-M08-NMO	1NA-M08-NNO	8	32	18	10	30	15	32	32	35	SPPB-M08-XS	ASB-M08-XS	SB-M08-XS
1NA-M12-NMO	1NA-M12-NNO	12	39	20	12	38	20	43	42	43	SSEPB-M12-XS	ASB-M12-XS	SB-M12-XS
1NA-M16-NMO	1NA-M16-NNO	16	43	24	16	47	25	53	50	53	SSEPB-M16-XS	ASB-M16-XS	SB-M16-XS
1NA-M20-NMO	1NA-M20-NNO	20	54	30	20	55	30	60	60	60	SSEPB-M20-XS	ASB-M20-XS	SB-M20-XS
1NA-M25-NMO	1NA-M25-NNO	25	67	38	25	65	35	78	74	78	SSEPB-M25-XS	ASB-M25-XS	SB-M25-XS
1NA-M30-NMO	1NA-M30-NNO	30	79	40	28	75	40	87	84	87	SSEPB-M30-XS	ASB-M30-XS	SB-M30-XS
1NA-M40-NMO	1NA-M40-NNO	40	91	48	32	95	50	108	108	108	SSEPB-M40-XS	ASB-M40-XS	SB-M40-XS

End Support	t Linear Guid	e 1NA	with 1	Twin P	illow Bl	ock						(Dimensio	ons in mm)
Part Nu	umber	Nom.	L2	L3	L4	Н	H1	В	Bb	B9	Pillow	Shaft	Support
W/ Type ASB	W/ Type SB	Dia.									Block	Туре	Туре
Shaft	Shaft											ASB	SB
Supports	Supports												
1NA-M08-PMO	1NA-M08-PNO	8	62	18	10	30	15	32	32	35	SPTWN-M08-XS	ASB-M08-XS	SB-M08-XS
1NA-M12-PMO	1NA-M12-PNO	12	76	20	12	38	20	43	42	43	SSETWN-M12-XS	ASB-M12-XS	SB-M12-XS
1NA-M16-PMO	1NA-M16-PNO	16	84	24	16	47	25	53	50	53	SSETWN-M16-XS	ASB-M16-XS	SB-M16-XS
1NA-M20-PMO	1NA-M20-PNO	20	104	30	20	55	30	60	60	60	SSETWN-M20-XS	ASB-M20-XS	SB-M20-XS
1NA-M25-PMO	1NA-M25-PNO	25	130	38	25	65	35	78	74	78	SSETWN-M25-XS	ASB-M25-XS	SB-M25-XS
1NA-M30-PMO	1NA-M30-PNO	30	152	40	28	75	40	87	84	87	SSETWN-M30-XS	ASB-M30-XS	SB-M30-XS
1NA-M40-PMO	1NA-M40-PNO	40	176	48	32	95	50	108	108	108	SSETWN-M40-XS	ASB-M40-XS	SB-M40-XS

### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for Deflection calculations.





## End Support Linear Guide **1NA Benefits:**

- Requires only one part number to specify entire linear guide.
- Available with 60 Case\* LinearRace\* shaft end support blocks in either light weight aluminum or rigid iron materials.
- Used as a load support, transport and guidance solution.

cess for Lubrication M6 x 1

12 13

- 19

.18

Type SPPB Super Plus Ball Bushing Pillow Block

Type SSEPB Super Smart Ball Bushing Pillow Block

Type SPTWN Super Plus Ball Bushing Twin Pillow Block Type SSETWN Super Smart Ball Bushing Twin Pillow Block

Access for

Lubrication M6 x 1 (2 Plcs.)

N2 H8

N2

₹H8

N

## End Support Linear Guide 1NA Components: 1

- 2 Super Smart Ball Bushing\* pillow blocks or 1 Super Smart Ball Bushing twin pillow block.
- 1 60 Case LinearRace shaft.

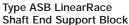
### Specifying a Thomson Linear Guide:

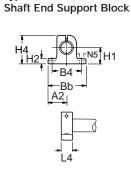
1. Determine the proper Linear Guide for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number.

### Part Numbering System

1NA-M	12-NN	NO L600
Linear Guide		Linear Guide
Designation 🚽		Length
Nominal Diamete	r 🗆 📔	

Type of Bearing Block -Type of Support





Type SB LinearRace

Type SPPB a	ind SS	SEPB	Pillo	N Blo	ocks					(Dir	nensi	ons in	mm)	Type SPTWN an	d SSE	TWN	Pillo	ow Bl	ock	s	
Part Number	Nom. Dia.	L1	H8	H9	B1	B9	J	J1	J6	J7	N Dia.	N2	Mass kg	Part Number	Nom. Dia.	L2	J3	78	J9	Mass kg	
SPPB-M08-XS	8	32	15	28	17,5	35	25	20	15	19,5	3,3	M4	0,07	SPTWN-M08-XS	8	62	50	19,5	25	0,15	
SSEPB-M12-XS	12	39	18	35	21,5	43	32	23	18	23,0	4,3	M5	0,13	SFTWN-M08-XS         8         62         50         19,3         23         0           SSETWN-M12-XS         12         76         56         23,0         28         0							
SSEPB-M16-XS	16	43	22	42	26,5	53	40	26	22	25,0	5,3	M6	0,20	SSETWN-M16-XS	16	84	64	25,0	32	0,41	
SSEPB-M20-XS	20	54	25	50	30,0	60	45	32	25	30,5	6,6	M8	0,35	SSETWN-M20-XS	20	104	76	30,5	38	0,73	
SSEPB-M25-XS	25	67	30	60	39,0	78	60	40	30	37,0	8,4	M10	0,66	SSETWN-M25-XS	25	130	94	37,0	47	1,37	
SSEPB-M30-XS	30	79	35	70	43,5	87	68	45	35	43,0	8,4	M10	0,99	SSETWN-M30-XS	30	152	106	43,0	53	2,04	
SSEPB-M40-XS	40	91	45	90	54,0	108	86	58	45	49,0	10,5	M12	1,83	SSETWN-M40-XS	40	176	124	49,0	62	3,73	
Housing Material	Alumir	num All	oy Grey	Anodi	zed									Housing Material: A	luminur	n Alloy	y Gre	y Anoc	lized		

Housing Material: Aluminum Alloy Grey Anodized

Type ASB	Linea	rRace	e Shaf	t End	Suppo	rt Blo	ck				Type SE	3 Line	earRa	ace S	haft	End	Sup	port	Bloc	k	
Part	Nom.	A1	В	B3	H1	H3	L3	N3	N4	Mass	Part	Nom.	A2	B4	Bb	H1	H2	H4	L4	N5	Mass
Number	Dia.							Dia.		kg	Number	Dia.								Dia.	kg
ASB-M08-XS	8	16,0	32	22	15	28	18	3,5	M4	0,04	SB-M08-XS	8	16	25	32	15	5,2	27	10	4,5	0,03
ASB-M12-XS	12	21,5	43	30	20	36	20	5,3	M6	0,10	SB-M12-XS	12	21	32	42	20	5,5	35	12	5,5	0,06
ASB-M16-XS	16	26,5	53	38	25	43	24	6,6	M8	0,15	SB-M16-XS	16	25	40	50	25	6,5	42	16	5,5	0,11
ASB-M20-XS	20	30,0	60	42	30	51	30	8,4	M10	0,23	SB-M20-XS	20	30	45	60	30	8,0	50	20	5,5	0,21
ASB-M25-XS	25	39,0	78	56	35	61	38	10,5	M12	0,41	SB-M25-XS	25	37	60	74	35	9,0	58	25	6,6	0,35
ASB-M30-XS	30	43,5	87	64	40	71	40	10,5	M12	0,53	SB-M30-XS	30	42	68	84	40	10,0	68	28	9,0	0,52
ASB-M40-XS	40	54,0	108	82	50	88	48	13,5	M16	0,99	SB-M40-XS	40	54	86	108	50	12,0	86	32	11,0	0,92

End Support Material: Aluminum Alloy Grey Anodized

End Support Material: Iron

Dynamic Load Capacity	Matrix	(100	km travel)	Dynamic Load Capacity	v Matrix	(100	km travel)
Linear Guide Assembly Part No.	Dynamic Load Capacity (N) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Capacity (N)	Linear Guide Assembly Part No.	Dynamic Load Capacity (N) (Even Distribution)	Part No.	Pillow Block Dynamic Load Capacity (N)
1NA-M08-NMO 1NA-M08-NNO	INA-M08-NNO         620         SPPB-M08-XS		310	1NA-M08-PMO 1NA-M08-PNC	500	SPTWN-M08-XS	500
1NA-M12-NMO 1NA-M12-NNO	1300	SSEPB-M12-XS	650	1NA-M12-PMO 1NA-M12-PNC	1060	SSETWN-M12-XS	1060
1NA-M16-NMO 1NA-M16-NNO	4400	SSEPB-M16-XS	2200	1NA-M16-PMO 1NA-M16-PNC	4400	SSETWN-M16-XS	4400
1NA-M20-NMO 1NA-M20-NNO	8000	SSEPB-M20-XS	4000	1NA-M20-PMO 1NA-M20-PNC	8000	SSETWN-M20-XS	8000
1NA-M25-NMO 1NA-M25-NNO	13400	SSEPB-M25-XS	6700	1NA-M25-PMO 1NA-M25-PNC	13400	SSETWN-M25-XS	13400
1NA-M30-NMO 1NA-M30-NNO	16600	SSEPB-M30-XS	8300	1NA-M30-PMO 1NA-M30-PNC	16600	SSETWN-M30-XS	16600
1NA-M40-NMO 1NA-M40-NNO	27400	SSEPB-M40-XS	13700	1NA-M40-PMO 1NA-M40-PNC	27400	SSETWN-M40-XS	27400

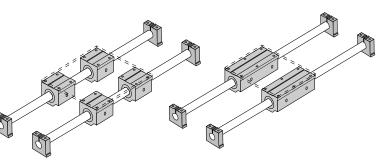
<sup>†</sup> Super Plus Ball Bushing<sup>\*</sup> bearings are used in 8 mm size pillow blocks.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

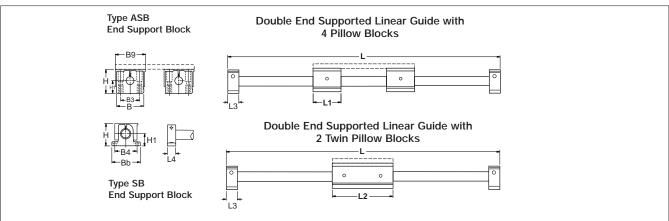




## End Support 1NB Linear Guide #9 End Supported, Industry Standard Dimension



## METRIC



End Support	Linear Guid	e 1NB	with 4 l	Pillow	Blocks							(Dimensio	ons in mm)
Part Nu	umber	Nom.	L1	L3	L4	Н	H1	В	Bb	B9	Pillow	Shaft S	upport
W/ Type ASB	W/ Type SB	Dia.									Block	Туре	Туре
Shaft	Shaft											ASB	SB
Supports	Supports												
1NB-M08-NMO	1NB-M08-NNO	8	32	18	10	30	15	32	32	35	SPPB-M08-XS	ASB-M08-XS	SB-M08-XS
1NB-M12-NMO	1NB-M12-NNO	12	39	20	12	38	20	43	42	43	SSEPB-M12-XS	ASB-M12-XS	SB-M12-XS
1NB-M16-NMO	1NB-M16-NNO	16	43	24	16	47	25	53	50	53	SSEPB-M16-XS	ASB-M16-XS	SB-M16-XS
1NB-M20-NMO	1NB-M20-NNO	20	54	30	20	55	30	60	60	60	SSEPB-M20-XS	ASB-M20-XS	SB-M20-XS
1NB-M25-NMO	1NB-M25-NNO	25	67	38	25	65	35	78	74	78	SSEPB-M25-XS	ASB-M25-XS	SB-M25-XS
1NB-M30-NMO	1NB-M30-NNO	30	79	40	28	75	40	87	84	87	SSEPB-M30-XS	ASB-M30-XS	SB-M30-XS
1NB-M40-NMO	1NB-M40-NNO	40	91	48	32	95	50	108	108	108	SSEPB-M40-XS	ASB-M40-XS	SB-M40-XS

End Support	Linear Guid	e 1NB	with 2 <sup>-</sup>	Twin P	illow Bl	ocks						(Dimensio	ons in mm)
Part Nu	umber	Nom.	L2	L3	L4	Н	H1	В	Bb	B9	Pillow	Shaft S	Support
W/ Type ASB	W/ Type SB	Dia.									Block	Туре	Туре
Shaft	Shaft											ASB	SB
Supports	Supports												
1NB-M08-PMO	1NB-M08-PNO	8	62	18	10	30	15	32	32	35	SPTWN-M08-XS	B-XS ASB-M08-XS SB-M08-XS	
1NB-M12-PMO	1NB-M12-PNO	12	76	20	12	38	20	43	42	43	SSETWN-M12-XS	ASB-M12-XS	SB-M12-XS
1NB-M16-PMO	1NB-M16-PNO	16	84	24	16	47	25	53	50	53	SSETWN-M16-XS	ASB-M16-XS	SB-M16-XS
1NB-M20-PMO	1NB-M20-PNO	20	104	30	20	55	30	60	60	60	SSETWN-M20-XS	ASB-M20-XS	SB-M20-XS
1NB-M25-PMO	1NB-M25-PNO	25	130	38	25	65	35	78	74	78	SSETWN-M25-XS	ASB-M25-XS	SB-M25-XS
1NB-M30-PMO	1NB-M30-PNO	30	152	40	28	75	40	87	84	87	SSETWN-M30-XS	ASB-M30-XS	SB-M30-XS
1NB-M40-PMO	1NB-M40-PNO	40	176	48	32	95	50	108	108	108	SSETWN-M40-XS	ASB-M40-XS	SB-M40-XS

### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for Deflection calculations.





## End Support Linear Guide **1NB Benefits:**

- Requires only one part number to specify entire linear guide.
- Available with 60 Case\* LinearRace\* shaft end support blocks in either light weight aluminum or rigid iron materials.
- Used in end supported applications when spanning or bridging a gap.

## End Support Linear Guide 1NB Components: <sup>†</sup>

- 4 Super Smart Ball Bushing\* pillow blocks or 2 Super Smart Ball Bushing twin pillow blocks.
- 2 60 Case LinearRace shafts.

### Specifying a Thomson Linear guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number.

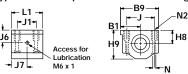
### Part Numbering System

1NB-M12-	-NMO L600
Linear Guide	Linear Guide
Designation	Length
Nominal Diameter	
vpe of Bearing Block -	Type of Support

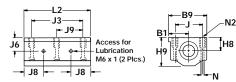
Type of Bearing Block

Type SB LinearRace

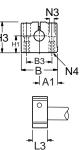
Type SPPB Super Plus Ball Bushing Pillow Block Type SSEPB Super Smart Ball Bushing Pillow Block

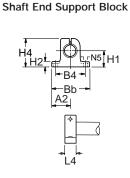


Type SPTWN Super Plus Ball Bushing Twin Pillow Block Type SSETWN Super Smart Ball Bushing Twin Pillow Block



### Type ASB LinearRace Shaft End Support Block





				cks					(Dir	mensio	ons in	mm)	Type SPTWN an	d SSE	TWN	Pillo	ow Bl	OCKS	5
lom. Dia.	L1	H8	H9	B1	B9	J	J1	J6	J7	N Dia.	N2	Mass kg	Part Number	Nom. Dia.	L2	J3	78	J9	Mass kg
8	32	15	28	17,5	35	25	20	15	19,5	3,3	M4	0,07	SPTWN-M08-XS	8	62	50	19,5	25	0,15
12	39	18	35	21,5	43	32	23	18	23,0	4,3	M5	0,13	SSETWN-M12-XS	12	76	56	23,0	28	0,27
16	43	22	42	26,5	53	40	26	22	25,0	5,3	M6	0,20	SSETWN-M16-XS	16	84	64	25,0	32	0,41
20	54	25	50	30,0	60	45	32	25	30,5	6,6	M8	0,35	SSETWN-M20-XS	20	104	76	30,5	38	0,73
25	67	30	60	39,0	78	60	40	30	37,0	8,4	M10	0,66	SSETWN-M25-XS	25	130	94	37,0	47	1,37
30	79	35	70	43,5	87	68	45	35	43,0	8,4	M10	0,99	SSETWN-M30-XS	30	152	106	43,0	53	2,04
40	91	45	90	54,0	108	86	58	45	49,0	10,5	M12	1,83	SSETWN-M40-XS	40	176	124	49,0	62	3,73
D 1 2 3 4	lia. 8 12 16 20 25 80 10	iia.           8         32           12         39           16         43           20         54           25         67           30         79           10         91	Na.         Image: Constraint of the second sec	Nia.     Image: Constraint of the state of t	Na.         Image: Constraint of the state of the s	Na.         Image: Constraint of the state of the s	Na.         Image: Constraint of the state of the s	Na.         Image: Constraint of the state of the s	Ma.         Image: Constraint of the state of the s	Na.         Image: Constraint of the state of the s	Na.         Image: Constraint of the constraint of t	Na.         Image: Constraint of the constraint of t	Nia.         Image: Normal System         Image: Normal System	Nia.         Image: Constraint of the state of the	Na.         Image: Constraint of the stress of the str	Nia.     Image: Number     Image: Number     Number     Dia.     kg     Number     Dia.       8     32     15     28     17,5     35     25     20     15     19,5     3,3     M4     0,07     SPTWN-M08-XS     8     62       12     39     18     35     21,5     43     32     23     18     23,0     4,3     M5     0,13     SSETWN-M12-XS     12     76       16     43     22     42     26,5     53     40     26     22     25,0     5,3     M6     0,20     SSETWN-M16-XS     16     84       20     54     25     50     30,0     60     45     32     25     30,5     6,6     M8     0,35     SSETWN-M16-XS     16     84       25     67     30     60     39,0     78     60     40     30     37,0     8,4     M10     0,66     SSETWN-M26-XS     25     130       30     79     35     70     43,5     87     68     45     35     43,0     8,4     M10     0,69     SSETWN-M30-XS     30     152       40     91     45     90     54,0     108     86	Name         Image         Image <thi< td=""><td>Name       Image       Image</td><td>Name       Image       Image</td></thi<>	Name       Image       Image	Name       Image       Image

Housing Material: Aluminum Alloy Grey Anodized

Housing Material: Aluminum Alloy Grey Anodized

Type ASB	Linea	arRace	e Shaf	t End	Suppo	rt Blo	ck				Type SE	3 Line	earRa	ice S	haft	End	Sup	port	Bloc	k	
Part	Nom.	A1	В	B3	H1	H3	L3	N3	N4	Mass	Part	Nom.	A2	B4	Bb	H1	H2	H4	L4	N5	Mass
Number	Dia.							Dia.		kg	Number	Dia.								Dia.	kg
ASB-M08-XS	8	16,0	32	22	15	28	18	3,5	M4	0,04	SB-M08-XS	8	16	25	32	15	5,2	27	10	4,5	0,03
ASB-M12-XS	12	21,5	43	30	20	36	20	5,3	M6	0,10	SB-M12-XS	12	21	32	42	20	5,5	35	12	5,5	0,06
ASB-M16-XS	16	26,5	53	38	25	43	24	6,6	M8	0,15	SB-M16-XS	16	25	40	50	25	6,5	42	16	5,5	0,11
ASB-M20-XS	20	30,0	60	42	30	51	30	8,4	M10	0,23	SB-M20-XS	20	30	45	60	30	8,0	50	20	5,5	0,21
ASB-M25-XS	25	39,0	78	56	35	61	38	10,5	M12	0,41	SB-M25-XS	25	37	60	74	35	9,0	58	25	6,6	0,35
ASB-M30-XS	30	43,5	87	64	40	71	40	10,5	M12	0,53	SB-M30-XS	30	42	68	84	40	10,0	68	28	9,0	0,52
ASB-M40-XS	40	54,0	108	82	50	88	48	13,5	M16	0,99	SB-M40-XS	40	54	86	108	50	12,0	86	32	11,0	0,92
End Support	Materia	I: Alumir	num Allo	by Grey A	Anodized						End Supp	ort Ma	terial: li	ron							

ibb

Dynamic Loa	d Capacity	Matrix	(100	km travel)	Dynamic Lo	ad Capacity	Matrix	(100	km travel)
Linear C Assen Part M	nbly	Dynamic Load Capacity (N) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Capacity (N)	Asse	<sup>-</sup> Guide embly t No.	Dynamic Load Cap Capacity (N) (Even Distribution)	Part No.	Pillow Block Dynamic Load Capacity (N)
1NB-M08-NMO 1	M08-NMO         1NB-M08-NNO         1240         SPPB-M08-XS		310	1NB-M08-PMO	1NB-M08-PNO	1000	SPTWN-M08-XS	500	
1NB-M12-NMO 1	1NB-M12-NNO			650	1NB-M12-PMO	1NB-M12-PNO	2120	SSETWN-M12-XS	1060
1NB-M16-NMO 1	1NB-M16-NNO	8800	SSEPB-M16-XS	2200	1NB-M16-PMO	1NB-M16-PNO	8800	SSETWN-M16-XS	4400
1NB-M20-NMO 1	1NB-M20-NNO	16000	SSEPB-M20-XS	4000	1NB-M20-PMO	1NB-M20-PNO	16000	SSETWN-M20-XS	8000
1NB-M25-NMO 1	1NB-M25-NNO	26800	SSEPB-M25-XS	6700	1NB-M25-PMO	1NB-M25-PNO	26800	SSETWN-M25-XS	13400
1NB-M30-NMO 1	1NB-M30-NNO	33200	SSEPB-M30-XS	8300	1NB-M30-PMO	1NB-M30-PNO	33200	SSETWN-M30-XS	16600
1NB-M40-NMO 1	1NB-M40-NNO	54800	SSEPB-M40-XS	13700	1NB-M40-PMO	1NB-M40-PNO	54800	SSETWN-M40-XS	27400

<sup>†</sup> Super Plus Ball Bushing<sup>\*</sup> bearings are used in 8 mm size pillow blocks.

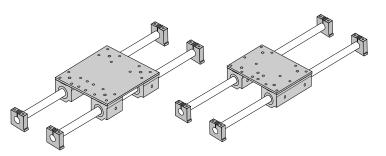
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

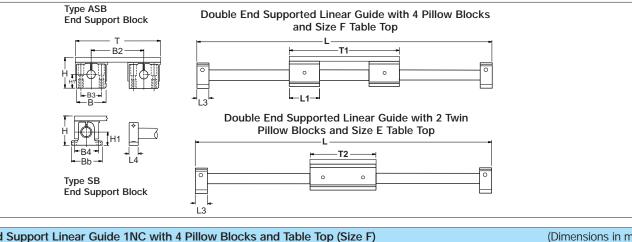




## End Support 1NC Linear Guide #9

with Table Top *End Supported, Industry Standard Dimension* METRIC





End Support	Linear Guid	e 1NC	with 4	4 Pillo	ow Blo	ocks a	and Ta	able T	op (S	ize F)					(Dimensi	ons in mm)
Part N	umber	Nom.	L1	L3	L4	Н	H1	В	Bb	B2	B9	Т	T1	Pillow	Shaft S	Support
W/ Type ASB	W/ Type SB	Dia.												Block	Туре	Туре
Shaft	Shaft														ASB	SB
Supports	Supports															
1NC-M08-NMF	1NC-M08-NNF	8	32	18	10	40	15	32	32	50	35	85	85	SPPB-M08-XS	ASB-M08-XS	SB-M08-XS
1NC-M12-NMF	1NC-M12-NNF	12	39	20	12	48	20	43	42	55	43	100	100	SSEPB-M12-XS	ASB-M12-XS	SB-M12-XS
1NC-M16-NMF	1NC-M16-NNF	16	43	24	16	60	25	53	50	70	53	125	125	SSEPB-M16-XS	ASB-M16-XS	SB-M16-XS
1NC-M20-NMF	1NC-M20-NNF	20	54	30	20	71	30	60	60	110	60	175	175	SSEPB-M20-XS	ASB-M20-XS	SB-M20-XS
1NC-M25-NMF	1NC-M25-NNF	25	67	38	25	85	35	78	74	140	78	225	225	SSEPB-M25-XS	ASB-M25-XS	SB-M25-XS
1NC-M30-NMF	1NC-M30-NNF	30	79	40	28	95	40	87	84	180	87	275	275	SSEPB-M30-XS	ASB-M30-XS	SB-M30-XS
1NC-M40-NMF	1NC-M40-NNF	40	91	48	32	120	50	108	108	210	108	325	325	SSEPB-M40-XS	ASB-M40-XS	SB-M40-XS

End Support	Linear Guide	e 1NC	with	2 Twin	Pillov	v Bloc	ks an	d Table	Top (	Size E	)			(Dimensio	on in mm)
Part N	umber	Nom.	L3	L4	Н	H1	В	Bb	B2	B9	Т	T2	Pillow	Shaft S	upport
W/ Type ASB	W/ Type SB	Dia.											Block	Туре	Туре
Shaft	Shaft													ASB	SB
Supports	Supports														
1NC-M08-PME	1NC-M08-PNE	8	18	10	40	15	32	32	50	35	85	62	SPTWN-M08-XS	(S ASB-M0B8-XS SB-M	
1NC-M12-PME	1NC-M12-PNE	12	20	12	48	20	43	43	55	43	100	76	SSETWN-M12-XS	ASB-M12-XS	SB-M12-XS
1NC-M16-PME	1NC-M16-PNE	16	24	16	60	25	53	53	70	53	125	84	SSETWN-M16-XS	ASB-M16-XS	SB-M16-XS
1NC-M20-PME	1NC-M20-PNE	20	30	20	71	30	60	60	110	60	175	104	SSETWN-M20-XS	ASB-M20-XS	SB-M20-XS
1NC-M25-PME	1NC-M25-PNE	25	38	25	85	35	78	74	140	78	225	130	SSETWN-M25-XS	ASB-M25-XS	SB-M25-XS
1NC-M30-PME	1NC-M30-PNE	30	40	28	95	40	87	84	180	87	275	152	SSETWN-M30-XS	ASB-M30-XS	SB-M30-XS
1NC-M40-PME	1NC-M40-PNE	40	48	32	120	50	108	108	210	108	325	176	SSETWN-M40-XS	ASB-M40-XS	SB-M40-XS

Dynamic Loa	ad Capacity	Matrix	(100	km travel)	Dynamic Lo	ad Capacity	Matrix	(100	km travel)
	Guide mbly : No.	Dynamic Load Capacity (N) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Capacity (N)	Asse	Guide embly t No.	Dynamic Load Cap Capacity (N) (Even Distribution)		Pillow Block Dynamic Load Capacity (N)
1NC-M08-NMF	1NC-M08-NNF	1240	SPPB-M08-XS	310	1NC-M08-PME	1NC-M08-PNE	1000	SPTWN-M08-XS	500
1NC-M12-NMF	1NC-M12-NNF	2600	SSEPB-M12-XS	650	1NC-M12-PME	1NC-M12-PNE	2120	SSETWN-M12-XS	1060
1NC-M16-NMF	1NC-M16-NNF	8800	SSEPB-M16-XS	2200	1NC-M16-PME	1NC-M16-PNE	8800	SSETWN-M16-XS	4400
1NC-M20-NMF	1NC-M20-NNF	16000	SSEPB-M20-XS	4000	1NC-M20-PME	1NC-M20-PNE	16000	SSETWN-M20-XS	8000
1NC-M25-NMF	1NC-M25-NNF	26800	SSEPB-M25-XS	6700	1NC-M25-PME	1NC-M25-PNE	26800	SSETWN-M25-XS	13400
1NC-M30-NMF	1NC-M30-NNF	33200	SSEPB-M30-XS	8300	1NC-M30-PME	1NC-M30-PNE	33200	SSETWN-M30-XS	16600
1NC-M40-NMF	1NC-M40-NNF	54800	SSEPB-M40-XS	13700	1NC-M40-PME	1NC-M40-PNE	54800	SSETWN-M40-XS	27400



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.

Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



## **End Support Linear Guide 1NC Benefits:**

- Includes table top with standard tapped holes for quick and easy mounting of the work piece.
- Includes Ball Screw Assembly attachment holes for ease of assembly and actuation.
- Available with 60 Case\* LinearRace\* shaft end support blocks in either light weight aluminum or rigid iron materials.

## End Support Linear Guide 1NC Components: 1

- 4 Super Smart Ball Bushing\* pillow blocks or 2 Super Smart Ball Bushing twin pillow blocks.
- 2 60 Case LinearRace shafts.
- 1 mounting table top with work piece and Ball Screw Assembly attachment holes.

### Specifying a Thomson Linear guide:

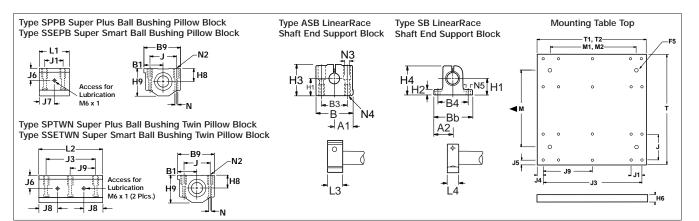
1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number.

#### Part Numbering System



Nominal Diameter Type of Bearing Block -

 Length - Type of Table Top L Type of Support



Type SPPB a	nd SS	SEPB	Pillo	v Blo	cks					(Dii	mensi	ons in	ı mm)	Type SPTWN an	d SSE	TWN	Pillo	ow Bl	ock	s
Part Number	Nom. Dia.	L1	H8	H9	B1	B9	J	N2	Mass kg	Part Number	Nom. Dia.	L2	J3	78	J9	Mass kg				
SPPB-M08-XS	8	32	15	28	17,5	35	25	20	15	19,5	3,3	M4	0,07	SPTWN-M08-XS	8	62	50	19,5	25	0,15
SSEPB-M12-XS	12	39	18	35	21,5	43	32	23	18	23,0	4,3	M5	0,13	SSETWN-M12-XS	12	76	56	23,0	28	0,27
SSEPB-M16-XS	16	43	22	42	26,5	53	40	26	22	25,0	5,3	M6	0,20	SSETWN-M16-XS	16	84	64	25,0	32	0,41
SSEPB-M20-XS	20	54	25	50	30,0	60	45	32	25	30,5	6,6	M8	0,35	SSETWN-M20-XS	20	104	76	30,5	38	0,73
SSEPB-M25-XS	25	67	30	60	39,0	78	60	40	30	37,0	8,4	M10	0,66	SSETWN-M25-XS	25	130	94	37,0	47	1,37
SSEPB-M30-XS	30	79	35	70	43,5	87	68	45	35	43,0	8,4	M10	0,99	SSETWN-M30-XS	30	152	106	43,0	53	2,04
SSEPB-M40-XS	40	91	45	90	54,0	108	86	58	45	49,0	10,5	M12	1,83	SSETWN-M40-XS	40	176	124	49,0	62	3,73

Housing Material: Aluminum Alloy Grey Anodized

Housing Material: Aluminum Alloy Grey Anodized

Linea	rRace	e Shaf	t End	Suppo	rt Blo	ck				Type SB LinearRace Shaft End Support Block										
Nom.	A1	В	B3	H1	H3	L3	N3	N4	Mass	Part	Nom.	A2	B4	Bb	H1	H2	H4	L4	N5	Mass
Dia.							Dia.		kg	Number	Dia.								Dia.	kg
8	16,0	32	22	15	28	18	3,5	M4	0,04	SB-M08-XS	8	16	25	32	15	5,2	27	10	4,5	0,03
12	21,5	43	30	20	36	20	5,3	M6	0,10	SB-M12-XS	12	21	32	42	20	5,5	35	12	5,5	0,06
16	26,5	53	38	25	43	24	6,6	M8	0,15	SB-M16-XS	16	25	40	50	25	6,5	42	16	5,5	0,11
20	30,0	60	42	30	51	30	8,4	M10	0,23	SB-M20-XS	20	30	45	60	30	8,0	50	20	5,5	0,21
25	39,0	78	56	35	61	38	10,5	M12	0,41	SB-M25-XS	25	37	60	74	35	9,0	58	25	6,6	0,35
30	43,5	87	64	40	71	40	10,5	M12	0,53	SB-M30-XS	30	42	68	84	40	10,0	68	28	9,0	0,52
40	54,0	108	82	50	88	48	13,5	M16	0,99	SB-M40-XS	40	54	86	108	50	12,0	86	32	11,0	0,92
	Nom. Dia. 8 12 16 20 25 30	Nom. Dia.A1816,01221,51626,52030,02539,03043,5	Nom. Dia.         A1         B           8         16,0         32           12         21,5         43           16         26,5         53           20         30,0         60           25         39,0         78           30         43,5         87	Nom. Dia.         A1         B         B3           8         16,0         32         22           12         21,5         43         30           16         26,5         53         38           20         30,0         60         42           25         39,0         78         56           30         43,5         87         64	Nom. Dia.         A1         B         B3         H1           8         16,0         32         22         15           12         21,5         43         30         20           16         26,5         53         38         25           20         30,0         60         42         30           25         39,0         78         56         35           30         43,5         87         64         40	Nom. Dia.         A1         B         B3         H1         H3           8         16,0         32         22         15         28           12         21,5         43         30         20         36           16         26,5         53         38         25         43           20         30,0         60         42         30         51           25         39,0         78         56         35         61           30         43,5         87         64         40         71	Dia.         Image: Constraint of the system         Image: Constand of the system	Nom. Dia.         A1         B         B3         H1         H3         L3         N3 Dia.           8         16.0         32         22         15         28         18         3.5           12         21.5         43         30         20         36         20         5.3           16         26.5         53         38         25         43         24         6.6           20         30.0         60         42         30         51         30         8.4           25         39.0         78         56         35         61         38         10.5           30         43.5         87         64         40         71         40         10.5	Nom. Dia.         A1         B         B3         H1         H3         L3         N3         N4           B         16,0         32         22         15         28         18         3,5         M4           12         21,5         43         30         20         36         20         5,3         M6           16         26,5         53         38         25         43         24         6,6         M8           20         30,0         60         42         30         51         30         8,4         M10           25         39,0         78         56         35         61         38         10,5         M12           30         43,5         87         64         40         71         40         10,5         M12	Nom. Dia.         A1         B         B3         H1         H3         L3         N3         N4         Mass kg           8         16,0         32         22         15         28         18         3,5         M4         0,04           12         21,5         43         30         20         36         20         5,3         M6         0,10           16         26,5         53         38         25         43         24         6,6         M8         0,15           20         30,0         60         42         30         51         30         8,4         M10         0,23           25         39,0         78         56         35         61         38         10,5         M12         0,41           30         43,5         87         64         40         71         40         10,5         M12         0,53	Nom.         A1         B         B3         H1         H3         L3         N3         N4         Mass kg         Part Number           8         16,0         32         22         15         28         18         3,5         M4         0,04         SB-M08-XS           12         21,5         43         30         20         36         20         5,3         M6         0,10         SB-M08-XS           16         26,5         53         38         25         43         24         6,6         M8         0,15         SB-M16-XS           20         30,0         60         42         30         51         30         8,4         M10         0,23         SB-M20-XS           25         39,0         78         56         35         61         38         10,5         M12         0,41         SB-M25-XS           30         43,5         87         64         40         71         40         10,5         M12         0,53         SB-M30-XS	Nom.         A1         B         B3         H1         H3         L3         N3         N4         Mass kg         Part Number         Nom. Dia.           8         16,0         32         22         15         28         18         3,5         M4         0,04         SB-M08-XS         8           12         21,5         43         30         20         36         20         5,3         M6         0,10         SB-M08-XS         12           16         26,5         53         38         25         43         24         6,6         M8         0,15         SB-M16-XS         16           20         30,0         60         42         30         51         30         8,4         M10         0,23         SB-M20-XS         20           25         39,0         78         56         35         61         38         10,5         M12         0,41         SB-M25-XS         25           30         43,5         87         64         40         71         40         10,5         M12         0,53         SB-M30-XS         30	Nom.         A1         B         B3         H1         H3         L3         N3         N4         Mass kg         Part Number         Nom.         A2           8         16,0         32         22         15         28         18         3,5         M4         0,04         SB-M08-xs         8         16           12         21,5         43         30         20         36         20         5,3         M6         0,10         SB-M12-xs         12         21           16         26,5         53         38         25         43         24         6,6         M8         0,15         SB-M16-xs         16         25           20         30,0         60         42         30         51         30         8,4         M10         0,23         SB-M20-xs         20         30           25         39,0         78         56         35         61         38         10,5         M12         0,41         SB-M25-xs         25         37           30         43,5         87         64         40         71         40         10,5         M12         0,53         SB-M30-xs         30         42	Nom. Dia.         A1         B         B3         H1         H3         L3         N3         N4         Mass Nu         Part Number         Nom. Dia.         A2         B4           B         16.0         32         22         15         28         18         3,5         M4         0,04         SB-M08-xs         8         16         25           12         21,5         43         30         20         36         20         5,3         M6         0,10         SB-M12-xs         12         21         32           16         26,5         53         38         25         43         24         6,6         M8         0,15         SB-M16-xs         16         25         40           20         30,0         60         42         30         51         30         8,4         M10         0,23         SB-M20-xs         20         30         45           25         39,0         78         56         35         61         38         10,5         M12         0,41         SB-M25-xs         25         37         60           30         43,5         87         64         40         71         40 <td< td=""><td>Nom. Dia.         A1         B         B3         H1         H3         L3         N3         N4         Mass kg         Part Number         Nom. Dia.         A2         B4         B5           8         16,0         32         22         15         28         18         3,5         M4         0,04         SB-M08-xs         8         16         25         32           12         21,5         43         30         20         36         20         5,3         M6         0,10         SB-M08-xs         12         21         32         42           16         26,5         53         38         25         43         24         6,6         M8         0,15         SB-M16-xs         16         25         40         50           20         30,0         60         42         30         51         30         8,4         M10         0,23         SB-M20-xs         20         30         45         60           25         39,0         78         56         35         61         38         10,5         M12         0,41         SB-M30-xs         30         42         68         84           30         4</td><td>Nom.         A1         B         B3         H1         H3         L3         N3         N4         Mass kg         Part Number         Nom.         A2         B4         B4         Bb         H1           8         16,0         32         22         15         28         18         3,5         M4         0,04         SB-M08-xs         8         16         25         32         15           12         21,5         43         30         20         36         20         5,3         M6         0,10         SB-M08-xs         8         16         25         32         15           12         21,5         43         30         20         36         20         5,3         M6         0,10         SB-M08-xs         8         16         25         32         15           16         26,5         53         38         25         43         24         6,6         M8         0,15         SB-M16-xs         16         25         40         50         25           20         30,0         60         42         30         51         30         8,4         M10         0,23         SB-M20-xs         20</td><td>Nom. Dia.         A1         B         B3         H1         H3         L3         N3 Dia.         N4         Mass kg         Part Number         Nom. Dia.         A2         B4         B4         B4         H2           8         16,0         32         22         15         28         18         3,5         M4         0,04         SB-M08-XS         8         16         25         32         15         5,2           12         21,5         43         30         20         36         20         5,3         M6         0,10         SB-M08-XS         8         16         25         32         15         5,2           16         26,5         53         38         25         43         24         6,6         M8         0,15         SB-M16-XS         16         25         40         50         25         6,5           20         30,0         60         42         30         51         30         8,4         M10         0,23         SB-M26-XS         20         30         45         60         30         8,0           25         39,0         78         56         35         61         38         10,5</td><td>Nom. Dia.         A1         B         B3         H1         H3         L3         N3 Dia.         N4 Dia.         Mass kg         Part Number         Nom. Dia.         A2         B4         Bb         H1         H2         H4           B4         10.0         32         22         15         28         18         3.5         M4         0.04         SB-M08-xs         8         16         25         32         15         5.2         27           12         21.5         43         30         20         36         20         5.3         M6         0.10         SB-M08-xs         8         16         25         32         15         5.2         27           12         21.5         43         30         20         36         20         5.3         M6         0.10         SB-M08-xs         8         16         25         32         15         5.2         27           16         26.5         53         38         25         43         24         6.6         M8         0.15         SB-M16-xs         16         25         40         50         25         6.5         42           20         30.0</td><td>Nom. Dia.         A1         B         B3         H1         H3         L3         N3         N4         Mass kg         Part Number         Nom. Dia.         A2         B4         Bb         H1         H2         H4         L4           B4         16.0         32         22         15         28         18         3.5         M4         0.04         SB-M08-xs         8         16         25         32         15         5.2         27         10           12         21.5         43         30         20         36         20         5.3         M6         0.10         SB-M08-xs         8         16         25         32         15         5.2         27         10           12         21.5         43         30         20         36         20         5.3         M6         0.10         SB-M12-xs         12         21         32         42         20         5.5         35         12           16         26.5         53         38         25         43         24         6.6         M8         0.15         SB-M16-xs         16         25         40         50         25         6.5         42</td><td>Nom. Dia.         A1         B         B3         H1         H3         L3         N3         N4         Mass kg         Part Number         Nom. Dia.         A2         B4         B5         H1         H2         H4         L4         N5 Dia.           8         16.0         32         22         15         28         18         3.5         M4         0.04         SB-M08-xs         8         16         25         32         15         5.2         27         10         4.5           12         21.5         43         30         20         36         20         5.3         M6         0.10         SB-M12-xs         12         21         32         42         20         5.5         35         12         5.5           16         26.5         53         38         25         43         24         6.6         M8         0.15         SB-M16-xs         16         25         40         50         25         6.5         42         16         5.5           20         30.0         60         42         30         51         30         8.4         M10         0.23         SB-M20-xs         20         30         45</td></td<>	Nom. Dia.         A1         B         B3         H1         H3         L3         N3         N4         Mass kg         Part Number         Nom. Dia.         A2         B4         B5           8         16,0         32         22         15         28         18         3,5         M4         0,04         SB-M08-xs         8         16         25         32           12         21,5         43         30         20         36         20         5,3         M6         0,10         SB-M08-xs         12         21         32         42           16         26,5         53         38         25         43         24         6,6         M8         0,15         SB-M16-xs         16         25         40         50           20         30,0         60         42         30         51         30         8,4         M10         0,23         SB-M20-xs         20         30         45         60           25         39,0         78         56         35         61         38         10,5         M12         0,41         SB-M30-xs         30         42         68         84           30         4	Nom.         A1         B         B3         H1         H3         L3         N3         N4         Mass kg         Part Number         Nom.         A2         B4         B4         Bb         H1           8         16,0         32         22         15         28         18         3,5         M4         0,04         SB-M08-xs         8         16         25         32         15           12         21,5         43         30         20         36         20         5,3         M6         0,10         SB-M08-xs         8         16         25         32         15           12         21,5         43         30         20         36         20         5,3         M6         0,10         SB-M08-xs         8         16         25         32         15           16         26,5         53         38         25         43         24         6,6         M8         0,15         SB-M16-xs         16         25         40         50         25           20         30,0         60         42         30         51         30         8,4         M10         0,23         SB-M20-xs         20	Nom. Dia.         A1         B         B3         H1         H3         L3         N3 Dia.         N4         Mass kg         Part Number         Nom. Dia.         A2         B4         B4         B4         H2           8         16,0         32         22         15         28         18         3,5         M4         0,04         SB-M08-XS         8         16         25         32         15         5,2           12         21,5         43         30         20         36         20         5,3         M6         0,10         SB-M08-XS         8         16         25         32         15         5,2           16         26,5         53         38         25         43         24         6,6         M8         0,15         SB-M16-XS         16         25         40         50         25         6,5           20         30,0         60         42         30         51         30         8,4         M10         0,23         SB-M26-XS         20         30         45         60         30         8,0           25         39,0         78         56         35         61         38         10,5	Nom. Dia.         A1         B         B3         H1         H3         L3         N3 Dia.         N4 Dia.         Mass kg         Part Number         Nom. Dia.         A2         B4         Bb         H1         H2         H4           B4         10.0         32         22         15         28         18         3.5         M4         0.04         SB-M08-xs         8         16         25         32         15         5.2         27           12         21.5         43         30         20         36         20         5.3         M6         0.10         SB-M08-xs         8         16         25         32         15         5.2         27           12         21.5         43         30         20         36         20         5.3         M6         0.10         SB-M08-xs         8         16         25         32         15         5.2         27           16         26.5         53         38         25         43         24         6.6         M8         0.15         SB-M16-xs         16         25         40         50         25         6.5         42           20         30.0	Nom. Dia.         A1         B         B3         H1         H3         L3         N3         N4         Mass kg         Part Number         Nom. Dia.         A2         B4         Bb         H1         H2         H4         L4           B4         16.0         32         22         15         28         18         3.5         M4         0.04         SB-M08-xs         8         16         25         32         15         5.2         27         10           12         21.5         43         30         20         36         20         5.3         M6         0.10         SB-M08-xs         8         16         25         32         15         5.2         27         10           12         21.5         43         30         20         36         20         5.3         M6         0.10         SB-M12-xs         12         21         32         42         20         5.5         35         12           16         26.5         53         38         25         43         24         6.6         M8         0.15         SB-M16-xs         16         25         40         50         25         6.5         42	Nom. Dia.         A1         B         B3         H1         H3         L3         N3         N4         Mass kg         Part Number         Nom. Dia.         A2         B4         B5         H1         H2         H4         L4         N5 Dia.           8         16.0         32         22         15         28         18         3.5         M4         0.04         SB-M08-xs         8         16         25         32         15         5.2         27         10         4.5           12         21.5         43         30         20         36         20         5.3         M6         0.10         SB-M12-xs         12         21         32         42         20         5.5         35         12         5.5           16         26.5         53         38         25         43         24         6.6         M8         0.15         SB-M16-xs         16         25         40         50         25         6.5         42         16         5.5           20         30.0         60         42         30         51         30         8.4         M10         0.23         SB-M20-xs         20         30         45

End Support Material: Aluminum Alloy Grey Anodized

End Support Material: Iron

Mounting	g Table	Тор												(Dimen	sions i	n mm)
System		All	l Table To	ps			Tab	le Top Siz	ze F			Т	able To	p Size <b>E</b>		
	Т	М	J	H6	F5 <sup>(2)</sup>	T1	J1	J4	J5	M1	T2	J3	J4	J5	J9	M2
1NC-M08	85	50	25	10	M6	85	20	6,0	5,0	50	62	50	6	5,0	25	35
1NC-M12	100	55	32	10	M6	100	23	8,0	6,5	55	76	56	10	6,5	28	40
1NC-M16	125	70	40	13	M6	125	26	10,0	7,5	70	84	64	10	7,5	32	45
1NC-M20	175	110	45	16	M8	175	32	11,0	10,0	110	104	76	14	10,0	38	55
1NC-M25	225	140	60	20	M8	225	40	13,5	12,5	140	130	94	18	12,5	47	65
1NC-M30	275	180	68	20	M8	275	45	17,0	13,5	180	152	106	23	13,5	53	75
1NC-M40	325	210	86	25	M10	325	58	16,5	14,5	210	176	124	26	14,5	62	85

Material: Aluminum Alloy Grey Anodized

<sup>(2)</sup> Customer Mounting hole.

<sup>†</sup> Super Plus Ball Bushing<sup>\*</sup> bearings are used in 8 mm size pillow blocks.





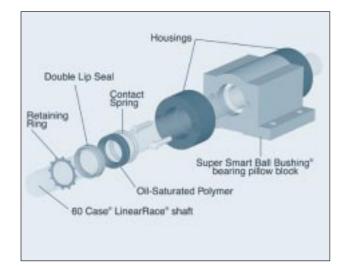
## **End Support Linear Ball Guide Accessories**



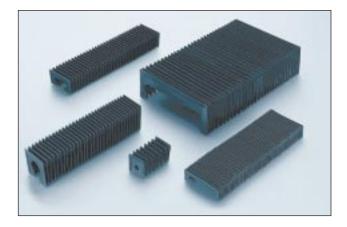
## -LL Self-Lubricating Option<sup>1</sup>

The new LL Option provides maintenancefree operation and enhanced bearing protection.

- Eliminates the need for expensive lubrication system in most applications
- Increases effective bearing life by increasing protection from contamination
- Environmentally friendly
- NOTE: Carriage drag with the -LL option will be approximately 2x the seal drag.
- <sup>±</sup> See page 210 for technical data.



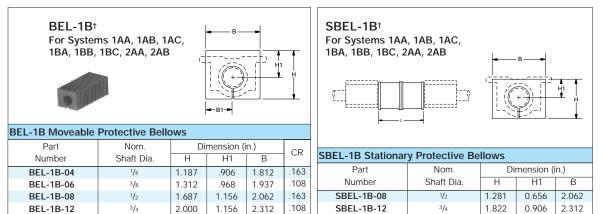
## **Bellows (Way Covers) Option**





This illustration describes the proper usage for stationary and moveable bellows for System 1AA.

Stationary Protective Bellows are designed to fit between two fixed pillow blocks and underneath the profile of the carrriage mounting top.



.163

.108

SBEL-1B-16

SBEL-1B-24

1

11/2

2.281

3.031

<sup>†</sup> Each moveable bellows comes with 1 section of bellows and 2 pairs of Velcro® Fasteners.

2.625

3.125



BEL-1B-16

BEL-1B-24

The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Trademark of Thomson industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

1.281

1.531

2.375

3.062

1

**1**<sup>1</sup>/<sub>2</sub>



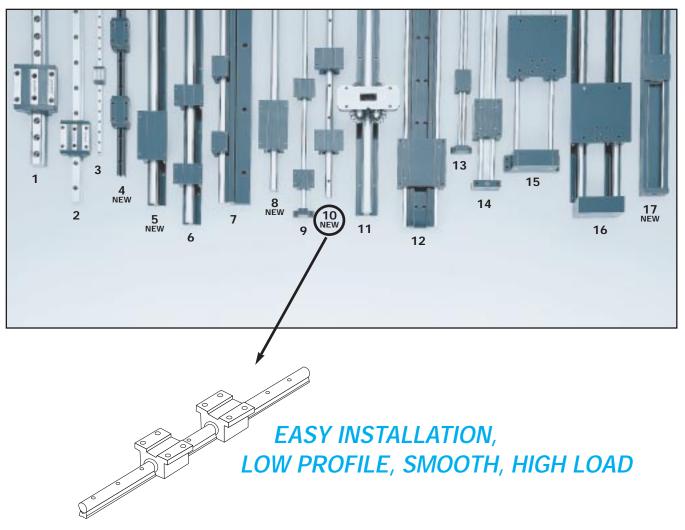
1.031

1.531

2.625

3.125

## Smart Rail Linear Ball Guides



## Smart Rail\* Linear Ball Guides Offer:

- Bolt down from the top mounting for quick and easy installation
- Increased life within the same envelope. RoundRail\* linear guides feature the new patented Super Smart Ball Bushing\* bearings for up to 216X the life or 6X the load capacity of conventional bearings
- Cost savings: save time and money preparing your mounting surfaces before bolting down RoundRail linear guides
- Maximum performance. Fully supported for maximum down load applications without concerns for shaft deflection

- The RoundRail Advantage\*. The inherent self-aligning-in-all-directions design of the Super Smart Ball Bushing bearing allows for ultra smooth travel when mounted to wider toleranced prepared surfaces
- Unlimited travel lengths without concerns for machined reference edges or butt joint alignment
- The Super Smart Ball Bushing bearing... the most technologically advanced and most robust linear bearing in the world
- Corrosion resistant versions for maximum performance in harsh environments.

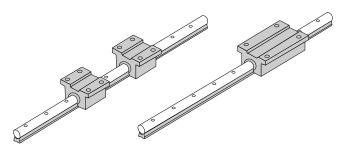
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



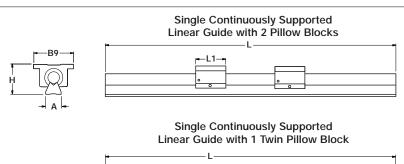
Page 123

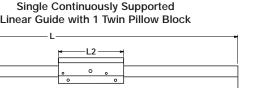
#10

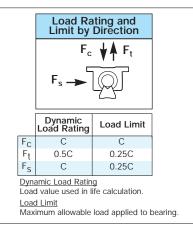
## Smart Rail\* 1FA Linear Guide #10 Low Profile, Easy to Install



## INCH







Smart Rail Line	ear Guide 1FA	Single Continu	uously Support	ed with 2 Pillov	v Blocks	(Dime	nsions in inches)
Part Number	Nom.† Dia.	L1	Н	A	В9	Pillow Block	Shaft Support Rail Assembly
1FA-12-FBO	.75	1.88	1.687	.51	2.75	SSUPBO-12-XS	LSRA-12-XS
1FA-16-FBO	1.00	2.63	2.187	.69	3.25	SSUPBO-16-XS	LSRA-16-XS
1FA-20-FBO	1.25	3.38	2.687	.78	4.00	SSUPBO-20-XS	LSRA-20-XS
1FA-24-FBO	1.50	3.75	3.125	.93	4.75	SSUPBO-24-XS	LSRA-24-XS

Smart Rail Line	ar Guide 1	FA Single Cor	ntinuously Su	pported with	1 Twin Pillo	w Block	(Dimei	nsions in inches)
Part	Nom.†	L2	Н	А	B9	Maximum	Pillow	Shaft
Number	Dia.					Stroke	Block	Support
						Length		Rail
								Assembly
1FA-12-HBO	.75	4.5	1.687	.51	2.75	L-(4.5)	SSUTWNO-12-XS	LSRA-12-XS
1FA-16-HBO	1.00	6.0	2.287	.69	3.25	L-(6.0)	SSUTWNO-16-XS	LSRA-16-XS
1FA-20-HBO	1.25	7.5	2.687	.78	4.00	L-(7.5)	SSUTWNO-12-XS	LSRA-20-XS
1FA-24-HBO	1.50	9.0	3.125	.93	4.75	L-(9.0)	SSUTWNO-24-XS	LSRA-24-XS

<sup>†</sup>.625" diameter Smart Rail Linear Guide also available, contact factory for specifications.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.





## Smart Rail\* Linear Guide 1FA Benefits:

- Requires only one part number to specify the entire linear guide.
- More mounting flexibility through bolt down from the top access.
- Used in continuously supported applications when rigidity is required.
- Lower overall linear guide height.

# Smart Rail Linear Guide 1FA Components:

- 2 Super Smart Ball Bushing\* open type pillow blocks or 1 Super Smart Ball Bushing open twin pillow block.
- 1 60 Case\* LinearRace\* shaft Support Rail Assembly.

#### Specifying this Thomson Linear Guide:

 Determine the proper Linear Guide for your load and life requirements.
 Select the part number.
 Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

### Part Numbering System

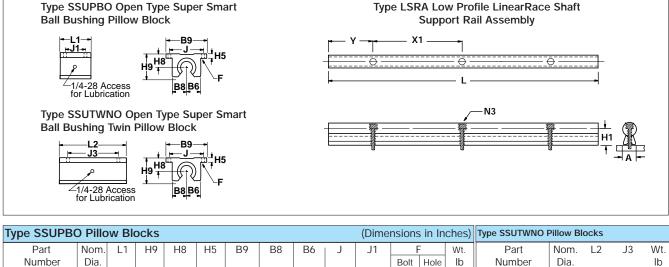
 IFA-12-FBO L24

 Linear Guide

 Designation

 Nominal Diameter

 Type of Bearing Block



туре эзоры			UCKS							(Dime	11510113	5	cnes)	Type SSUTWIND I		UCKS		
Part	Nom.	L1	H9	H8	H5	B9	B8	B6	IJ	J1	ŀ	-	Wt.	Part	Nom.	L2	J3	Wt.
Number	Dia.										Bolt	Hole	lb	Number	Dia.			lb
SSUPBO-12-XS	.75	1.88	1.56	.937	.31	2.75	1.00	.94	2.38	1.25	#8	.19	.51	SSUTWNO-12-XS	.75	4.5	3.5	1.02
SSUPBO-16-XS	1.00	2.63	2.00	1.187	.38	3.25	1.25	1.19	2.88	1.75	#10	.22	1.03	SSUTWNO-16-XS	1.00	6.0	4.5	2.06
SSUPBO-20-XS	1.25	3.38	2.56	1.500	.43	4.00	1.63	1.50	3.50	2.00	#10	.22	2.15	SSUTWNO-20-XS	1.25	7.5	5.5	4.30
SSUPBO-24-XS	1.50	3.75	2.94	1.750	.50	4.75	1.88	1.75	4.12	2.50	<sup>1</sup> /4	.25	3.29	SSUTWNO-24-XS	1.50	9.0	6.5	6.88
Llouing Motorial	Alumation			Anodia										Llouoing Motoriol	Alumation		Diaak	

Housing Material: Aluminum Alloy Black Anodized

Housing Material: Aluminum Alloy Black Anodized

Type LSRA Lo	ow Profile Linea	arRace Shaft Su	pport Rail Asse	mbly		(Dimen	sions in Inches)
Part Number	Nom. Dia.	H1	A	X1	Y	N3 <sup>(1)</sup>	Wt. Ib/ft
LSRA-12-XS	.75	.750	.51	3	1.5	#6 - 32 x 1 <sup>1</sup> /4	2.09
LSRA-16-XS	1.00	1.000	.69	3	1.5	#10 - 32 x 1 <sup>1</sup> / <sub>2</sub>	3.67
LSRA-20-XS	1.25	1.187	.78	3	1.5	<sup>5</sup> /₁₀ - 18 x 2	5.86
LSRA-24-XS	1.50	1.375	.93	4	2	<sup>3</sup> /8 - 16 x 2 <sup>1</sup> /2	7.68

LinearRace Shaft Support Rail Material: Black Oxided Steel

<sup>(1)</sup> Each system is shipped with attachment screws as noted by N3 and cap plugs. If a non-standard screw length is required, it must be user supplied.

Dynamic Loa	ad Rating (C) Ma	trix (4 million	n inches travel)
Linear Guide Assembly Part No.	Dynamic Load Rating, C (lb <sub>f</sub> ) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (lb <sub>f</sub> )
1FA-12-FBO	1800	SSUPBO-12-XS	900
1FA-16-FBO	3000	SSUPBO-16-XS	1500
1FA-20-FBO	3730	SSUPBO-20-XS	1865
1FA-24-FBO	6160	SSUPBO-24-XS	3080
1FA-12-HBO	1800	SSUTWNO-12-XS	1800
1FA-16-HBO	3020	SSUTWNO-16-XS	3020
1FA-20-HBO	3730	SSUTWNO-12-XS	3730
1FA-24-HBO	6160	SSUTWNO-24-XS	6160

Maximum length of LinearRace Shaft Support Rail is 144 inches. If longer continuous one-piece LinearRace Shaft Support Rails are required, contact the Thomson Linear Guides Application Engineering department.

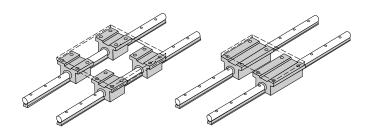
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



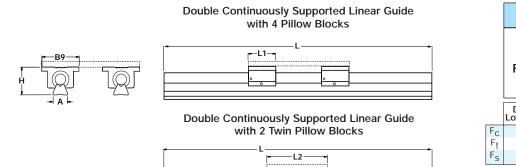


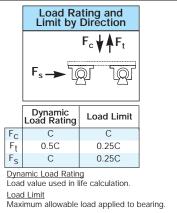
## Smart Rail\* 1FB Linear Guide #10

Linear Guide # 10 Low Profile, Easy to Install



## INCH





Smart Rail Line	ear Guide 1FB I	Double Continu	ously Supporte	ed with 4 Pillow	Blocks	(Dimen:	sions in inches)
Part	Nom.†	L1	Н	А	B9	Pillow	Shaft
Number	Dia.					Block	Support
							Rail
							Assembly
1FB-12-FBO	.75	1.88	1.687	.51	2.75	SSUPBO-12-XS	LSRA-12-XS
1FB-16-FBO	1.00	2.63	2.187	.69	3.25	SSUPBO-16-XS	LSRA-16-XS
1FB-20-FBO	1.25	3.38	2.687	.78	4.00	SSUPBO-20-XS	LSRA-20-XS
1FB-24-FBO	1.50	3.75	3.125	.93	4.75	SSUPBO-24-XS	LSRA-24-XS

Smart Rail Line	Smart Rail Linear Guide 1FB Double Continuously Supported with 2 Twin Pillow Blocks (Dimensions in inch												
Part	Nom.†	L2	Н	А	B9	Maximum	Pillow	Shaft					
Number	Dia.					Stroke	Block	Support					
						Length		Rail					
								Assembly					
1FB-12-HBO	.75	4.5	1.687	.51	2.75	L-(4.5)	SSUTWNO-12-XS	LSRA-12-XS					
1FB-16-HBO	1.00	6.0	2.287	.69	3.25	L-(6.0)	SSUTWNO-16-XS	LSRA-16-XS					
1FB-20-HBO	1.25	7.5	2.687	.78	4.00	L-(7.5)	SSUTWNO-20-XS	LSRA-20-XS					
1FB-24-HBO	1.50	9.0	3.125	.93	4.75	L-(9.0)	SSUTWNO-24-XS	LSRA-24-XS					

<sup>†</sup> .625" diameter Smart Rail Linear Guide also available, contact factory for specifications.

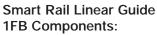
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.





## Smart Rail\* Linear Guide **1FB Benefits:**

- Requires only one part number to specify the entire linear quide.
- More mounting flexibility through bolt down from the top access.
- Used in continuously supported applications when rigidity is required.
- Lower overall linear guide height.



- 4 Super Smart Ball Bushing\* open type pillow blocks or 2 Super Smart Ball Bushing open type twin pillow blocks.
- 2 60 Case\* LinearRace\* shaft Support Rail Assemblies.

#### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

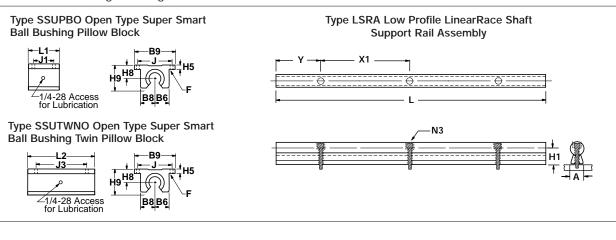
### Part Numbering System

1FB-12-FBO L24 Linear Guide Linear Guide Designation -Nominal Diameter

Type of Bearing Block

- Length

- Type of Support



Type SSUPBC	e SSUPBO Pillow Blocks (Dimensions in Inche													Type SSUTWNO I	Pillow B	locks		
Part	Nom.	L1	H9	H8	H5	B9	B8	B6	J	J1	F		Wt.	Part	Nom.	L2	J3	Wt.
Number	Dia.										Bolt	Hole	lb	Number	Dia.			lb
SSUPBO-12-XS	.75	1.88	1.56	.937	.31	2.75	1.00	.94	2.38	1.25	#8	.19	.51	SSUTWNO-12-XS	.75	4.5	3.5	1.02
SSUPBO-16-XS	1.00	2.63	2.00	1.187	.38	3.25	1.25	1.19	2.88	1.75	#10	.22	1.03	SSUTWNO-16-XS	1.00	6.0	4.5	2.06
SSUPBO-20-XS	1.25	3.38	2.56	1.500	.43	4.00	1.63	1.50	3.50	2.00	#10	.23	2.15	SSUTWNO-20-XS	1.25	7.5	5.5	4.30
SSUPBO-24-XS	1.50	3.75	2.94	1.750	.50	4.75	1.88	1.75	4.12	2.50	1/4	.25	3.20	SSUTWNO-24-XS	1.50	9.0	6.5	6.88

Housing Material: Aluminum Alloy Black Anodized

Housing Material: Aluminum Alloy Black Anodized

Type LSRA Lo	w Profile Linea	rRace Shaft Su	pport Rail Asser	mbly		(Dimen	sions in Inches)
Part Number	Nom. Dia.	H1	A	X1	Y	N3 <sup>(1)</sup>	Wt. Ib/ft
LSRA-12-XS	.75	.750	.51	3	1.5	#6 - 32 x 1 <sup>1</sup> / <sub>4</sub>	2.09
LSRA-16-XS	1.00	1.000	.69	3	1.5	#10 - 32 x 1 <sup>1</sup> / <sub>2</sub>	3.67
LSRA-20-XS	1.25	1.187	.78	3	1.5	<sup>5</sup> / <sub>16</sub> - 18 x 2	5.86
LSRA-24-XS	1.50	1.375	.93	4	2	<sup>3</sup> / <sub>8</sub> - 16 x 2 <sup>1</sup> / <sub>2</sub>	7.68

LinearRace Shaft Support Rail Material: Black Oxided Steel

<sup>(1)</sup> Each system is shipped with attachment screws as noted by N3 and cap plugs. If a non-standard screw length is required, it must be user supplied.

Dynamic Loa	ad Rating (C) Ma	trix (4 million	n inches travel)
Linear Guide Assembly Part No.	Dynamic Load Rating, C (lb <sub>f</sub> ) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (lb <sub>f</sub> )
1FB-12-FBO	3600	SSUPBO-12-XS	900
1FB-16-FBO	6000	SSUPBO-16-XS	1500
1FB-20-FBO	7460	SSUPBO-20-XS	1865
1FB-24-FBO	12320	SSUPBO-24-XS	3080
1FB-12-HBO	3600	SSUTWNO-12-XS	1800
1FB-16-HBO	6040	SSUTWNO-16-XS	3020
1FB-20-HBO	7460	SSUTWNO-12-XS	3730
1FB-24-HBO	12320	SSUTWNO-24-XS	6160

Maximum length of LinearRace Shaft Support Rail is 144 inches. If longer continuous one-piece LinearRace Shaft Support Rails are required, contact the Thomson Linear Guide Application Engineering department.

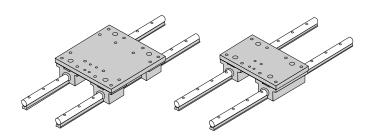
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearquides@thomsonmail.com.



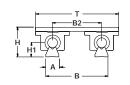


# Smart Rail\* 1FC

Linear Guide #10 with Table Top Low Profile, Easy to Install



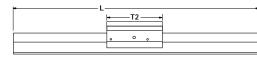
## INCH

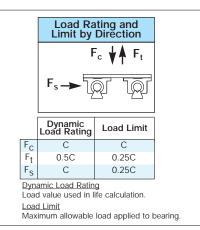


Double Continuously Supported Linear Guide with 4 Pillow Blocks and Size B Table Top



Double Continuously Supported Linear Guide with 2 Twin Pillow Blocks and Size A Table Top





Smart Rail Lin	ear Guid	e 1FC D	ouble Co	ontinuou	sly Supp	orted wi	ith 4 Pillo	ow Block	s and Ta	able Top (S	Size B) (Dimens	sions in inches)
Part Number	Nom.† Dia.	A	T1	Т	Η	H1	В	B2	L1	Maximum Stroke Length	Pillow Block	Shaft Support Rail Assembly
1FC-12-FBB	.75	.51	7.5	7.5	2.187	.750	5.01	4.50	1.88	L-(7.5)	SSUPBO-12-XS	LSRA-12-XS
1FC-16-FBB	1.00	.69	9.0	9.0	2.687	1.000	6.19	5.50	2.63	L-(9.0)	SSUPBO-16-XS	LSRA-16-XS
1FC-20-FBB	1.25	.78	11.0	11.0	3.437	1.187	7.53	6.75	3.38	L-(11.0)	SSUPBO-20-XS	LSRA-20-XS
1FC-24-FBB	1.50	.93	13.0	13.0	3.875	1.375	8.93	8.00	3.75	L-(13.0)	SSUPBO-24-XS	LSRA-24-XS

Smart Rail Line	ar Guide	e 1FC Dou	ble Contir	nuously Si	upported	with 2 Twi	n Pillow B	locks and	d Table Top	(Size A) (Dimen	sions in inches)
Part	Nom.†	А	T2	Т	Н	H1	В	B2	Maximum	Pillow	Shaft
Number	Dia.								Stroke	Block	Support
									Length		Rail
											Assembly
1FC-12-HBA	.75	.51	4.5	7.5	2.187	.750	5.01	4.50	L-(4.5)	SSUTWNO-12-XS	LSRA-12-XS
1FC-16-HBA	1.00	.69	6.0	9.0	2.687	1.000	6.19	5.50	L-(6.0)	SSUTWNO-16-XS	LSRA-16-XS
1FC-20-HBA	1.25	.78	7.5	11.0	3.437	1.187	7.53	6.75	L-(7.5)	SSUTWNO-20-XS	LSRA-20-XS
1FC-24-HBA	1.50	.93	9.0	13.0	3.875	1.375	8.93	8.00	L-(9.0)	SSUTWNO-24-XS	LSRA-24-XS

t .625" diameter Smart Rail Linear Guide also available, contact factory for specifications.

Dynamic Load	Rating (C) Matrix	(4 millioi	n inches travel)	Dynamic Load	Rating (C) Matrix	(4 millior	n inches travel)
Linear Guide Assembly Part No.	Dynamic Load Rating, C (lb <sub>f</sub> ) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (lb <sub>f</sub> )	Linear Guide Assembly Part No.	Dynamic Load Rating, C (lb <sub>f</sub> ) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Rating, C (lb <sub>f</sub> )
1FC-12-FBB	3600	SSUPBO-12-XS	900	1FC-12-HBA	3600	SSUTWNO-12-XS	1800
1FC-16-FBB	6000	SSUPBO-16-XS	1500	1FC-16-HBA	6040	SSUTWNO-16-XS	3020
1FC-20-FBB	7460	SSUPBO-20-XS	1865	1FC-20-HBA	7460	SSUTWNO-12-XS	3730
1FC-24-FBB	12320	SSUPBO-24-XS	3080	1FC-24-HBA	12320	SSUTWNO-24-XS	6160



## Smart Rail\* Linear Guide 1FC Benefits:

- Requires only one part number to specify the entire linear guide.
- Includes table top with standard tapped holes for quick and easy mounting of the work piece.
- More mounting flexibility through bolt down from the top access.
- Used in continuously supported applications when rigidity is required.
- Lower overall linear guide height.

# Smart Rail Linear Guide 1FC Components:

- 4 Super Smart Ball Bushing\* open type pillow blocks or 2 Super Smart Ball Bushing open type twin pillow blocks.
- 2 60 Case\* LinearRace\* shaft Support Rail Assemblies.
- 1 mounting table top with work piece attachment holes.

#### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

### Part Numbering System

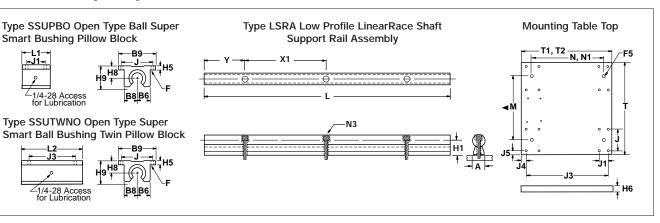
 IFC-12-FBB L24

 Linear Guide

 Designation

 Nominal Diameter

 Type of Bearing Block



Type SSUPBC	) Pillo	w Blo	ocks							(Dimen	sions	in Inc	hes)	Type SSUTWNO	Pillow B	locks		
Part	Nom.	L1	H9	H8	H5	B9	B8	B6	J	J1	F	-	Wt.	Part	Nom.	L2	J3	Wt.
Number	Dia.										Bolt	Hole	lb	Number	Dia.			lb
SSUPBO-12-XS	.75	1.88	1.56	.937	.31	2.75	1.00	.94	2.38	1.25	#8	.19	.51	SSUTWNO-12-XS	.75	4.5	3.5	1.02
SSUPBO-16-XS	1.00	2.63	2.00	1.187	.38	3.25	1.25	1.19	2.88	1.75	#10	.22	1.03	SSUTWNO-16-XS	1.00	6.0	4.5	2.06
SSUPBO-20-XS	1.25	3.38	2.56	1.500	.43	4.00	1.63	1.50	3.50	2.00	#10	.23	2.15	SSUTWNO-20-XS	1.25	7.5	5.5	4.30
SSUPBO-24-XS	1.50	3.75	2.94	1.750	.50	4.75	1.88	1.75	4.12	2.50	1/4	.25	3.20	SSUTWNO-24-XS	1.50	9.0	6.5	6.88

Housing Material: Aluminum Alloy Black Anodized

Housing Material: Aluminum Alloy Black Anodized

Type LSRA Lo	w Profile Linea	rRace Shaft Su	oport Rail Asser	mbly		(Dimen	sions in Inches)
Part Number	Nom. Dia.	H1	A	X1	Y	N3 <sup>(1)</sup>	Wt. Ib/ft
LSRA-12-XS	.75	.750	.51	3	1.5	#6 - 32 x 1 <sup>1</sup> / <sub>4</sub>	2.09
LSRA-16-XS	1.00	1.000	.69	3	1.5	#10 - 32 x 1 <sup>1</sup> / <sub>2</sub>	3.67
LSRA-20-XS	1.25	1.187	.78	3	1.5	⁵/ <sub>16</sub> - 18 x 2	5.86
LSRA-24-XS	1.50	1.375	.93	4	2	<sup>3</sup> / <sub>8</sub> - 16 x 2 <sup>1</sup> / <sub>2</sub>	7.68

LinearRace Shaft Support Rail Material: Black Oxided Steel

 $^{(1)}$  Each system is shipped with attachment screws as noted by N3 and cap plugs. If a non-standard screw length is required, it must be user supplied.

Maximum length of LinearRace Shaft Support Rail is 144 inches. If longer continuous one-piece LinearRace Shaft Support Rails are required, contact the Thomson **Linear Guides** application engineering department.

Mountin	g Table	Тор											(Dimen	sions in	inches)
Nominal		All	Table To	ps			Tabl	e Top Siz	e <b>B</b>			Tabl	le Top Siz	e A	
Diameter	Т	М	J	H6	F5 <sup>(2)</sup>	T1	J1	J4	J5	N	T2	J3	J4	J5	N1
.75	7.5	4.50	2.38	.500	<sup>5</sup> /16-18	7.5	1.25	.41	.31	6.0	4.5	3.5	.50	.31	3.0
1.00	9.0	5.50	2.88	.500	<sup>3</sup> /8-16	9.0	1.75	.53	.31	7.0	6.0	4.5	.75	.31	4.0
1.25	11.0	6.75	3.50	.750	1/2-13	11.0	2.00	.82	.38	8.5	7.5	5.5	1.00	.38	5.0
1.50	13.0	8.00	4.12	.750	<sup>1</sup> /2-13	13.0	2.50	.75	.44	10.0	9.0	6.5	1.25	.44	6.0

Material: Aluminum Alloy Black Anodized

(2) Customer Mounting Hole

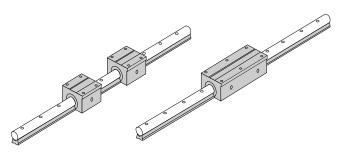
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



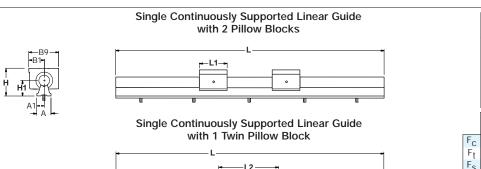


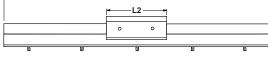
# Smart Rail\* 1QA

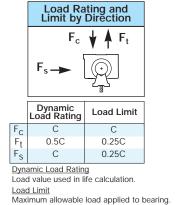
Linear Guide #10 Low Profile, Easy to Install



## METRIC







Smart Rail Line	ear Guide 10	2A Singl	e Conti	nuously	Suppor	ted with	2 Pillow	Blocks		(Dimensions in mm)
Part Number	Nominal Diameter	L1	Н	H1	A	A1	B1	B9	Pillow Block	Shaft Support Rail Assembly
1QA-M16-LLO	16	43	40	18	14	7,0	26,5	53	SSEPBO-M16-XS	LSRA-M16-XS
1QA-M20-LLO	20	54	47	22	17	8,5	30,0	60	SSEPBO-M20-XS	LSRA-M20-XS
1QA-M25-LLO	25	67	56	26	21	10,5	39,0	78	SSEPBO-M25-XS	LSRA-M25-XS
1QA-M30-LLO	30	79	65	30	23	11,5	43,5	87	SSEPBO-M30-XS	LSRA-M30-XS
1QA-M40-LLO	40	91	84	39	30	15,0	54,0	108	SSEPBO-M40-XS	LSRA-M40-XS

Smart Rail Linea	ar Guide 10	2A Singl	le Conti	inuously	Suppo	rted wi	th 1 Tw	in Pillo	w Block	(Din	nensions in mm)
Part	Nominal	L2	Н	H1	A	A1	B1	B9	Maximum	Pillow	Shaft
Number	Diameter								Stroke	Block	Support
									Length		Rail
											Assembly
1QA-M16-MLO	16	84	40	18	14	7,0	26,5	53	L-(84)	SSETWNO-M16-XS	LSRA-M16-XS
1QA-M20-MLO	20	104	47	22	17	8,5	30,0	60	L-(104)	SSETWNO-M20-XS	LSRA-M20-XS
1QA-M25-MLO	25	130	56	26	21	10,5	39,0	78	L-(130)	SSETWNO-M25-XS	LSRA-M25-XS
1QA-M30-MLO	30	152	65	30	23	11,5	43,5	87	L-(152)	SSETWNO-M30-XS	LSRA-M30-XS
1QA-M40-MLO	40	176	84	39	30	15,0	54,0	108	L-(176)	SSETWNO-M40-XS	LSRA-M40-XS





## Smart Rail\* Linear Guide 1QA Benefits:

- Requires only one part number to specify the entire linear guide.
- More mounting flexibility through bolt down from the top access.
- Used in continuously supported applications when rigidity is required.
- Lower overall linear guide height.

Access for Lubrication M6 x 1

r+J1+i

J8

12 J3

- J9-

J8

16

## Smart Rail Linear Guide 1QA Components:

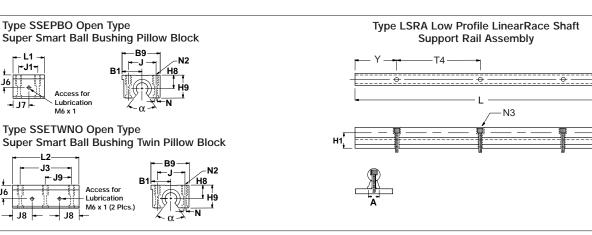
- 2 Super Smart Ball Bushing\* open type pillow blocks or 1 Super Smart Ball Bushing open type twin pillow block.
- 1 60 Case\* LinearRace\* shaft Support Rail Assembly.

### Specifying this Thomson Linear Guide:

1. Determine the proper Linear Guide for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number.

#### Part Numbering System

1QA-M16-L	LO L600
Linear Guide	Linear Guide
Designation	Length
Nominal Diameter	
Type of Bearing Block —	Type of Support



Type SSEPBO F	Pillow	Bloc	:ks								(Din	nensio	ons ir	n mm)	Type SSETWNO	Pillow	I Blo	cks			
Part	Nom.	L1	H8	H9	B1	B9	J6	J7	J	J1	Ν	N2	α	Mass	Part	Nom.	L2	J3	J8	J9	Mass
Number	Dia.										Dia.		Deg	kg	Number	Dia.					kg
SSEPBO-M16-XS	16	43	22	35	26,5	53	22,0	21,5	40	26	5,3	M6	66	0,17	SSETWNO-M16-XS	16	84	64	21,5	32	0,34
SSEPBO-M20-XS	20	54	25	41	30,0	60	25,0	27,0	45	32	6,6	M8	60	0,30	SSETWNO-M20-XS	20	104	76	27,0	38	0,63
SSEPBO-M25-XS	25	67	30	50	39,0	78	31,5	33,5	60	40	8,4	M10	60	0,57	SSETWNO-M25-XS	25	130	94	33,6	47	1,18
SSEPBO-M30-XS	30	79	35	60	43,5	87	33,0	39,5	68	45	8,4	M10	60	0,87	SSETWNO-M30-XS	30	152	106	39,5	53	1,70
SSEPBO-M40-XS	40	91	45	77	54,0	108	43,5	45,5	86	58	10,5	M12	60	1,62	SSETWNO-M40-XS	40	176	124	45,5	62	3,18
Housing Material: Alu	minum .	Alloy	Grey A	nodize	ed										Housing Material: Alu	iminum	Alloy	Grey	Anod	ized	

Housing Material: Aluminum Alloy Grey Anodized

Type LSRA Low	Profile Linear	Race Shaft S	upport Rail As	sembly			(Dimens	ions in mm)
Part Number	Nominal Diameter	H1	A	A1	Τ4	Y	N3 <sup>(1)</sup>	Mass kg/m
LSRA-M16-XS	16	18	14	7,0	40	20	M3 x 30	3,6
LSRA-M20-XS	20	22	17	8,5	60	30	M4 x 35	5,5
LSRA-M25-XS	25	26	21	10,5	60	30	M5 x 45	8,5
LSRA-M30-XS	30	30	23	11,5	80	40	M6 x 50	13,0
LSRA-M40-XS	40	39	30	15,0	105	52,5	M10 x 65	21,0

LinearRace Shaft Support Rail Material: Black Oxided Steel

<sup>(1)</sup> Each system is shipped with attachment screws as noted by N3 and cap plugs.

If a non-standard screw length is required, it must be user supplied.

ynamic Loa	d Rating (C) N	latrix	(100 km travel)	Dynamic Loa	d Rating (C) M	flatrix (	(10
Linear Guide	Dynamic Load	Pillow Block	Pillow Block	Linear Guide	Dynamic Load	Pillow Block	
Assembly	Rating, C (N)	Part No.	Dynamic Load	Assembly	Rating, C (N)	Part No.	
Part No.	(Even Distribution)		Rating, C (N)	Part No.	(Even Distribution)		
1QA-M16-LLO	4400	SSEPBO-M16-XS	2200	1QA-M16-MLO	4400	SSETWNO-M16-XS	
1QA-M20-LLO	8000	SSEPBO-M20-XS	4000	1QA-M20-MLO	8000	SSETWNO-M20-XS	
1QA-M25-LLO	13400	SSEPBO-M25-XS	6700	1QA-M25-MLO	13400	SSETWNO-M25-XS	
1QA-M30-LLO	16600	SSEPBO-M30-XS	8300	1QA-M30-MLO	16600	SSETWNO-M30-XS	
1QA-M40-LLO	27400	SSEPBO-M40-XS	13700	1QA-M40-MLO	27400	SSETWNO-M40-XS	

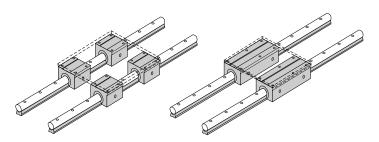
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



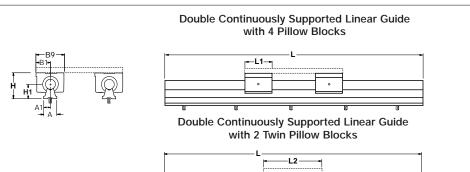
Page 131

# Smart Rail\* 1QB

Linear Guide #10 Low Profile, Easy to Install

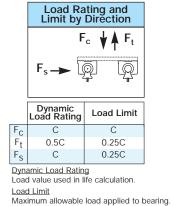


## METRIC



0

0



Smart Rail Line	ar Guide 10	B Doub	le Cont	inuously	v Suppo	rted wit	h 4 Pillo	w Blocks	5	(Dimensions in mm)
Part Number	Nominal Diameter	L1	Н	H1	A	A1	B1	В9	Pillow Block	Shaft Support Rail Assembly
1QB-M16-LLO	16	43	40	18	14	7,0	26,5	53	SSEPBO-M16-XS	LSRA-M16-XS
1QB-M20-LLO	20	54	47	22	17	8,5	30,0	60	SSEPBO-M20-XS	LSRA-M20-XS
1QB-M25-LLO	25	67	56	26	21	10,5	39,0	78	SSEPBO-M25-XS	LSRA-M25-XS
1QB-M30-LLO	30	79	65	30	23	11,5	43,5	87	SSEPBO-M30-XS	LSRA-M30-XS
1QB-M40-LLO	40	91	84	39	30	15,0	54,0	108	SSEPBO-M40-XS	LSRA-M40-XS

Smart Rail Linea	ar Guide 10	B Doub	ole Con	tinuousl	y Supp	orted w	vith 2 Tv	vin Pillo	w Blocks	(Din	nensions in mm)
Part	Nominal	L2	Н	H1	Α	A1	B1	B9	Maximum	Pillow	Shaft
Number	Diameter								Stroke	Block	Support
									Length		Rail
											Assembly
1QB-M16-MLO	16	84	40	18	14	7,0	26,5	53	L-(84)	SSETWNO-M16-XS	LSRA-M16-XS
1QB-M20-MLO	20	104	47	22	17	8,5	30,0	60	L-(104)	SSETWNO-M20-XS	LSRA-M20-XS
1QB-M25-MLO	25	130	56	26	21	10,5	39,0	78	L-(130)	SSETWNO-M25-XS	LSRA-M25-XS
1QB-M30-MLO	30	152	65	30	23	11,5	43,5	87	L-(152)	SSETWNO-M30-XS	LSRA-M30-XS
1QB-M40-MLO	40	176	84	39	30	15,0	54,0	108	L-(176)	SSETWNO-M40-XS	LSRA-M40-XS

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

Page 132

Linear Guides



## Smart Rail\* Linear Guide 1QB Benefits:

- Requires only one part number to specify the entire linear guide.
- Allows for custom table mounting.
- Used in continuously supported applications when rigidity is required.
- More mounting flexibility through bolt down from the top access.

# Smart Rail Linear Guide 1QB Components:

- 4 Super Smart Ball Bushing\* open type pillow blocks or 2 Super Smart Ball Bushing open type twin pillow blocks.
- 2 60 Case\* LinearRace\* shaft Support Rail Assemblies.

#### Specifying a Thomson Linear Guide:

 Determine the proper system for your load and life requirements.
 Select the part number.
 Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number.

### Part Numbering System

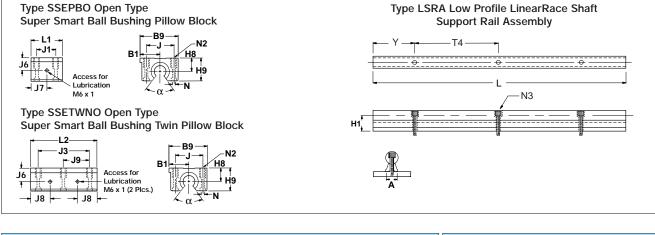
 IQB-M16-LLO L600

 Linear Guide

 Designation

 Nominal Diameter

 Type of Bearing Block



Type SSEPBO F	Part Number         Nom. Dia.         L1         H8         H9         B1         B9         J6         J7         J         J1         N         N2         α Deg           SSEPBO-M16-XS         16         43         22         35         26,5         53         22,0         21,5         40         26         5,3         M6         66           SSEPBO-M20-XS         20         54         25         41         30,0         60         25,0         27,0         45         32         6,6         M8         60           SSEPBO-M25-XS         25         67         30         50         39,0         78         31,5         33,5         60         40         8,4         M10         60           SSEPBO-M30-XS         30         79         35         60         43,5         87         33,0         39,5         68         45         8,4         M10         60													n mm)	Type SSETWNO	Pillow	I Blo	cks			
Part	Nom.	L1	H8	H9	B1	B9	J6	J7	J	J1	Ν	N2	α	Mass	Part	Nom.	L2	J3	J8	J9	Mass
Number	Dia.										Dia.		Deg	kg	Number	Dia.					kg
SSEPBO-M16-XS	16	43	22	35	26,5	53	22,0	21,5	40	26	5,3	M6	66	0,17	SSETWNO-M16-XS	16	84	64	21,5	32	0,34
SSEPBO-M20-XS	20	54	25	41	30,0	60	25,0	27,0	45	32	6,6	M8	60	0,30	SSETWNO-M20-XS	20	104	76	27,0	38	0,63
SSEPBO-M25-XS	25	67	30	50	39,0	78	31,5	33,5	60	40	8,4	M10	60	0,57	SSETWNO-M25-XS	25	130	94	33,6	47	1,18
SSEPBO-M30-XS	30	79	35	60	43,5	87	33,0	39,5	68	45	8,4	M10	60	0,87	SSETWNO-M30-XS	30	152	106	39,5	53	1,70
SSEPBO-M40-XS	40	91	45	77	54,0	108	43,5	45,5	86	58	10,5	M12	60	1,62	SSETWNO-M40-XS	40	176	124	45,5	62	3,18
Housing Material: Al	minum	Allov	Croy A	nodiz	od.										Housing Material: Alu	minum	Allov	Grov	Anod	izod	

Housing Material: Aluminum Alloy Grey Anodized

Type LSRA Low	Profile Linear	Race Shaft S	upport Rail As	sembly			(Dimens	ions in mm)
Part Number	Nominal Diameter	H1	A	A1	T4	Y	N3 <sup>(1)</sup>	Mass kg/m
LSRA-M16-XS	16	18	14	7,0	40	20	M3 x 30	3,6
LSRA-M20-XS	20	22	17	8,5	60	30	M4 x 35	5,5
LSRA-M25-XS	25	26	21	10,5	60	30	M5 x 45	8,5
LSRA-M30-XS	30	30	23	11,5	80	40	M6 x 50	13,0
LSRA-M40-XS	40	39	30	15,0	105	52,5	M10 x 65	21,0

LinearRace Shaft Support Rail Material: Black Oxided Steel

<sup>(1)</sup> Each system is shipped with attachment screws as noted by N3 and cap plugs.

If a non-standard screw length is required, it must be user supplied.

Dynamic Loa	d Rating (C) N	latrix	(100 km travel)	Dynamic Loa	d Rating (C) N	latrix	(100 km travel)
Linear Guide	Dynamic Load	Pillow Block	Pillow Block	Linear Guide	Dynamic Load	Pillow Block	Pillow Block
Assembly Part No.	Rating, C (N) (Even Distribution)	Part No.	Dynamic Load Rating, C (N)	Assembly Part No.	Rating, C (N) (Even Distribution)	Part No.	Dynamic Load Rating, C (N)
1QB-M16-LLO	8800	SSEPBO-M16-XS	2200	1QB-M16-MLO	8800	SSETWNO-M16-XS	4400
1QB-M20-LLO	16000	SSEPBO-M20-XS	4000	1QB-M20-MLO	16000	SSETWNO-M20-XS	8000
1QB-M25-LLO	26800	SSEPBO-M25-XS	6700	1QB-M25-MLO	26800	SSETWNO-M25-XS	13400
1QB-M30-LLO	33200	SSEPBO-M30-XS	8300	1QB-M30-MLO	33200	SSETWNO-M30-XS	16600
1QB-M40-LLO	54800	SSEPBO-M40-XS	13700	1QB-M40-MLO	54800	SSETWNO-M40-XS	27400

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

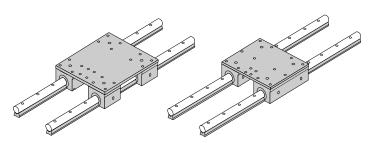


Page 133

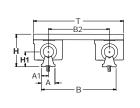


# Smart Rail\* 1QC

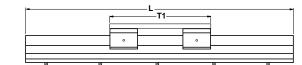
Linear Guide #10 with Table Top Low Profile, Easy to Install



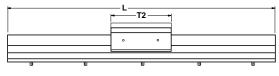
## METRIC

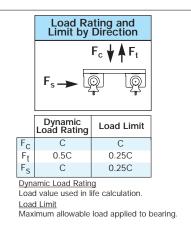


Double Continuously Supported Linear Guide with 4 Pillow Blocks and Size F Table Top



Double Continuously Supported Linear Guide with 2 Twin Pillow Blocks and Size E Table Top





Smart Rail Line	ar Guide	e 1QC D	ouble Co	ontinuou	sly Supp	orted wi	ith 4 Pillo	w Block	s and T	able Top (Si	ze F) (Dir	mensions in mm)
Part	Nom.	T1	Т	Н	H1	А	A1	В	B2	Maximum	Pillow	Shaft
Number	Dia.									Stroke	Block	Support
										Length		Rail
												Assembly
1QC-M16-LLF	16	125	125	53	18	14	7,0	86	70	L-(125)	SSEPBO-M16-XS	LSRA-M16-XS
1QC-M20-LLF	20	175	175	63	22	17	8,5	132	110	L-(175)	SSEPBO-M20-XS	LSRA-M20-XS
1QC-M25-LLF	25	225	225	76	26	21	10,5	168	140	L-(225)	SSEPBO-M25-XS	LSRA-M25-XS
1QC-M30-LLF	30	275	275	85	30	23	11,5	211	180	L-(275)	SSEPBO-M30-XS	LSRA-M30-XS
1QC-M40-LLF	40	325	325	109	39	30	15,0	247	210	L-(325)	SSEPBO-M40-XS	LSRA-M40-XS

Smart Rail Line	ar Guide	e 1QC Do	ouble Co	ntinuous	ly Suppo	rted with	1 2 Twin	Pillow Bl	ocks an	d Table Top	(Size E) (Dir	mensions in mm)
Part	Nom.	T2	Т	Н	H1	А	A1	В	B2	Maximum	Pillow	Shaft
Number	Dia.									Stroke	Block	Support
										Length		Rail
												Assembly
1QC-M16-MLE	16	84	125	53	18	14	7,0	86	70	L-(84)	SSETWNO-M16-XS	LSRA-M16-XS
1QC-M20-MLE	20	104	175	63	22	17	8,5	132	110	L-(104)	SSETWNO-M20-XS	LSRA-M20-XS
1QC-M25-MLE	25	130	225	76	26	21	10,5	168	140	L-(130)	SSETWNO-M25-XS	LSRA-M25-XS
1QC-M30-MLE	30	152	275	85	30	23	11,5	211	180	L-(152)	SSETWNO-M30-XS	LSRA-M30-XS
1QC-M40-MLE	40	176	325	109	39	30	15,0	247	210	L-(176)	SSETWNO-M40-XS	LSRA-M40-XS

Dynamic Loa	d Capacity Ma	atrix (	(100 km travel)	Dynamic Loa	d Capacity Ma	atrix (	100 km travel)
Linear Guide Assembly Part No.	Dynamic Load Capacity (N) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Capacity (N)	Linear Guide Assembly Part No.	Dynamic Load Capacity (N) (Even Distribution)	Pillow Block Part No.	Pillow Block Dynamic Load Capacity (N)
1QC-M16-LLF	8800	SSEPBO-M16-XS	2200	1QC-M16-MLE	8800	SSETWNO-M16-XS	4400
1QC-M20-LLF	16000	SSEPBO-M20-XS	4000	1QC-M20-MLE	16000	SSETWNO-M20-XS	8000
1QC-M25-LLF	26800	SSEPBO-M25-XS	6700	1QC-M25-MLE	26800	SSETWNO-M25-XS	13400
1QC-M30-LLF	33200	SSEPBO-M30-XS	8300	1QC-M30-MLE	33200	SSETWNO-M30-XS	16600
1QC-M40-LLF	54800	SSEPBO-M40-XS	13700	1QC-M40-MLE	54800	SSETWNO-M40-XS	27400





## Smart Rail\* Linear Guide **1QC Benefits:**

r+J1+∣

-| J7 |-

J8

- Requires only one part number to specify the entire linear guide.
- Includes table top with standard tapped holes for quick and easy mounting of the work piece.
- Includes Ball Screw Assembly attachment holes for ease of assembly and actuation.
- Used in continuously supported applications when rigidity is required.

Access for

Lubrication

M6 x 1

J3

J9

- J8

## Smart Rail Linear Guide 1QC Components:

- 4 Super Smart Ball Bushing\* open type pillow blocks or 2 Super Smart Ball Bushing open type twin pillow blocks.
- 2 60 Case\* LinearRace\* shaft Support Rail Assemblies.
- 1 mounting table top with work piece and Ball Screw Assembly attachment holes.

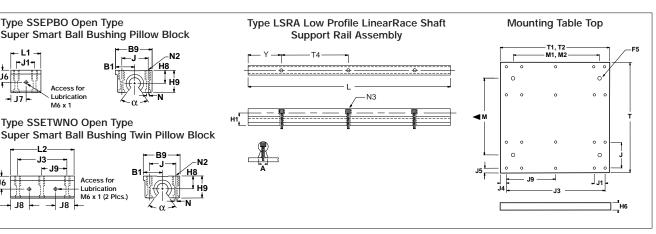
#### Specifying a Thomson Linear Guide:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number.

### Part Numbering System

#### 1QC-M16-MLE L600

Linear Guide	Linear Guide
Designation _	Length
Nominal Diameter	☐ Type of Table Top
Type of Bearing Block -	Type of Support



Type SSEPBO P	Pillow	Bloc	:ks								(Din	nensi	ons ir	n mm)	Type SSETWNO	Pillow	Blo	cks			
Part	Nom.	L1	H8	H9	B1	B9	J6	J7	J	J1	N	N2	α	Mass	Part	Nom.	L2	J3	J8	J9	Mass
Number	Dia.										Dia.		Deg	kg	Number	Dia.					kg
SSEPBO-M16-XS 16 43 22 35 26,5 53 22,0 21,5 40 26 5,3 M6 66 0,17 SSETWNO-M16-XS 16 84 64 21,5 32 0,3														0,34							
SSEPBO-M20-XS	20	54	25	41	30,0	60	25,0	27,0	45	32	6,6	M8	60	0,30	SSETWNO-M20-XS	20	104	76	27,0	38	0,63
SSEPBO-M25-XS	25	67	30	50	39,0	78	31,5	33,5	60	40	8,4	M10	60	0,57	SSETWNO-M25-XS	25	130	94	33,6	47	1,18
SSEPBO-M30-XS	30	79	35	60	43,5	87	33,0	39,5	68	45	8,4	M10	60	0,87	SSETWNO-M30-XS	30	152	106	39,5	53	1,70
SSEPBO-M40-XS	40	91	45	77	54,0	108	43,5	45,5	86	58	10,5	M12	60	1,62	SSETWNO-M40-XS	40	176	124	45,5	62	3,18
Housing Material: Alu	minum /	Alloy	Grey A	nodize	ed										Housing Material: Alu	uminum	Alloy	Grey	Anod	ized	

Housing Material: Aluminum Alloy Grey Anodized

Type LSRA Low Profile LinearRace Shaft Support Rail Assembly (Dimensions in mm) Part Nominal H1 А A1 Τ4 Υ N3<sup>(1)</sup> Mass Number Diameter kg/m LSRA-M16-XS 16 18 14 7,0 40 20 M3 x 30 3,6 LSRA-M20-XS 20 22 17 8,5 60 30 M4 x 35 5,5 LSRA-M25-XS 25 26 21 10,5 60 30 M5 x 45 8,5 LSRA-M30-XS 30 30 23 11,5 80 40 M6 x 50 13,0 LSRA-M40-XS 40 39 30 15,0 105 52,5 M10 x 65 21,0

LinearRace Shaft Support Rail Material: Black Oxided Steel

<sup>(1)</sup> Each system is shipped with attachment screws as noted by N3 and cap plugs.

If a non-standard screw length is required, it must be user supplied.

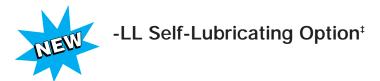
Mounting	g Table	Тор												(Dimen	sions i	n mm)
System		All	Table Top	os			Tabl	e Top Siz	e F			Т	able To	p Size <b>E</b>		
	Т	М	J	H6	F5 <sup>(2)</sup>											M2
1QC-M16	125	70	40	13	M6	125	26	10,0	7,5	70	84	64	10	7,5	32	45
1QC-M20	175	110	45	16	M8	175	32	11,0	10,0	110	104	76	14	10,0	38	55
1QC-M25	225	140	60	20	M8	225	40	13,5	12,5	140	130	94	18	12,5	47	65
1QC-M30	275	180	68	20	M8	275	45	17,0	13,5	180	152	106	23	13,5	53	75
1QC-M40	325	210	86	25	M10	325	58	16,5	14,5	210	176	124	26	14,5	62	85

Material: Aluminum Alloy Grey Anodized

(2) Customer Mounting Hole

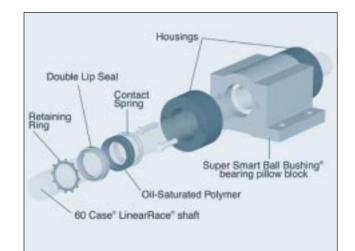
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.





The new LL Option provides maintenancefree operation and enhanced bearing protection.

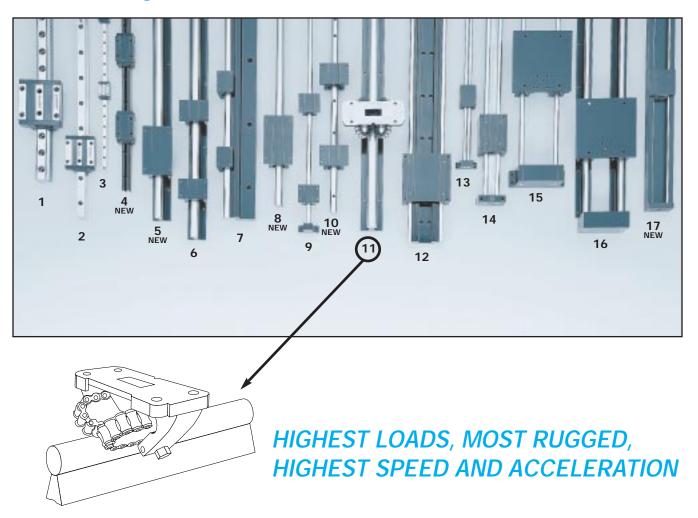
- Eliminates the need for expensive lubrication system in most applications
- Increases effective bearing life by increasing protection from contamination
- Environmentally friendly
- NOTE: Carriage drag with the -LL option will be approximately 2x the seal drag.
- <sup>+</sup>See Page 210 for technical data.







# RoundWay Linear Roller Guides



## RoundWay\* Linear Roller Guides Offer:

- Up to twenty times the load capacity of conventional linear ball bearings. This dramatic increase allows for more compact machine designs with a reduction in hardware costs
- Industry's highest load capacity. RoundWay Linear Roller bearings handle up to 35 tons/bearing and speeds up to 100 ft/second
- Virtual insensitivity to contamination without concerns of stroke length reduction from way covers
- A self-aligning capability that reduces installation time and cost by compensating for rail misalignment errors
- Interchangeable components for quick, costeffective machine maintenance.
- Curved rollers running on a curved inner race which make this linear guide resistant to severe shock loads
- Corrosion resistant versions for maximum performance in harsh environments.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



\* The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.
\* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

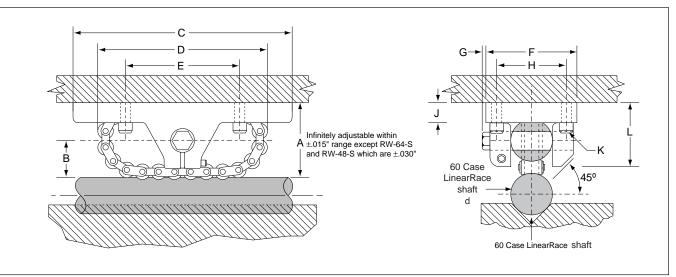
Page 137

#11

# **RoundWay 1WA**

Linear Guide #11 Single Type Contaminated Environments, High Shock Loads



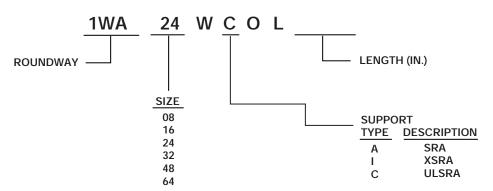


RoundWay* Linear	Guide	e 1W	A (S	ingle	е Тур	e) ar	nd 60	) Ca	se* l	Line	arRa	ace*	Sha	ft		(Dimen	sions in	inches)
Part	Nom.	Α	В	С	D	E	F	G	Н	J		K	L	60 Case	60 Case	60 Case	Bearing	Dynamic <sup>(1)</sup>
Number	Dia.													LinearRace	LinearRace	Solid	Mass	Load
														shaft Dia.	shaft Max.	LinearRace	lb	Capacity
											Bolt	Hole		d	Length <sup>‡</sup>	shaft Ib/in		lb <sub>f</sub>
1WA-08-WCO	.500	1.00	.45	3.0	2.38	1.50	1.25	.19	.94	.31	#6	.16	.88	.4995/.4990	168	.06	.50	970
1WA-16-WCO	1.000	1.75	.80	5.0	3.75	2.50	2.13	.25	1.63	.50	#10	.25	1.50	.9995/.9990	180	.22	2.20	3020
1WA-24-WCO	1.500	2.50	1.15	6.5	5.38	3.50	2.88	.31	2.13	.63	5/16	.38	2.13	1.4994/1.4989	204	.50	5.60	6020
1WA-32-WCO	2.000	3.25	1.50	8.5	7.38	4.50	3.63	.38	2.75	.75	3/8	.44	2.88	1.9994/1.9987	204	.89	12.40	12360
1WA-48-WCO	3.000	5.00	2.30	13.0	11.00	7.00	6.00	.50	4.25	1.25	3/8	.69	4.25	2.9992/2.9983	204	2.00	48.00	24000
1WA-64-WCO	4.000	6.50	3.00	17.0	14.88	9.00	7.75	.50	5.50	1.50	3/4	.81	5.88	3.9988/3.9976	204	3.56	105.00	48000

<sup>(1)</sup> Dynamic Load Capacity is based on 10 million inches of travel.

‡ Maximum length of 60 Case LinearRace Shafts are indicated above. If longer 60 Case LinearRace Shafts Support Rails are required, contact the Thomson Linear Guide Application Engineering department.

## ROUNDWAY LINEAR GUIDE PART NUMBER



For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



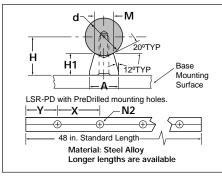
The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.





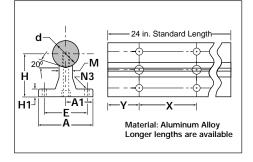
## 60 Case\* LinearRace\* Shaft Support Rails and Assemblies for Continuously Supported Applications





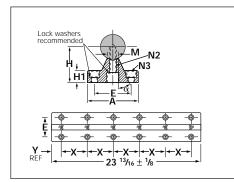
ULSRA Low P	rofile Shaft	Support	Rail Ass	emblies		(Din	nensior	is in inch	nes)
Part Number	Nominal LinearRace Shaft	Н	H1	А	М	Ν	12	Х	Y
	Diameter <b>d</b>	±.002				Hole	Bolt		
ULSRA-08-XS	.500	.562	.34	.37	.25	.17	#6-32	4	2
ULSRA-16-XS	1.000	1.000	.56	.69	.50	.28	1/4-20	6	3
ULSRA-24-XS	1.500	1.375	.70	.93	.69	.41	3/8-16	8	4
ULSRA-32-XS	2.000	1.750	.85	1.18	.88	.53	1/2-13	8	4
ULSRA-48-XS	3.000	2.750	1.40	1.88	1.38	.81	3/4-10	8	4
ULSRA-64-XS	4.000	3.500	1.75	2.50	1.88	1.06	1-8	8	4

## SUPPORT TYPE A

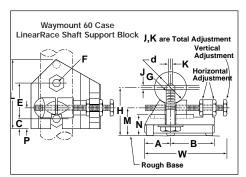


SRA Lin	earRace S	Shaft Supp	oort Ra	ail As	semb	lies			(E	Dimensions in	inch	ies)
Assembly With Solid	Nom. LinearRace Shaft Dia.	Н	H1	A	A1	E	М	N	3	Shaft Mounting Bolt	Х	Y
LinearRace	d	±.002			±.002			Hole	Bolt	N1		
SRA-08-XS	.500	1.125	.19	1.50	.750	1.00	.25	.17	#6	#6-32 x .88	4	2
SRA-16-XS	1.000	1.750	.25	2.13	1.063	1.50	.50	.28	1/4	<sup>1</sup> /4-20 x 1.50	6	3
SRA-24-XS	1.500	2.500	.38	3.00	1.500	2.25	.69	.34	<sup>5</sup> /16	<sup>3</sup> / <sub>8</sub> -16 x 2.50	8	4
SRA-32-XS	2.000	3.250	.50	3.75	1.875	2.75	.88	.41	<sup>3</sup> /8	<sup>1</sup> /2-13 x 2.50	8	4

## SUPPORT TYPE I



XSRA Linea	rRace	Supp	oort	Rai	I As	ssen	nblie	s				(Dimens	ion	s in in	nches)
Assy. With Solid	Nominal LinearRace Shaft	H 001	H1	A	Ε	М		N2				13	а	Х	Y
LinearRace	Diameter	+.000					Hole	Bolt	Counterbore	Hole	Bolt	Counterbore	deg		
XSRA-32	2.000	2.750	1.00	4.50	3.13	.88	.56	1⁄2-13 x 2	1 x .75 DP	.56	.50	1 x .63 DP	15	4	1.97
XSRA-48	3.000	4.000	1.31	6.00	4.25	1.25	.81	<sup>3</sup> / <sub>4</sub> -10 x 2.75	1.44 x 1.13 DP	.69	.63	1.25 x .75 DP	25	6	2.97



Waymou	unt* Linea	rRac	e Sh	aft S	uppo	ort Bl	ock					([	Dimer	nsion	s in ir	nches)
Waymount Part Number	Nominal LinearRace Shaft Diameter <b>d</b>	L	Η	W	A	В	С	E	F	G <sup>(4)</sup>	J	K	М	N	Ρ	Weight <sup>Ib</sup> f
WM-8	.500	1.50	1.06	1.75	.50	.88	.25	.75	.22	#8-32	.05	.09	.69	.50	.44	.20
WM-16	1.000	2.00	1.50	2.50	.75	1.25	.31	1.06	.28	1/4-28	.06	.13	.81	.69	.69	.50
WM-24	1.500	2.50	2.00	3.50	1.19	1.63	.44	1.19	.34	<sup>5</sup> /16-24	.13	.13	1.00	.75	.75	1.10
WM-32	2.000	3.00	2.50	4.00	1.44	1.88	.50	1.38	.41	<sup>3</sup> /8-24	.13	.13	1.25	.94	1.00	1.80
WM-48	3.000	5.00	4.31	6.75	2.38	3.38	.75	2.63	.66	<sup>5</sup> /8-18	.13	.13	2.25	1.63	1.50	10.20
WM-64	4.000	6.50	5.44	8.50	3.00	4.25	1.00	3.13	.78	<sup>3</sup> /4-16	.13	.13	2.75	2.00	2.00	21.20

 ${}^{\scriptscriptstyle (4)}\mbox{Supplied}$  with Waymount LinearRace Shaft support block

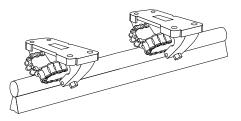
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



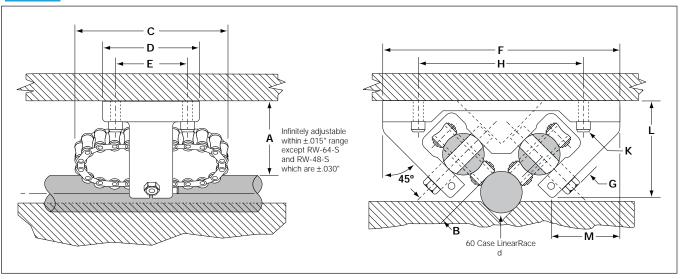


# RoundWay 1WA

Linear Guide #11 Dual Type Contaminated Environments, High Shock Loads



## INCH

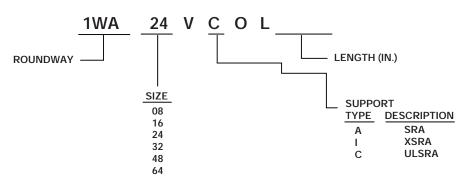


RoundWay* Linear	Guide	e 1W	A (S	ingle	е Тур	e) ar	nd 60	Са	se*	Line	arRa	ace*	Sha	ft		])	Dimensior	ns in ind	ches)
Part	Nom.	Α	В	С	D	E	F	G	Н	J	ł	<	L	Μ	60* Case*	60 Case	60 Case	Bearing	Dyn. <sup>(1)</sup>
Number	Dia.														LinearRace	LinearRace	Solid	Mass	Load
															Shaft Dia.	Shaft Max.	LinearRace	lb	Cap.
											Bolt	Hole			d	Length <sup>‡</sup>	shaft Ib/in		lbf
1WA-08-VCO	.500	1.00	.45	1.38	2.38	1.00	3.00	.19	2.25	.31	#8	.19	1.38	.69	.4995/.4990	168	.06	1.10	1370
1WA-16-VCO	1.000	1.75	.80	2.25	3.75	1.63	5.75	.25	4.0	.50	#10	.25	2.38	1.56	.9995/.9990	180	.22	4.90	4300
1WA-24-VCO	1.500	2.50	1.15	2.75	5.38	2.00	7.88	.31	6.0	.63	5/16	.38	3.38	2.13 2.50	1.4994/1.4989	204	.50	11.70	8600
1WA-32-VCO	2.000	3.25	1.50	3.50	7.38	2.50	9.75	.38	7.5	.75	3/8	.44	4.38	4.25	1.9994/1.9987	204	.89	25.20	17500
1WA-48-VCO	3.000	5.00	2.30	5.50	11.00	4.00	15.50	.63	12.0	1.25	5/8	.69	7.00	5.00	2.9992/2.9983	204	2.00	90	35000
1WA-64-VCO	4.000	6.50	3.00	7.00	14.88	5.00	19.25	.75	15.0	1.50	3/4	.81	8.63		3.9988/3.9976	204	3.56	193	70000

<sup>(1)</sup> Dynamic Load Capacity is based on 10 million inches of travel.

‡ Maximum length of 60 Case LinearRace Shafts are indicated above. If longer 60 Case LinearRace Shafts Support Rails are required, contact the Thomson Linear Guide Application Engineering department.

## ROUNDWAY LINEAR GUIDE PART NUMBER

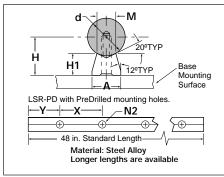






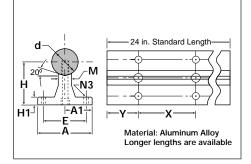
## 60 Case\* LinearRace\* Shaft Support Rails and Assemblies for Continuously Supported Applications





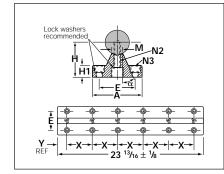
ULSRA Low P	rofile Shaft	Support F	ail Asse	mblies		(Dimer	nsions i	n inches	)
Part Number	Nominal LinearRace					Ν	2		
	Shaft	Н	H1	A	М			Х	Y
	Diameter <b>d</b>	±.002				Hole	Bolt		
ULSRA-08-XS	.500	.562	.34	.37	.25	.17	#6-32	4	2
ULSRA-16-XS	1.000	1.000	.56	.69	.50	.28	1/4-20	6	3
ULSRA-24-XS	1.500	1.375	.70	.93	.69	.41	3/8-16	8	4
ULSRA-32-XS	2.000	1.750	.85	1.18	.88	.53	1/2-13	8	4
ULSRA-48-XS	3.000	2.750	1.40	1.88	1.38	.81	3/4-10	8	4
ULSRA-64-XS	4.000	3.500	1.75	2.50	1.88	1.06	1-8	8	4

## SUPPORT TYPE A

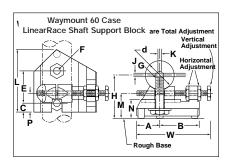


SRA Lin	earRace S	Shaft Supp	oort Ra	ail As	semb	lies			(E	)imensions in	inch	es)
Assembly With Solid	Nom. LinearRace Shaft Dia.	Н	H1	A	A1	E	М	N	3	Shaft Mounting Bolt	Х	Y
LinearRace	d	±.002			±.002			Hole	Bolt	N1		
SRA-08-XS	.500	1.125	.19	1.50	.750	1.00	.25	.17	#6	#6-32 x .88	4	2
SRA-16-XS	1.000	1.750	.25	2.13	1.063	1.50	.50	.28	1/4	<sup>1</sup> /4-20 x 1.50	6	3
SRA-24-XS	1.500	2.500	.38	3.00	1.500	2.25	.69	.34	<sup>5</sup> /16	<sup>3</sup> /8-16 x 2.50	8	4
SRA-32-XS	2.000	3.250	.50	3.75	1.875	2.75	.88	.41	<sup>3</sup> /8	<sup>1</sup> /2-13 x 2.50	8	4

## SUPPORT TYPE I



XSRA Linea	rRace	Shaf	t Su	ippo	ort I	Rail	Ass	emblies				(Dimens	ion	s in ir	iches)
Assy. With Solid	Nominal LinearRace Shaft	H 001	H1	A	E	М		N2			Ν	13	а	Х	Y
LinearRace	Diameter	+.000					Hole	Bolt	Counterbore	Hole	Bolt	Counterbore	deg		
XSRA-32	2.000	2.750	1.00	4.50	3.13	.88	.56	1⁄2-13 x 2	1 x .75 DP	.56	.50	1 x .63 DP	15	4	1.97
XSRA-48	3.000	4.000	1.31	6.00	4.25	1.25	.81	<sup>3</sup> /4-10 x 2.75	1.44 x 1.13 DP	.69	.63	1.25 x .75 DP	25	6	2.97



Waymou	unt* Linea	rRac	e Sh	aft S	uppo	rt Bl	ock					([	Dimer	nsions	s in ir	iches)
Waymount Part Number	Nominal LinearRace Shaft Dia. <b>d</b>	L	Η	W	A	В	С	E	F	G <sup>(4)</sup>	J	K	М	N	Р	Weight Ib <sub>f</sub>
WM-8	.500	1.50	1.06	1.75	.50	.88	.25	.75	.22	8-32	.05	.09	.69	.50	.44	.20
WM-16	1.000	2.00	1.50	2.50	.75	1.25	.31	1.06	.28	1/4-28	.06	.13	.81	.69	.69	.50
WM-24	1.500	2.50	2.00	3.50	1.19	1.63	.44	1.19	.34	<sup>5</sup> /16-24	.13	.13	1.00	.75	.75	1.10
WM-32	2.000	3.00	2.50	4.00	1.44	1.88	.50	1.38	.41	<sup>3</sup> /8-24	.13	.13	1.25	.94	1.00	1.80
WM-48	3.000	5.00	4.31	6.75	2.38	3.38	.75	2.63	.66	<sup>5</sup> /8-18	.13	.13	2.25	1.63	1.50	10.20
WM-64	4.000	6.50	5.44	8.50	3.00	4.25	1.00	3.13	.78	<sup>3</sup> /4-16	.13	.13	2.75	2.00	2.00	21.20

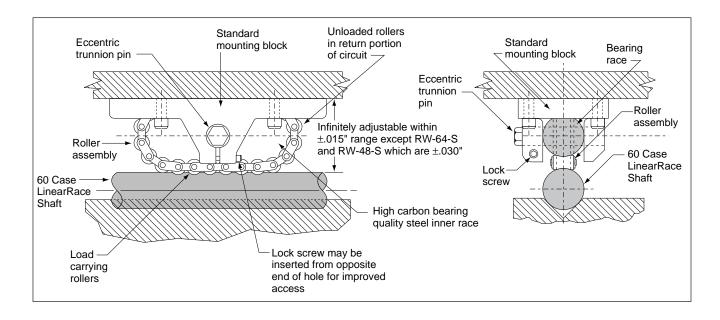
<sup>(4)</sup> Supplied with Waymount LinearRace Shaft support block

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.





## **RoundWay Linear Roller Bearings** RoundWay Operating Principle



Thomson invented the RoundWay\* Linear roller bearing for use in high load, heavy duty applications. Each RoundWay bearing combines the high load capacity of hardened and ground steel recirculating rollers with a rigid malleable iron pillow block providing extremely high load capacity with smooth linear travel. The RoundWay linear roller bearing comes in both a single and dual version. A single RoundWay linear roller bearing does not resist side loads and is therefore always used in conjunction with a dual version.

Each RoundWay linear roller bearing is designed for use on 60 Case\* LinearRace\* shaft. The 60 Case LinearRace shaft can be continuously supported using type LSR, SR, or XSR 60 Case LinearRace shaft support rails or intermittently supported using the adjustable Waymount\* LinearRace shaft supports type WM.

The RoundWay linear roller bearing consists of four basic parts: the bearing race, the roller assembly, the eccentric trunnion pin and the mounting block. The rolling elements of a RoundWay linear roller bearing are a series of concave rollers interconnected and linked by a chain assembly. As load is applied to the mounting block it is transferred through the bearing race and roller assembly to the supported 60 Case LinearRace shaft. Connecting the mounting block to the RoundWay bearing and roller assembly is an eccentric trunnion pin that allows the height of the RoundWay linear roller bearing to be adjusted to compensate for variations in the mounting surfaces or the build-up of tolerances between component elements. The eccentric trunnion pin can also be used to preload the RoundWay bearing by eliminating internal bearing clearance. After the eccentric trunnion pin has been adjusted it can be held in place by simply tightening the lock screw.

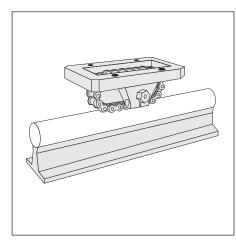
## Self-Aligning

The RoundWay single and dual bearings are designed with a built-in self-aligning capability that absorbs misalignment caused by inaccuracies in carriage or base machining. The RoundWay single bearing has an additional built-in self-aligning capability that allows it to absorb misalignment caused by two slightly out of parallel 60 Case LinearRace shafts. This feature is realized when two RoundWay single bearings are mounted on one 60 Case LinearRace shaft and two dual RoundWay bearings are on a parallel 60 Case LinearRace shaft.





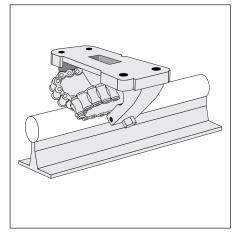
## **RoundWay Linear Roller Bearings** for Continuously Supported Applications



## RoundWay\* Linear Roller Bearing (Single Type)

- Available in <sup>1</sup>/<sub>2</sub> through 4 inch diameters.
- Load capacity range between 970 and 48,000 lb<sub>f</sub>.
- Travel speeds up to 100 ft/s.
- Accelerations up to 450 ft/s<sup>2</sup>.
  Can be adjusted to compensate for variations in the mounting surface.
- Self-aligning in all directions.
- Designed to compensate for two 60 Case\* LinearRace\* shafts that are slightly out of parallel
- Should always be used in conjunction with RoundWay Dual version.
- Can be mounted in a custom housing.

- Available with a two piece seal that retains lubrication while protecting the bearing from the ingress of dirt or contaminants.
- Easily mounted to carriage with four mounting bolts.

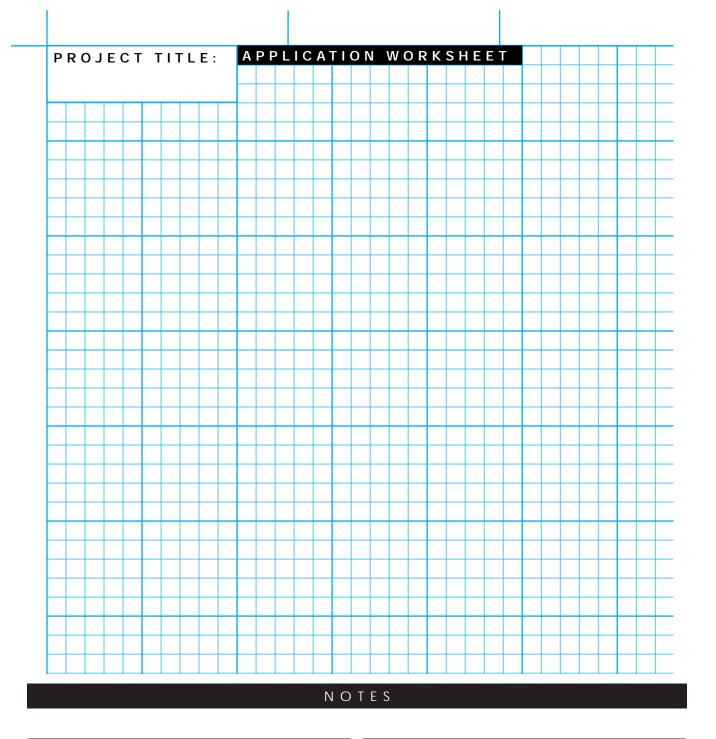


## RoundWay Linear Roller Bearing (Dual Type)

- Available in 1/2 through 4 inch diameters.
- $\bullet$  Load capacity range between 1370 and 70,000  $\rm lb_{f^{\rm .}}$
- Travel speeds up to 100 ft/s.
- Accelerations up to 450 ft/s<sup>2</sup>.
- Can be adjusted to compensate for variations in the mounting surface.
- Self-aligning in all directions.
- Available with a two piece seal that retains lubrication while protecting the bearing from the ingress of dirt or contaminants.
- Easily mounted to carriage with four mounting bolts.







For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

\_

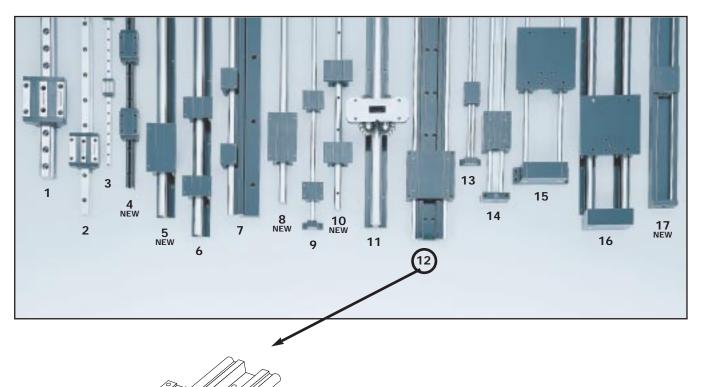


Linear Guides

The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



# Dual Shaft Rail Linear Ball Guides



HIGH LOADS IN ALL DIRECTIONS, PRE-ALIGNED SHAFTS, SMOOTH OPERATION, EASY TO INSTALL

### Dual Shaft Rail\* Linear Ball Guides Offer:

- Increased life within the same envelope. RoundRail\* linear guides feature the new patented Super Smart Ball Bushing\* bearings for up to 216X the life or 6X the load capacity of conventional bearings
- Cost savings: save time and money preparing your mounting surfaces before bolting down RoundRail linear guides
- The RoundRail Advantage\*. The inherent self-aligning-in-all-directions design of the Super Smart Ball Bushing bearing allows for ultra smooth travel when mounted to wider toleranced prepared surfaces

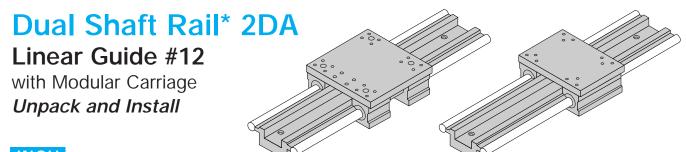
- Maximum performance. Fully supported for maximum (multidirectional) load applications without concerns for shaft deflection
- Unlimited travel lengths without concerns for machined reference edges or butt joint alignment
- The Super Smart Ball Bushing bearing... the most technologically advanced and most robust linear bearing in the world
- Pre-aligned 60 Case\* LinearRace\* shaft for quick and easy mounting
- Corrosion resistant versions for maximum performance in harsh environments.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

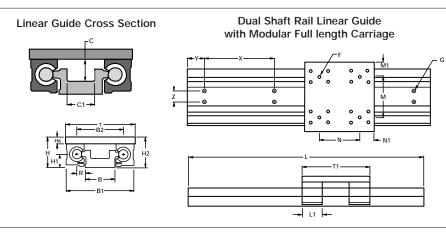


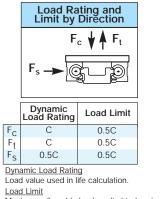


#12



### INCH





Maximum allowable load applied to bearing.

Dual Shaft Rai	I Linear Gu	de 2DA	with Mo	dular Full	Length Ca	arriage				(Dime	nsions in	inches)
Part	Nominal	L1	T1	Н	H1	H2	H6	Т	В	B1	R	B2
Number	Diameter											
2DA-08-JOB	.50	1.50	4.5	2.062	.875	1.94	.50	4.5	2.00	4.37	.500	3.0
2DA-12-JOB	.75	1.88	6.0	2.562	1.125	2.44	.50	6.0	2.62	5.87	.688	4.0
2DA-16-JOB	1.00	2.63	7.5	3.062	1.375	2.97	.50	7.5	3.25	7.37	.875	5.0

Dual Shaft R	ail Lin	ear Gu	ide 2D	A with	Modu	lar Ful	I Leng	th Carı	riage					(Dimensior	ns in inches)
Part	C1	С	N	N1	Μ	M1	Х	Y	Z	F	(	3	Max.	Carriage	Dual Shaft
Number											Bolt	Hole	Stroke	Part	Rail Asmbly.
													Length	Number	Part No.
2DA-08-JOB	1.25	1.07	4.0	.25	3.25	.63	4.0	2.0	.75	1/4-20	1/4	.28	L-(4.5)	DSRC-08-BB	DSRA-08
2DA-12-JOB	1.62	1.31	5.0	.50	4.50	.75	6.0	3.0	1.00	1/4-20	<sup>5</sup> /16	.34	L-(6.0)	DSRC-12-BB	DSRA-12
2DA-16-JOB	2.00	1.68	6.5	.50	5.50	1.00	6.0	3.0	1.25	1/4-20	3/8	.41	L-(7.5)	DSRC-16-BB	DSRA-16

Dual Shaft Rail Support Material: Black Anodized Aluminum Alloy Maximum continuous length of support rails is 72". If longer continuous shaft support rails are required, please contact the Thomson Linear Guides Application Engineering department.





#### **Dual Shaft Rail\* Linear Guide** 2DA Benefits:

- Used in continuously supported applications when rigidity is required.
- Adaptable to any drive system.
- Pre-aligned and preassembled for immediate installation and use.
- Designed for medium to heavy loads.

#### **Dual Shaft Rail Linear Guide** 2DA Components: †

- 1 Dual LinearRace\* shaft rail assembly.
- 1 modular carriage with 4 open type Super Smart Ball Bushing\* pillow blocks.

#### Specifying this Thomson Linear Guide:

1. Determine the proper Linear Guide for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System

2DA	12-JOB L24
Linear Guide	Linear Guide
Designation _	Length
Nominal Diamet	er 」 └ Type of Carriage

F<sub>t</sub>

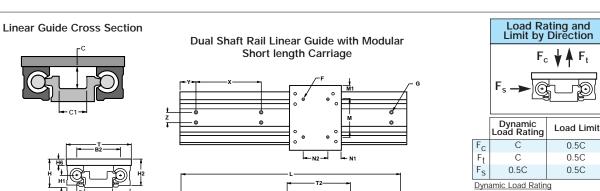
0.5C

0.5C

0.5C

<sup>†</sup> Super Ball Bushing bearings are

used in .500 inch size carriages.



Load value used in life calculation.

Load Limit Maximum allowable load applied to bearing

Dual Shaft Rai	ual Shaft Rail Linear Guide 2DA with Modular Short Length Carriage											
Part	Nominal	L1	T2	Н	H1	H2	H6	Т	В	R	B1	B2
Number	Diameter											
2DA-08-KOA	.500	1.50	3.5	2.062	.875	1.94	.50	4.5	2.00	.500	4.37	3.0
2DA-12-KOA	.750	1.88	4.5	2.562	1.125	2.44	.50	6.0	2.62	.688	5.87	4.0
2DA-16-KOA	1.000	2.63	6.0	3.062	1.375	2.97	.50	7.5	3.25	.875	7.37	5.0

Dual Shaft Ra	il Line	ar Gui	de 2DA	A with I	Modula	ar Shoi	rt Leng	th Car	riage					(Dimension	ns in inches)
Part	C1	С	N1	N2	M	M1	Х	Y	Z	F	G		Max.	Carriage	Dual Shaft
Number											Bolt	Hole	Stroke Length	Part Number	Rail Asmbly. Part No.
2DA-08-KOA	1.25	1.07	.250	3.00	3.25	.63	4.0	2.0	.75	1/4-20	1/4	.28	L-(3.5)	DSRC-08-BA	DSRA-08
2DA-12-KOA	1.62	1.31	.250	4.00	4.50	.75	6.0	3.0	1.00	1/4-20	<sup>5</sup> /16	.34	L-(4.5)	DSRC-12-BA	DSRA-12
2DA-16-KOA	2.00	1.68	.375	5.25	5.50	1.00	6.0	3.0	1.25	1/4-20	3/8	.41	L-(6.0)	DSRC-16-BA	DSRA-16

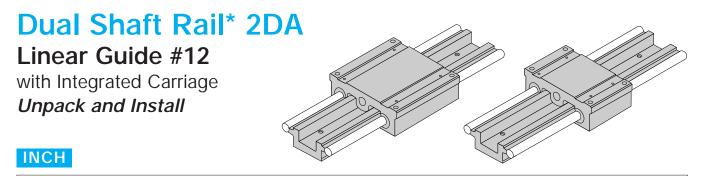
Dual Shaft Rail Support Material: Black Anodized Aluminum Alloy Maximum continuous length of support rails is 72". If longer continuous shaft support rails are required, please contact the Thomson Linear Guides Application Engineering department.

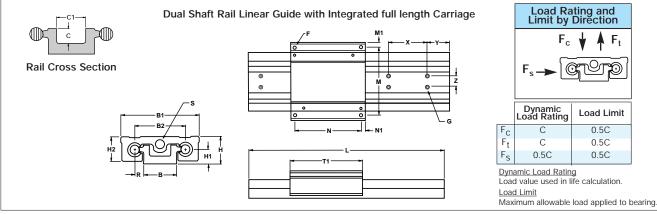
Dynamic Load	Rating (C) Matrix	(4 m	illion inches travel)
Linear Guide Assembly Part No.	Dynamic Load Rating, C (Ib <sub>f</sub> ) (Even Distribution)	Pillow Block Dynamic Load Rating, C (lb <sub>f</sub> )	Dynamic Roll Moment Rating, C (in - Ib <sub>f</sub> )
2DA-08-JOB	480	120	720
2DA-12-JOB	3200	800	6400
2DA-16-JOB	5400	1350	13500
2DA-08-KOA	480	240*	720
2DA-12-KOA	3200	1600*	6400
2DA-16-KOA	5400	2700*	13500

\* Twin Pillow Block









Dual Shaft Rai	l Linear Gui	de 2DA w	vith Integra	ated Carria	age				(Dir	nensions i	in inches)
Part Number	Nominal Diameter	T1	Н	H1	H2	В	R	B1	B2	С	C1
2DA-08-00B	.50	4.5	1.625	.875	1.43	2.00	.500	4.6	3.0	.64	1.25
2DA-12-00B	.75	6.0	2.125	1.125	1.93	2.63	.688	6.1	4.0	.75	1.62
2DA-16-00B	1.00	7.5	2.625	1.375	2.44	3.25	.875	7.6	5.0	.99	2.00

Dual Shaft Ra	il Linea	ar Guid	e 2DA v	with Int	egrated	d Carria	age						(Dimensior	ns in inches)
Part	N	N1	M	M1	Х	Y	Z	S	F	0	à	Max.	Carriage	Dual Shaft
Number								As		Bolt	Hole	Stroke	Part	Rail Asmbly.
								Extruded				Length	Number	Part No.
2DA-08-00B	4.00	.25	4.00	.30	4.0	2.0	.75	.50	#10-32	1/4	.28	L-(4.5)	DSRC-08-SB	DSRA-08
2DA-12-00B	5.25	.37	5.25	.42	6.0	3.0	1.00	.70	1/4-20	<sup>5</sup> /16	.34	L-(6.0)	DSRC-12-SB	DSRA-12
2DA-16-00B	6.75	.37	6.75	.42	6.0	3.0	1.25	.90	<sup>5</sup> /16-18	3/8	.41	L-(7.5)	DSRC-16-SB	DSRA-16

Dual Shaft Rail Support Material: Black Anodized Aluminum Alloy

Maximum continuous length of support rails is 72". If longer continuous shaft support rails are required, please contact the Thomson Linear Guides

Application Engineering department.

Page 148





## Dual Shaft Rail\* Linear Guide 2DA Benefits:

- Used in continuously supported applications when rigidity is required.
- Adaptable to any drive system.
- Pre-aligned and preassembled for immediate installation and use.
- Designed for medium to heavy loads.

## Dual Shaft Rail Linear Guide 2DA Components:<sup>†</sup>

- 1 Dual LinearRace\* shaft rail assembly.
- 1 integrated carriage with 4 open type Super Smart Ball Bushing\* bearings.

#### Specifying this Thomson Linear Guide:

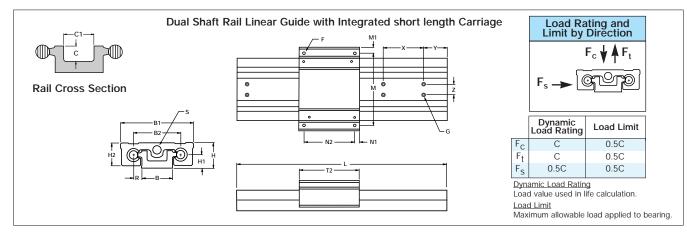
 Determine the proper Linear Guide for your load and life requirements.
 Select the part number.
 Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System

2DA-12-OOB L24 Linear Guide Designation \_\_\_\_\_ Linear Guide Designation \_\_\_\_\_ Type of Carriage

<sup>†</sup> Super Ball Bushing<sup>\*</sup> bearings are used in

500 inch size carriages



Dual Shaft Rai	l Linear Gui	de 2DA w	ith Integr	ated Car	riage				([	Dimensions	in inches)
Part Number	Nominal Diameter	T2	Н	H1	H2	В	R	B1	B2	С	C1
2DA-08-00A	.500	3.5	1.625	.875	1.43	2.00	.500	4.60	3.0	.64	1.25
2DA-12-00A	.750	4.5	2.125	1.125	1.93	2.63	.688	6.10	4.0	.75	1.62
2DA-16-00A	1.000	6.0	2.625	1.375	2.44	3.25	.875	7.60	5.0	.99	2.00

Dual Shaft Ra	il Linea	ar Guide	e 2DA v	vith Inte	egrated	I Carria	ige						(Dimension	is in inches)
Part	N	N2	Μ	M1	Х	Y	Z	S	F	(	3	Max.	Carriage	Dual Shaft
Number								As		Bolt	Hole	Stroke	Part	Rail Asmbly.
								Extruded				Length	Number	Part No.
2DA-08-00A	.25	3.00	4.00	.30	4.0	2.0	.75	.50	#10-32	1/4	.28	L-(3.5)	DSRC-08-SA	DSRA-08
2DA-12-00A	.37	3.75	5.25	.42	6.0	3.0	1.00	.70	1/4-20	<sup>5</sup> /16	.34	L-(4.5)	DSRC-12-SA	DSRA-12
2DA-16-00A	.37	5.25	6.75	.42	6.0	3.0	1.25	.90	<sup>5</sup> /16-18	3/8	.41	L-(6.0)	DSRC-16-SA	DSRA-16

Dual Shaft Rail Support Material: Black Anodized Aluminum Alloy Maximum continuous length of support rails is 72". If longer continuous shaft support rails are required, please contact the Thomson Linear Guides Application Engineering department.

Dynamic Load R	ating (C) Matrix (4	million inches travel)
Linear Guide Assembly Part No.	Dynamic Load Rating, C (lb <sub>f</sub> ) (Even Distribution)	Dynamic Roll Moment Rating, C (in - Ib <sub>f</sub> )
2DA-08-00B	480	720
2DA-12-00B	3200	6400
2DA-16-00B	5400	13500
2DA-08-00A	480	720
2DA-12-00A	3200	6400
2DA-16-00A	5400	13500

Note: Above load ratings used for life calculations. Load limit of assembly 50%.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



\* The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.
\* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

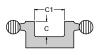


# Dual Shaft Rail\* 2DA

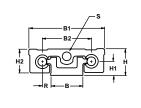
### Linear Guide #12

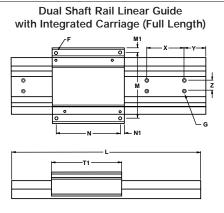
with Integrated Carriage Unpack and Install

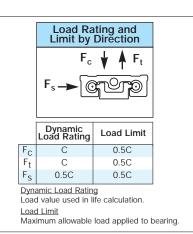
### METRIC



Dual Shaft Rail Support Cross Section







Dual Shaft Rai	I Linear Gu	ide 2DA wi	th Integrate	ed Carriage					(Dimensi	ons in mm)
Part Number	T1	Н	H1	H2	В	R	B1	B2	С	C1
2DA-08-00K	110	41	22,2	36,3	50,8	12,7	116,8	76,2	16	32
2DA-12-00K	150	54	28,6	49,0	66,8	17,5	155	101,6	19	41
2DA-16-OOK	190	66	34,9	61,3	82,5	22,3	193	127	25	51

Dual Shaft Ra	Dual Shaft Rail Linear Guide 2DA with Integrated Carriage         (Dimensions)												sions in mm)
Part	Ν	N1	М	M1	Х	Y	Z	S	F	G	Max.	Carriage	Dual Shaft
Number								As			Stroke	Part	Rail Asmbly.
								Extruded			Length	Number	Part No.
2DA-08-00K	100	5	105	5,9	120	60	20	13	M5	M6	L-(110)	DSRC-08-SK	DSRA-08M
2DA-12-00K	130	10	135	10,0	150	75	25	18	M6	M8	L-(150)	DSRC-12-SK	DSRA-12M
2DA-16-00K	170	10	175	9,0	200	100	30	23	M8	M10	L-(190)	DSRC-16-SK	DSRA-16M

Maximum continuous length of 2DA LinearRace\* shaft support rail is 1828 mm. If longer continuous one-piece LinearRace Shaft support rails are required, contact the Thomson Systems Application Engineering Department.





## Dual Shaft Rail\* Linear Guide 2DA Benefits:

- Used in continuously supported applications when rigidity is required.
- Adaptable to any drive system.
- Pre-aligned and preassembled for immediate installation and use.
- Designed for medium to heavy loads.

## Dual Shaft Rail Linear Guide 2DA Components:<sup>†</sup>

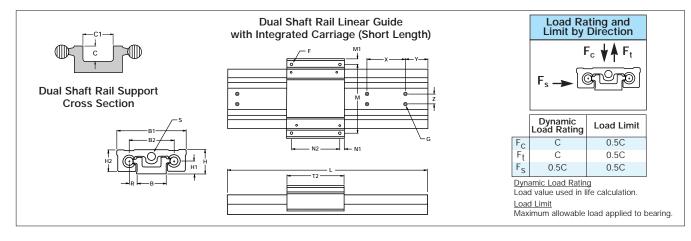
- 1 Dual LinearRace\* shaft rail assembly
- 1 integrated carriage with 4 open type Super Smart Ball Bushing\* bearings.

#### Specifying this Thomson Linear Guide:

 Determine the proper Linear Guide for your load and life requirements.
 Select the part number.
 Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number.

#### Part Numbering System

2DA-12-	OOK L600
Linear Guide	Linear Guide
Designation	Length
Nominal Diameter	Type of Carriage



Dual Shaft Rail	(Dimensions in mm)									
Part Number	T2	Н	H1	H2	В	R	B1	B2	С	C1
2DA-08-OOJ	85	41	22,2	36,3	50,8	12,7	116,8	76,2	16	32
2DA-12-00J	110	54	28,6	49,0	66,8	17,5	155	101,6	19	41,3
2DA-16-OOJ	150	66	34,9	61,2	82,4	22,3	193	127	25	50,8

Dual Shaft Ra	Dual Shaft Rail Linear Guide 2DA with Integrated Carriage         (Dimensions in m)												sions in mm)
Part	N1	N2	М	M1	Х	Y	Z	S	F	G	Max.	Carriage	Dual Shaft
Number								As			Stroke	Part	Rail Asmbly.
								Extruded			Length	Number	Part No.
2DA-08-00J	5	75	105	5,9	120	60	20	13	M5	M6	L-(85)	DSRC-08-SJ	DSRA-08M
2DA-12-00J	10	90	135	10,0	150	75	25	18	M6	M8	L-(110)	DSRC-12-SJ	DSRA-12M
2DA-16-00J	10	130	175	9,0	200	100	30	23	M8	M10	L-(150)	DSRC-16-SJ	DSRA-16M

Maximum continuous length of 2DA LinearRace\* Shaft support rail is 1828 mm. If longer continuous one-piece LinearRace shaft support rails are required, contact the Thomson Systems Application Engineering Department.

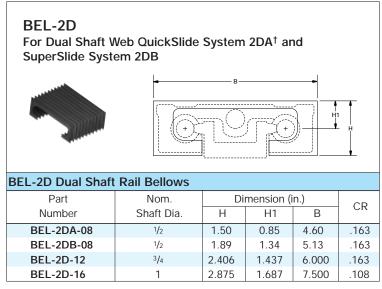
Dynamic Load	Rating (C) Matrix	(100 km travel)			
Linear Guide	Dynamic Load	Dynamic			
Assembly	Rating, C (N)	Roll Moment			
Part No.	(Even Distribution)	Rating, C (N • M)			
2DA-08-00K	2140	82			
2DA-12-00K	14250	725			
2DA-16-OOK	24000	1525			
2DA-08-OOJ	2140	82			
2DA-12-00J	14250	725			
2DA-16-OOJ	24000	1525			

<sup>†</sup> Super Ball Bushing<sup>\*</sup> bearings are used in 500 inch size carriages





### **Bellow (Way Covers) Option**



Each moveable bellows comes with 1 section of bellowS and 2 mounting brackets and mounting screws.

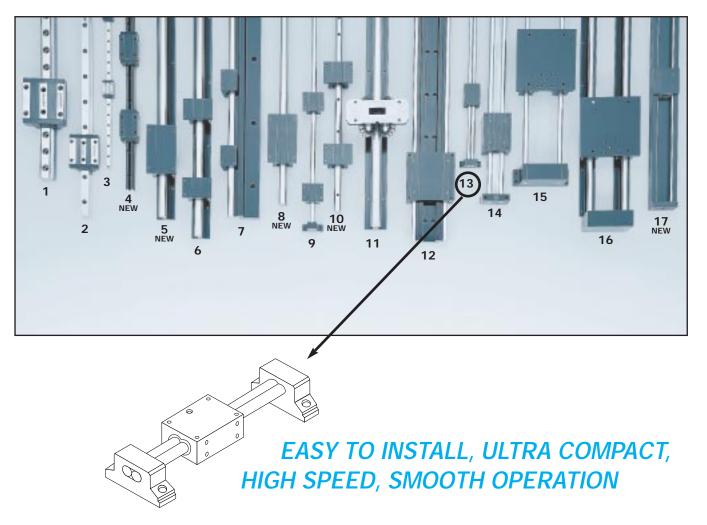
<sup>†</sup> Appropriate arrangements for afixing the Bellows at each end of the QuickSlide 2DA System are required.

- Note 1: For Dual Shaft Rail Linear Ball Guide with **Manual Brake** see page 294 in Systems section of this catalog
- Note 2: For a **Ball Screw Actuated** version of a Dual Shaft Rail Linear Ball Guide, see page 230 and 258 in the Systems section of this catalog.





# Twin Shaft Linear Ball Guides



### Twin Shaft\* Linear Ball Guides Offer:

- Pre-aligned shafts, very compact, ultra smooth travel
- Pre-aligned shafts, end supported for gantry style or 'bridge' applications
- Available in horizontal and vertical orientations for increased mounting flexibility
- Compact, twin shaft design for use in applications with over turning loads
- End supported for quick and easy installation

- RoundRail\* linear guides feature the new patented Super Smart Ball Bushing\* bearing for up to 216X the life or 6X the load capacity of conventional bearings
- Cost savings: save time and money preparing your mounting surfaces before bolting down RoundRail linear guides
- Corrosion resistant versions for maximum performance in harsh environments.

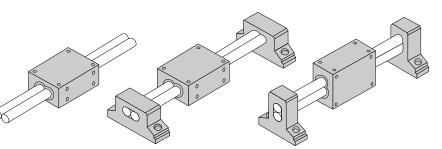
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



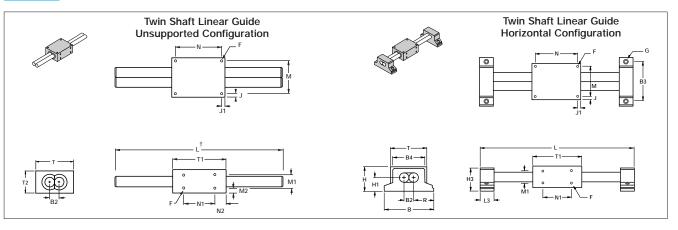
Page 153

#13

### Twin Shaft\* 2BA Linear Guide #13 Unpack and Install



### INCH



Twin Shaft Linea	win Shaft Linear Guide Unsupported 2BA (Dimensio										
Part Number	Nominal Diameter	Т	T1	Τ2	B2	MAX. Stroke Length <sup>(1)</sup>					
2BA-04-00E	.250	1.25	1.75	.75	.25	L-(1.75)					
2BA-06-OOE	.375	1.50	2.00	.87	.37	L-(2.00)					
2BA-08-OOE	.500	2.00	2.75	1.25	.50	L-(2.75)					

<sup>(1)</sup> Allowance must be made for user supplied end supports.

Twin Shaft I	win Shaft Linear Guide End Supported 2BA (Horizontal Configuration) (Dimensions in inches												n inches)				
Part	Nom.	L3	T	T1	T2	Н	H1	H3	В	R	B3	B4	(	3	MAX.	End	Twin
Number	Dia.												Bolt	Hole	Stroke Length	Support Part No.	Shaft Part No.
2BA-04-OPE	.250	.50	1.25	1.75	.75	.875	.50	.80	1.75	.750	1.38	1.05	#6	.17	L-(2.75)	TSB-04-H	TS-04
2BA-06-OPE	.375	.56	1.50	2.00	.87	1.000	.56	.94	2.00	.813	1.63	1.30	#6	.17	L-(3.12)	TSB-06-H	TS-06
2BA-08-OPE	.500	.62	2.00	2.75	1.25	1.375	.75	1.25	2.60	1.050	2.13	1.70	#8	.19	L-(4.00)	TSB-08-H	TS-08

Universal	Jniversal Carriage (Dimensions in in											in inches)	
Part Number	Nominal Diameter	Т	T1	T2	N	N1	N2	Μ	M1	M2	J	J1	Mounting Screw F
TSC-04-U	.250	1.25	1.75	.75	1.375	1.00	.37	1.00	.50	.12	.13	.19	#6-32
TSC-06-U	.375	1.50	2.00	.87	1.62	1.25	.37	1.25	.62	.12	.13	.19	#6-32
TSC-08-U	.500	2.00	2.75	1.25	2.37	2.00	.37	1.62	.87	.18	.19	.19	#8-32

† Maximum Overall Length is 36 inches.

#### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for Deflection calculations.





## Twin Shaft\* Linear Guide 2BA Benefits:

- Used when spanning or bridging a gap.
- Twin welded LinearRace\* shaft design resists torque.
- Compact low profile design allows for minimal machine size.
- Designed to move light loads with virtually frictionless travel.

# Twin Shaft Linear Guide 2BA Components:

- Universal integrated, carriage with 4 special open type Super Ball Bushing\* bearings.
- Twin welded 60 Case\* LinearRace shafts.
- 2 vertical or horizontal double end supports.

#### Specifying this Thomson Linear Guide:

 Determine the proper Linear Guide for your load and life requirements.
 Select the part number.
 Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

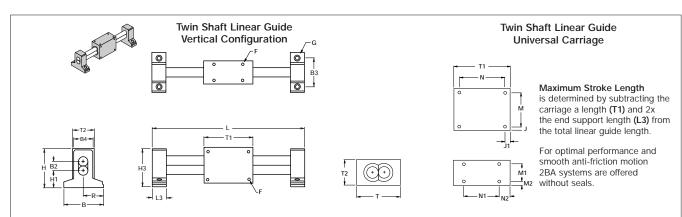
#### Part Numbering System

Designation -

Nominal Diameter

2BA-08-ONE L24 Linear Guide | | | |

Linear Guide Length Type of Carriage Type of Support



Twin Shaft L	vin Shaft Linear Guide End Supported 2BA (Vertical Configuration) (Dimensions in inches											n inches)					
Part	Nom.	L3	Т	T1	T2	Н	В	H1	H3	R	B3	B4	0	ć	Max.	End	Twin
Number	Dia.												Bolt	Hole	Stroke	Support	Shaft
															Length	Part No.	Part No.
2BA-04-ONE	.250	.50	1.25	1.75	.75	1.375	1.50	.625	1.31	.750	1.13	.68	#6	.17	L-(2.75)	TSB-04-V	TS-04
2BA-06-ONE	.375	.56	1.50	2.00	.87	1.620	1.62	.688	1.56	.813	1.25	.80	#6	.17	L-(3.12)	TSB-06-V	TS-06
2BA-08-ONE	.500	.62	2.00	2.75	1.25	2.125	2.00	.875	2.00	1.000	1.50	1.10	#8	.19	L-(4.00)	TSB-08-V	TS-08

Dynamic Load C	apacity Matrix (4	million inches travel)				
Linear Guide Assembly Part No.	Dynamic Load Capacity (lb <sub>f</sub> ) (Even Distribution)	Dynamic Roll Moment Capacity (in - Ib <sub>f</sub> )				
2BA-04-OOE 2BA-06-OOE	10 20	2.5 7.4				
2BA-08-00E	50	25				
	10	2.5				
2BA-04-OPE 2BA-06-OPE	10 20	2.5 7.4				
2BA-08-OPE	50	25				

Dynamic Load C	apacity Matrix (4	million inches travel)
Linear Guide Assembly Part No.	Dynamic Load Capacity (lb <sub>f</sub> ) (Even Distribution)	Dynamic Roll Moment Capacity (in - Ib <sub>f</sub> )
2BA-04-ONE	10	2.5
2BA-06-ONE	20	7.4
2BA-08-ONE	50	25

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

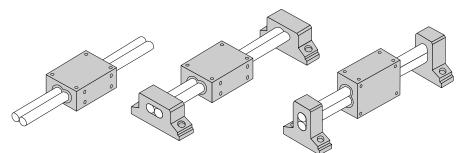


\* The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.
\* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

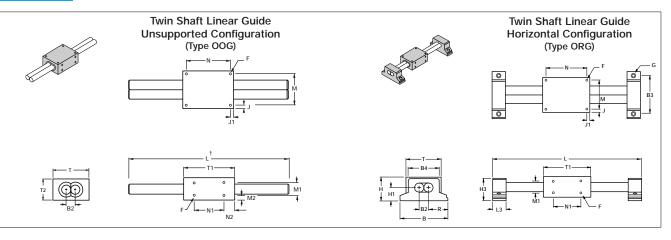


# Twin Shaft<sup>\*</sup> 2BA Linear Guide #13

Unpack and Install



### METRIC



Twin Shaft Linea	win Shaft Linear Guide Unsupported 2BA										
Part	Т	T1	T2	B2	Max.						
Number					Stroke						
					Length (1)						
2BA-04-00G	31,8	45	19,1	6,34	L-(45)						
2BA-06-OOG	38,1	50	22,2	9,50	L-(50)						
2BA-08-00G	50,8	70	31,8	12,70	L-(70)						

<sup>(1)</sup> Allowance must be made for user supplied end supports.

Twin Shaft Linea	ar Guic	le End	Suppo	orted 2	BA (Ho	orizont	al Con	figurat	ion)					(Dimensior	ns in mm)
Part	L3	Т	T1	T2	Н	H1	H3	В	R	B3	B4	G	Max.	End	Twin
Number													Stroke	Support	Shaft
													Length	Part No.	Part No.
2BA-04-ORG	15	31,8	45	19	22	12,5	20,1	44,3	19,0	35	26,7	M3	L-(75)	TSB-04-HM	TS-04
2BA-06-ORG	15	38,1	50	22,2	25	13,9	23,5	50	20,0	41	33	M3	L-(80)	TSB-06-HM	TS-06
2BA-08-ORG	15	50,8	70	31,8	35	19,1	31,8	65,5	26,5	54	43,2	M4	L-(100)	TSB-08-HM	TS-08

Universal Carria	ge									(Dir	nensior	ns in mm)
Part Number	Т	T1	T2	N	N1	N2	М	M1	M2	J	J1	Mounting Screw F
TSC-04-UM	31,8	45	19	35	25	10	24	12	3,5	3,9	5,0	M3
TSC-06-UM	38,1	50	22,2	40	30	10	30	15	3,6	4,0	5,0	M3
TSC-08-UM	50,8	70	31,8	60	50	10	40	22	4,9	5,4	5,0	M4

† Maximum Overall Length is 900 mm.

#### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for Deflection calculations.





#### Twin Shaft\* Linear Guide **2BA Benefits:**

- Used when spanning or bridging a gap.
- Twin welded LinearRace\* shaft design resists torque.
- Compact low profile design allows for minimal machine size.
- Designed to move light loads with virtually frictionless travel.

#### Twin Shaft Linear Guide **2BA Components:**

- Universal integrated carriage with 4 special open type Super Ball Bushing\* bearings.
- Twin welded 60 Case\* LinearRace shafts.
- 2 vertical or horizontal double end supports.

#### Specifying this Thomson Linear Guide:

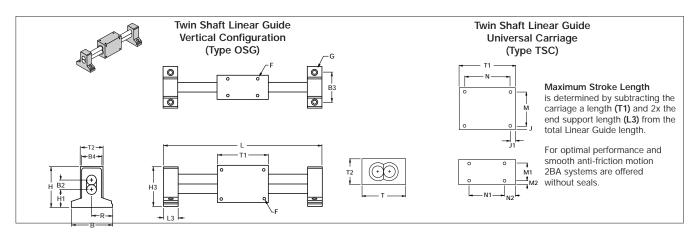
1. Determine the proper Linear Guide for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number.

#### Part Numbering System

Designation

#### 2BA-08-ORG L600 Linear Guide

Linear Guide Length Nominal Diameter -Type of Carriage Type of Support



Twin Shaft Linea	r Guic	le End	Suppo	orted 2	BA (Ve	rtical (	Config	uration	)					(Dimensio	ns in mm)
Part Number	L3	Т	T1	T2	Н	H1	H3	R	В	B3	B4	G	Max. Stroke Length	End Support Part No.	Twin Shaft Part No.
2BA-04-OSG	15	31,8	45	19	35	16	33,4	18,95	38	28	17,3	M3	L-(75)	TSB-04-VM	
2BA-06-OSG 2BA-08-OSG	15 15	38,1 50,8	50 70	22,2 31,8	40 54	16,2 22,2	38,4 50,9	20,25 25,00	40 50	31 38	20,3 27,9	M3 M4	L-(80) L-(100)	TSB-06-VM TSB-08-VM	

Dynamic Load	Capacity Matrix	(100 km travel)	Dynamic Load	Capacity Matrix	(100 km travel)
Linear Guide Assembly Part No.	Dynamic Load Capacity (N) (Even Distribution)	Dynamic Roll Moment Capacity (N • mm)	Linear Guide Assembly Part No.	Dynamic Load Capacity (N) (Even Distribution)	Dynamic Roll Moment Capacity (N • mm)
2BA-04-00G	45	285	2BA-04-OSG	45	285
2BA-06-OOG	90	855	2BA-06-OSG	90	855
2BA-08-OOG	225	2860	2BA-08-OSG	225	2860
2BA-04-ORG	45	285			
2BA-06-ORG	90	855			

2860

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



2BA-08-ORG

225

Page 157

### **Twin Shaft Linear Ball Guide Accessories**

Note: For a Lead Screw Actuated version of a Twin Shaft Linear Ball Guide, see page 226 in the systems section of this catalog.

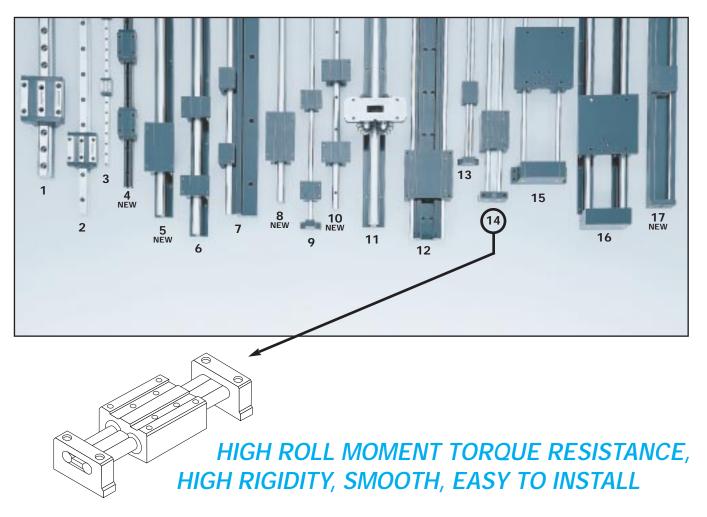
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



## Twin Shaft Web Linear Ball Guides



### Twin Shaft Web\* Linear Ball Guides Offer:

- Twin Shaft Web design for high roll moment capacity, high rigidity and ultra smooth travel
- Pre-aligned shafts, end supported for gantry style or 'bridge' applications
- Available in horizontal and vertical orientations for increased mounting flexibility
- End supported for quicker and easy installation
- The Super Smart Ball Bushing\* bearing... the most technologically advanced and most robust linear bearing in the world
- The RoundRail Advantage\*. The inherent self-aligning-in-all-directions design of the Super Smart Ball Bushing bearing allows for ultra smooth travel when mounted to wider toleranced prepared surfaces
- Cost savings: save time and money preparing your mounting surfaces before bolting down RoundRail\* linear guides
- Corrosion resistant versions for maximum performance in harsh environments.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

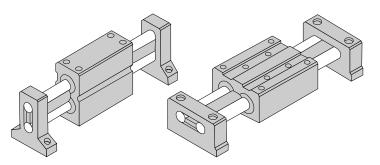


Page 159

#14

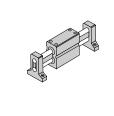
# Twin Shaft Web\* 2CA

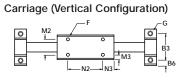
Linear Guide #14 with Universal Carriage Unpack and Install



-H2

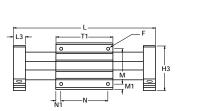
INCH





Twin Shaft Web Linear Guide with Universal





Twin Shaft W	eb Linear	Guide	End Sup	ported	2CA (Ve	rtical C	onfigura	ation)				(Dimen:	sions in	inches)
Part Number	Nominal Diameter	L3	H	H1	H3	H7	В	R	B2	B3	B4	B6	T1	N
2CA-08-0KE	.50	.63	2.750	.875	2.56	.38	2.25	1.125	1.13	1.63	1.12	.31	3.5	3.00
2CA-12-0KE	.75	.75	3.625	1.125	3.44	.56	3.00	1.500	1.50	2.25	1.63	.38	4.5	4.00
2CA-16-OKE	1.00	1.00	4.625	1.375	4.50	.75	4.00	2.000	2.00	3.00	2.25	.50	6.0	5.25

Twin Shaft We	b Line	ar Guid	e End	Suppo	rted 2C	A (Vert	ical Co	onfigura	ation)				(Dimensio	ns in inches)
Part	N1	N2	N3	H2	B1	M	M1	M2	M3	F	(	3	Max.	Twin Shaft
Number											Bolt	Hole	Stroke	Web
													Length	Part Number
2CA-08-OKE	.25	2.5	.50	1.5	2.62	2.00	.31	.88	.31	#10-32	#10	.22	L-(4.75)	TSW-08
2CA-12-0KE	.25	3.5	.50	2.0	3.50	2.87	.31	1.38	.31	1/4-20	1/4	.28	L-(6.00)	TSW-12
2CA-16-OKE	.38	4.5	.75	2.5	4.50	3.62	.44	1.62	.44	<sup>5</sup> /16-18	<sup>5</sup> /16	.34	L-(8.00)	TSW-16

2CA (Vertical Configuration	) Carriage and End Suppor	t Part No.
Linear Guide	Carriage	End Support
Part Number	Part Number	Part Number
2CA-08-OKE	WC-08	WSB-08-V
2CA-12-0KE	WC-12	WSB-12-V
2CA-16-OKE	WC-16	WSB-16-V

Maximum Length is 72 inches.

#### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for Deflection calculations.



## Twin Shaft Web\* Linear Guide 2CA Benefits:

- Used when spanning or bridging a gap.
- Double LinearRace\* shaft and welded integral web design maximizes torque and dramatically improves deflection characteristics.
- Pre-aligned for quick and easy installation.
- Designed to move medium loads with virtually frictionless travel.

## Twin Shaft Web Linear Guide 2CA Components: †

Universal integrated, carriage with

- 4 open type Super Smart Ball Bushing\* bearings.
- Twin welded 60 Case\* LinearRace shafts with integral web.
- 2 vertical or horizontal double end supports.

#### Specifying this Thomson Linear Guide:

 Determine the proper Linear Guide for your load and life requirements.
 Select the part number.
 Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

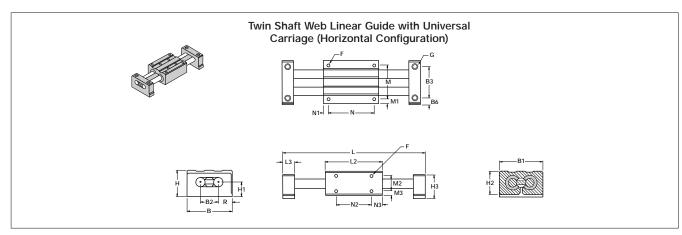
#### Part Numbering System

Designation

Nominal Diameter

2CA-12-OME L24 Linear Guide | | | |

Linear Guide Length Type of Carriage Type of Support



Twin Shaft We	b Linear	Guide En	d Suppo	win Shaft Web Linear Guide End Supported 2CA (Horizontal Configuration)         (Dimensions in inches)													
Part Number	Nominal Diameter	L3	Н	H1	H3	В	R	B2	B3	B6	T1	N					
2CA-08-OME	.50	.63	1.625	.875	1.5	2.62	.750	1.13	2.00	.31	3.5	3.00					
2CA-12-OME	.75	.75	2.125	1.125	2.0	3.50	1.000	1.50	2.75	.37	4.5	4.00					
2CA-16-OME	1.00	1.00	2.625	1.375	2.5	4.50	1.250	2.00	3.62	.50	6.0	5.25					

Twin Shaft We	b Linea	ar Guid	e End	Suppo	rted 2C	A (Hori	izonta	Config	juratio	n)			(Dimensio	ns in inches)
Part Number	N1	N2	N3	H2	B1	М	M1	M2	M3	F	Bolt	G Hole	Max. Stroke Length	Twin Shaft Web Part Number
2CA-08-OME	.25	2.5	.50	1.5	2.62	2.00	.31	.88	.31	#10-32	#10	.22	L-(4.75)	TSW-08
2CA-12-OME	.25	3.5	.50	2.0	3.50	2.87	.31	1.38	.31	<sup>1</sup> /4-20	1/4	.28	L-(6.00)	TSW-12
2CA-16-OME	.38	4.5	.75	2.5	4.50	3.62	.44	1.62	.44	<sup>5</sup> /16-18	<sup>5</sup> /16	.34	L-(8.00)	TSW-16

2CA (Horizontal Configurat	ion) Carriage and End Supp	oort Part No.
Linear Guide	Carriage	End Support
Part Number	Part Number	Part Number
2CA-08-OME	WC-08	WSB-08-H
2CA-12-OME	WC-12	WSB-12-H
2CA-16-OME	WC-16	WSB-16-H

#### Dynamic Load Capacity Matrix (4 million inches travel)

-		
Linear Guide Assembly Part No.	Dynamic Load Capacity (lb <sub>f</sub> ) (Even Distribution)	Dynamic Roll Moment Capacity (in - Ib <sub>f</sub> )
2CA-08-OKE	290	165
2CA-12-0KE	1800	1350
2CA-16-OKE	3000	3000
2CA-08-OME	290	165
2CA-12-OME	1800	1350
2CA-16-OME	3000	3000

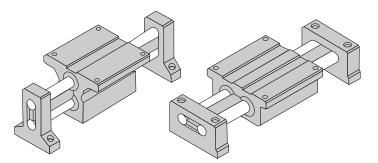
† Super Ball Bushing\* bearings are used in .500 inch size carriages.



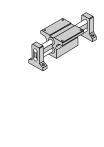


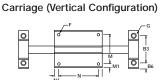
# Twin Shaft Web\* 2CA

### Linear Guide #14 with Flanged Carriage Unpack and Install



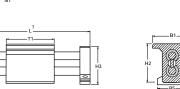
INCH





Twin Shaft Web Linear Guide with Flanged





Twin Shaft We	b Linear (	Guide E	nd Sup	ported 2	2CA (Vei	rtical Co	onfigura	tion)				(Dimens	sions in	inches)
Part Number	Nominal Diameter	L3	H	H1	H3	H7	В	R	B2	B3	B4	B6	T1	N
2CA-08-OKA	.50	.63	2.750	.875	2.56	.38	2.25	1.125	1.13	1.63	1.12	.31	3.5	3.00
2CA-12-OKA	.75	.75	3.625	1.125	3.44	.56	3.00	1.500	1.50	2.25	1.63	.38	4.5	4.00
2CA-16-OKA	1.00	1.00	4.625	1.375	4.50	.75	4.00	2.000	2.00	3.00	2.25	.50	6.0	5.25

Twin Shaft We	Twin Shaft Web Linear Guide End Supported 2CA (Vertical Configuration)												
Part	N1	H2	H5	B1	B5	M	M1	F	(	3	Max.	Twin Shaft	
Number									Bolt	Hole	Stroke	Web	
											Length	Part Number	
2CA-08-OKA	.25	2.62	.37	3.5	1.5	3.00	.25	#10-32	#10	.22	L-(4.75)	TSW-08	
2CA-12-OKA	.25	3.50	.50	4.5	2.0	4.00	.25	1/4-20	1/4	.28	L-(6.00)	TSW-12	
2CA-16-OKA	.38	4.50	.62	6.0	2.5	5.25	.38	<sup>5</sup> /16-18	<sup>5</sup> /16	.34	L-(8.00)	TSW-16	

2CA (Vertical Configuration)	Flanged Carriage and End S	Support Part No.
Linear Guide	Carriage	End Support
Part Number	Part Number	Part Number
2CA-08-0KA	FWC-08-V	WSB-08-V
2CA-12-0KA	FWC-12-V	WSB-12-V
2CA-16-OKA	FWC-16-V	WSB-16-V

† Maximum Overall Length is 72 inches.

#### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for Deflection calculations.





## Twin Shaft Web\* Linear Guide 2CA Benefits:

- Used when spanning or bridging a gap.
- Double LinearRace\* Shaft and welded integral web design maximizes torque and dramatically improves deflection characteristics.
- Pre-aligned for quick and easy installation.
- Designed to move medium loads with
- virtually frictionless travel. Flanged carriage provides a larger
- Flanged carriage provides a larger mounting surface.

# Twin Shaft Web Linear Guide 2CA Components: †

- Flanged integrated, carriage with 4 open type Super Smart Ball Bushing\* bearings.
- Twin welded 60 Case\* LinearRace shafts with integral web.
- 2 vertical or horizontal double end supports.

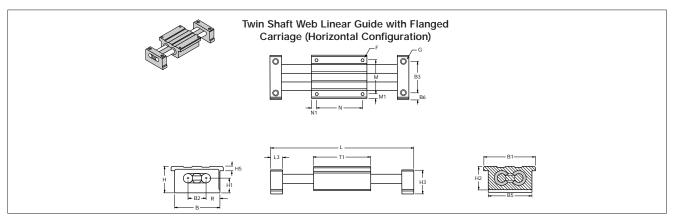
#### Specifying this Thomson Linear Guide:

 Determine the proper Linear Guide for your load and life requirements.
 Select the part number.
 Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System

2CA-12-OKA L24 Linear Guide Designation \_\_\_\_\_ Nominal Diameter \_\_\_\_\_Type

Linear Guide Length Type of Carriage



Twin Shaft We	win Shaft Web Linear Guide End Supported 2CA (Vertical Configuration)											
Part Number	Nominal Diameter	L3	Н	H1	H3	В	R	B2	B3	B6	T1	N
2CA-08-OMB	.50	.63	1.625	.875	1.5	2.62	.75	1.13	2.00	.31	3.5	3.00
2CA-12-OMB	.75	.75	2.125	1.125	2.0	3.50	1.00	1.50	2.75	.37	4.5	4.00
2CA-16-OMB	1.00	1.00	2.625	1.375	2.5	4.50	1.25	2.00	3.62	.50	6.0	5.25

Twin Shaft We	Twin Shaft Web Linear Guide End Supported 2CA (Horizontal Configuration)         (Dimensions in inche)												
Part Number	N1	B1	B5	М	M1	H2	H5	F	( Bolt	G Hole	Max. Stroke Length	Twin Shaft Web Part Number	
2CA-08-OMB	.25	3.5	2.62	3.00	.25	1.5	.37	#10-32	#10	.22	L-(4.75)	TSW-08	
2CA-12-OMB	.25	4.5	3.50	4.00	.25	2.0	.50	1/4-20	1/4	.28	L-(6.00)	TSW-12	
2CA-16-OMB	.38	6.0	4.50	5.25	.38	2.0	.62	<sup>5</sup> /16-18	<sup>5</sup> /16	.34	L-(8.00)	TSW-16	

2CA (Horizontal Configuratio	n) Flanged Carriage and End	Support Part No.
Linear Guide	Carriage	End Support
Part Number	Part Number	Part Number
2CA-08-OMB	FWC-08-H	WSB-08-H
2CA-12-OMB	FWC-12-H	WSB-12-H
2CA-16-OMB	FWC-16-H	WSB-16-H

#### Dynamic Load Capacity Matrix (4 million inches travel)

-		
Linear Guide Assembly Part No.	Dynamic Load Capacity (lb <sub>f</sub> ) (Even Distribution)	Dynamic Roll Moment Capacity (in - Ib <sub>f</sub> )
2CA-08-OKA	290	165
2CA-12-OKA	1800	1350
2CA-16-OKA	3000	3000
2CA-08-OMB	290	165
2CA-12-OMB	1800	1350
2CA-16-OMB	3000	3000

† Super Ball Bushing\* bearings are used in .500 inch size carriages.

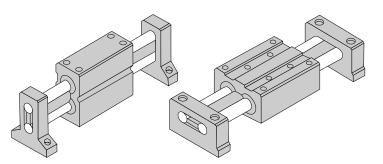


Page 163

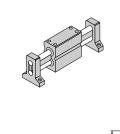
# Twin Shaft Web\* 2CA

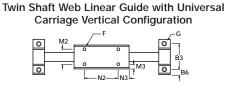
# Linear Guide #14 with Universal Carriage

Unpack and Install

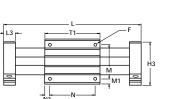


METRIC









Twin Shaft Web Linear Guide End Supported 2CA (Vertical Configuration) (Dimensions in m											s in mm)		
Part Number	L3	Н	H1	H3	H7	В	R	B2	B3	B4	B6	T1	N
2CA-08-OTH	15	70	22,5	65,0	10,6	55	27,5	28,6	41	28,6	7,5	90	75
2CA-12-OTH	20	92	28,4	87,3	15,4	74	36,9	38,1	56	41,3	10	115	100
2CA-16-OTH	25	117	34,6	114,0	19,6	100	50,0	50,7	76	57,2	12,5	155	135

Twin Shaft Web Linear Guide End Supported 2CA (Vertical Configuration)         (Dimensions in m)													imensions in mm)
Part Number	N1	N2	N3	H2	B1	M	M1	M2	M3	F	G	Max. Stroke Length	Twin Shaft Web Part Number
2CA-08-OTH	7,5	60	15	38,1	66,6	50	8,3	25	6,6	M5	M5	L-(120)	TSW-08
2CA-12-OTH	7,5	85	15	50,8	88,9	75	7,0	35	7,9	M6	M6	L-(155)	TSW-12
2CA-16-OTH	10	115	20	63,3	114,1	90	12,0	45	9,0	M8	M8	L-(205)	TSW-16

2CA (Vertical Configuration) Carriage and End Support Part No.									
Linear Guide Part Number	Carriage Part Number	End Support Part Number							
2CA-08-OTH	WC-08-SM	WSB-08-VM							
2CA-12-OTH	WC-12-SM	WSB-12-VM							
2CA-16-OTH	WC-16-SM	WSB-16-VM							

Maximum Length is 1800 mm.

#### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for Deflection calculations.





## Twin Shaft Web\* Linear Guide 2CA Benefits:

- Used when spanning or bridging a gap.
- Double LinearRace\* shaft and welded integral web design maximizes torque and dramatically improves deflection characteristics.
- Prealigned for quick and easy installation. 2 vertical or horizontal double end
- Designed to move medium loads with virtually frictionless travel.

## Twin Shaft Web Linear Guide 2CA Components: <sup>†</sup>

- Universal integrated, carriage with
- 4 open type Super Smart Ball Bushing\* bearings.
- Twin welded 60 Case\* LinearRace shafts with integral web.
- 2 vertical or horizontal double enc supports.

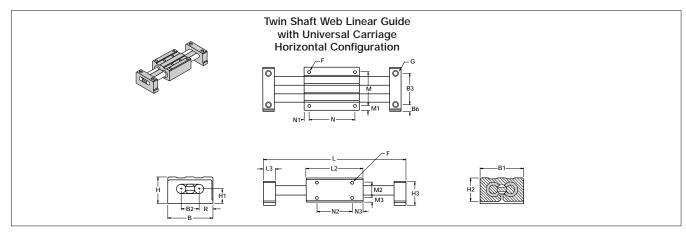
#### Specifying this Thomson Linear Guide:

 Determine the proper Linear Guide for your load and life requirements.
 Select the part number.
 Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number.

#### Part Numbering System

2CA-12-OWH L600 Linear Guide Designation Nominal Diameter

Linear Guide Length Type of Carriage Type of Support



Twin Shaft We		(Dimension	ns in mm)								
Part Number	L3	Н	H1	H3	В	R	B2	B3	B6	T1	N
2CA-08-OWH	15	41	21,9	37,8	65,3	18,5	28,6	50	8	90	75
2CA-12-OWH	20	54	28,6	50,8	88	24,5	38,1	70	8,5	115	100
2CA-16-OWH	25	65	33,5	62,1	114	31,5	50,8	90	12	155	135

Twin Shaft Web Linear Guide End Supported 2CA (Horizontal Configuration)         (Dimens)													ensions in mm)
Part Number	N1	N2	N3	H2	B1	М	M1	M2	M3	F	G	Max. Stroke Length	Twin Shaft Web Part Number
2CA-08-OWH	7,5	60	15	38,1	66,6	50	8,3	25	6,6	M5	M5	L-(120)	TSW-08
2CA-12-OWH 2CA-16-OWH	7,5 10,0	85 115	15 20	50,8 63,3	88,9 114,1	75 90	7,0 12,0	35 45	7,9 9,0	M6 M8	M6 M8	L-(155) L-(205)	TSW-12 TSW-16

2CA (Horizontal Configuration) Carriage and End Support Part No.									
Linear Guide Part Number	Carriage Part Number	End Support Part Number							
2CA-08-OWH	WC-08-SM	WSB-08-HM							
2CA-12-OWH	WC-12-SM	WSB-12-HM							
2CA-16-OWH	WC-16-SM	WSB-16-HM							

Dynamic Load	Dynamic Load Capacity Matrix						
Linear Guide	Dynamic Load	Dynamic					
Assembly	Capacity (N)	Roll Moment					
Part No.	(Even Distribution)	Capacity (N • M)					
2CA-08-OTH	1290	18.5					
2CA-12-OTH	8000	150					
2CA-16-OTH	13,350	3385					
2CA-08-OWH	1290	18.5					
2CA-12-OWH	8000	150					
2CA-16-OWH	13,350	340					

<sup>†</sup> Super Ball Bushing<sup>\*</sup> bearings are used in .500 inch size carriages.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

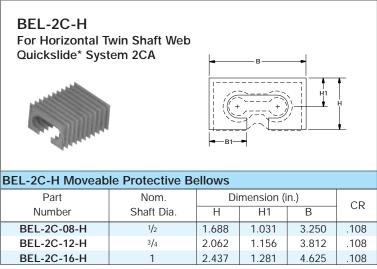


The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.
\* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

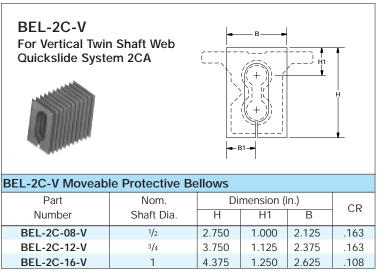


### **Twin Shaft Web Linear Ball Guide Accessories**

### **Bellows (Way Covers) Option**



Each moveable bellows comes with 1 section of bellows and 2 pairs of Velcro® Fasteners.



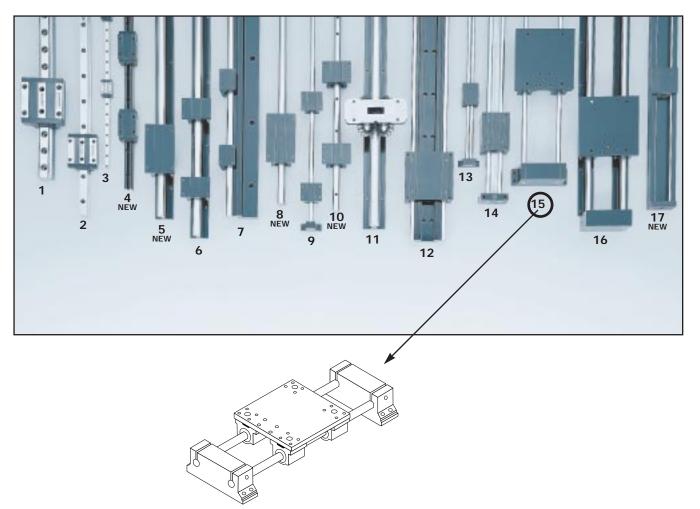
Each moveable bellows comes with 1 section of bellows and 2 pairs of Velcro® Fasteners.

Note: For a <u>Ball Screw Actuated</u> version of a Twin Shaft Web Linear Ball Guide, see page 228 in the systems section of this catalog.





# Double End Support Linear Ball Guides #15



### Double End Support Linear Ball Guides Offer:

- Increased life within the same envelope. RoundRail\* linear guides feature the new patented Super Smart Ball Bushing\* bearings for up to 216X the life or 6X the load capacity of conventional bearings
- Cost savings: save time and money preparing your mounting surfaces before bolting down RoundRail linear guides
- End supported for gantry style or 'bridge' applications
- The RoundRail Advantage\*. The inherent self-aligning-in-all-directions design of the Super Smart Ball Bushing bearing allows for ultra smooth travel when mounted to wider toleranced prepared surfaces
- The Super Smart Ball Bushing bearing... the most technologically advanced and most robust linear bearing in the world
- Pre aligned 60 Case\* LinearRace\* shaft for quick and easy mounting

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



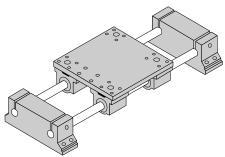
The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Trademark of Thomson industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Page 167

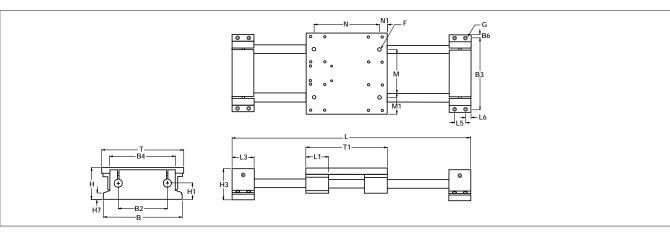
# **Double End Support 2AA**

### Linear Guide #15

with Intergrated End Supports and Carriage Unpack and Install







Double End Su	uble End Support Linear Guide 2AA with Carriage (Dimensions in inches										in inches)	
Part Number	Nominal Diameter	L1	L3	L5	L6	T1	Н	H1	H3	H6	H7	H9
2AA-08-AXB	.50	1.69	1.5	.75	.38	5.5	2.187	1.13	2.37	.38	.48	1.25
2AA-12-AXB	.75	2.06	2.0	1.00	.50	7.5	2.937	1.50	2.70	.50	.60	1.75
2AA-16-AXB	1.00	2.81	2.2	1.20	.50	9.0	3.437	1.75	3.45	.50	.60	2.19
2AA-24-AXB	1.50	4.00	2.8	1.50	.65	13.0	5.000	2.50	5.00	.75	.81	3.25

#### Shaft Deflection Note:

Load limit may be below the dynamic load rating due to shaft deflection. Bearings can accommodate up to 1/2° deflection. See Engineering Section (pg 204) for Deflection calculations.





2AA Benefits:

- Used when spanning or bridging a gap.
- System is pre-aligned for quick and easy installation.
- Easily adaptable to any drive system.
- Single part number is all that is required to specify.

#### Double End Support Linear Guide Double End Support Linear Guide 2AA Components: †

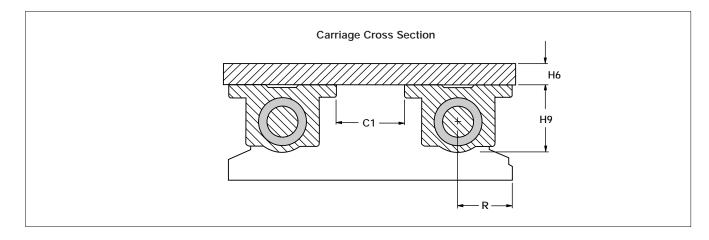
- 4 Super Smart Ball Bushing\* pillow blocks.
- 2 60 Case\* LinearRace\* shafts.
- 2 integrated double end supports.
- 1 mounting carriage top.

#### Specifying this Thomson Linear Guide:

1. Determine the proper Linear Guide for your load and life requirements. **2**. Select the part number. **3**. Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System

2AA-12-AXB L24 Linear Guide Linear Guide Designation \_ Length Nominal Diameter Type of Carriage Type of Bearing Block — Type of Support



Double End S	upport	Linear	Guide	2AA w	ith Car	riage							(D	imensi	ions i	n inches)
Part Number	В	R	Т	B2	B3	B4	B6	C1	N	N1	М	M1	F	( Bolt	G Hole	Max. Stroke Length
2AA-08-AXB	5.3	1.025	5.5	3.25	4.8	4.25	.24	1.25	4.5	.50	3.25	1.13	1/4-20	#8	.19	L-(8.5)
2AA-12-AXB	7.2	1.350	7.5	4.50	6.7	6.00	.25	1.75	6.0	.75	4.50	1.50	<sup>5</sup> /16-18	#10	.22	L-(11.50)
2AA-16-AXB	8.7	1.600	9.0	5.50	8.0	7.25	.35	2.25	7.0	1.00	5.50	1.75	<sup>3</sup> /8-16	1/4	.28	L-(13.40)
2AA-24-AXB	13.0	2.500	13.00	8.00	12.0	10.75	.50	3.25	10.0	1.50	8.00	2.50	1/2-13	<sup>5</sup> /16	.34	L-(18.60)

Dynamic Load	Capacity Matrix	(4 m	nillion inches travel)
Linear Guide Assembly Part No.	Dynamic Load Capacity (Ib <sub>f</sub> ) (Even Distribution)	Pillow Block Dynamic Load Capacity (lbf)	Dynamic Roll Moment Capacity (in - Ib <sub>f</sub> )
2AA-08-AXB	800	200	1300
2AA-12-AXB	3600	900	8100
2AA-16-AXB	6000	1500	16,500
2AA-24-AXB	12320	3080	57,280

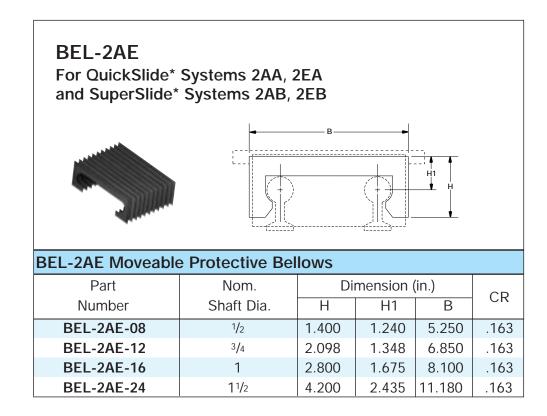
† Super Ball Bushing\* bearings are used in .500 inch size carriages.





### **Double End Support Linear Ball Guide Accessories**

### Bellows (Way Covers) Option

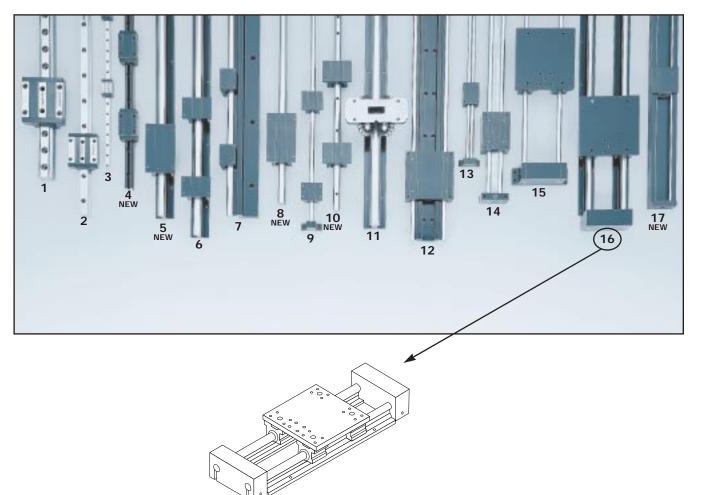


Note: For a **<u>Ball Screw Actuated</u>** version of a Double End Support Linear Ball Guide, see page 224 in the systems section of this catalog.





## Double Continuous Support Linear Ball Guides #16



### Double Continuous Support Linear Ball Guides Offer:

- Increased life within the same envelope. RoundRail\* linear guides feature the new patented Super Smart Ball Bushing\* bearings for up to 216X the life or 6X the load capacity of conventional bearings
- Maximum performance. Fully supported for maximum (multidirectional) load applications without concerns for shaft deflection
- The RoundRail Advantage\*. The inherent self-aligning-in-all-directions design of the Super Smart Ball Bushing bearing allows for ultra smooth travel when mounted to wider toleranced prepared surfaces

- Unlimited travel lengths without concerns for machined reference edges or butt joint alignment
- The Super Smart Ball Bushing bearing...the most technologically advanced and most robust linear bearing in the world
- Pre aligned 60 Case\* LinearRace\* shaft for quick and easy mounting
- Cost savings: save time and money preparing your mounting surfaces before bolting down RoundRail linear guides.



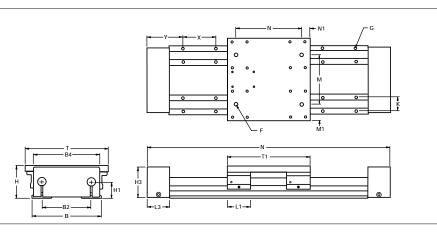
Page 171

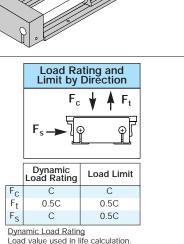
# **Double Continuous Support 2EA**

### Linear Guide #16

with Integrated End Supports and Carriage

INCH





Load Value used in life calcu Load Limit

Maximum allowable load applied to bearing.

Double Contin	bouble Continuously Supported Linear Guide 2EA with Carriage (Dimensions in inch										
Part Number	Nominal Diameter	L1	L3	T1	К	Н	H1	H3	H6	H7	H9
2EA-08-FAB	.50	1.50	1.5	5.5	1.00	2.187	1.13	2.38	.38	.19	1.12
2EA-12-FAB	.75	1.88	2.0	7.5	1.25	2.937	1.50	2.75	.50	.25	1.56
2EA-16-FAB	1.00	2.63	2.2	9.0	1.50	3.437	1.75	3.37	.50	.25	2.00
2EA-24-FAB	1.50	3.75	2.8	13.0	2.25	5.000	2.50	4.87	.75	.30	2.94

Maximum continuous length of support rails is 24". If longer continuous shaft support rails are required, please contact the Thomson Linear Guides Application Engineering department.





#### Double Continuous Support Linear Guide 2EA Benefits:

- Used in continuously supported applications when rigidity is required.
- Adaptable to any drive system.
- Pre-aligned and preassembled for immediate installation and use.
- Designed for medium to heavy loads.

#### Double Continuous Support Linear Guide 2EA Components:

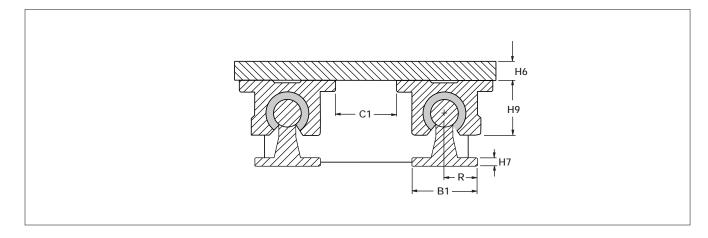
- 4 open type Super Smart Ball Bushing\* pillow blocks.
- 2 60 Case\* LinearRace\* shaft assemblies.
- 2 integrated double end supports.
- 1 mounting table top.

#### Specifying this Thomson Linear Guide:

 Determine the proper Linear Guide for your load and life requirements.
 Select the part number.
 Add the letter "L" followed by the overall length in inches, as a suffix to the part number.

#### Part Numbering System

2EA-12-FAB L24 Linear Guide Designation \_\_\_\_\_\_ Nominal Diameter \_\_\_\_\_ Type of Bearing Block \_\_\_\_\_Type of Support



Double Contin	uously	y Supj	oorted	Linea	r Guio	de 2EA	with	Carria	ge						(Dimer	nsions	in inches)
Part Number	Т	В	R	B1	B2	B4	C1	N	N1	M	M1	Х	Y <sup>(1)</sup>	F	Bolt	Hole	Max. Stroke Length
2EA-08-FAB	5.5	4.75	.750	1.50	3.25	4.25	1.25	4.5	.50	3.25	1.13	4.0	2.0	1/4-20	#8	.19	L-(8.5)
2EA-12-FAB	7.5	6.25	.875	1.75	4.50	6.00	1.75	6.0	.75	4.50	1.50	6.0	3.0	<sup>5</sup> /16-18	#10	.22	L-(11.5)
2EA-16-FAB	9.0	7.63	1.062	2.12	5.50	7.25	2.25	7.0	1.00	5.50	1.75	6.0	3.0	<sup>3</sup> /8-16	1/4	.28	L-(13.4)
2EA-24-FAB	13.0	11.00	1.500	3.00	8.00	10.75	3.25	10.0	1.50	8.00	2.50	8.0	4.0	1/2-13	<sup>5</sup> /16	.34	L-(18.6)

(1) For 18, 30 ad 42 inch Standard lengths Y is 3.0

Maximum continuous length of support rails is 24". If longer continuous shaft support rails are required, please contact the Thomson Linear Guides Application Engineering department.

Dynamic Load R	Dynamic Load Rating (C) Matrix (4 million inches travel)									
Linear Guide Assembly Part No.	Dynamic Load Rating, C (lbs) (Even Distribution)	Pillow Block Dynamic Load Rating, C (lbs)								
2EA-08-FAB	580	145								
2EA-12-FAB	3600	900								
2EA-16-FAB	6000	1500								
2EA-24-FAB	12320	3080								

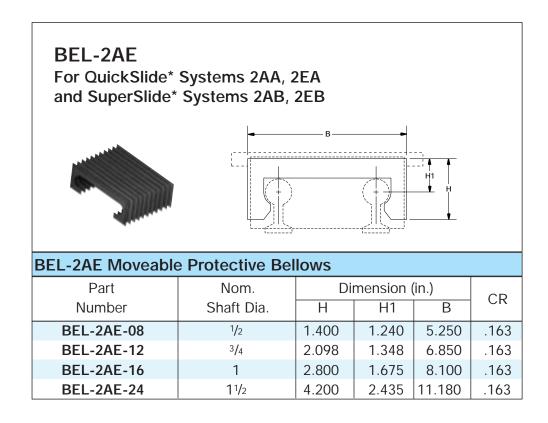
† Super Ball Bushing\* bearings are used in .500 inch size carriages.



Page 173

### **Double Continuous Support Linear Ball Guide Accessories**

**Bellows (Way Covers) Option** 



Note: For a <u>Ball Screw Actuated</u> version of a Double Continuous Support Linear Ball Guide, see page 234 in the systems section of this catalog.

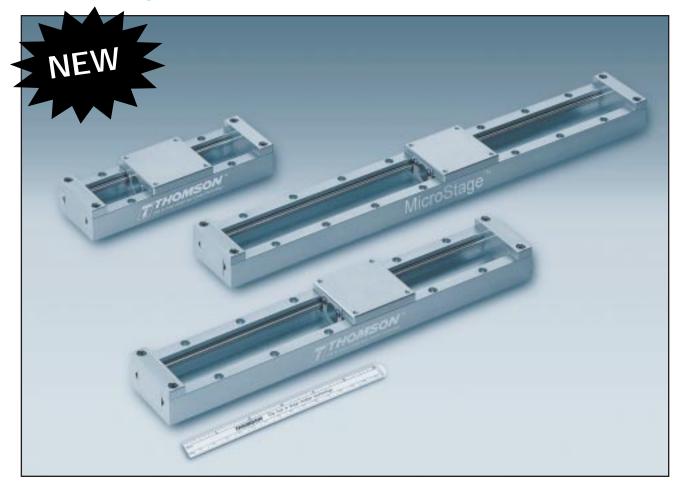
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

Page 174

The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



# MicroStage Linear Ball Guides



### MicroStage\* Linear Guides Offer:

- Smooth precision Linear Motion. Thomson MicroStage linear guide features unique bearing segment design and offers a backlash free slide assembly without sacrificing load capacity or smoothness.
- Rugged but light-weight MicroStage linear guides are manufactured from aerospace alloys providing the optimum in strength and rigidity, while dramatically decreasing the mass of the system. This provides for lower inertia and higher performance than either built-in, or external actuators.
- Flexible mounting configuration. MicroStage linear guides offer hole patterns and T-slots that allow them to be easily interchanged and also provide simple X-Y mounting.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

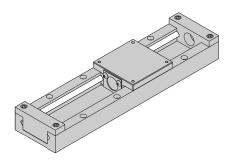


The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

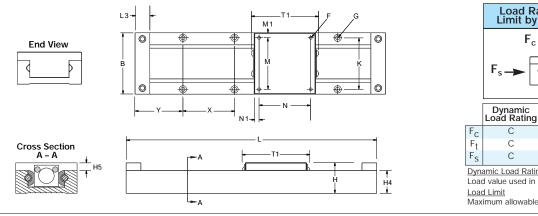


#17

### MicroStage\* MS25 Linear Guide #17 Unpack and Install







	Load Rating and Limit by Direction								
	F <sub>c</sub> ↓ ↑ F <sub>t</sub>								
	F <sub>s</sub> →								
	Dynamic Load Rating Load Limit								
	Dynamic Load Rating	Load Limit							
F <sub>C</sub>	Dynamic Load Rating C	Load Limit							
F <sub>C</sub> F <sub>t</sub>	-								
	С	С							
F <sub>t</sub> F <sub>s</sub> Dyn	C C	C C C							

MicroStage Line	ar Guide MS	25					(Dimer	isions in mm)
Part Number	В	F	G	Н	H4	H5	K	L3
MS25	50	M3 x 0,5	M3 Screw	25	18,6	6	42	12

MicroStage Line	icroStage Linear Guide MS25(Dimensions in mm)										
Part Number	Ν	N1	М	M1	T1	Base Mour X	nting Hole Y	Load Rating			
MS25	42	4	42	4	55	42	39	425N			

MicroStage Line	MicroStage Linear Guide MS25 (Dimensions in mm)									
Part Number	Length (L)	Stroke	Weight (kg)							
MS25-L120	120	41	0,31							
MS25-L204	204	125	0,45							
MS25-L288	288	209	0,59							
MS25-L372	372	293	0,72							

Part Numbering System MS25	1 1 2 0
Linear Guide Designation	Linear Guide Length

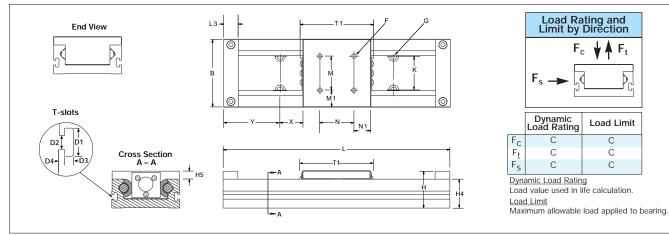
Note: For a <u>Lead Screw Actuated</u> version of a MicroStage Linear Ball Guide, see page 245 in the systems section of this catalog.





### MicroStage\* MS33 Linear Guide #17 Unpack and Install

### METRIC



MicroStage Linear Guide MS33 (Dimensions in mm									ons in mm)	
Part Number	В	D1	D2	D3	D4	F	G	Н	H4	H5
MS33	60	8,0	4,2	2,75	2	M5 x 0,8	M5 Screw	33	25,5	7

MicroStage Linear Guide MS33 (Dimensions in mm									ons in mm)	
Part	К	L3	N	N1	Μ	M1	T1	Base Mour	nting Hole	Load
Number								Х	Y	Rating
MS33	30	13	30	15	30	15	65	100	50	850N

MicroStage Linear Guide MS33 (Dimensions in mm)							
Part	Length	Stroke	Weight				
Number	(L)		(kg)				
MS33-L200	200	109	0,74				
MS33-L300	300	209	1,00				
MS33-L400	400	309	1,27				

Note: For a <u>Lead Screw Actuated</u> version of a MicroStage Linear Ball Guide, see page 245 in the systems section of this catalog.

Part Numbering System MS33-L200 Linear Guide Designation Linear Guide Length

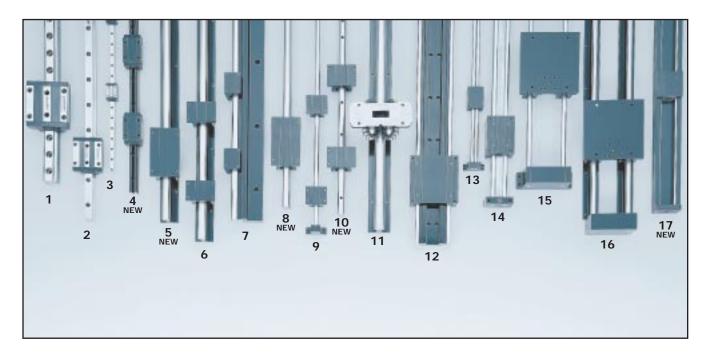
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



\* The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.
\* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



# **Installation Guidelines**



Installation Guidelines for :

Linear Guides #1 – 4

Linear Guides #5 – 11

Linear Guides #12 – 17

Pages 179 – 182

Pages 183–184

Page 184





# Installation Guidelines for Linear Guides #1-4

### **Surface Preparation**

ProfileRail\* bearings are generally mounted to structures that are inherently stiffer than the rail. For this reason, the bearings tend to assume the orientation of the surfaces to which they are fastened, through bearing deflection. When a deflection is imposed upon a bearing, especially a preloaded one, resultant forces occur. These forces are applied to the rolling elements and races, causing an increase in system friction and a decrease in system resolution, precision and life.

Various sources contribute to the overall error of the mounting surfaces. These include the surface flatness of the base surfaces, the location and parallelism of the reference surfaces, and the attendant errors of the bearing as described within the accuracy classes.

The surfaces that contact the base and reference edges may be milled, scraped, ground, or prepared by any other method that will produce a flat surface free of inconsistencies, which will tend to distort or skew the bearing. A simple stone may be used to remove high spots. Dirt and debris also contribute to the inaccuracies.

Associated with preload is a slight concavity of the carriage top surface. The preload is established when all the carriage screws are affixed to a planar surface, flattening the carriage base. Deviations from planarity of the carriage mounting surface will result in a preload change.

### **Mounting Tolerances**

The tolerances found in Tables 1-3 are intended to yield an installation for which the associated derating is negligible. These specifications are based upon the assumption that the structures of the application are infinitely rigid and are based upon the bearing reactions only.

### Rail Parallelism

A variation in the distance between the rails will induce a shear or side load on the bearings.

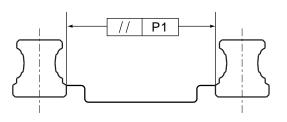


Figure 1

In order to reduce the effect of this shear load, tolerances for rail reference edge parallelism may be found in Table 1.

#### Table 1. Parallelism Between Multiple Rails, mm

Preload								
Bearing Type	Clearance	0,03 C <sup>†</sup>	0,08 C <sup>†</sup>	0,13 C <sup>†</sup>				
AccuMax* linear guide								
35	-	0,008	0,005	0,003				
45	-	0,010	0,007	0,004				
55	-	0,012	0,008	0,005				
65	-	0,014	0,010	0,007				
AccuGlide* linear guide								
20	0,016	0,011	0,007	0,005				
25	0,017	0,012	0,008	0,005				
30	0,021	0,014	0,009	0,006				
35	0,023	0,015	0,010	0,007				
45	0,027	0,018	0,012	0,008				
55	0,035	0,024	0,015	0,011				
AccuGlide Minia	AccuGlide Miniature linear guide							
10	0,009	0,004	-	-				
15	0,011	0,006	-	-				
20	0,013	0,008	-	-				
AccuGlide T-Series* linear guide								
20	-	0,045	-	-				
25	-	0,050	-	-				
30	-	0,055	-	-				
35	-	0,060	-	-				

<sup>†</sup>Where C=Dynamic Load Capacity

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-55-4-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

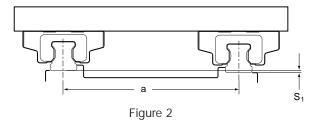


The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



# **Rail Vertical Offset**

A vertical offset of the rails across the axis will induce a roll moment onto the carriages.



In order to reduce the effect of this roll moment, tolerances for the vertical offset may be found in Table 2. This tolerance describes the attributes of the mounting surface, perpendicular to the rail axis.

Table 2. Allowable Vertical Offsets Between Rails (S1/a)

Preload				
Bearing Type	Clearance	0,03 C <sup>†</sup>	0,08 C <sup>†</sup>	0,13 C <sup>†</sup>
AccuMax* Linear Guide	-	0,0007	0,0005	0,0004
AccuGlide* Linear Guide	0,0006	0,0004	0,0003	0,0002
AccuGlide Miniature Linear Guide	0,0006	0,0004	-	-
AccuGlide T-Series* Linear Guide	.0020	-	-	-

<sup>†</sup>Where C=Dynamic Load Capacity

# Vertical Carriage Offset

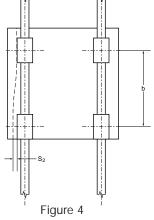
A vertical offset between fore and aft carriages will induce a pitch moment on the bearings.



Figure 3

### Lateral Carriage Offset

A lateral offset of the carriage reference edges will induce a yaw moment.  $\frac{1}{2}$ 



For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

In order to reduce the effects of these pitch and yaw moments, tolerances may be found in Table 3. This tolerance describes the attributes of the mounting surface parallel to the rail axis, and the reference edge straightness.

Table 3. Allowable Carriage Offsets (S<sub>2</sub>/b)

Preload			
Clearance	0,03 C <sup>†</sup>	0,08 C <sup>†</sup>	0,13 C <sup>†</sup>
0,00006	0,00005	0,00004	0,00003

<sup>†</sup>Where C=Dynamic Load Capacity

**NOTE:** All mounting tolerances should be inclusive of the H and A3 tolerances. Thus, a lower accuracy class bearing may require a more accurate installation.

# Mounting Hole Tolerances

The positional tolerance between the through holes in the rails is 0,5 mm.

The positional tolerance of the first rail mounting hole dimensioned from the datum end (called the "Y-dimension") is  $\pm 1,0$  mm.

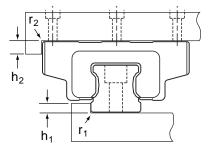
The overall rail length tolerance is  $\pm 2,0$  mm.

The positional tolerance between the mounting holes in the carriages is 0,2 mm.

# **Reference Edge Specifications**

The maximum shoulder heights and corner radii are listed in Table 4.

Figure 5. Shoulder Heights and Corner Radii





#### Table 4. Shoulder heights and corner radii, mm

Guide Type	Rail		Carı	riage
	h₁ max	r <sub>1</sub> max	h <sub>2</sub>	r <sub>2</sub> max
AccuMax* linear gui	de			
30	4	0,8	6	0,5
35	5	0,8	8	0,8
45	6,5	1	9	1
55	7	1,2	10	1,2
65	9	1,5	12	1,2
AccuGlide* linear gu	ide			
20	4	0,5	8	0,4
25	5,5	0,8	10	0,4
30	5,25	0,8	12	0,6
35	6	0,8	14	0,6
45	8,25	1,2	18	0,9
55	11	1,2	22	1,2
AccuGlide Miniature	e linear guide			
10	1,75	0,4	3,5	0,4
15	1,75	0,4	5	0,4
20	2	0,5	7	0,5
AccuGlide T-Series* linear guide				
20	3,9	0,4	10	0,3
25	5,5	0,5	12	0,4
30	5,9	0,7	14	0,5
35	5,9	0,8	15	0,6

### Installation Procedure

Clean and inspect all mating surfaces for burrs, nicks, dirt, etc. A simple stone can be used to remove minor imperfections in the mounting surfaces.

### Recommended Bolt Tightening Torque, Nm

Table 5

Bolt Size	Class 8.8	Class 12.9
M2.5	0,7	1,2
M4	2,8	4,6
M5	5,7	9,5
M6	9,5	16
M8	23	39
M10	46	77
M12	80	135
M14	129	215
M16	198	330

### **Rail Mounting**

1. Carefully place the rail on the mounting surface.

2. Insert screws into the mounting holes and tighten lightly.

**3.** Clamp the reference edge of the rail against a locating edge on the mounting surface.

The locating edge can be a machined reference edge, a straight edge, a row of dowels or keys, or some other edge which the rail can be clamped against. It should be straight, either within the mounting tolerances shown in Table 3 or according to the application requirements, whichever is tighter.

**4.** Starting from the center of the rail, tighten each screw to the recommended tightening torque in Table 5.

**5.** If parallel rails are to be used, one of the following methods may be employed to obtain the parallelism recommended in Table 1.

- a. 2 parallel locating edges
- b. a gage block or parallel between the rails
- c. the use of the top plate with the carriages mounted, to locate or "float" the second rail into place.

6. Repeat steps 1-4 to install the second rail.

**7.** Insert a rail plug into each counterbore in the rail. Carefully tap rail plugs into place using a soft material such as brass or wood. When properly installed, the rail plugs should be flush with the top surface of the rail. Do not countersink the rail plugs.

**Note:** Rail plugs are available and are shipped with all rails except for the AccuGlide<sup>\*</sup> Miniature Linear Guide size 10.

**8.** If desired, rail tape can then be applied to the top of the rail. For sizes 35 and below, the rail tape may be used without the rail plugs.





### **Butt Joints**

For rails longer than the longest length available in one piece, a butt joint is required. A butt joint is formed by butting the end of two matched rails together. The ends of rails to be butt jointed are specially machined and marked with same letter (A, B, C, etc.).

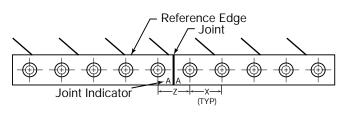
We strongly recommend the use of a locating edge when using butt jointed rails. This will ensure proper alignment of the raceways across the joint.

For AccuGlide\* and AccuGlide Miniature linear guide rails, the mounting hole spacing across the joint, Z, will be 1/2 the standard mounting hole spacing, X. For AccuMax\* linear guide rails, the mounting hole spacing across the joint, Z, will be equal to the standard mounting hole spacing, X.

Figure 6. Butt jointed rails

**Note:** Extreme care should be taken when mounting the carriages to the rails. Forcing a carriage onto a rail can knock out rolling elements and/or damage the carriage and rail.

For large side forces, hard mounting is recommended to resist any translation. Some methods for hard mounting are the use of tapered gibs, retaining plates, or set screws in combination with machined reference edges. Other methods include the use of an epoxy/replicating material, dowels, and keys. Upon request, carriages and rails can be special machined to accommodate dowels or keys. Consult the factory for details.



Once mounted, a gap between the ends of the butt jointed rails of 0,5 mm or less is acceptable.

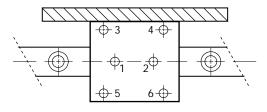
### **Carriage Mounting**

- 1. Carefully place the table top on the carriages.
- **2.** Insert the screws into the mounting holes and tighten lightly.
- **3.** Clamp the reference edge of the carriages to locating edges under the top plate.

**Note:** This is only required if the location of the center of the top plate is critical to the application, or if the top plate is being used to position a second rail parallel.

**4.** Tighten each screw to the recommended tightening torque in Table 5. For carriages with six mounting screws, the tightening sequence shown in Figure 7 is recommended.

Figure 7. Recommended Tightening Sequence



#### 5. Lubricate bearings.





# Installation Guidelines for Linear Guides #5–11

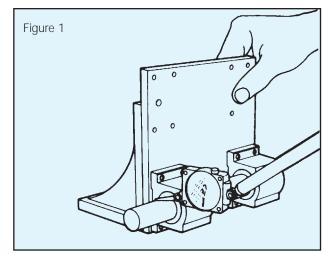
Thomson Ball Bushing\* bearings are manufactured to exceptionally close tolerances and offer smooth, virtually frictionfree linear motion. The performance features of the bearings will only be realized, however, if care is taken during their installation.

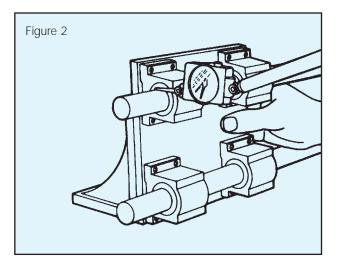
Two areas of primary importance are the bearing alignment and the 60 Case\* LinearRace\* shaft parallelism. Two bearings are normally used on each 60 Case LinearRace shaft to assure smooth operation. The housing should be carefully aligned using the method given below. If a single twin-type housing is used, these procedures are not necessary.

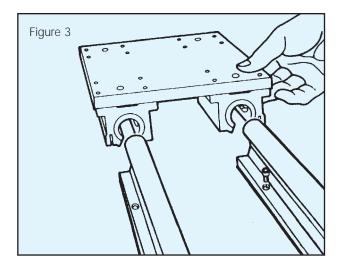
It is also necessary to assure that the height from the housing mounting surface to the 60 Case LinearRace shaft is consistent within .001 in. Shimming may be necessary depending on the accuracy of the mounting surfaces to which the housings are bolted.

The housing can be mounted to the plate using the following procedure:

- a. Prepare the table top with one side having an abutting surface.
- Mount two housings with the reference edges located against the abutting surface and tighten the hold down bolts. Figure 1
- c. Mount the second pair of housings on the opposite side of the carriage and tighten the bolts finger tight.
- d. Insert a locating 60 Case LinearRace shaft of correct diameter and tolerance through these two housings and reference the distance from the abutting surface in [b] above, to this locating 60 Case LinearRace shaft. Figure 2
- e. After appropriate alignment of this pair of housings, tighten bolts to secure housings to table top, now considered a "carriage assembly".







For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.

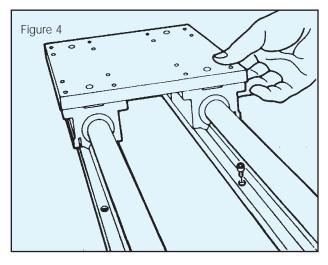


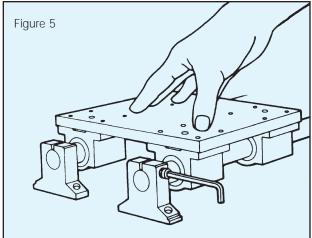
The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

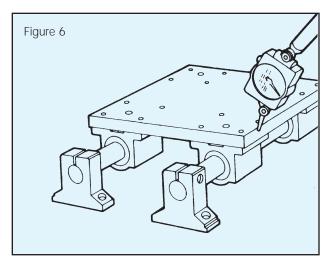


After the carriage assembly is properly prepared, the 60 Case\* LinearRace\* shaft must be mounted to the surface. To achieve smooth, accurate motion, the 60 Case LinearRace shaft must be mounted parallel within .001 inch over the length of the stroke. This can be done by using the following procedure:

- Mount one 60 Case LinearRace shaft (either end supported or continuously supported) to the surface with mounting bolts finger tight.
- b. Using an aligning device such as a laser, autocollimator or other optics, sight the 60 Case LinearRace shaft straight to .002"/ft or less and secure to mounting surface.
- c. After this first 60 Case LinearRace shaft is fixed, the second 60 Case LinearRace shaft can be positioned and held down with bolts finger tight.
- d. The carriage assembly is then mounted and its movement will pull this second 60 Case LinearRace shaft parallel to the first. Figures 3, 4
- e. If the second 60 Case LinearRace shaft is then secured into position, the procedure is complete. Note that for continuously supported systems, this securing should be done when the carriage is close to the bolts. For end supported systems, the securing should be done when the carriage is at the ends of the 60 Case LinearRace shaft. Figure 5
- f. An additional check can be done at this time to assure that the carriage assembly is tracking correctly (i.e., that the carriage assembly edge is moving parallel to the 60 Case LinearRace shaft). An indicator touching the carriage assembly edge should not vary, as the carriage assembly is moved along the 60 Case LinearRace shaft. Figure 6







### Installation Guidelines for Linear Guides #12–17



Remove linear guide from shipping package.

Fasten linear guide to mounting surface.





# Linear Guide Engineering Section

- Linear Guide Selection
- Technology Overview
- Sizing & Defining Guide Characteristics
- Applied Loading Calculations
- Load Ratings: Rolling Element Guides
   Sliding Contact Guides
- Preloading & Linear Guide Deflection
- Accuracy Class
- Actuation Force
- Lubrication
- Way Cover Length Calculations
- Butt Joint fax-back Worksheet
- Conversion Table



\* The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product suer to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.
\* Trademark of Thomson industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



### Linear Guide Selection

The selection of the type of linear guide can greatly affect machine performance and overall cost. In order to meet the wide variety of demands created by today's applications, proper selection from a broad range of linear guides is required.

For example, selecting a guide with too much rigidity will decrease the allowable installation tolerances, therefore, greatly increasing surface preparation costs. If the mounting surface is not prepared properly, the guide will run rough, and need to be replaced more frequently due to an unexpected reduction in travel life.

Consider all criteria appropriate for the application. Selection criteria include:

- Rigidity
- Travel accuracy
- Travel life
- Smoothness of travel
- Speed & Acceleration
- Envelope
- Environment
- Cost of Product
- Cost of Installation
  - Cost of Replacement

Selection of the most appropriate type of guide, should be based on quantitative/qualitative requirements and ranking by importance of the above selection criteria, as well as the following guidelines for the technology available.

### **Technology Overview**

The performance of a linear guide is based upon contact type, rolling element type, inner race geometry (Round Rail and Profile Rail), and other characteristics such as self-aligning capabilities. It is important to recognize that the options available for each characteristic have performance attributes. The selection process should be focused on matching these attributes with the most critical requirements of the application. The following technology guidelines can be used to assist in selecting the most appropriate type of linear guide. For a detailed application analysis, contact the **Thomson Technical Helpline\* at (800) 554-8466** or your local Thomson Linear Motion Specialist.

# Linear Guide Contact Types: Rolling Element and Sliding Contact



Rolling Element Type Guide Advantages

- Better resolution, due to minimal difference between the static & dynamic coefficients of friction
- Reduced drive costs, due to a coefficient of friction approximately 100 times less than that of sliding contact.
- Higher speeds
- Predictable life due to minimal wear which also eliminates bearing play concerns

# Linear Guides: 1, 2, 3, 4, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17



Sliding Contact Type Guide Advantages

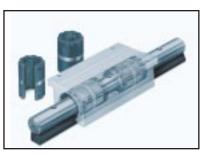
- Greater rigidity
- Better shock load capacity, due to maximum bearing surface contact
- Low corrosive materials, (i.e., aluminum and polymer) which provide greater reliability in extreme environmental conditions

Linear Guide: 5





# Linear Guide Rolling Element Types: Ball and Roller



Ball Type Guide Advantages:

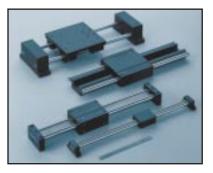
- Less sensitivity to installation error
- Smoother operation due to minimized bearing surface contact
- Linear Guides: 2, 3, 4, 6, 7, 8, 9, 10, 12, 13, 14, 15, 16, 17



Roller Type Guide Advantages:

- Approximately 2X the load capacity (or 10X the life) vs. the same size ball guide
- Up to 2X the rigidity
- Linear Guides: 1, 11

### Linear Guide Inner Race Geometry Types: Round Rail and Profile Rail



Round Rail Type Guide Advantages:

- Greatly increased allowable installation tolerances yield lower installation cost. This results from the compliance offered by the RoundRail Advantage<sup>1</sup> and inherent self-aligning capabilities of the bearings..
- Smoother operation due to minimal bearing surface contact
- Higher profile allows easy access for the addition of an actuator
- End supported configurations for spanning gaps
- Lower replacement costs due to standard replaceable sub components

### Linear Guides: 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17



Profile Rail Type Guide Advantages:

- Greater lateral rigidity, yielding minimal deflection
- Maximum bearing element surface contact enables maximized rigidity and load capacity for use in extremely critical applications (i.e, machine tools)
- Roll, pitch, and yaw moment capacity enables use in single rail/single carriage applications
- Better damping characteristics

Linear Guides: 1, 2, 3, 4

<sup>1</sup> The RoundRail Advantage<sup>\*</sup> describes the ability for this type of bearing technology to compensate for flatness errors of the mounting surface & top plate without any negative effects on the life of the bearings.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



\* The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.
\* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



# Sizing & Defining Guide Characteristics

The previous sections along with the "Application Selector Guide" (Page 8) should help narrow down the selection to one or two types of linear guides. From here, it is necessary to formulate the appropriate part number so that other comparisons, such as "Cost of Product" can be made.

The following 9 step procedure can be used to select the characteristics necessary to generate the appropriate part number:

- 1. Determine the load on the most heavily loaded carriage or bearing (see Applied Loading Calculations). Multiply by a safety factor if desired in your application.
- 2. Determine the minimum required travel life for the application based on the intended duty cycle.
- 3. Calculate the Minimum Required Dynamic Load Rating, C<sub>min</sub> (see Page 192).
- 4. Select the size which offers the load rating, C, equal to or greater than the minimum required dynamic load rating, C<sub>min</sub>. Also, consider **Dynamic Load Limit** and **Static Capacities**.
- If the guide selected offers various preload<sup>†</sup> levels, select a preload based upon the allowable bearing deflection. Contact the factory for detailed deflection information. Some carriage or bearing Deflection Charts are provided in this catalog, (pg195 through 203).
- 6. If the guide selected offers various accuracy classes, select an accuracy class based upon the required travel accuracy.
- 7. Determine the need for accessories or options.
- 8. Calculate the guide length based upon the stroke and platten length. Remember to include additional length of accessories (i.e. self-lubricating option) and the stroke reduction caused by the use of bellows, if applicable.
- 9. Once the above characteristics have been determined, assign the appropriate part number based on the part numbering instructions located in the catalog section corresponding to the linear guide selected.

#### Note:

<sup>†</sup> Choosing a higher preload level will reduce the allowable installation tolerances. For this reason, the minimum preload which meets the applications requirements should be selected. If the highest preload level does not meet the deflection requirements, a larger size may be required.





# **Applied Loading Calculations**

The majority of applications utilize a four carriage or bearing and two rail design for stability. Shown are four typical configurations and calculations for the resultant loads applied to each bearing. Resultant loads are divided into a horizontal and a vertical components, which represent the static or constant velocity condition and account for gravity but not acceleration.

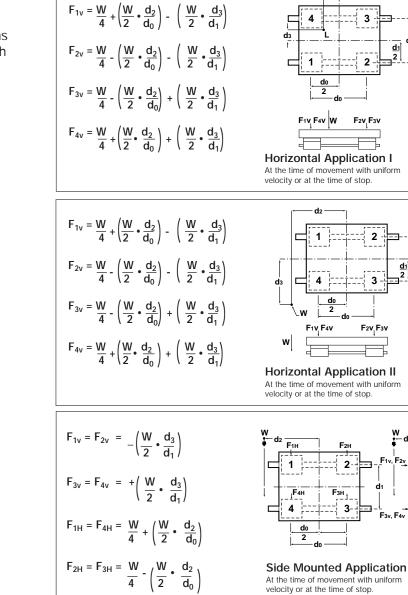
Use the appropriate configuration to determine the horizontal and vertical components of the resultant applied load on the most heavily loaded carriage or bearing. These values will be referred to henceforth as F<sub>H</sub> & F<sub>V</sub>, respectively.

#### Terms:

- d<sub>0</sub> = distance between centerlines of carriages or bearings (in) or (mm)
- d<sub>1</sub> = distance between centerlines of rails (in) or (mm)
- $d_2$  = distance from centerline of carriage or bearing to load action point (in) or (mm)
- distance from centerline of d<sub>3</sub> = carriage or bearing to load action point (in) or (mm)
- W = Applied Load (lb<sub>f</sub>) or (N)
- F<sub>NH</sub>= Horizontal component of resultant applied load with respect to each carriage or bearing (lb<sub>f</sub>) or (N)
- F<sub>NV</sub>= Vertical component of resultant applied load with respect to each carriage or bearing (lb<sub>f</sub>) or (N)

#### Reminder:

- Be sure to use consistent units (english or metric).
- ٠ Be sure to use the appropriate sign (positive or negative).
- A negative number is used when • the actual force is in the opposite direction represented by the arrow.

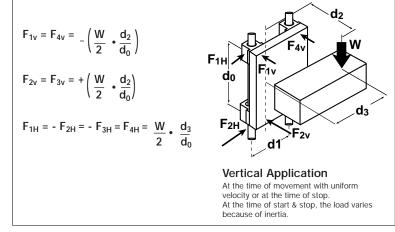


At the time of movement with uniform velocity or at the time of stop.

Ò

Ø

d2 .--



For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries

# Equivalent Load<sup>†</sup>

An equivalent load is used to consolidate applied load components into one value which can later be used to calculate the minimum required load rating and the expected life of the carriage/bearing selected.

### For ProfileRail\* Carriages & Closed RoundRail\* Bearings:

 $F_{EQ} = F_{H} + F_{V}$ 

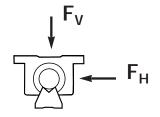
- F<sub>EO</sub> = Equivalent Load
- F<sub>H</sub> = Horizontal Component of Resultant Applied Load
- F<sub>V</sub> = Vertical Component of Resultant Applied Load

# For Open RoundRail Bearings: <sup>‡</sup>

When Fv is negative:

$$F_{EQ} = F_{H} + (F_{V} 0.5)$$

When Fv is positive:  $F_{FO} = F_{H} + F_{V}$ 



For Single Carriage or Single Rail Configurations:

$F_{EQ} = F_{H} + F_{V} + (M/M_{C}) \times C$	Μ	= Applied Moment Load
	$M_{C}$	= Dynamic Moment Capacity of Bearing
	С	= Dynamic Load Capacity of Bearing

### For Preloaded Carriages [ Only when $F_{EQ} < (3 \times F_p)$ ] :

Even with no external load applied, a preloaded bearing has a load on the races. A load greater than the externally applied load is present within a bearing with an externally applied load less than the preload end point. In order to calculate the loads on the load sets, the following formulae may be employed:

 $F_{EQ} = F_p + 2/3 (F_H + F_v)$ (i.e., for 'B' Preload Designation  $F_p = .03 \times C$ )

### **Equivalent Load**

- † Before calculating  $F_{EQ}$ , make sure that neither  $F_H$  or  $F_V$  exceeds the Dynamic Load Limit of the guide intended for use. (See **Dynamic Load Limit** on Page 192).
- <sup>‡</sup> The 0.5 value used accounts for a derating factor of the capacity during tensile loading. Therefore, when calculating expected life based on  $F_{EQ}$ , the Full Dynamic Load Rating (C) may be used.





### Mean Dynamic Load

In applications with loads of varying magnitude, a mean dynamic load should be calculated.

$$F_{EQ} = \sqrt{F_{EQ1}^{P}\left(\frac{d1}{D}\right) + F_{EQ2}^{P}\left(\frac{d2}{D}\right) + \dots + F_{EQn}^{P}\left(\frac{dn}{D}\right)}$$

Where:

ere: F<sub>EQ1</sub>..F<sub>EQn</sub>= equivalent dynamic loads for distances d1 through dn D = total distance of stroke = d1+d2...+dm P = 3 (linear guides w/Ball Type Rolling Elements)

10/3 (linear guides w/Roller Type Rolling Elements)

# Load Ratings for Rolling Element Guides

### Dynamic Load Rating, C, and Travel Life

The dynamic load rating, C, is the load at which when applied will yield the rated travel life. The rated travel life, Lr, for most linear guides is 100km for metric products and 4 million inches for inch products (the rated travel life is listed on the page with the dynamic load rating). For a given applied load, P, the dynamic load rating and rated travel life are used to calculate the travel life using the following load/life equation:

 $L = (C/F_{EQ})^n \times Lr$ 

Where:

L = calculated travel life C = dynamic load rating

 $F_{FO}$  = equivalent applied load

- n = 3 for ball guides, 10/3 for roller guides
- $L_r$  = rated travel life

*Note:* Some manufacturers dynamic load ratings are based upon a 50km life. To compare dynamic load ratings for guides with a 50km rated life with a 100km life, divide the 50km dynamic load rating by 1.26.

 $C_{100km} = C_{50km}/1.26$ 

Some types of linear guides do not have the same dynamic load rating in all directions. The dynamic load rating for orthogonal load directions is shown as a percentage of C. (It is not necessary to use this percentage of C in the load/life equation provided that the **Equivalent Applied Load Section** has been adhered to, because the calculations for equivalent applied load already account for it.)

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



\* The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.
\* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



# Calculating the Minimum Required Dynamic Load Rating, Cmin

The load/life equation above can be rewritten to calculate the minimum required dynamic load rating which should be selected for a given applied load and minimum required travel life:

 $C_{\min} = P(L_m/L_r)^{1}/n$ 

Where:

- C<sub>min</sub> = minimum required dynamic load rating
- P = applied load
- L<sub>m</sub> = minimum required travel life

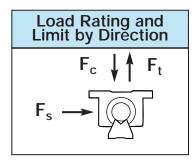
L<sub>r</sub> = rated travel life

n = 3 for ball guides, 10/3 for roller guides

Note: Check that the applied load, P does not exceed the dynamic load limit.

### Dynamic Load Limit

The dynamic load limit, is the maximum load which should be applied to the carriage/pillowblock. In some cases, the dynamic load capacity equals the dynamic load rating. In others, a limit shown as percentage of the dynamic load rating is the maximum load which should be applied. A dynamic load limit less then the dynamic load rating does not derate the life of the guide.



		Dynamic Load Rating	Load Limit
ſ	F <sub>C</sub>	С	С
	Ft	0.5C	0.25C
	$F_S$	С	0.25C

Dynamic Load Rating Load value used in life calculation. Load Limit Maximum allowable load applied to bearing.

### Static Capacities

The static capacities are the maximum loads that should be applied to the bearing while there is no relative motion between the rolling elements and the raceways. The value  $C_0$  is the static load capacity for a radial load acting orthogonal to the axis of travel. The values  $M_{ro}$ ,  $M_{po}$ , and  $M_{yo}$  are the static roll, pitch, and yaw moment capacities.

It is important to analyze the application so that shock loads do not exceed these capacities. Exceeding these capacities may permanently deform the rolling elements and raceways. This type of damage will be realized by an increase in friction, noise, and vibration, as well as by an increase in clearance between the carriage and the rail.

*Note:* For systems experiencing repetitive shock loading less than the static load capacities, the bearing life should be determined by means of fatigue calculations.





### Load Capacities for Sliding Contact Guides

### Dynamic Load Rating, Pv, and Travel Life

For sliding contact linear guides, dynamic load ratings are represented as PV (Pressure•Velocity) ratings. To determine if the guide is adequately sized, the following variables must be examined:

Pressure (P)  $P = \overline{F_{EQ}}$ 

Where: A = Projected Area = Shaft Diameter x Bearing Length

Velocity (V) If motion is linear: V = Travel speed of guide If motion is rotational: V = RPM x Shaft Diameter x 3.14

А

PV Value

PV = Pressure x Velocity

As well as a maximum PV rating, each sliding contact linear guide is also rated for maximum velocity and maximum pressure.

#### Wear Rates & Life Expectancy

I) <u>Wear rates</u>: The wear rates of a plain bearing are dependent upon a number of variables, including characteristics of the counter-face, velocity, lubrication, load and contamination. Tests conducted on FNYBEM-25 bearings operating in the linear mode at approximately 21 m/min, and at a pressure of approximately 0.23 MPa, demonstrated an average radial wear change of 0.028 mm, after 2 million meters of travel. This yields the following formula:

 $W_R = 14x(10^{-6})xT$ 

Where:

 $W_R$  = Radial Wear (microns) T = Travel (meters)

II) <u>Life expectancy</u>: The life expectancy may be calculated from the wear rate. This is normally associated with the allowable radial clearance for a given application. The absolute wear limit is the bearing material thickness, which is 0,71 mm.





### Preload

A preloaded bearing has a condition of interference between the races of the rails, the rolling elements, and the races of the carriage.

Preloading decreases the deflection due to external loads. This occurs because the contact reaction has already developed, eliminating much of the initial non-linear deflection associated with rolling elements.

The rolling element reactions within a preloaded bearing may be considered as having two components. One component acts in the direction of external load, and one component acts in the opposing direction in order to maintain static equilibrium. These components are referred to as load sets. As external load is applied, one load set increases in load, as the opposite load set decreases in load. At some point, the load on the decreasing load set becomes zero. This point, at which the preload is relieved, is called the preload end point. Preload end typically occurs when the external load is approximately three times the preload.

Preload end point :  $F_{ext} = 3F_p$ where:

 $F_{ext}$  = externally applied load  $F_p$  = preload

By definition, a preloaded bearing, loaded beyond the preload endpoint, has the same deflection characteristics of an unpreloaded bearing externally loaded to that percentage of its dynamic load capacity. A preload level is assigned as a percentage of the dynamic load capacity of the bearing.

### **Deflection Curves**

The following pages contain deflection curves for linear guides typically selected when rigidity is critical. Note that the deflection decreases as the preload level is increased & also as the bearing size increases.

#### Curves shown are for the AA (standard) type carriages.

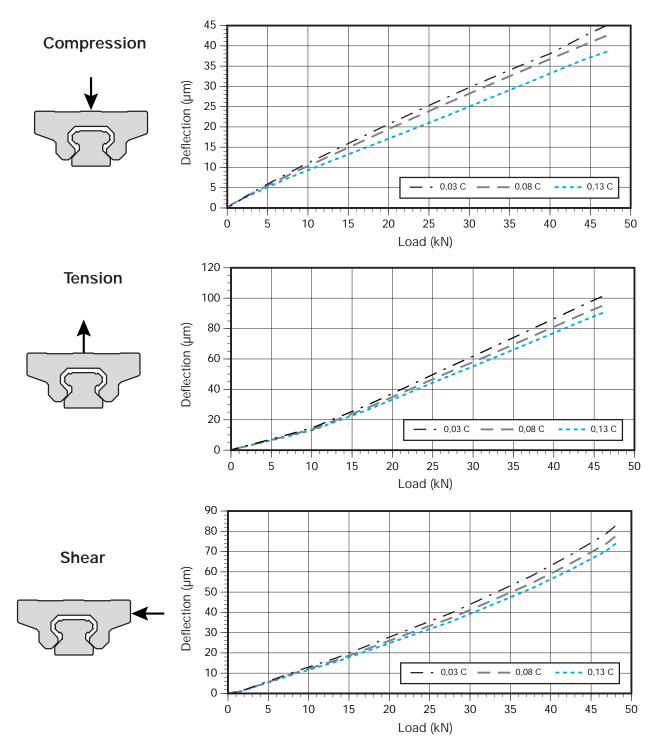
For deflection characteristics of guide types not shown, contact the Thomson Technical Helpline at (800) 554-8466.





# **Deflection vs. Applied Load**

# AccuMax\* Linear Guide Size 35<sup>t</sup>



† Curves shown are for the AA (standard) type carriages.

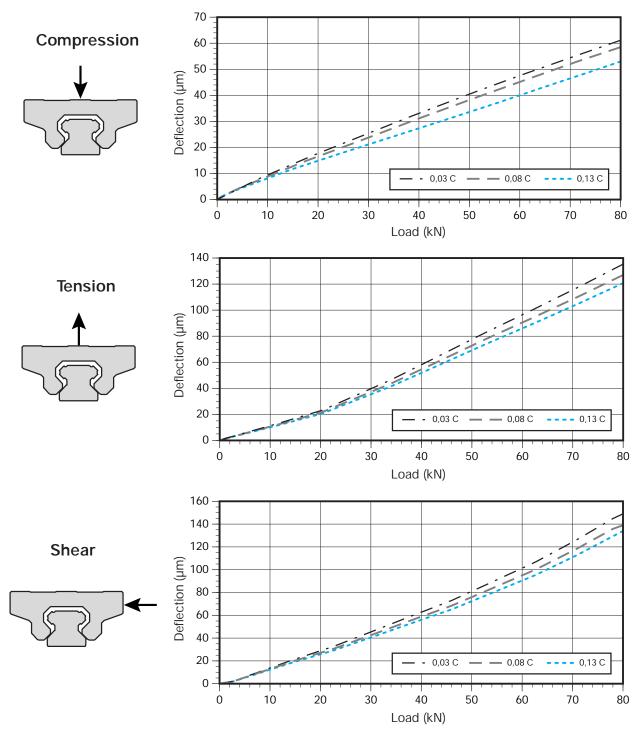
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.





Linear Guides Engineering Support

# Deflection vs. Applied Load AccuMax\* Linear Guide Size 45<sup>t</sup>

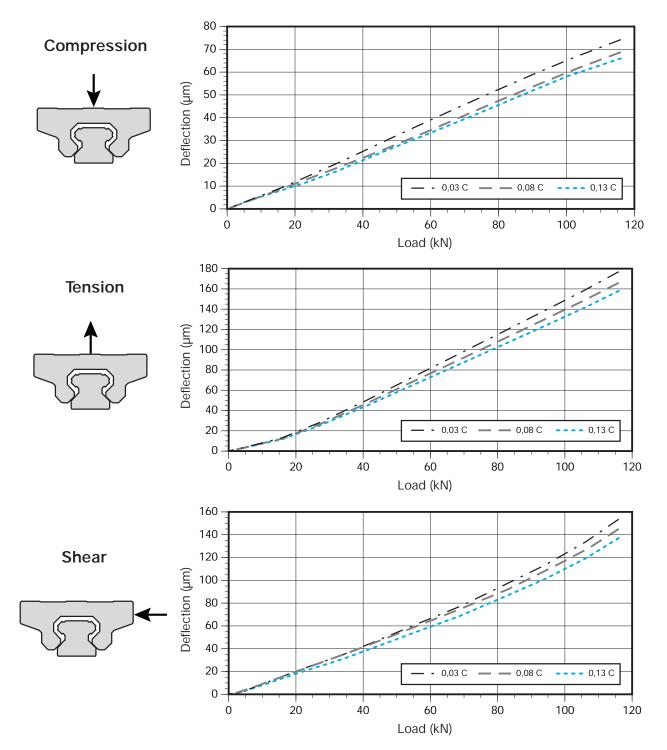


† Curves shown are for the AA (standard) type carriages.





# Deflection vs. Applied Load AccuMax\* Linear Guide Size 55<sup>†</sup>



† Curves shown are for the AA (standard) type carriages.

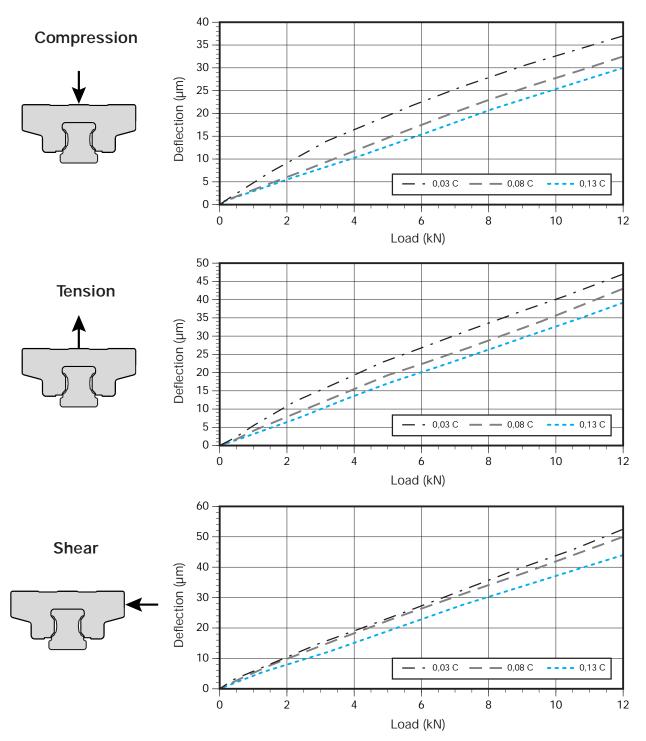
For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



Page 197

Linear Guides Engineering Support

# Deflection vs. Applied Load AccuGlide\* Linear Guide Size 20<sup>t</sup>

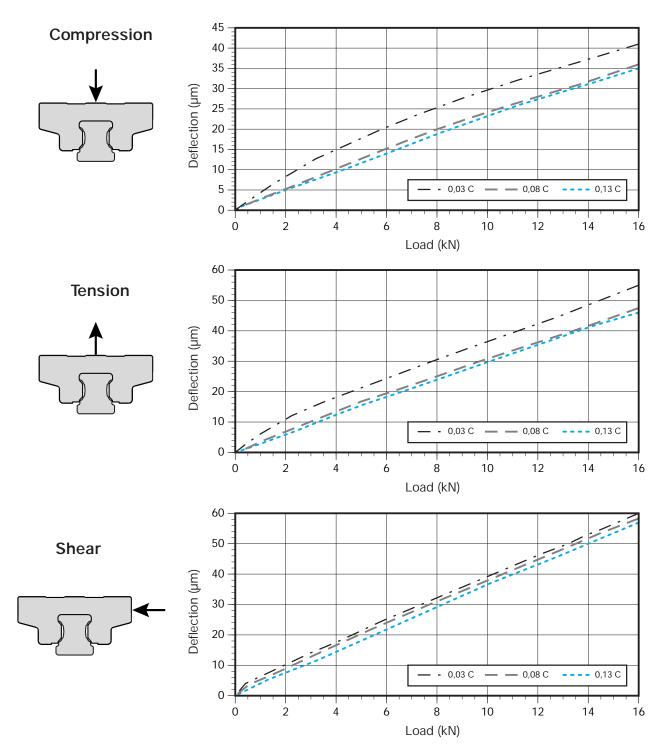


† Curves shown are for the AA (standard) type carriages.





# Deflection vs. Applied Load AccuGlide\* Linear Guide Size 25<sup>t</sup>



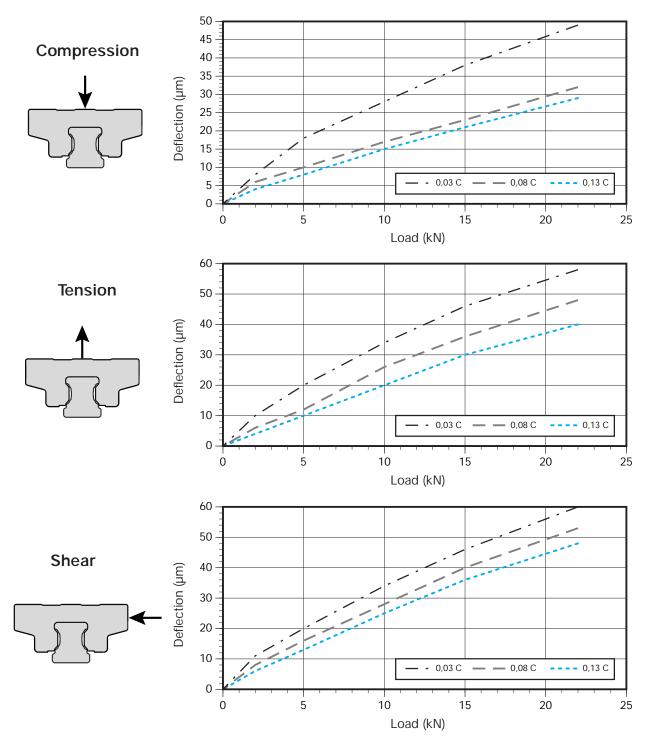
† Curves shown are for the AA (standard) type carriages.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.





Linear Guides Engineering Support

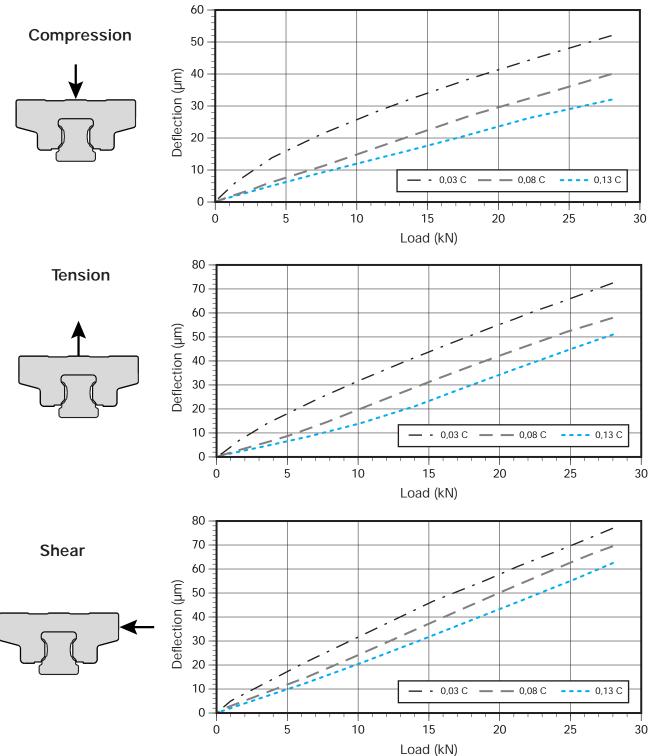


† Curves shown are for the AA (standard) type carriages.





# Deflection vs. Applied Load AccuGlide\* Linear Guide Size 35<sup>†</sup>



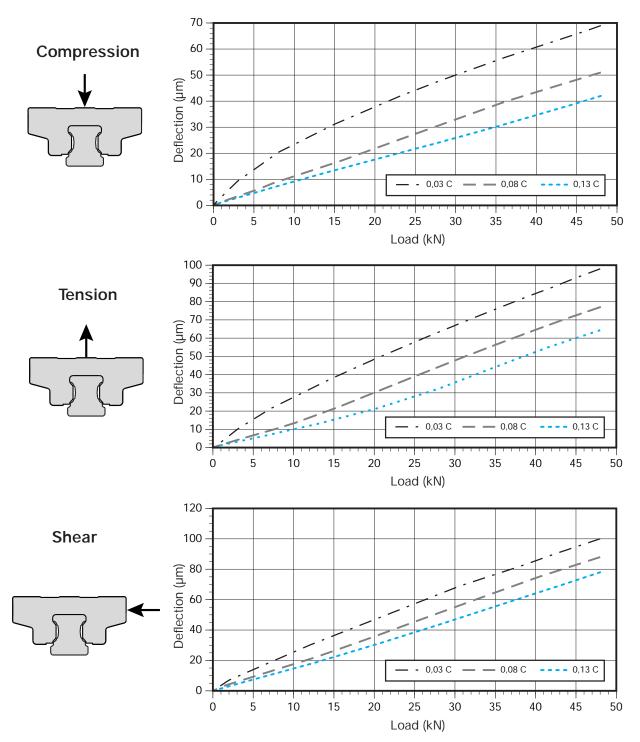
† Curves shown are for the AA (standard) type carriages.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



Linear Guides Engineering Support

# Deflection vs. Applied Load AccuGlide\* Linear Guide Size 45<sup>†</sup>

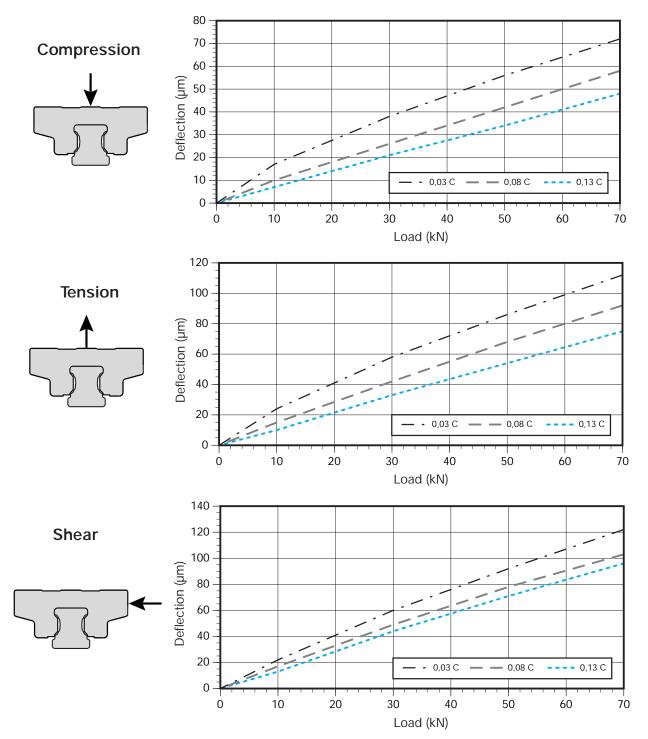


† Curves shown are for the AA (standard) type carriages.





# Deflection vs. Applied Load AccuGlide\* Linear Guide Size 55<sup>†</sup>



† Curves shown are for the AA (standard) type carriages.

For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



Page 203

Linear Guides Engineering Support

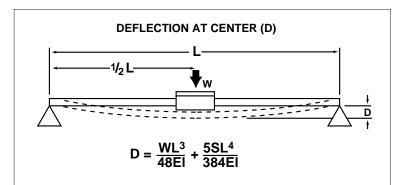
# End Supported Linear Guide Deflection

When a linear guide is used in an end supported configuration it is important to ensure that system deflections at the bearing locations are kept within performance limitations.

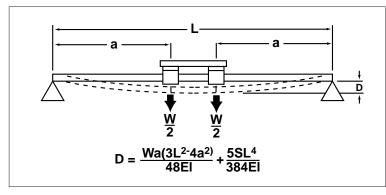
These equations give the deflection at the center of an end supported system. Linear guides with continuous support are not subject to the same types of deflection.

60 Case* Lin	60 Case* LinearRace* Shaft Stiffness and Weights				
Inch Size		Metric Size			
Diameter (in)	El (Ibr • in <sup>2</sup> )	S (lb <sub>f</sub> /in)	Diameter (mm)	EI (N • mm²)	S (N/mm)
1/4	5.8 x 10 <sup>3</sup>	0.014	8	3,83 x 10 <sup>7</sup>	0,0038
3/8	2.9 x 104	0.031	12	1,94 x 10 <sup>8</sup>	0,0087
1/2	9.2 x 104	0.055	16	6,12 x 10 <sup>8</sup>	0,0154
5/ <sub>8</sub>	2.3 x 10⁵	0.086	20	1,50 x 10 <sup>9</sup>	0,0240
3/4	4.7 x 10⁵	0.125	25	3,65 x 10 <sup>9</sup>	0,0379
1	1.5 x 10 <sup>6</sup>	0.222	30	7,57 x 10 <sup>9</sup>	0,0542
11/4	3.6 x 10 <sup>6</sup>	0.348	40	2,39 x 10 <sup>10</sup>	0,0968
<b>1</b> <sup>1</sup> / <sub>2</sub>	7.5 x 10 <sup>6</sup>	0.500			

# Simply Supported Linear Guide with One Block

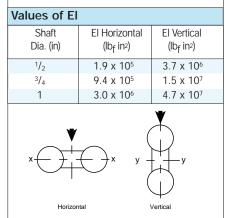


### Simply Supported Linear Guide with Two Blocks



#### Deflection for Twin Shaft Web\* Linear Guide

Since the Twin Shaft Web rail has different stiffness depending on its orientation, an appropriate El value must be used based upon the direction of loading. Select the orientation of your load from the figure below and then use the appropriate El value in the deflection equation.



#### LEGEND

- D = Deflection (in) or (mm)
- $W = Load (lb_f) or (mm)$
- L = Length of unsupported 60 Case LinearRace shaft (in) or (mm)
- a = Distance to first bearing with carriage at center position (in) or (mm)
- $S = Unit weight of LinearRace shaft (lb_f/in) or (N/mm)$
- $E = Modulus of Elasticity (lb_f/in^2) of (N/mm^2)$
- I = Moment of inertia of area through diameter of LinearRace shaft (in<sup>4</sup>) of (mm<sup>4</sup>)

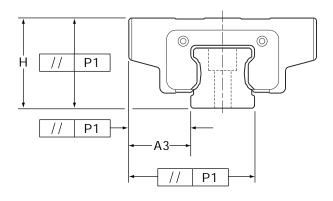




### **Accuracy Class**

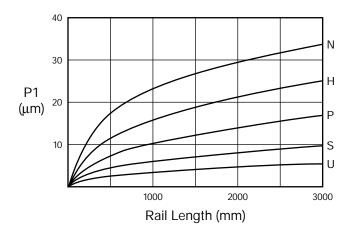
Three tolerances describe the accuracy of a ProfileRail bearing: Running Parallelism, Pair Variation, and Assembly Accuracy. These are measured from the rail base to the center of the carriage top (H), and from the rail reference edge to the center of the carriage reference edge (A3). (Figure 1)

Figure 1. Dimensions H and A3



Running Parallelism describes the tolerance on H and A3 as a function of axial travel, measured from one carriage down the length of rail (Figure 2). This is analogous to straightness of travel. As such, parallelism describes attributes of the rail only.

Figure 2. Running Parallelism



Assembly Accuracy [Table 1] describes the tolerance on H and A3 as a function of a carriage - rail assembly, measured from the nominal dimensions.

Pair Variation [Table 1] describes the tolerance on H and A3 as a function of carriages, measured with multiple carriages at the same position on a common rail. Pair variation describes carriage precision only.

Table 1. Tolerances on H and A3,  $\mu m$ 

	Accuracy Class				
	<b>N</b> Normal	<b>H</b> High	<b>P</b> Precision	<b>S</b> Super Precision	<b>U</b> Ultra Precision
1. Assembly Accuracy Tolerance on dim. H and A3 (measured at middle of carriage at any point along rail)	±100	±40	±20	±10	±5
2. Pair Variation Max variation in dimensions H and A3 measured on multiple carriages mounted on the same rail (measured at middle of carriage at same position on rail)	30	15	7	5	3

The accuracy class selected will partially determine the accuracy of the system. Other factors such as mounting surface flatness and straightness also significantly affects system accuracy.

ultra ±5





# **Actuation Force**

The force required to actuate a linear guide  $(F_A)$  has four basic components:

- 1. Frictional resistance ( $F_f$ )
- 2. Intrinsic resistance (D<sub>int</sub>)

 $F_A = F_f + D_{int} + F_{inertia} + D_l$ 

- 3. Inertia of the moving components ( $F_{inertia}$ )
- 4. Viscose drag of the lubrication (D<sub>I</sub>)

# Frictional Resistance

### **Rolling Element Guides**

Friction occurs in rolling element guides as a result of slipping of the rolling elements on the raceways. The frictional resistance can be calculated by means of the following equation:

 $F_f = \mu \times F_i$ 

Where:

- $\mu$  = coefficient of friction (dependent upon type of guide type, rolling element type and load)
- $F_i$  = force internal to the linear guide

The following table lists the coefficient of friction for different types of guides:

Round Rail		Profile Rail	
Ball Type	Roller Type	Ball Type	Roller Type
0.001 - 0.002	0.005 - 0.010	0.002 - 0.003	0.001 - 0.002

The value for the coefficient of friction is a function of the applied load. The coefficient of friction increases as load is applied. This is due to the increased contact area between the rolling elements and races.

The force internal to the linear guide is equal to the external force ( $F_{ext}$ ) applied to the linear guide in non-preloaded guides, and preloaded guides loaded beyond 3 times the preload value ( $F_p$ ).

 $F_i = F_{ext}$ 

For preloaded guides loaded below a level of 3 times the preload value ( $F_p$ ), the internal force can be approximated with the following equation:

 $F_{i} = 2F_{p} + 1/3 F_{ext}$ 







### Sliding Contact Guide

 Static: Tests performed on dry FNYBU-16 bearings indicate that the force required to initiate motion is dependent upon the applied load according to the following equation:

$$F_{f} = 1.3 + 0.18 F_{a}$$



Where:

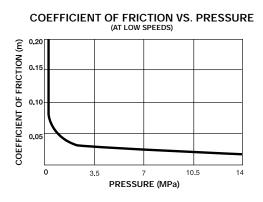
 $F_f$  = Friction force, static (Newtons)

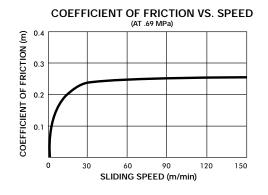
F<sub>a</sub> = Applied force (Newtons)

### Maximum Operating Parameters per Bearing

Characteristic	Limit
Liner Temperature Range	-240° C to 288° C (-400° F to 550° F)
Velocity, dry	42.7 m/min. Continuous
Velocity, dry	122 m/min. Intermittent
Velocity, lubricated	122 m/min. Continuous
Pressure	10.35 MPa
PV	21 MPa/m/min

 II) Dynamic: The coefficient of friction is dependent upon both the pressure and the velocity. Pressure: Coefficient of friction decreases rapidly with increase in pressure. Velocity: Coefficient of friction increases with an increase in velocity, and quickly stabilizes. For example, at .69 MPa, the coefficient of friction is approximately 0.25 for velocities of 30.5 m/min and higher.





For more information, or to place an order, please contact your local authorized Thomson distributor or Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at linearguides@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.
Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



### Intrinsic Resistance

The intrinsic resistance is the measured actuation force required to move the guide at a constant velocity, without lubrication, regardless of load. It consists of the seal drag (larger component) and force required to circulate the rolling elements (smaller component). The intrinsic resistance can be assumed to be a constant for linear guides carrying more than 5% of their dynamic load rating (C). For guides loaded below that value, the force required to circulate the rolling elements will increase.

The following chart shows the intrinsic resistance, D<sub>int</sub>, for different types and sizes of linear guides.

### AccuMax\* linear guide

Size	Carriage Style AA D <sub>int</sub> (N)
30	13,5
35	14,7
45	27,5
55	46,1
65	70,6

### AccuGlide\* Miniature linear guide

Size	Carriage Style AA D <sub>int</sub> (N)			
10	0,9			
15	2,8			
20	7			

### AccuGlide\* linear guide

Size D <sub>int</sub> (N)	Carriage Style AA, CE D <sub>int</sub> (N)	Carriage Style BA, DE D <sub>int</sub> (N)		
20	5,5	7		
25	7,5	10		
30	12,5	15,5		
35	18	24		
45	33,5	44		
55	55,5	73,5		

### Inertia of Moving Components

Inertia is directly related to the mass and acceleration by the following equation: F<sub>inertia</sub> = Ma

### Viscose Drag of the Lubrication

The viscose drag of the lubricant is dependent upon the visiosity of the lubricant selected.

For information on linear guides not shown, contact the Thomson Technical Hotline at (800) 554-8466





### **Lubrication**

Lubrication provides protection against wear, corrosion, heat, and friction. Application-specific variables, such as load, speed, and environmental conditions, determine the most suitable lubricant and lubrication schedule for that specific application.

Thomson's general lubricant recommendation for linear guides is a grade 2 grease. A maximum of one year or 100km, whichever comes first, between applications of lubricant is recommended. A grease with an extreme pressure additive should be used for guides loaded beyond 50 of their dynamic load rating (C). Oil can also be used and is recommended in applications where the bearings experience high speeds. Use the uppermost lubrication port on oil-lubricated bearings that are vertically oriented to ensure gravity-assisted lubricant dispersal.

Linear guide products are supplied with a light coating of preservative oil. This preservative oil is for storage purposes only and is not recommended as lubrication for the bearing. AccuGlide\* Miniature Series carriages are shipped prelubricated with an EP2 grease should always be lubricated before use.

### **Lubrication Procedure**

For best lubrication dispersal, the carriage should be moved on the rail while applying lubricant to ensure circulation to all internal bearing surfaces. It is not possible to over lubricate the bearings, as excess lubricant will merely exit the carriage under the seals.

Recommended initial volumes of lubricant for AccuMax and AccuGlide bearings are shown in Tables 2 and 3. The recommended volume for relubrication is 1/2 the initial volume.

#### Initial Lubricant Volume for AccuMax Bearings

Size	Carriage Style AA cm <sup>3</sup>
30	6
35	10
45	20
55	38
65	60

#### Initial Lubricant Volume for AccuGlide Bearings

Size	Carriage Style AA, CE cm <sup>3</sup>	Carriage Style BA, DE cm <sup>3</sup>		
	CIII	CIII		
20	4	6		
25	6	8		
30	10	12		
35	14	18		
45	30	38		
55	54	66		





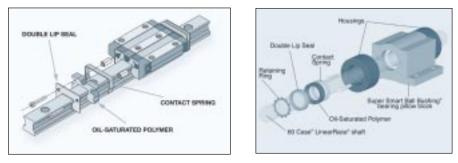
# Self-Lubricating Linear Guides

The self-lubricating option offers maintenance free operation and enhanced protection for a broad range of applications.

It offers:

- Reduced system cost by eliminating the need for designing, purchasing, and installing expensive lubrication systems.
- Environmentally friendly operation
- Increased bearing life by offering enhanced protection

### Design



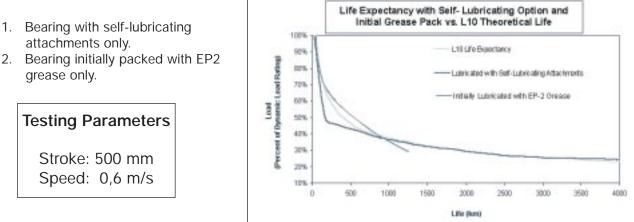
The self-lubricating option utilizes self-lubricating attachments at both ends of the carriage and includes an initial EP2 grease pack of the carriage. The self-lubricating attachments consist of a section of oil saturated polymer actively compressed by a contact spring, inside a double lip seal.

A contact spring assures continuous contact with the rail, releasing oil as the carriage moves. This ensures a film of lubricant between the rolling elements and races. When the carriage is at rest, oil is re-absorbed by the polymer.

# Performance

The design has incorporated a proven oil-saturated polymer used for over 10 years to lubricate radial bearings. This method of lubrication has a successful track record in applications ranging from food processing to automotive assembly.

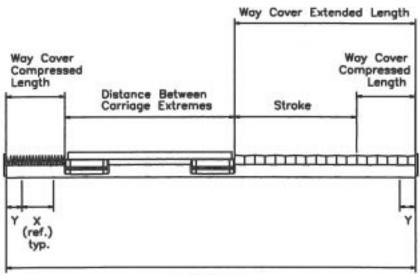
The graph below shows the theoretical L10 life expectancy and actual test results for the following two methods of lubrication:



This chart illustrates how using the self-lubricating option, which combines the self-lubricating attachments and initial grease pack, will enable the bearing to achieve the L10 life expectancy under all loading condition. Note that for travel lives exceeding 30,000 km, recharging or replacing of the self-lubricating polymer is recommended.









### Given the Stroke and Distance Between Carriage Extremes:

Way Cover Extended Length (mm) = Stroke (mm) / (1-CR). After dividing, round number up to the next increment of 5mm. This value is used as the length in the way cover part number when ordering.

Note: The Way Cover Extended Length will be cut to next vee at the factory.

Way Cover Compressed Length (mm) = Way Cover Extended Length (mm) - Stroke (mm)

Rail Length = Compressed Length + Extended Length + Distance Between Carriage Extremes.

#### Example:

Product: AccuGlide\* Linear Guide Size 35 Stroke Length = 200mm Distance Between Carriage Extremes = 520mm Bellows Type = Walk-On

CR = 0.19 for size 35 AccuGlide Walk-on type bellows

Way Cover Extended Length = Stroke / (1-CR) = 200mm / (1-0.19) = 200mm / .81 = 246.91mm Round up to next increment of 5mm, therefore, Way Cover Extended Length = 250 mm

Way Cover Compressed Length = Way Cover Extended Length - Stroke = 250mm - 200mm = 50mm

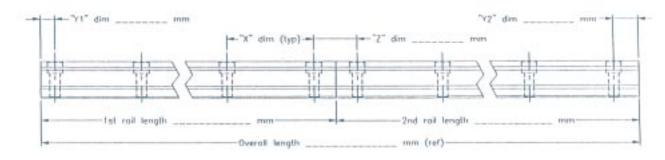
Rail Length = Compressed Length + Extended Length + Distance Between Carriage Extremes = 50mm + 250mm + 520mm = 820mm



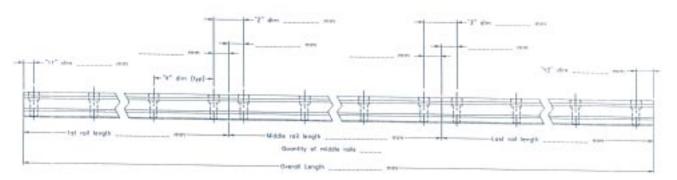
Page 211

# Specification sheet for the butting of 2 rails

A butt joint will be require for rail lengths longer than the maximum shown in the chart below. If a butt joint is required, the 1st and 2nd rail lengths must each be less than the maximum shown. The "Y1" and "Y2" dimensions must be between the minimum and maximum shown below to avoid cutting into a mounting hole. The standard "Z" dimension should be used for best performance.



### Specification sheet for the butting of 3 or more rails



Linear Guide Product	"X" dim	Standard "Z" dim	Minimum "Y" dim	Maximum "Y" dim	Fastener size	Maximum length without a joint
AccuMini* 10	25	12.5	5	20	M2.5	1,500
AccuMini 15	40	20	7	33	M4	1,500
AccuMini 20	60	30	8	52	M5	3,000
AccuGlide* 15	60	30	8	52	M4	3,000
AccuGlide 20	60	30	8	52	M5	3,000
AccuGlide 25	60	30	8	52	M5	3,000
AccuGlide 30	80	40	10	70	M8	3,000
AccuGlide 35	80	40	10	70	M8	3,000
AccuGlide 45	105	52.5	13	92	M12	3,000
AccuGlide 55	120	60	15	105	M14	3,000
AccuMax* 35	40	40	10	30	M8	3,000
AccuMax 45	52.5	52.5	13	39.5	M12	3,000
AccuMax 55	60	60	15	45	M14	3,000
AccuMax 65* <sup>†</sup>	75	75	17	58	M16	3,000

<sup>†</sup> Contact Factory for Availability

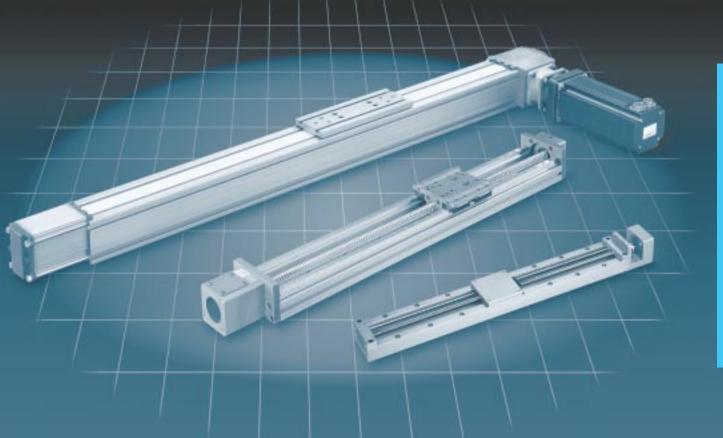




THOMSON INDUSTRIES, INC.

# SYSTEMS, SLIDES, & STAGES SOLUTIONS

Engineering Guide for Systems, Slides & Stages



### SYSTEMS, SLIDES & STAGES

Pre-engineered, pre-assembled, ready to install
The most complete product line available



# www.thomsonsystems.com

For Application Engineering assistance contact the Thomson Technical HelpLine at 1-800-554-8466. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



# Put Over 50 Years Of Linear Motion



Thomson 60 Case\* shafting Provides Superior LinearRace\* Way Performance



Thomson Saginaw Ball Screws Provide High Efficiency and Reliable Performance



Super Smart Ball Bushing\* bearing • 216 Times the Travel Life or • 6 Times the Load Capacity • 5 Times the Shaft Life



Thomson Precision Balls– Load Carrying Element for the Super Smart Ball Bushing Bearing



Thomson IBL Ball Screws for High Accuracy and Repeatability

Metric SuperSlide\* 2RB Ball Screw Drive System

(See page 262 for more details)

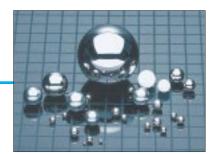




# System Experience to Work for You



Super Plus Ball Bushing\* bearing • 3 times the load capacity • 27 times the travel life or • Self-aligning up to 0,5



Thomson Precision Balls— Load Carrying Element for the Super Smart Ball Bushing\* bearing



Thomson Nyliner\* Engineered Polymer Products Serve as Lightweight and High Strength Retainers for the Super Smart Ball bushing bearing

Metric SuperSlide\* 2NE Belt Drive System

(See page 272 for more details)



Thomson Micron NemaTRUE\* Planetary\* gearheads for Torque Multiplication and Inertia Matching



Thomson 60 Case\* Shafting Provides Superior LinearRace\* Way Performance





# Thomson Systems...Modular, Pre-engineered,



Thomson Saginaw Ball Screws Provide High Efficiency and Reliable Performance



Thomson Molded Products Serve as Lightweight and High Strength Ball Retainers in the ProfileRail\* System Carriage



Thomson ProfileRail Products Provide High Rigidity in a Compact Design



Thomson Precision Balls— Load Carrying Elements for ProfileRail Systems and Ball Screw Assemblies



Thomson IBL Ball Screws for High Accuracy and Reliability

Metric AccuSlide<sup>\*</sup> 2HB Ball Screw Driven System

See page 260 for more details







# Pre-assembled, Ready to Ship, Ready to Install



AccuMax\* Linear Roller Bearing System • Twice the load capacity of linear ball guide systems • Twice the rigidity of linear ball guide systems • Offers the Arcuate Advantage\* a patented design which includes cylindrical rollers on continuously crowned races



Thomson Precision Balls— Load Carrying Elements for ProfileRail\* Linear Bearing Systems



Thomson Nyliner\* Engineered Polymer Products Serve as Lightweight and High Strength Ball Retainers in the ProfileRail System Carriage



Thomson Micron AccuTRUE\* Planetary Gearheads for Torque Multiplication and Inertia Matching

See page 279 for more details.

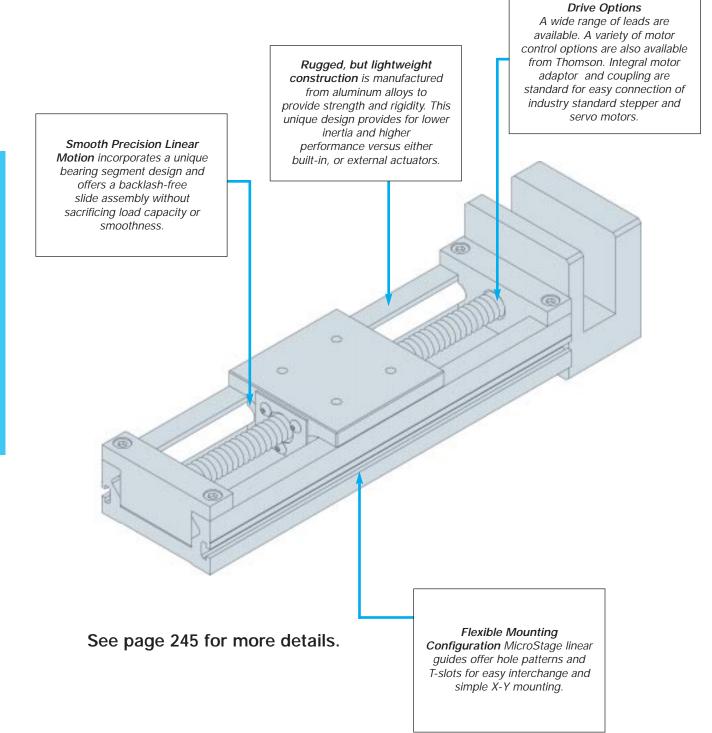
Turbo Module\* 2GE Belt Driven System



Page 217

# Thomson Systems . . . MicroStage\*

Lead Screw Actuated Linear Motion System

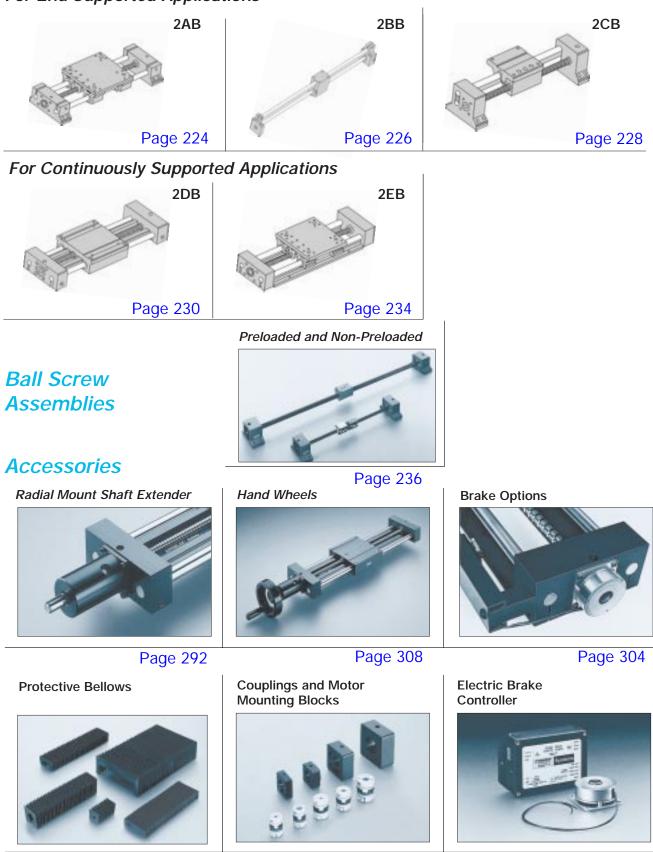






### SuperSlide\* Ball Screw Actuated Systems

For End Supported Applications





Page 291

The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Page 288

Page 306

Page 219



### SuperSlide Ball Screw Actuated Systems

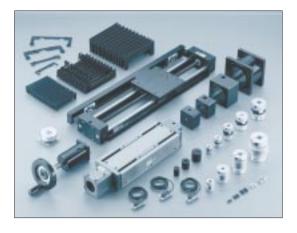
### for End and Continuously Supported Applications

SuperSlide\* Ball Screw Driven Systems are available in five configurations with over fifty different drive diameters and leads designed to meet the most stringent of applications. End supported systems are designed to be used when spanning or bridging a gap. Continuously supported systems are used when rigidity is required. Standard system positioning accuracy is less than .002 inch per foot and standard repeatability is less than .002 inch. Most SuperSlide systems are available with preloaded ball screw assemblies achieving repeatabilities as low as .0002 inch. All SuperSlide systems are available with polyurethane coated polyester bellows for corrosion resistant applications. Superslide systems are shipped in less than a week with special length systems shipped in less than two weeks. Available from over 1800 authorized distributor locations worldwide. (See page 221)



### **Ball Screw Assemblies**

Ball Screw Assemblies are available in metric or inch sizes in over fifty diameters and lead combinations. Each Ball Screw Assembly consists of a ball screw, a ball screw nut with mounting surfaces and two mounting blocks equipped with sealed angular contact bearings. The motor end block is designed for mounting to NEMA 23, 34 and 42 standards. Inch size Ball Screw assemblies are available in sizes .500 x .200 through 1.500 x 1.875 in both preloaded and non-preloaded versions. Metric Ball Screw Assemblies are available in sizes 12 mm x 5 mm through 40 mm x 40 mm in both preloaded and non-preloaded versions. They are designed to easily mount to the carriage of Building Block System 1CC and can be modified to mount to any manually driven system. Standard Ball Screw Assembly positioning accuracy is better than .002 inch per foot (.025 mm per 300 mm) and standard repeatability is less than .002 inch (0.05 mm). Most Ball Screw Assembly Systems are available with preloaded ball screw assemblies achieving repeatabilities as low as .0002 inch (.005 mm). Standard Ball Screw Assembly special length Assemblies shipped in less than two weeks. (See page 236)



#### Accessories

#### Motor Couplings, and Motor Adaptor Blocks, Limit Switch Packages, Protective Shroud Covers, Radial Mount, Protective Bellows and Brake Options

The uniquely designed Radial Mount Ball screw shaft extender consists of an oversized shaft, a heavy duty radial bearing, a housing with a standard NEMA mounting face and an easy to mount coupling. The Radial Mount provides a dramatic increase in side or cantilever load capacity. All Protective Bellows are manufactured from a durable polyurethane coated polyester material which will protect your Linear Motion System from most contaminants or corrosive environments. The flexible convoluted folding construction reinforced with bonded integral stiffeners minimizes the reduction in system stroke length. Compact design eliminates work surface interference and assures uninterrupted movement of the carriage during operation. Brake Options are available in three versions. QuickSilde\* 2DA Manual Brake System allows the system carriage to have infinite fixed positioning capability. The Electric Brake is designed to engage when power is lost. The Electric Brake can be equipped with a controller option that interfaces directly with a PLC, switch, relay, computer, or controller output. Available from over 1800 authorized distributor locations wordwide. (See page 287)

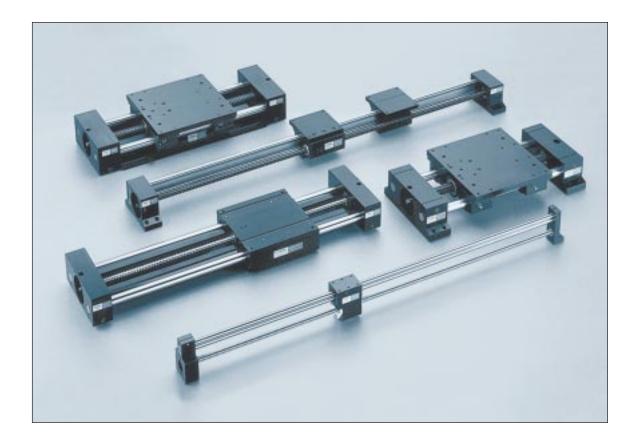
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.



### SuperSlide Ball Screw Actuated Systems



### Thomson SuperSlide\* Systems offer:

- A pre-engineered, pre-assembled linear motion system complete with prealigned LinearRace\* ways and an integral ball screw assembly. A single part number specifies a complete system.
- A variety of highly efficient ball screw assemblies with diameters and leads designed to meet the most stringent motion control requirements.
- Available with the Super Smart Ball Bushing\* bearings which provide up to twice the load capacity or eight times the travel life of standard Super Ball Bushing\* bearing based systems.
- Positioning accuracy as low as .001 inch per foot with repeatability better than .0002 inch.
- An end supported or continuously supported version. End Supported Systems are used when spanning or bridging a gap.

Continuously Supported Systems are used when rigidity is required.

- Easy integration to the TMC 1000 Motion Control options using the standard NEMA face mounted hole spacing. Motion control of exacting standards is realized immediately.
- Available with standard carriages that provide smooth and virtually frictionless linear movement.
- Four drilled and tapped holes for quick and easy mounting of the work piece to the carriage.
- Optional protective bellows, a black anodized coating, lubrication fittings and integral double acting seals for protection in corrosive environments.
- Travel speeds up to 10 ft/s with high positioning accuracy and repeatability.
- Available from over 1800 distributors worldwide.



Page 221

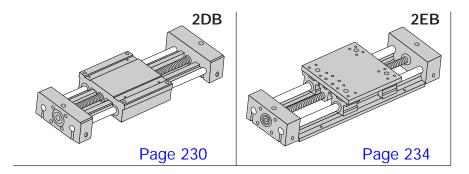
# SuperSlide Solution Matrix

# SuperSlide\* Ball Screw Actuated Systems

For End Supported Applications



### For Continuously Supported Applications



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





# SuperSlide\* Ball Screw Actuated Systems Selection Criteria

Many variables influence the selection of a Linear Motion System. The best solution demands a thorough evaluation of the application; only then can design criteria be established. Issues such as envelope limitations, system load capacity, actuator load capacity, speed and acceleration, drive requirements, accuracy and repeatability, and operating environment are looked at from a broad perspective to determine the type of system, type of actuator, and whether the system need be built of special materials.

Typically, a ball screw actuated linear motion system is ideal for tight precision, highly repeatable, high load, moderate speed applications. Long lead ball screws are available for most style systems, but it is important to be mindful of the critical speed (first harmonic of the resonant ball screw whirling vibration) in longer stroke systems when attempting to reach higher linear velocities. If an application requires rigidity, then a fully supported system should be specified in lieu of an end supported type system. When zero backlash is required for the best repeatability, then a preloaded version ball screw assembly need be specified. For extremely heavy-duty applications, the AccuSlide (2HB series) system, with its use of ProfileRail type linear guides is adept at handling normal axis, overhung, or cantilever loads of increased magnitude. In environments that are corrosive or high temperature, special materials may be required and are available. Contact Application Engineering for details on special materials.

In order to determine the Ball Screw Actuated SuperSlide System that meets the needs of your application, it is first necessary to evaluate the following detail design criteria:

- System support requirements
- System stroke length
- Maximum allowable shaft deflection
- Required travel life
- Force on the most heavily loaded bearing
- Load correction factor
- Load/Life requirements linear bearings
- Load/Life requirements ball screws
- Motion (move) profile (velocity, acceleration)
- Maximum acceptable travel rate
- Torque considerations
- Size motor using torque/speed curves

A detailed explanation of the procedure for selecting a Ball Screw Actuated Linear Motion System is given on page 310 in the Engineering Support Section.

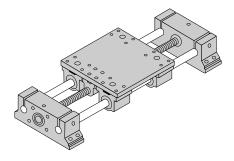




# Superslide<sup>\*</sup> 2AB

Double End Supported System

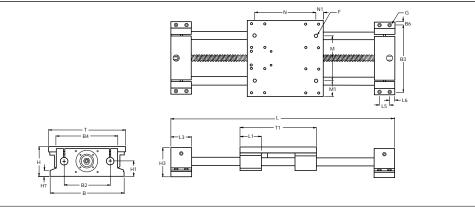
with Carriage and Integral Ball Screw Assembly



### New... Super Smart

### Ball Bushing\* Bearing...

Now Available in Select Sizes



### Maximum Stroke Length is determined by subtracting the

carriage length (**T1**) and 2x the end support length (**L3**) from the total system length.

Superslide 2A	B with	Carriage and In	tegral B	all Screw	Assem	nbly					(	Dimensi	ons in i	inches)
Part	Nom.	Ball Screw	Accuracy	Repeatability	L1	L3	L5	L6	T1	Н	H1	H3	H6	H7
Number	Dia.	Assembly	in/ft	in										
2AB-08-ARB-B	.50	12mm x 5mm NP	<.002	<.002	1.69	1.5	.75	.38	5.5	2.187	1.13	2.37	.38	.48
2AB-08-ARB-F		.500 x .200 <b>NP</b>	<.002	<.002										
2AB-08-ARB-V		.500 x .200 <b>P</b>	<.002	±.0002										
2AB-08-ARB-Q		.500 x .500 <b>P</b>	<.002	±.0002										
2AB-12-ARB-D	.75	20mm x 5mm <b>NP</b>	<.002	<.002	2.06	2.0	1.00	.50	7.5	2.937	1.50	2.70	.50	.60
2AB-12-ARB-G		.750 x .200 <b>NP</b>	<.002	<.002										
2AB-12-ARB-W		.750 x .200 <b>P</b>	<.002	±.0002										
2AB-12-ARB-L		.631 x 1.00 <b>P</b>	<.002	±.0002										
2AB-12-ARB-U		20mm x 20mm NP	<.002	<.002										
2AB-16-ARB-H		1.00 x .250 P	<.002	±.0002										
2AB-16-ARB-T	1.00	1.00 x 1.00 P	<.002	±.0002	2.81	2.2	1.20	.50	9.0	3.437	1.75	3.45	.50	.60
2AB-24-ARB-I		1.50 x .250 <b>P</b>	<.002	±.0002										
2AB-24-ARB-J	1.50	1.50 x 1.00 <b>P</b>	<.002	±.0002	4.00	2.8	1.5	.65	13.0	5.000	2.50	5.00	.75	.81
2AB-24-ARB-Z		1.50 x 1.875 <b>P</b>	<.002	±.0002										

< Indicates Less Than

P- Indicates preloaded ball screw.

NP- Indicates non-preloaded ball screw.

For Motion Control Options refer to the Motion Control Section, page 381.

To determine system Torque Requirements or Ball Screw travel life refer to the

Engineering Support Appendix, see page 310 For Bellows Way Covers, see page 291.

For Radial Mount Ball Screw Shaft Extenders, see page 292.

For Spring Set Electric Brakes, see page 304.

SuperSli	de S	Syst	em	2AB	Sta	nda	rd L	.eng	ths				(Len	gths	in in	ches)
System	18	24	30	32	36	40	42	48	54	56	60	64	66	72	Х	MAX
2AB-08															6	72
2AB-12															6	96
2AB-16															6	144
2AB-24															8	178

End supported systems are subject to shaft deflection based on load. Each application must be checked for maximum allowable shaft deflection.

#### Thomson actuated systems utilize standard NEMA motor mounting configurations for each system size.

configurations	Tor cach system size.
System	Motor Size
2AB-08	NEMA 23
2AB-12	NEMA 23
2AB-16	NEMA 34
2AB-24	NEMA 42

For motor coupling and motor mounting block specifications see the accessories section, page 288.

### Custom Lengths and Delivery Information

Systems ordered in standard lengths and longer lengths in increments of (X) are typically shipped in three to four weeks. Custom length systems are available and require four to six weeks for delivery. For special requirements, please contact the Thomson **Systems** application engineering department.





### SuperSlide\* 2AB Benefits:

- Used when spanning or bridging a gap.
- System is prealigned for quick and easy installation.
- Integrated Ball Screw Assembly with standard NEMA motor mounting.
- Single part number is all that is required to specify.
- Designed for medium loads.

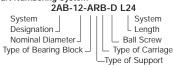
### SuperSlide 2AB Components:

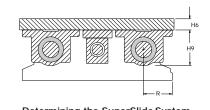
- 4 Super Smart\* Ball Bushing\* pillow blocks
- 2 60 Case\* LinearRace\* ways
- 2 Integrated double end supports with angular contact bearings
  - 1 mounting carriage top

#### Specifying a Thomson System: 1. Determine the proper system for your load and life

 Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number (choosing a standard length will reduce costs and speed delivery).
 Place your order with your local authorized Thomson distributor.

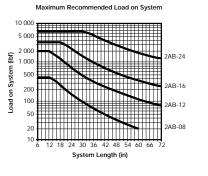
#### Part Numbering System

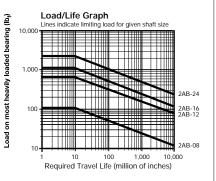




#### Determining the SuperSlide System for your application: To determine the System which best meets your needs, calculate travel life vs. load based on

needs, calculate travel life vs. load based on your application criteria. Calculate the load on the most heavily loaded bearing and total travel life requirements from stroke length and duty cycle. Select the System with a rated load life above your plotted point.

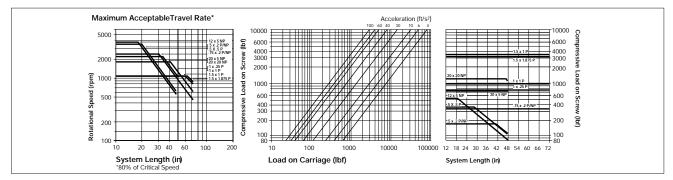




#### SuperSlide 2AB with Carriage and Integral Ball Screw Assembly (Dimensions in inches) Part H9 R R B2 B3 B4 B6 Ν N1 Μ M1 F Max. G Number Stroke Bolt Hole Length 2AB-08-ARB-B 1 25 5.3 1.025 5.5 3.25 4.8 4.25 .25 4.5 .50 3.25 1.13 1/4-20 #8 .19 L-(8.5) 2AB-08-ARB-F 2AB-08-ARB-V 2AB-08-ARB-Q 2AB-12-ARB-D 1.75 72 1.350 75 4.50 67 6.0 25 6.0 .75 4 5 1 50 5/16-18 L-(11.5) #10 .22 2AB-12-ARB-G 2AB-12-ARB-W 2AB-12-ARB-L 2AB-12-ARB-U 2AB-16-ARB-T 2.19 8.7 1.600 9.0 5.50 8.0 7.25 .35 7.0 1.00 5.5 1.75 3/8-16 1/4 .28 L-(13.4) 2AB-16-ARB-H 5/16 2AB-24-ARB-J 3.25 2.500 13.0 8.00 12.0 10.75 .50 10.0 1.50 8.0 2.50 L-(18.6) 13.0 $\frac{1}{2}-13$ .34 2AB-24-ARB-I 2AB-12-ARB-Z

The SuperSlide has a pre-designed Maximum Acceptable Travel Rate. Calculate maximum rotational speed (rpm) by dividing your required maximum linear speed (in/min) by the corresponding system ball screw lead (in/rev.). Enter the chart with the required system length and your maximum rotational speed. Select the system with a maximum acceptable travel rate curve above the plotted line. Compressive load on the ball screw is a key factor in selecting the proper System. Using maximum load and acceleration requirements, plot compressive load on the left side of the chart. Using System length and compressive load. plot the maximum allowable compressive force on the right chart. Select the System with a rated maximum compressive force above your plotted point. If you have questions concerning your system requirements, contact the Thomson **Systems** application engineering department.

Note: Ball screw should never exceed recommended critical speed.



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





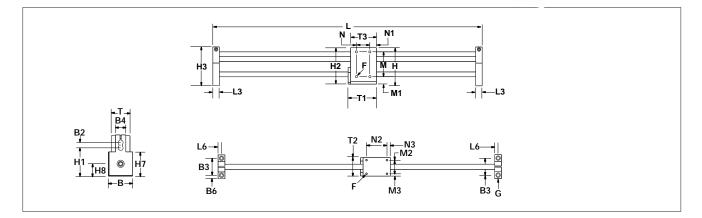


### SuperSlide<sup>\*</sup> 2BB

### TwinRace<sup>®</sup> End Supported System

with Integrated Screw Actuator Assembly





SuperSlide 2BB	TwinF	Race End Suppor	ted Syste	em with In	tegrate	ed Sc	rew A	Actuat	or Ass	embly		(Dim	ensior	ns in i	nches)
Part Number	Nom. Dia.	Lead Screw	Accuracy in/ft	Repeatability in	Н	Т	T1	T2	Т3	В	B2	B3	B4	B6	Motor size
2BB-06-0TH-AA	.375	.375 x .100 <b>P</b>	<.008	±.0002	2.938	1.38	2.19	1.38	2.0	1.75	.374	1.25	.75	.25	NEMA 17
2BB-06-0TH-AB		.375 x .250 <b>P</b>	<.008	±.0002											
2BB-06-0TH-AC		.375 x .500 <b>P</b>	<.008	±.0002											
2BB-06-0TH-AD		.375 x .750 <b>P</b>	<.008	±.0002											
2BB-06-0TH-AE		.375 x 1.00 <b>P</b>	<.008	±.0002											

< Indicates Less Than

P- Indicates preloaded lead screw.

For Motion Control Options refer to the Motion Control Section, see page 381.

To determine system Torque Requirements or Ball Screw travel life refer to the Engineering Support Appendix, page 310.

For information on Handwheels, see page 308.

SuperSlie	de Syste	em 2BB	Standard	Lengths		(L	engths in	inches)
System	4	8	12	16	20	24	Х	MAX
2BB-06							4	36

Maximum length for 2BB systems is 36". End supported systems are subject to shaft deflection based on load. Each application must be checked for maximum allowable shaft deflection.

#### Custom Lengths and Delivery Information

Systems ordered in standard lengths and longer lengths in increments of (X) are typically shipped in two to three weeks. Custom length systems are available and require three to four weeks for delivery. For special requirements, please contact the Thomson **Systems** application engineering department.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.

Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



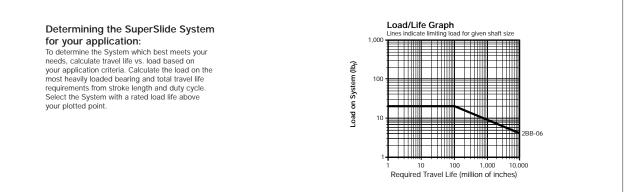
### SuperSlide\* 2BB Benefits:

- Used when spanning or bridging a gap.
- Welded LinearRace\* design provides torque resistance.
- Ultra compact design allows for minimal machine size.
- Integrated screw actuator assembly provides accurate movement of carriage.
- SuperSlide 2BB Components:
- Universal integrated, carriage with 4 special open type Super Ball Bushing\* bearings
- Welded Twin Shaft rail assembly
- 2 vertical end support blocks
- Integrated screw actuator assembly

#### Specifying a Thomson System:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number (choosing a standard length will reduce costs and speed delivery). 4. Place your order with your local authorized Thomson distributor. Part Numbering System

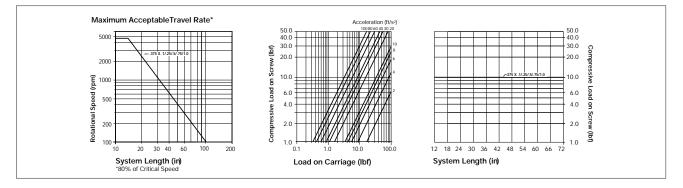




Super	SuperSlide 2BB TwinRace* End Supported System with Integrated Screw Actuator Assembly (Dimensions in inches															inches)	
H1	H2	H3	H7	H8	L3	L6	Μ	M1	M2	M3	F	G	N	N1	N2	N3	Max. Stroke Length
2.057	2.81	3.00	1.75	.875	.625	.31	2.0	.41	1.00	.18	#16-32	#10	1.0	.50	1.5	.25	L-(3.44)

The SuperSlide has a pre-designed Maximum Acceptable Travel Rate. Calculate maximum rotational speed (rpm) by dividing your required maximum linear speed (in/min) by the corresponding system screw lead (in/rev). Enter the chart with the required system length and your maximum rotational speed. Select the system with a maximum acceptable travel rate curve above the plotted line. Compressive load on the lead screw is a key factor in selecting the proper System. Using maximum load and acceleration requirements, plot compressive load on the left side of the chart. Using System length and compressive load. plot the maximum allowable compressive force on the right chart. Select the System with a rated maximum compressive force above your plotted point. If you have questions concerning your system requirements, contact the Thomson **Systems** application engineering department.

Note: Lead screw should never exceed recommended critical speed.



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



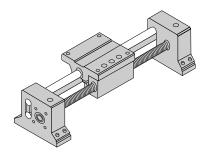




### SuperSlide<sup>\*</sup> 2CB

### Twin Shaft Web End Supported System

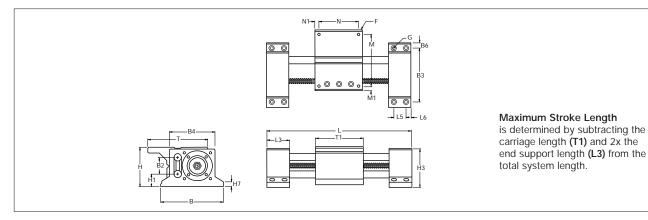
with Flanged Carriage and Integral Ball Screw Assembly



### New... Super Smart

Ball Bushing\* Bearing...

Now Available in Select Sizes



SuperSlide 2C	B with	n Flanged Carriage	and Inte	gral Ball S	Screw A	Asser	nbly					(Dim	nensior	ns in ir	nches)
Part Number	Nom. Dia.	Ball Screw	Accuracy in/ft	Repeatability in	Н	Т	T1	В	R	B1	B2	B3	B4	B5	B6
2CB-08-OVA-B	.50	12mm x 5mm NP	<.002	<.002	2.750	3.5	3.5	4.25	1.125	4.87	1.13	3.62	3.12	1.5	.31
2CB-08-OVA-F		.500 x .200 NP	<.002	<.002											
2CB-08-OVA-V		.500 x .200 <b>P</b>	<.002	±.0002											
2CB-12-OVA-C	.75	16mm x 5mm NP	<.002	<.002	3.625	4.5	4.5	5.00	1.500	5.75	1.50	4.25	3.50	2.0	.38
2CB-16-OVA-G	1.00	.750 x .200 <b>NP</b>	<.002	<.002	4.625	6.0	6.0	6.62	2.000	7.62	2.00	5.62	4.87	2.5	.50
2CB-16-OVA-W	1.00	.750 x .200 <b>P</b>	<.002	±.0002											
2CB-16-OVA-D		20mm x 5mm <b>NP</b>	<.002	<.002											

< Indicates Less Than

P- Indicates preloaded ball screw.

NP- Indicates non-preloaded ball screw.

For Motion Control Options refer to the Motion Control Section, page 381.

To determine system Torque Requirements or Ball Screw travel life refer to the

Engineering Support Appendix, page 310.

For Bellows Way Covers, see page 291.

For Radial Mount Ball Screw Shaft Extenders, see page 292.

For Spring Set electric brakes, see page 304.

For Handwheels, see page 308.

Thomson actuated systems utilize standard NEMA motor mounting configurations for each system size.

System	Motor Size
2CB-08	NEMA 23
2CB-12	NEMA 23
2CB-16	NEMA 34

For motor coupling and motor mounting block specifications see the accessories section, page 288

SuperSlie	de Sy	stem	2CB	Stan	dard	Leng	ths		(l	ength	ns in in	ches)
System	18	24	30	36	42	48	54	60	66	72	Х	MAX
2CB-08											4	72
2CB-12											6	72
2CB-16											6	72

Maximum length of 2CB systems is 72". End supported systems are subject to shaft deflection based on load. Each application must be checked for maximum allowable shaft deflection.

### Custom Lengths and Delivery Information

Systems ordered in standard lengths and longer lengths in increments of (X) are typically shipped in three to four weeks. Custom length systems are available and require four to six weeks for delivery. For special requirements, please contact the Thomson **Systems** application engineering department.





### SuperSlide\* 2CB Benefits:

- Used when spanning or bridging a gap.
- Double LinearRace\* and welded integral web design maximizes torque resistance and dramatically improves deflection characteristics.
- Prealigned for quick and easy installation.
- Designed to move medium loads with virtually frictionless travel.

### SuperSlide 2CB Components:

- Universal integrated, carriage with 4 open type Super Smart Ball Bushing\* bearings
- Twin welded 60 Case\* LinearRace\* with integral web
- 2 vertical double end supports with integral angular contact bearings
- 1 integrated ball screw assembly

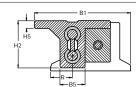
#### Specifying a Thomson System:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number (choosing a standard length will reduce costs and speed delivery). 4. Place your order with your local authorized Thomson distributor. Part Numbering System

#### 2CB-12-OVA-C L24

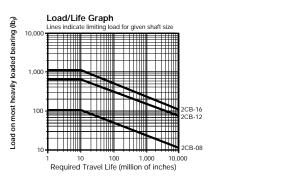
System \_\_\_\_\_ Ball Sc Nominal Diameter \_\_\_\_\_ Type of Ca

- Type of Support



Determining the SuperSlide System for your application:

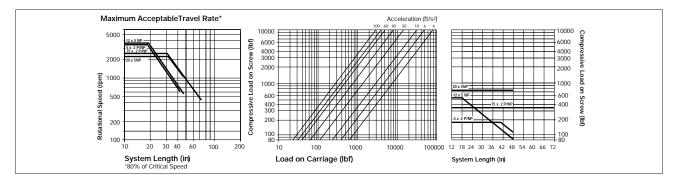
To determine the System which best meets your needs, calculate **travel life vs. load** based on your application criteria. Calculate the load on the most heavily loaded bearing and total travel life requirements from stroke length and duty cycle. Select the system with a rated load life above your plotted point.



SuperSlide 2Cl	B with	Flange	ed Carr	iage ar	nd Integ	jral Ba	II Screv	N Asse	mbly				(Di	imens	ions iı	n inches)
Part Number	L3	L5	L6	H1	H2	H3	H5	H7	N	N1	Μ	M1	F	Bolt	; Hole	Max. Stroke
Number														BOIL	Hole	Length
2CB-08-OVA-B	1.5	.88	.31	.88	2.62	2.62	.37	.44	3.00	.25	3.00	.25	#10-32	#10	.22	L-(6.5)
2CB-08-OVA-F																
2CB-08-OVA-V																
2CB-12-OVA-C	1.5	.75	.38	1.13	3.50	3.30	.50	.62	4.00	.25	4.00	.25	1/4-20	<sup>5</sup> /16	.34	L-(7.5)
2CB-16-OVA-G	2.0	1.00	.50	1.38	4.50	4.50	.62	.75	5.25	.38	5.25	.38	<sup>5</sup> /16-18	<sup>5</sup> /16	.34	L-(10.0)
2CB-16-OVA-W																
2CB-16-OVA-D																

The SuperSlide has a pre-designed Maximum Acceptable Travel Rate. Calculate maximum rotational speed (rpm) by dividing your required maximum linear speed (in/min) by the corresponding system ball screw lead (in/rev.). Enter the chart with the required system length and your maximum rotational speed. Select the system with a maximum acceptable travel rate curve above the plotted line. Compressive load on the ball screw is a key factor in selecting the proper System. Using maximum load and acceleration requirements, plot compressive load on the left side of the chart. Using System length and compressive load. plot the maximum allowable compressive force on the right chart. Select the System with a rated maximum compressive force above your plotted point. If you have questions concerning your system requirements, contact the Thomson **Systems** application engineering department.

Note: Ball screw should never exceed recommended critical speed.



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





# SuperSlide<sup>\*</sup> 2DB

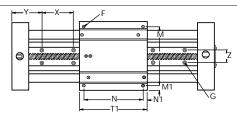
Continuously Supported System

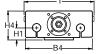
with Carriage and Integral Ball Screw Assembly

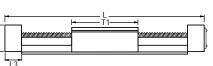
### New... Super Smart

### Ball Bushing\* Bearing...

Now Available in Select Sizes







Maximum Stroke Length (without Bellows) is determined by subtracting the carriage length (T1) and 2x the end support length (L3) from the total system length.

SuperSlide 2DE	3 with Ca	rriage and Integ	ral Ball So	crew Asser	nbly						(Dim	ensio	ns in ir	nches)
Part	Nominal	Ball or Lead	Accuracy	Repeatability	T1	L3	Н	H1	H2	H3	H4	В	R	Т
Number	Diameter	Screw	in/ft	in										
		(Dia. x Lead)												
2DB-08-OUB-AA	.50	.375 x .10 P	<.008	±.0002	4.5	1.25	1.625	.875	1.43	1.90	2.02	2.00	.500	4.600
2DB-08-OUB-AB		.375 x .25 P												
2DB-08-OUB-AC		.375 x .50 P												
2DB-08-OUB-AD		.375 x .75 P												
2DB-08-OUB-AE		.375 x 1.0 P												
2DB-12-OUB-B	.75	12mm x 5mm NP	<.002	<.002	6.0	1.50	2.125	1.125	1.93	2.37	2.62	2.63	.688	6.100
2DB-12-OUB-F		.500 x .200 NP	<.002	<.002										
2DB-12-OUB-V		.500 x .200 P	<.002	±.0002										
2DB-16-OUB-D	1.00	20mm x 5mm NP	<.002	<.002	7.5	2.00	2.625	1.375	2.45	3.37	3.49	3.25	.875	7.600
2DB-16-OUB-G		.750 x .200 NP	<.002	<.002										
2DB-16-OUB-W		.750 x .200 P	<.002	±.0002										

P- Indicates preloaded ball or lead screw. NP- Indicates non-preloaded ball screw.

For Motion Control Options refer to the Motion Control Section, see page 381.

To determine system Torque Requirements or Ball Screw travel life refer to the Engineering Support Appendix, see page 310.

SuperSlide 2D	B with C	Carriage	and Int	egral B	all Scre	w Assei	nbly					(Dim	ensions in inches)
Part	B2	B4	N	N1	M	M1	Х	Y	Z	F	(	3	Max. Stroke
Number											Bolt	Hole	Length
2DB-08-OUB	3.0	4.5	4.00	.25	4.00	.31	4.0	2.0	.75	#10-32	1/4	.28	L-(7.0)
2DB-12-OUB	4.0	6.0	5.25	.37	5.25	.42	6.0	3.0	1.00	1/4-20	<sup>5</sup> /16	.34	L-(9.0)
2DB-16-OUB	5.0	7.0	6.75	.37	6.75	.42	6.0	3.0	1.25	<sup>5</sup> /16-18	3/8	.41	L-(11.5)

SuperSli	SuperSlide System 2DB Standard Lengths (Lengths in inches)																	
System         12         16         18         20         24         28         30         32         36         40         42												44	48	54	60	72	Х	MAX
2DB-08										I							4	48
2DB-12																	6	72
2DB-16																	Б	<b>S</b>

Custom Lengths and Delivery Information Systems ordered in standard lengths and longer lengths in increments of (X) are typically shipped in three to four weeks. Custom length systems are available and require four to six weeks for delivery. For special requirements, please contact the Thomson **Systems** application engineering department.





#### SuperSlide\* 2DB Benefits:

- Used in continuously supported applications when rigidity is required.
- Pre-aligned and preassembled for immediate installation and use.
- Designed for medium to heavy loads.
- Integrated ball screw assembly with standard NEMA motor mounting

#### SuperSlide 2DB Components:

- 1 Dual LinearRace\* Rail Assembly
- 1 modular carriage with 4 open type Super Smart Ball Bushing\* Pillow blocks.
- 1 integrated ball screw assembly

#### Specifying a Thomson System:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number (choosing a standard length will reduce costs and speed delivery). 4. Place your order with your local authorized Thomson distributor

#### Part Numbering System



Thomson actuated systems utilize standard NEMA motor mounting configurations for each system size.

Motor Size

NEMA 23

NEMA 23

NEMA 23 or 34

1,000

100 Required Travel Life (million of inches) DB-16

2DB-12

2DB-08

10,000

System

2DB-08

2DB-12

2DB-16

10.000

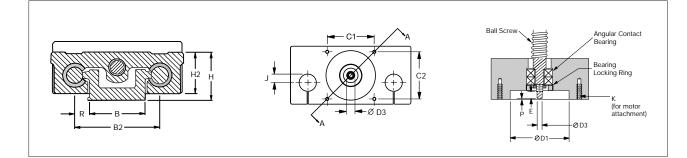
1.000

100

Load on most heavily loaded bearing ( $lb_{\beta}$ )

Load/Life Graph

Lines indicate limiting load for



SuperSlide 2DB w	vith Carria	age and I	ntegral B	all Screw	Assembl	<b>y</b> (Dim	ensions i	n inches)
Part Number	C1	C2	D1	D3	E	J	К	Р
2DB-08-OUB-	1.75	1.25	1.50	.188	.300	.275	10-32	.05
2DB-12-OUB-	1.86	1.86	2.150	.250	.335	.300	10-32	.05
2DB-16-OUB-D	2.74	2.74	2.876	.375	.560	.425	10-32	.05

Maximum continuous length of support rails is 24". If longer continuous shaft support rails are required, contact the Thomson Systems application engineering department.

For Motor Adaptor and Motor Coupling information, see page 288.

For Bellows Way Covers, see page 291.

For Radial Mount Ball Screw Shaft Extenders, see page 292.

For Spring Set electric brakes, see page 304.

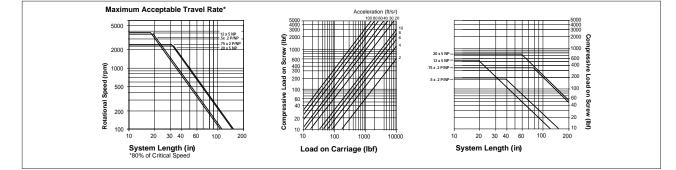
For Handwheels, see page 308.

The SuperSlide has a pre-designed Maximum Acceptable Travel Rate. Calculate maximum rotational speed (rpm) by dividing your required maximum linear speed (in/min) by the corresponding system ball screw lead (in/rev.). Enter the chart with the required system length and your maximum rotational speed. Select the system with a maximum acceptable travel rate curve above the plotted line. Compressive load on the ball screw is a key factor in selecting the proper System. Using maximum load and acceleration requirements, plot compressive load on the left side of the graph. Using System length and compressive load, plot the maximum allowable compressive force on the right chart. Select the System with a rated maximum compressive force above your plotted point.

If you have questions concerning your system requirements, contact the Thomson Systems application engineering department.

Note: Ball screw should never exceed recommended critical speed

10



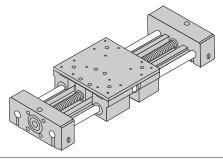
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





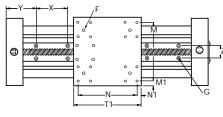
### SuperSlide<sup>\*</sup> 2DB Continuously Supported System

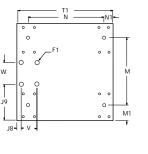
with Modular Carriage and Integral Ball Screw Assembly



### **New...** Super Smart Ball Bushing\* Bearing...

Now Available in Select Sizes





Maximum Stroke Length (without Bellows) is determined by subtracting the carriage length (T1) and 2x the end support length (L3) from the total system length.

SuperSlide 2D	B with Mo	odular Carriage a	nd Integr	al Ball Scr	ew Ass	sembly				(Dimer	nsions in	inches)
Part	Nominal	Ball	Accuracy	Repeatability	L3	Н	H1	H2	H3	H4	В	R
Number	Diameter	Screw	(in/ft)	in								
		(Dia. x Lead)										
2DB-12-JUB-Q	.75	.500 x .500 P	<.002	±.0002	1.5	2.562	1.125	2.44	2.37	2.62	2.63	.688
2DB-16-JUB-L	1.00	.631 x 1.000 P	<.002	±.0002	2.0	3.062	1.375	2.97	3.37	3.49	3.25	.875
2DB-16-JUB-R		.750 x .500 P	<.002	±.0002								

SuperSlide 2DI	B with N	Nodular	Carriag	je and I	ntegral	Ball Scr	ew Ass	embly				(Dime	ensions in inches)
Part	B2	B4	N	N1	M	M1	Х	Y	Z	F	(	3	Max. Stroke
Number											Bolt	Hole	Length
													Ũ
2DB-12-JUB-Q	4.0	6.0	5.00	.50	4.5	.75	6.0	3.0	1.00	1/4-20	<sup>5</sup> /16	.34	L-(9.0)
2DB-16-JUB-L	5.0	7.0	6.50	.50	5.5	1.00	6.0	3.0	1.25	1/4-20	3/8	.41	L-(11.5)
2DB-16-JUB-R													

SuperSlide 2DB wit	h Modular C	arriage and I	ntegral Ball	Screw Asser	nbly		(Dimens	ions in inches)
Part	J8	J9	V	W	F1	Т	T1	H6
Number								
2DB-12-JUB-Q	.44	2.53	1.00	.95	1/4-20	6.000	6.0	.50
2DB-16-JUB-L	.28	3.09	.50	1.33	1/4-20	7.500	7.5	.50
2DB-16-JUB-R								

P- Indicates preloaded ball screw.

For Motion Control Options refer to the Motion Control Section, page 381

To determine system **Torque Requirements** or Ball Screw travel life refer to the Engineering Support Appendix, page 310 For Motor Adaptor and Motor Coupling information, see page 288.

SuperSli	de S	ysten	n 2DE	3 Sta	ndar	d Ler	gths	(Ler	ngths	in inc	hes)
System	18	24	30	36	42	48	54	60	72	Х	MAX
2DB-12										6	72
2DB-16										6	96

### **Custom Lengths and Delivery Information**

Systems ordered in standard lengths and longer lengths in increments of (X) are typically shipped in three to four weeks. Custom length systems are available and require four to six weeks for delivery. For special requirements, please contact the Thomson **Systems** application engineering department.





### Superslide\* 2DB Benefits:

- Used in continuously supported applications when rigidity is required.
- Pre-aligned and preassembled for immediate installation and use.
- Designed for medium to heavy loads.
- Integrated ball screw assembly with standard NEMA motor mounting.

### Superslide 2DB Components:

- 1 Dual LinearRace\* Rail Assembly
- 1 modular carriage with 4 open type Super Smart Ball Bushing\* Pillow blocks
- 1 integrated ball screw assembly

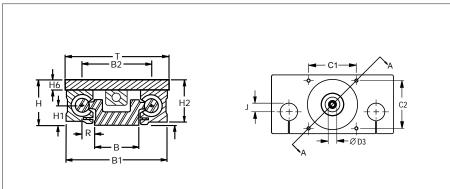
#### Specifying a Thomson System:

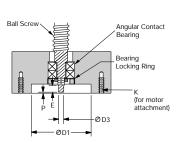
 Determine the proper system for your load and life requirements.
 Select the part number.
 Add the letter "L" followed by the overall length in inches, as a suffix to the part number (choosing a standard length will reduce costs and speed delivery).
 Place your order with your local authorized Thomson distributor.
 Part Numbering System

#### 2DB-12-JUB-Q L24

System \_\_\_\_\_ Ball Designation \_\_\_\_\_ Jule \_\_\_ Ball Nominal Diameter \_\_\_\_\_ Type of Type of Bearing Block \_\_\_\_\_ Type of

L System Length Ball Screw Type of Carriage Type of Support





# Superslide 2DB with Modular Carriage and Integral Ball Screw Assembly (Dimensions in inches)Thomson a<br/>standard N<br/>configuratPartC1C2D1D3EJKP

Part	C1	C2	D1	D3	E	J	K	Р	
Number									
2DB-12-JUB-Q	1.86	1.86	2.15	.250	.335	.300	10-32	.05	
2DB-16-JUB-L	2.74	2.74	2.876	.375	.560	.425	10-32	.05	
2DB-16-JUB-R									

Maximum continuous length of support rails is 24". If longer continuous shaft support rails are required, contact the Thomson Systems application engineering department.

For Bellows Way Covers, see page 291.

For Radial Mount Ball Screw Shaft Extenders, see page 292.

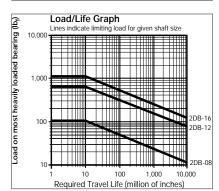
For Spring Set electric brakes, see page 304 For Handwheels, see page 308.

The SuperSlide has a pre-designed Maximum Acceptable Travel Rate. Calculate maximum rotational speed (rpm) by dividing your required maximum linear speed (in/min) by the corresponding system ball screw lead (in/rev). Enter the chart with the required system length and your maximum rotational speed. Select the system with a maximum acceptable travel rate curve above the plotted line.

Compressive load on the ball screw is a key factor in selecting the proper System. Using maximum load and acceleration requirements, plot compressive load on the left side of the chart. Using System length and compressive load, plot the maximum allowable compressive roce on the right chart. Select the System with a rated maximum compressive force above your plotted point.

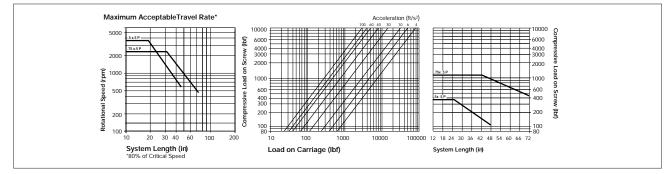
#### Thomson actuated systems utilize standard NEMA motor mounting configurations for each system size.

configurations	for each system size.
System	Motor Size
2DB-12	NEMA 23
2DB-16	NEMA 23 or 34



If you have questions concerning your system requirements, contact the Thomson **Systems** application engineering department.

Note: Ball screw should never exceed recommended critical speed.



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





# SuperSlide<sup>\*</sup> 2EB

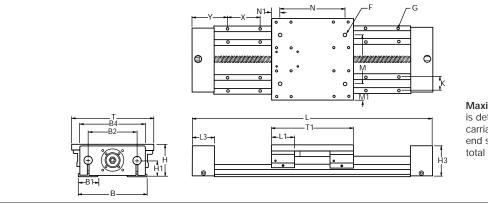
# **Double Continuously Supported System**

with Carriage and Integral Ball Screw Assembly

### **New...** Super Smart

Ball Bushing\* Bearing...

Now Available in Select Sizes



#### Maximum Stroke Length

is determined by subtracting the carriage length (T1) and 2x the end support length (L3) from the total system length.

SuperSlide 2E	B with	n Carriage and In	tegral B	all Screw	Assem	nbly					])	Dimensi	ons in	inches)
Part Number	Nom. Dia.	Ball Screw	Accuracy in /ft	Repeatability	L1	L3	T1	К	Н	H1	H3	H6	H7	H9
2EB-08-FTB-B	.50	12mm x 5mm NP	<.002	<.002	1.50	1.5	5.5	1.00	2.187	1.125	2.38	.38	.19	1.12
2EB-08-FTB-F		.500 x .200 NP	<.002	<.002										
2EB-08-FTB-V		.500 x .200 P	<.002	±.0002										
2EB-08-FTB-Q		.500 x .500 <b>P</b>	<.002	±.0002										
2EB-12-FTB-D	.75	20mm x 5mm NP	<.002	<.002	1.88	2.0	7.5	1.25	2.937	1.500	2.75	.50	.25	1.56
2EB-12-FTB-G		.750 x .200 NP	<.002	<.002										
2EB-12-FTB-W		.750 x .200 P	<.002	±.0002										
2EB-12-FTB-L		.631 x 1.00 <b>P</b>	<.002	±.0002										
2EB-12-FTB-U		20mm x 20mm NP	<.002	<.002										
2EB-16-FTB-H		1.00 x .250 P	<.002	±.0002										
2EB-16-FTB-T	1.00	1.00 x 1.00 <b>P</b>	<.002	±.0002	2.63	2.2	9.0	1.50	3.437	1.750	3.37	.50	.25	2.00
2EB-24-FTB-I		1.50 x .250 P	<.002	±.0002										
2EB-24-FTB-J	1.50	1.50 x 1.00 <b>P</b>	<.002	±.0002	3.75	2.8	13.0	2.25	5.000	2.500	4.87	.75	.38	2.94
2EB-24-FTB-Z		1.50 x 1.875 <b>P</b>	<.002	±.0002										

< Indicates Less Than ± Indicates Plus or Minus

P- Indicates preloaded ball screw.

NP- Indicates non-preloaded ball screw.

For Motion Control Options refer to the Motion Control Section, page 381.

To determine system Torque Requirements or Ball Screw travel life refer to the Engineering Support Appendix, see page 310.

For Bellows Way Covers, see page 291.

For Radial Mount Ball Screw Shaft Extenders, see page 292.

For Spring Set electric brakes, see page 304.

For Handwheels, see page 308

SuperSli	de 2	EB	Sta	ndaı	rd L	eng	ths						(Lei	ngth	s in ir	nches)
System	18	24	30	32	36	40	42	48	54	56	60	64	66	72	Х	MAX
2EB-08															6	72
2EB-12															6	96
2EB-16															6	144
2EB-24															8	176

#### Thomson actuated systems utilize standard NEMA motor mounting configurations for each system size.

System	Motor Size
2EB-08	NEMA 23
2EB-12	NEMA 23
2EB-16	NEMA 34
2EB-24	NEMA 42

For motor coupling and motor mounting block specifications see the accessories section, page 288.

#### **Custom Lengths and Delivery Information**

Systems ordered in standard lengths and longer lengths in increments of (X) are typically shipped in three to four weeks. Custom length systems are available and require four to six weeks for delivery. For special requirements, please contact the Thomson Systems application engineering department.





#### SuperSlide\* 2EB Benefits:

- Used in continuously supported appli cations when rigidity is required.
- Integrated ball screw assembly with standard NEMA motor mounting.
- Pre-aligned and preassembled for immediate installation and use.
- Designed for medium to heavy loads.

#### SuperSlide 2EB Components:

- 4 open type Super Smart Ball Bushing\* pillow blocks
- 2 60 Case\* LinearRace\* Assemblies
- 2 integrated double end supports
- 1 mounting carriage top
- 1 integrated ball screw assembly

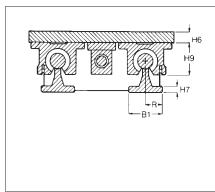
#### Specifying a Thomson System:

1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in inches, as a suffix to the part number (choosing a standard length will reduce costs and speed delivery). 4. Place your order with your local authorized Thomson distributor. Part Numbering System

#### 2EB-12-FTB-G L24

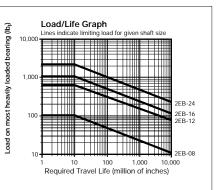
System Designation \_\_\_\_\_ Nominal Diameter\_\_\_\_ Type of Bearing Block \_\_\_\_\_ Typ

Ball Screw Type of Carriage Type of Support



### Determining the SuperSlide System for your application:

To determine the System which best meets your needs, calculate **travel life vs. load** based on your application criteria. Calculate the load on the most heavily loaded bearing and total travel life requirements from stroke length and duty cycle. Select the system with a rated load life above your plotted point.

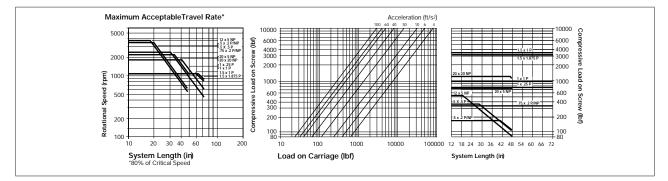


SuperSlide 2E	B with	Carria	ge and	Integr	al Ball S	Screw	Assem	bly					(D	imens	ions i	n inches)
Part Number	Т	В	R	B1	B2	B4	N	N1	Μ	M1	Х	Y	F	Bolt	; Hole	Max. Stroke Length
2EB-08-FTB-B 2EB-08-FTB-F 2EB-08-FTB-V 2EB-08-FTB-Q	5.5	4.75	.750	1.50	3.25	4.25	4.5	.50	3.25	1.13	4.0	2.0	1/4-20	#8	.19	L-(8.5)
2EB-12-FTB-D 2EB-12-FTB-G 2EB-12-FTB-W 2EB-12-FTB-L 2EB-12-FTB-U	7.5	6.25	.875	1.75	4.50	6.00	6.0	.75	4.50	1.50	6.0	3.0	<sup>5</sup> /16-18	#10	.22	L-(11.5)
2EB-16-FTB-H 2EB-16-FTB-T	9.0	7.63	1.062	2.12	5.50	7.25	7.0	1.00	5.50	1.75	6.0	3.0	<sup>3</sup> /8-16	1/4	.28	L-(13.4)
2EB-24-FTB-I 2EB-24-FTB-J 2EB-24-FTB-Z	13.0	11.00	1.500	3.00	8.00	10.75	10.0	1.50	8.00	2.50	8.0	4.0	1/2-13	5/16	.34	L-(18.6)

Maximum continuous length of support rails is 24". If longer continuous shaft support rails are required, contact the Thomson Systems application engineering department.

The SuperSlide has a pre-designed Maximum Acceptable Travel Rate. Calculate maximum rotational speed (rpm) by dividing your required maximum linear speed (in/min) by the corresponding system ball screw lead (in/rev). Enter the chart with the required system length and your maximum rotational speed. Select the system with a maximum acceptable travel rate curve above the plotted line. Compressive load on the ball screw is a key factor in selecting the proper System. Using maximum load and acceleration requirements, plot compressive load on the left side of the chart. Using System length and compressive load, plot the maximum allowable compressive loace on the right chart. Select the System with a rated maximum compressive force above your plotted point. If you have questions concerning your system requirements, contact the Thomson **Systems** application engineering department.

Note: Ball screw should never exceed recommended critical speed.



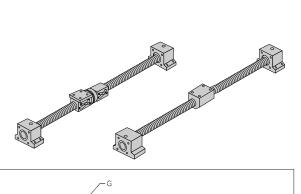
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

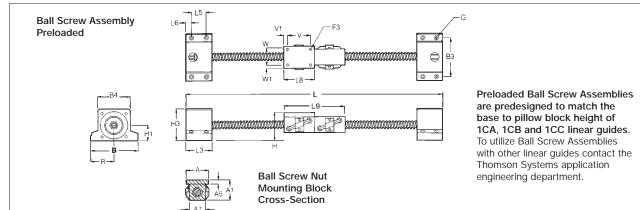


The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Trademark of Thomson industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Page 235

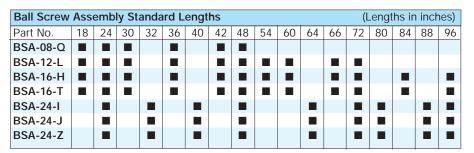
# **Ball Screw Assemblies**





Ball Screw	Assemblies -	(Preload	led)								(Dime	nsions ir	inches)
Part	Ball Screw	L3	L5	L6	L8	Н	H3	H1	В	B3	B4	R	G
Number	Dia. x Lead												
BSA-08-Q	.500 x .500	1.50	0.75	0.38	2.25	1.812	2.35	1.200	3.80	3.20	2.50	1.900	0.19
BSA-12-L	.631 x 1.00	2.00	1.00	0.50		2.437	2.70	1.500	3.80	3.20	2.50	1.900	0.22
BSA-16-H	1.00 x .250	2.20	1.20	0.50	2.40	2.937	3.45	1.750	5.00	4.20	3.50	2.500	0.28
BSA-16-T	1.00 x 1.00												
BSA-24-I	1.50 x .250												
BSA-24-J	1.50 x 1.00	2.80	1.50	0.65	2.82	4.250	5.000	2.500	7.25	6.20	5.00	3.625	0.34
BSA-24-Z	1.50 x 1.875												

Number         Dia. x Lead         Image: Constraint of the state of	
BSA-08-Q         .500 x .500         1.00         0.25         0.95         0.14         #6-32         1.23         1.20         0.23         0           BSA-12-L         .631 x 1.00         1.93         0.25         1.33         0.18         #8-32         1.69         1.80         -	A7 Motor
BSA-12-L         .631 x 1.00         1.93         0.25         1.33         0.18         #8-32         1.69         1.80         -	Frame Size
	.76 NEMA 23
	- NEMA 23
BSA-16-H         1.00 x .250         1.90         0.25         1.63         0.26         #10-32         2.15         2.03         0.44         2	.12 NEMA 34
BSA-16-T 1.00 x 1.00	NEMA 34
BSA-24-I 1.50 x .250	NEMA 42
<b>BSA-24-J</b> 1.50 x 1.00 2.00 0.41 2.00 0.37 1/4-20 2.75 3.25 0.63 2	.25 NEMA 42
BSA-24-Z 1.50 x 1.875	NEMA 42



# Custom Lengths and Delivery Information

Systems ordered in standard lengths are typically shipped in three to four weeks. Custom length systems are available and require four to six weeks for delivery. For special requirements, please contact the Thomson **Systems** application engineering department.

For Motion Control Options, refer to the Motion Control Section, see page 381. To determine system Torque Requirements of Ball Screw travel life refer to the Engineering Support Appendix, page 310. For Motor Adaptor and Motor Coupling information, see page 288.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





#### Ball Screw Assembly Benefits:

- Integrated ball screw, end support, motors and controllers provide complete drive capabilities.
- Designed to fit appropriately sized linear guides.
- Pre-engineered to meet your system needs.

# Ball Screw Assembly Components:

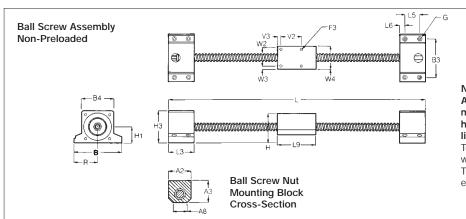
- 1 Ball Screw Assembly with Ball Nut Mounting Surface (Preloaded or Non-Loaded)
- 2 Integrated End Supports with Angular Contact Bearings
- 1 Motor and Controller with integrated indexer (optional)

Specifying a Thomson Ball Screw Assembly: 1. Determine your drive requirements (torque, speed, acceleration, etc. 2. Select the part number of the ball screw you have chosen. 3. Place your order with your local authorized Thomson distributor. Part Numbering System

### BSA-12-B L24

Type of Assembly —

Length Ball Screw System Size



Non-Preloaded Ball Screw Assemblies are predesigned to match the base to pillow block height of 1CA, 1CB and 1CC linear guides. To utilize Ball Screw Assemblies

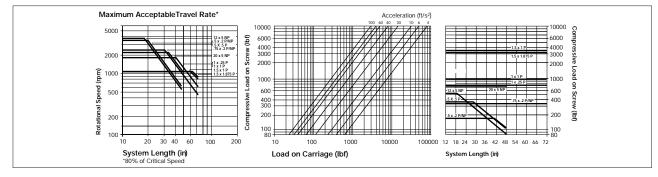
with other linear guides contact the Thomson Systems application engineering department.

Doll Corow /	all Screw Assemblies (Non-Preloaded) (Dimension in inches)														
Dall Screw F	an Screw Assembles (Non-Preloaded) (Dimension in Inches)														
Part	Ball Screw	L3	L5	L6	L9	Н	H3	H1	В	B3	B4	R	G		
Number	Dia. x Lead														
BSA-08-F	.500 x .200	1.50	0.75	0.38	2.25	1.812	2.35	1.200	3.80	3.20	2.50	1.90	0.19		
BSA-12-G	.750 x .200	2.00	1.00	0.50		2.437	2.70	1.500	3.80	3.20	2.50	1.90	0.22		
BSA-M12-B	12mm x 5mm	1.50	0.75	0.38	2.25	1.812	2.35	1.200	3.80	3.20	2.50	1.90	0.19		
BSA-M20-D	20mm x 5mm	2.00	1.00	0.50	2.46	2.437	2.70	1.500	3.80	3.20	2.50	1.90	0.22		

Ball Screw A	Assemblies (No	n-Preloa	ided)					(Dir	mension i	n inches)
Part	Ball Screw	A2	A3	A8	V2	V3	W2	W3	W4	F3
Number	Dia. x Lead									
BSA-08-F	.500 x .200	1.19	1.23	0.48	1.00	0.25	0.95	0.12	1.19	#6-32
BSA-12-G	.750 x .200	1.69	1.80	0.72	1.93	0.25	1.33	0.18	1.69	#8-32
BSA-M12-B	12mm x 5mm	1.19	1.23	0.48	1.00	0.25	0.95	0.12	1.19	#6-32
BSA-M20-D	20mm x 5mm	1.69	1.80	0.72	1.93	0.25	1.33	0.18	1.69	#8-32

The SuperSlide has a pre-designed Maximum Acceptable Travel Rate. Calculate maximum rotational speed (rpm) by dividing your required maximum linear speed (in/min) by the corresponding system ball screw lead (in/rev). Enter the chart with the required system length and your maximum rotational speed. Select the system with a maximum acceptable travel rate curve above the plotted line. Compressive load on the ball screw is a key factor in selecting the proper System. Using maximum load and acceleration requirements, plot compressive load on the left side of the chart. Using System length and compressive load. plot the maximum allowable compressive roce on the right chart. Select the System with a rated maximum compressive force above your plotted point. If you have questions concerning your system requirements, contact the Thomson **Systems** application engineering department.

Note: Ball screw should never exceed recommended critical speed.



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





Systems Applications
Application
Analysis
Jere

Determining the system which best meets the demands of your application and provides optimum performance requires the evaluation of a number of variables. The accompanying form establishes basic criteria to initiate the analysis of your application. In addition, the Engineering Support Appendix has been designed with pertinent data and formulas used to specify the proper system for your application. If you have questions or special needs a Thomson systems engineer can assist

you in evaluating your application and recommending a system solution. Simply call 1-800-554-8466.

Application Description:	Horizontal	Vertical

System Part Number:		
Quantity Required:		
Weight of Load (lbs):		
Space Requirements (LxHxW):		
Stroke Length Requirements (in):		
Support Requirements:	End Suppor	rted 🛛 Full Support
Maximum Velocity Requirements (in/s):		
Maximum Acceleration Requirements (in/s <sup>2</sup> ):		
Required Straightness of Travel Accuracy (in/ft):		
Required Positioning Accuracy (in):		
Required Repeatability (in):		
Life Requirement (in):		
Cycle (in/yr):		
Environmental Considerations:		
Other Design Criteria:		
Production Time Frame:		
Company:		
Name:		
Title:		
Address:		
City:	State:	Zip:
Telephone:	Fax:	

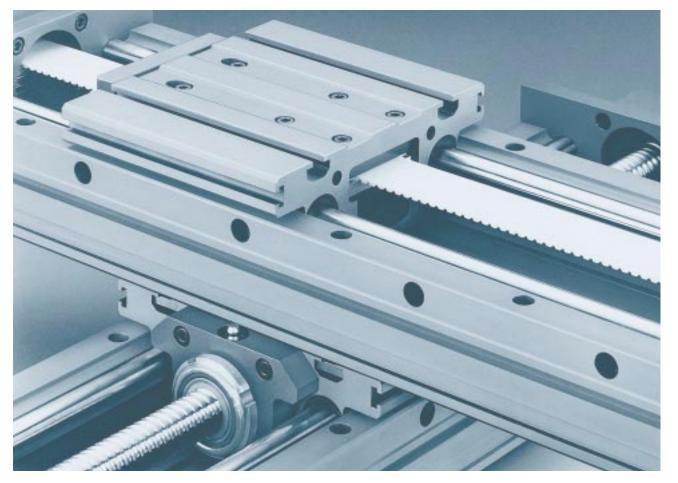
Please Fax your Application Analysis to 516-883-9039 Attention: Application Engineering.





# Systems, Slides, and Stages





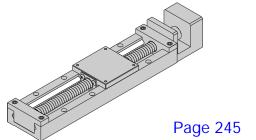
# **Engineering Selection Guide for Linear Motion System Solutions**

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





# *MicroStage\** Actuated Linear Motion System



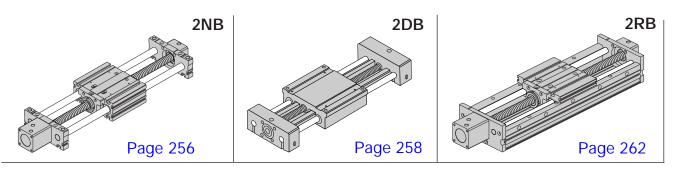
SuperSlide\* Ball Screw Actuated Systems For End Supported Applications

For Continuously Supported Applications

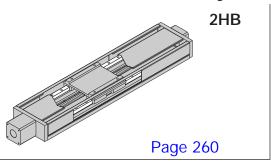
**Metric** 

**Product** 

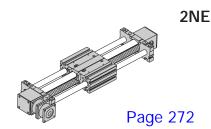
Matrix



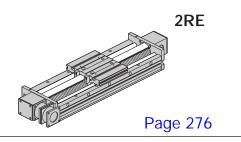
AccuSlide\* Ball Screw Actuated Systems



**SuperSlide** Belt Actuated Systems For End Supported Applications



For Continuously Supported Applications



For Application Engineering assistance contact the Thomson Technical HelpLine at 1-800-554-8466. <sup>\*</sup> Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



# Metric **Product** Matrix AccuSlide\* **Belt Actuated Systems 2HE** Page 274 Turbo Module\* **Belt Actuated Systems** 2GE

Page 279

Page 241

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



# **Product Selector**



# MicroStage\* Actuated Linear Motion Systems for lightly loaded, smooth travel applications

The MicroStage system incorporates a unique bearing segment design that offers smooth anti-friction linear motion in a very compact envelope for applications where high precision in a tight space are absolute requirements. The lead screw actuated stage is available in two different nominal sizes of 25mm and 33mm overall carriage mounting surface height. The lead screw is offered in both inch and metric dimensions with leads ranging from .025 inches to 1.2 inches and 1mm to 3mm. The slide is standard with a motor coupling and motor adapter block. The motor mounting arrangements are to recognized industry standards or custom stepper or servo motors can be configured to meet your needs. A standardized bolt hole pattern in the base assembly and on the carriage top as well as T-slots on the size 33 system allow for easy interchange and simple X-Y mounting. A range of standard overall lengths for each size stage is offered, while custom lengths can be accommodated. (Refer to page 245).



### AccuSlide<sup>\*</sup> Ball Screw Actuated Systems for high load, tight precision continuously supported applications

AccuSlide Ball Screw Actuated Systems are continuously supported linear motion systems complete with pre-aligned ProfileRail\* linear guides and an integral ball screw assembly. The load bearing members on the AccuSlide system are the AccuGlide\* linear guides which provide high precision, tight tolerance positioning on a modular base assembly with T-slot mounting. A uniquely designed carriage provides a bolt hole mounting pattern on pedestal table mounts which allow for an optional shroud cover that protects the moving elements from contamination with no stroke reduction and provides easy workpiece mounting. Integral ball screw assemblies are available in a wide range of diameters and leads for the most stringent motion control requirements. The motor end block is designed for industry standard servo motors to adapt directly to the system with only the use of a shaft coupling. Once the AccuSlide system has been selected, simply specify a standard Thomson AXI-PAK\* motion control package for a complete turnkey motion control solution. (Refer to page 260).



### AccuSlide Belt Driven Systems for high load, high speed continuously supported applications

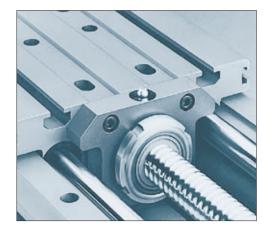
AccuSlide Belt Driven Systems are continuously supported linear motion systems complete with pre-aligned ProfileRail linear guides and an integral belt drive assembly. The load bearing members on the AccuSlide system are the AccuGlide linear guides which provide high precision, tight tolerance positioning on a modular base assembly with T-slot mounting. A uniquely designed carriage provides a bolt hole mounting pattern on pedestal table mounts which allow for an optional shroud cover that protects the moving elements from contamination with no stroke reduction and provides easy workpiece mounting. A Thomson Micron NemaTRUE\* Planetary\* gearhead provides speed reduction, torque multiplication and inertia matching and mounts directly to industry standard servo motors. Once the AccuSlide system has been selected, simply specify a standard Thomson AXI-PAK motion control package for a complete turnkey motion control solution. (Refer to page 274).

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



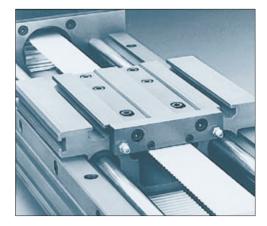


# **Product Selector**



# SuperSlide\* Ball Screw Actuated Systems for End and Continuously Supported Applications

SuperSlide Ball Screw Actuated Systems are available in an end and continuously supported version complete with prealigned LinearRace\* ways and an integral ball screw assembly. Uniquely designed carriages and LinearRace assemblies offer modularity with integrated T-slots for easy assembly and work piece mounting. All SuperSlide Ball Screw Actuated Systems can be mounted in any direction and are standard with Super Smart Ball Bushing\* bearings which provide up to 216 times the travel life of conventional linear bearing based systems. A uniquely designed lubrication system is available for all SuperSlide systems which disperses the proper amount of lubrication to the system. Integral ball screw assemblies are available in a wide range of diameters and leads and are designed to meet the most stringent motion control requirements. Once the SuperSlide system has been selected simply specify a standard Axi-Pak\* Motion Control package and your motion control needs are complete. (Refer to page 262).



# SuperSlide Belt Actuated Systems for End and Continuously Supported Applications

This belt drive system is available with uniquely designed carriages and LinearRace assemblies which offer modularity with integral T-slots for easy assembly and work piece mounting. The steel cable reinforced tooth belt provides high speed and acceleration combined with good positioning accuracy and repeatability. All SuperSlide Belt Actuated Systems offer the Super Smart Ball Bushing bearings which provide up to six times the load capacity of conventional linear bearing based systems. An anodized coating, double acting integral wipers combined with a uniquely designed lubrication system maximizes system reliability. A standard precision gearhead provides needed inertia matching and torque multiplication. The gearheads True Planetary\* design provides thrust capacity up to 1400 Nm at speeds as high as 4000 RPM. To specify all that is required is the system diameter and length. Once the SuperSlide Belt Actuated system has been selected, simply specify the standard Axi-Pak Motion Control package that meets your application needs. (Refer to page 276).

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





# **Product Selector**



### Turbo Module\* Belt Drive System

The Thomson Turbo Module combines the high load capacity of ProfileRail\* Linear bearing systems with high speed belt actuation. The Turbo Module is designed to meet the most stringent motion control requirements. The steel cable reinforced toothed belt in the Turbo Module provides rapid motion control with quick responsiveness and high acceleration. All Turbo Modules are designed with T-slots on the carriage top for easy mounting of the workpiece. T-slots down three sides of the Turbo Module allow for easy system mounting as well as multi-axis capability. Each Turbo Module is designed using the new advanced Thomson ProfileRail\* Linear bearing technology. Compared to other belt driven systems, the Turbo Module provides a dramatic increase in dynamic load capacity, moment loading and travel life. For maximum system performance, the Turbo Module comes standard with a precision gearhead. This True Planetary designed gearhead provides strong torgue multiplication and inertia matching capabilities that are commonly required in belt drive applications. Available in sizes 15, 25 and 35 with load capacities up to 60 kN. Available from over 1800 authorized distributor locations worldwide. (Refer to page 279).



#### Accessories Radial Mount, Protective Bellows and Brake Options

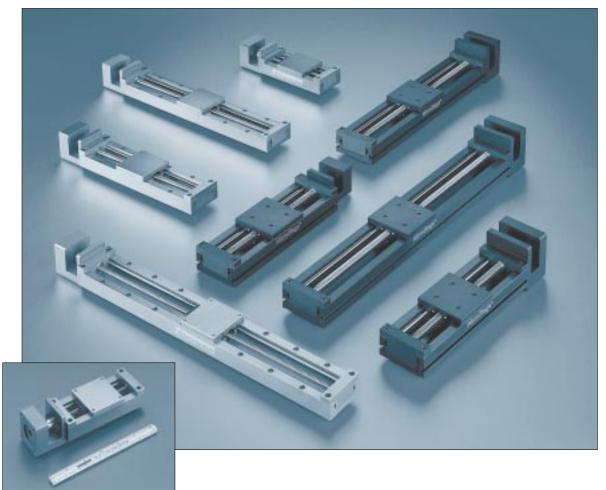
The uniquely designed Radial Mount Ball screw shaft extender consists of an oversized shaft, a heavy duty radial bearing, a housing with a standard NEMA mounting face and an easy to mount coupling. The Radial Mount provides a dramatic increase in side or cantilever load capacity. All Protective Bellows are manufactured from a durable polyurethane coated polyester material which will protect your Linear Motion System from most contaminants or corrosive environments. The flexible convoluted folding construction reinforced with bonded integral stiffeners minimizes the reduction in system stroke length. Compact design eliminates work surface interference and assures uninterrupted movement of the carriage during operation. Brake Options are available in three versions. QuickSlide\* 2DA Manual Brake System allows the system carriage to have infinite fixed positioning capability. The Electric Brake is used with all SuperSlide Systems and Ball Screw Assemblies. The Electric Brake is designed to engage when power is lost. The Electric Brake can be equipped with a controller option that interfaces directly with a PLC, switch, relay, computer, or controller output. Available from over 1800 authorized distributor locations worldwide. (Refer to page 287).

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





### Thomson MicroStage\* Actuated Linear Motion Systems



### Features:

- Smooth Precision Linear Motion Incorporates a unique bearing segment design and offers a backlash-free slide assembly without sacrificing load capacity or smoothness.
- Rugged, But Lightweight Construction It is manufactured from aluminum alloys to provide the optimum in strength and rigidity, and to dramatically decrease the mass of the system. This unique design provides for lower inertia and higher performance versus either built-in, or external actuators.
- Flexible Mounting Configuration MicroStage linear guides offer hole patterns and T-slots for easy interchange and simple X-Y mounting.
- Drive Options

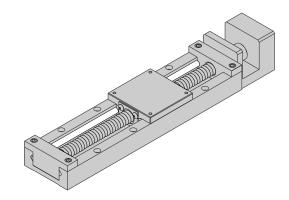
A wide range of leads are available for the lead screw driven MicroStage Linear Motion System. MicroStage Systems are readily adaptable to most industry standard air cylinders and micrometer movement devices. A variety of motor control options are also available from Thomson.

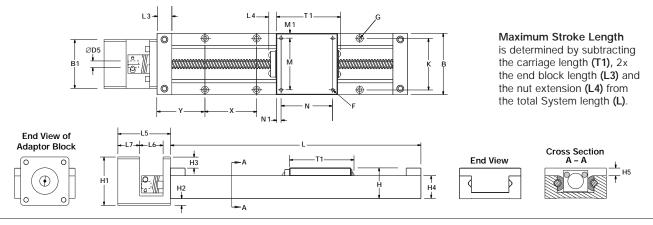
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



Page 245

# Thomson MicroStage\* MS25 **Actuated Linear Motion System**





MicroStage MS2	MicroStage MS25 Lead Screw Actuated Linear Motion System (Dimensions in mn												
Part Number	В	B1	D5	F	G	Н	H1	H2	H3	H4	H5	К	L3
MS25-LXA-LXXX	50	32,0	3,0	M3 x 0,5	M3 Screw	25	22,0	3,25	0,45	18,6	6	42	12
MS25-LXB-LXXX	50	39,9	6,35	M3 x 0,5	M3 Screw	25	39,9	5,7†	9,4	18,6	6	42	12

MicroStage MS2	MicroStage MS25 Lead Screw Actuated Linear Motion System (Dimensions in m													
Part Number	L4	L5	L6	L7	Ν	N1	М	M1	T1	Base Mou X	nting Hole Y	Load Capacity		
MS25-LXA-LXXX	12	27,75	18,75	3,0	42	4	42	4	52,5	42	39	100N		
MS25-LXB-LXXX	12	43,25	19,25	18,0	42	4	42	4	52,5	42	39	100N		

MS25-LJX-LXXX

3mm

0,250"

0,250"

0,250"

0,250"

0,250"

0,250"

0,250"

0,250"

0,250"

MicroStage MS2	5 System			]	MicroStage MS2	5 System
Part	Length	Stroke	Weight	]	Part	Screw
Number	(L) (mm)	(mm)	(kg)		Number	Lead
MS25-LXA-L120	120	31,5	0,42		MS25-LAX-LXXX	0,025"
MS25-LXA-L204	204	115,5	0,56		MS25-LBX-LXXX	0,050"
MS25-LXA-L288	288	199,5	0,71		MS25-LCX-LXXX	0,062"
MS25-LXA-L372	372	283,5	0,86		MS25-LDX-LXXX	0,200"
MS25-LXB-L120	120	31,5	0,45		MS25-LEX-LXXX	0,250"
MS25-LXB-L204	204	115,5	0,60		MS25-LFX-LXXX	0,500"
MS25-LXB-L288	288	199,5	0,75		MS25-LGX-LXXX	1,000"
MS25-LXB-L372	372	283,5	0,89		MS25-LHX-LXXX	1,5mm
				-	MS25-LIX-LXXX	2mm

mounting surface of the System Rail Assembly. Screw Diameter 0,250"

<sup>†</sup> Adaptor Block extends below the

Specifying a Thomson Linear Motion System:

1. Determine the proper system for your load and life requirements.

2. Select the part number.

3. Place your order with your local authorized Thomson distributor.

Part Numbering System



and Delivery Information	Custom Lengths ar
--------------------------	-------------------

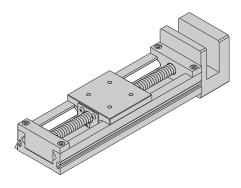
Systems ordered in standard lengths are typically shipped in one week. For special requirements, please contact the Thomson Systems Application Engineering Department.

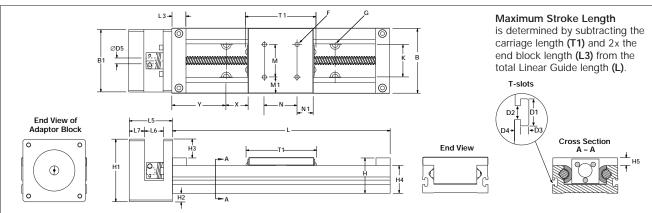
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





### Thomson MicroStage\* MS33 Actuated Linear Motion System





MicroStage MS3	3 Leac	Screv	v Actua	ated Li	near N	lotion	System	า				(D	Dimensi	ons in	mm)
Part Number	В	B1	D1	D2	D3	D4	D5	F	G	Н	H1	H2	H3	H4	H5
MS33-LXA-LXXX	60	39,9	8,0	4,2	2,75	2	6,35	M5 x 0,8	M5 Screw	33	39,9	1,05	8,45	25,5	7
MS33-LXB-LXXX	60	57,66	8,0	4,2	2,75	2	6,35	M5 x 0,8	M5 Screw	33	57,66	7,83⁺	17,33	25,5	7

MicroStage MS33 Lead Screw Actuated Linear Motion System (Dimensions in mm)											s in mm)		
Part	К	L3	L5	L6	L7	N	N1	Μ	M1	T1	Base Mour	nting Hole	Load
Number											Х	Y	Capacity
MS33-LXA-LXXX	30	13	43,25	19,25	18,0	30	15	30	15	65	100	50	150N
MS33-LXB-LXXX	30	13	39,75	17,75	14,0	30	15	30	15	65	100	50	150N

MicroStage MS33 System								
Part Number	Length (L) (mm)	Stroke (mm)	Weight (kg)					
MS33-LXA-L200	200	100	0,95					
MS33-LXA-L300	300	200	1,25					
MS33-LXA-L400	400	300	1,56					
MS33-LXB-L200	200	100	1,07					
MS33-LXB-L300	300	200	1,37					
MS33-LXB-L400	400	300	1,68					

	MicroStage MS33 System											
	Part	Screw	Screw									
	Number	Lead	Diameter									
	MS33-LAX-LXXX	0,0625"	0,375"									
	MS33-LBX-LXXX	0,100"	0,375"									
	MS33-LCX-LXXX	0,125"	0,375"									
	MS33-LDX-LXXX	0,200"	0,375"									
	MS33-LEX-LXXX	0,250"	0,375"									
	MS33-LFX-LXXX	0,375"	0,375"									
	MS33-LGX-LXXX	0,500"	0,375"									
	MS33-LHX-LXXX	1,000"	0,375"									
1	MS33-LIX-LXXX	1,200"	0,375"									
	MS33-LJX-LXXX	2mm	0.375"									

<sup>†</sup> Adaptor Block extends below the mounting surface of the System Rail Assembly.

Specifying a Thomson Linear Motion System:

- 1. Determine the proper system for your load and life requirements.
- 2. Select the part number.

3. Place your order with your local authorized Thomson distributor.





Custom Lengths and Delivery Information

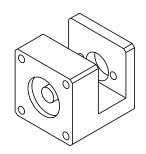
Systems ordered in standard lengths are typically shipped in one week. For special requirements, please contact the Thomson **Systems** Application Engineering Department.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

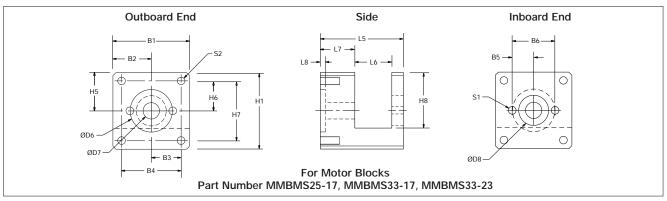




# MicroStage\* Actuated Linear Motion System Accessories

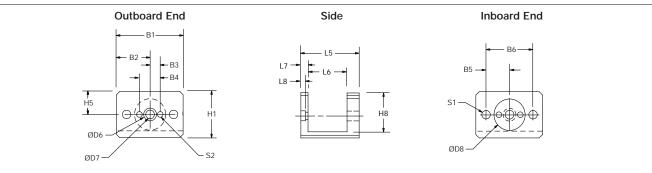


### Motor Mount Block with Four Bolt Hole Pattern



### Motor Mount Block with Two Bolt Hole Pattern





### For Motor Blocks Part Number MMBMS25-22 Only

Motor Mount Blocks (Dimensions in mm)																						
Part Number	B1	B2	B3	B4	B5	B6	ØD6	ØD7	ØD8	H1	H5	H6	H7	H8	L5	L6	L7	L8	S1	S2	Used w/System L	1 5
MMBMS25-22	32	16	5	10	11,38	22,75	6,02	4,0	14,5	22	11	-	-	18,75	27,75	18,75	3,0	1,7	4,60	2,40	MS25-LXA-LXXX	MCMS25-22
MMBMS25-17	39,9	19,95	15,5	31	11,38	22,75	22,03	8,5	16,4	39,9	19,95	15,5	31	29	43,25	19,25	18,0	2,75	4,60	M4	MS25-LXB-LXXX	MCMS25-17
MIMBMS33-17	39,9	19,95	15,5	31	11,15	22,3	22,03	8,5	16,4	39,9	19,95	15,5	31	29	43,25	19,25	18,0	2,75	M4	M4	MS33-LXA-LXXX	MCMS33-17
MIMBMS33-23	57,7	28,83	23,57	47,14	11,15	22,3	38,18	8,5	16,4	57,7	28,83	23,57	47,14	38	39,75	17,75	14,0	4,0	M4	M4	MS33-LXB-LXXX	MCMS33-23

### **Motor Couplings**

	Motor Couplings		(Dimension	ns in mm)			
	Part Number	ØD9	ØD10	ØD11	L9	Used w/System	Used w/Motor Adaptor Block
	MCMS25-22	M5	3,0	12	19	MS25-LXA-LXXX	MMBMS25-22
	MCMS25-17	M5	6,35	15	22	MS25-LXB-LXXX	MMBMS25-17
	MCMS33-17	M5	6,35	15	22	MS33-LXA-LXXX	MMBMS33-17
► L9 - ►	MCMS33-23	M5	6,35	15	22	MS33-LXB-LXXX	MMBMS33-23

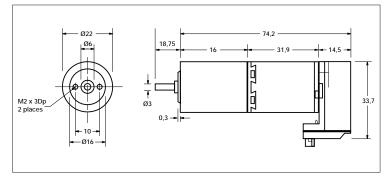
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





# Motors

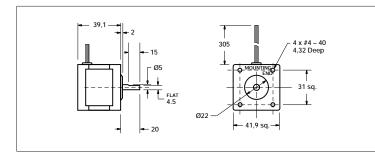
### 22mm DC Gearmotor



Parameter	Units	BRD22M715D10100
Rated Power <sup>†</sup>	Watts	3
Cont. Stall Torque <sup>†</sup>	mNm	29.2
No Load Speed <sup>†</sup>	rpm	1500
Resistance	ohm	13.6
Feedback	-	2 channel 100 line encoder
Gear Ratio	n:1	4.4

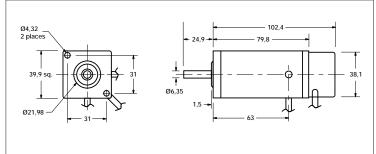
 $^{\scriptscriptstyle \dagger}$  At gear box output

### Size 17 Step Motor



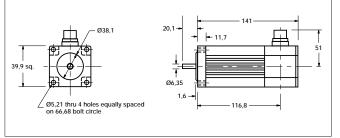
Parameter	Units	AMPHT17-071
Holding Torque	oz-in	36.1
Leads	-	8
Current	amp	1.2
Resistance	ohm	3.3

### Size 17 Brushless Servo Motor



Parameter	Units	BLD1715D10100
Rated Power	Watts	40
Cont. Stall Torque	Nm	0.20
Peak Torque	NM	0.55
Inertia	Kg-cm <sup>2</sup>	0.0275
Torque Const.	Nm/A	0.06
Voltage Const.	Vrms/krpm	6.47
Feedback	-	1000 line encoder & Halls

### NEMA 23 Brushless Servo Motor



Parameter	Units	BLX232A2E000	BLX234A2E000
Rated Power	Watts	160	360
Cont. Stall Torque	Nm	0.56	1.12
Peak Torque	NM	1.7	3.36
Inertia	Kg-cm <sup>2</sup>	0.109	.179
Torque Const.	Nm/A	0.204	0.204
Voltage Const.	Vrms/krpm	18.2	17.8
Feedback	-	2000 line commu	utating encoder

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. 'Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries. Systems, Slides, and Stages - Metric



### Systems Applications Application Analysis

Determining the system which best meets the demands of your application and provides optimum performance requires the evaluation of a number of variables. The accompanying form establishes basic criteria to initiate the analysis of your application. In addition, the Engineering Support Appendix has been designed with pertinent data and formulas used to specify the proper system for your application. If you have questions or special needs a Thomson systems engineer can assist you in evaluating your application and recommending a system solution.

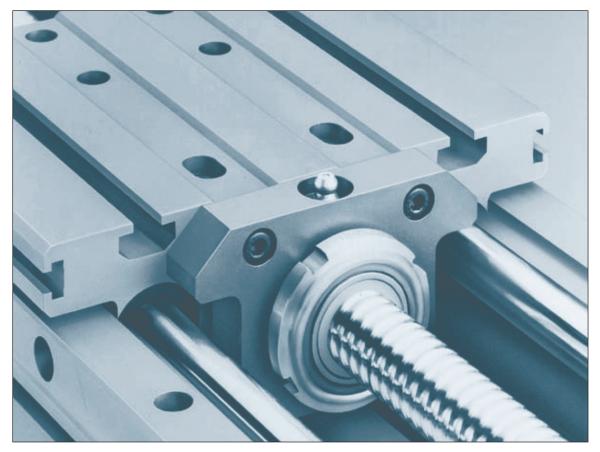
Simply call 1-800-554-8466.	5,	
Application Description:	Horizontal	Vertical
System Part Number:		
Quantity Required:		
Weight of Load (lbs):		
Space Requirements (LxHxW):		
Stroke Length Requirements (in):		
Support Requirements:	End Supported	Full Support
Maximum Velocity Requirements (in/s):		
Maximum Acceleration Requirements (in/s <sup>2</sup> ):		
Required Straightness of Travel Accuracy (in/ft):		
Required Positioning Accuracy (in):		
Required Repeatability (in):		
Life Requirement (in):		
Cycle (in/yr):		
Environmental Considerations:		
Other Design Criteria:		
Production Time Frame:		
Company:		
Name:		
Title:		
Address:		
_ City:	State:	Zip:
Telephone:	Fax:	

Please Fax your Application Analysis to 516-883-9039 Attention: Application Engineering





### SuperSlide Ball Screw Actuated Systems



# SuperSlide<sup>•</sup> Ball Screw Actuated Systems offer:

- An end supported and continuously supported version complete with prealigned LinearRace\* ways and an integral ball screw assembly. End Supported Systems are used when spanning or bridging a gap. Continuously Supported Systems are used when rigidity is required.
- Available with uniquely designed carriages and LinearRace assemblies with integrated T-slots for easy assembly and mounting.
- Positioning accuracy better than 0,01 mm with repeatability as low as 0,025 mm/ 300mm. Improvement in system performance is realized immediately.
- Available with integrated Super Smart Ball Bushing\* bearings which provide up to six times the load capacity or 216 times the travel life of conventional linear bearing based systems.

- Anodized coating, double acting integral wipers and bellows for protection in corrosive environments. A uniquely designed lubrication system option is available for all systems.
- A variety of highly efficient ball screw assemblies with diameters and leads designed to meet the most stringent motion control requirements.
- A single part number system. All that is required to order is to specify the system nominal size and length.
- Easy integration to the Thomson AXI-PAK\* motion control system. Once the Superslide system has been selected simply specify a standard Thomson Motion Control package that meets your complete motion control needs.

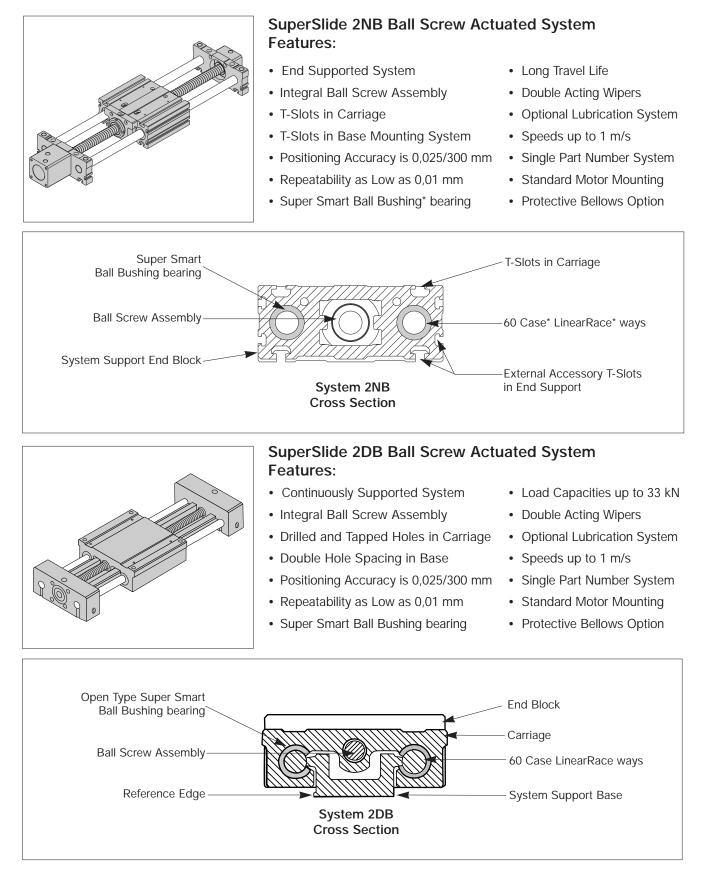
(See the Motion Control Section on page 381)

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





# SuperSlide\* Ball Screw Actuated Systems



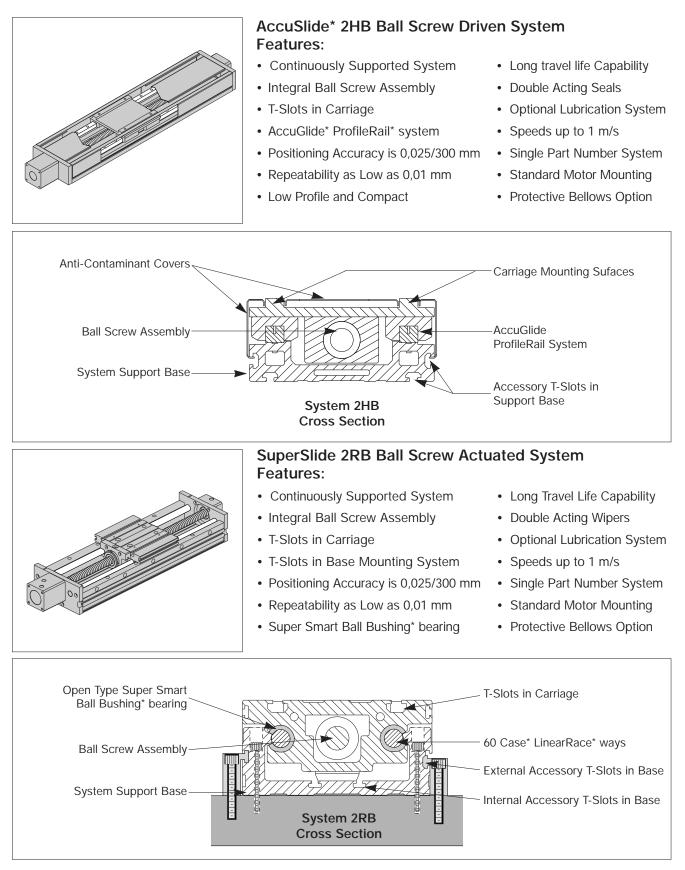
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

Systems, Slides, and Stages - Metric





# SuperSlide\* Ball Screw Actuated Systems



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



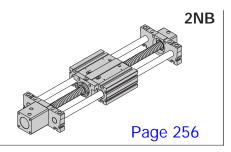
The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Page 253

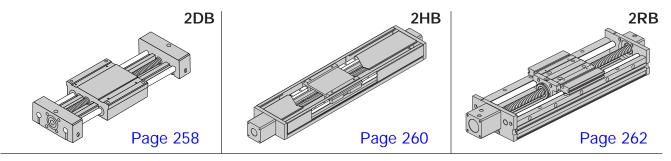
# SuperSlide Ball Screw Actuated Systems Solution Matrix

SuperSlide\* Ball Screw Actuated Systems

For End Supported Applications



### For Continuously Supported Applications



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





# SuperSlide\* Ball Screw Actuated Systems Selection Criteria

Many variables influence the selection of a Linear Motion System. The best solution demands a thorough evaluation of the application; only then can design criteria be established. Issues such as envelope limitations, system load capacity, actuator load capacity, speed and acceleration, drive requirements, accuracy and repeatability, and operating environment are looked at from a broad perspective to determine the type of system, type of actuator, and whether the system need be built of special materials.

Typically, a ball screw actuated linear motion system is ideal for tight precision, highly repeatable, high load, moderate speed applications. Long lead ball screws are available for most style systems, but it is important to be mindful of the critical speed (first harmonic of the resonant ball screw whirling vibration) in longer stroke systems when attempting to reach higher linear velocities. If an application requires rigidity, then a fully supported system should be specified in lieu of an end supported type system. When zero backlash is required for the best repeatability, then a preloaded version ball screw assembly need to be specified. For extremely heavy-duty applications, the AccuSlide\* (2HB series) system, with its use of ProfileRail\* type linear guides is adept at handling normal axis, overhung, or cantilever loads of increased magnitude. In environments that are corrosive or high temperature special materials may be required and are available. Contact Application Engineering for details on special materials.

In order to determine the Ball Screw Actuated SuperSlide System that meets the needs of your application, it is first necessary to evaluate the following detail design criteria:

- System support requirements
- System stroke length
- Maximum allowable shaft deflection
- Required travel life
- Force on the most heavily loaded bearing
- Load correction factor
- Load/Life requirements-linear bearings
- Load/Life requirements-ball screws
- Motion (move) profile (velocity, acceleration)
- Maximum acceptable travel rate
- Torque considerations
- Size motor using torque/speed curves

A detailed explanation of the procedure for selecting a Ball Screw Actuated Linear Motion System is given on page 327 in the Engineering Support Section.





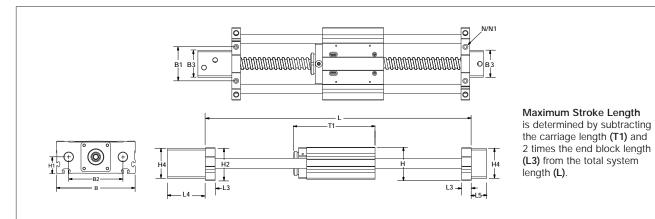
## SuperSlide<sup>\*</sup> 2NB End Supported System

with Integral Ball Screw Assembly and T-Slot Carriage

### **New...** Super Smart

Ball Bushing\* Bearing...

Now Available For All Sizes



SuperSlide 2NB	System	with Integra	al Ball Screv	v Assemb	y and T-Slo	ot Carriage	e		(Dimensio	ons in mm)
Part Number	Nominal Dia.	Ball Screw (Dia. x Lead)	Accuracy mm/300 mm	Repeatability	В	B1	B2	B3	B9	Max. Stroke Length
2NB-M16-OGL-G	16	16 x 5 P	0,025	± 0,005						L-(000)
2NB-M16-OGL-H	16	16 x 10 P	0,025	± 0,005						
2NB-M20-OGL-I	20	20 x 5 P	0,025	± 0,005	160	75	110	60	120	L-200
2NB-M20-OGL-J	20	20 x 10 P	0,025	± 0,005						
2NB-M20-OGL-K	20	20 x 20 P	0,025	± 0,005						

SuperSlide 2NB	System v	vith Integr	al Ball Sci	rew Asser	nbly and 1	-Slot Ca	rriage			(Dimensic	ns in mm)
Part Number	Н	H1	H2	H4	L3	L4	L5	N Bolt	N1 Hole	T1	NEMA SIZE
2NB-M16-OGL											
2NB-M20-OGL	66	34	65	60	20	75	31,5	M6	11,25	160	23

System 2NB	Star	ndar	d Le	engt	hs																				(Le	ngtł	ns in mm)
System	300	375	400	450	500	525	600	675	700	750	800	825	900	975	1000	1050	1100	1125	1200	1275	1300	1350	1400	1425	1500	Х	MAX
2NB-M16																										75	1500
2NB-M20																										100	2000

For Motion Control Options refer to the Motion Control Section on page 381.

For Motor Coupling specifications, see page 290.

For Bellows Way Covers, see page 291.

For Radial Mount Ball Screw Shaft Extenders, see page 292.

For Spring Set electric brakes, see page 304.

For TNUT mounting hardware, see page 308.

Custom Lengths and Delivery Information Systems ordered in standard lengths and longer lengths in increments of (X) are typically shipped in two to three weeks. Custom length systems are available and require three to four weeks for delivery. For special requirements, please contact the Thomson Systems application engineering department.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.





#### SuperSlide\* 2NB Benefits:

- Used in end supported applications when spanning or bridging a gap is required.
- Single part number is all that is required
- T-Slot in carriage provides quick and easy mounting and removal of the workpiece.

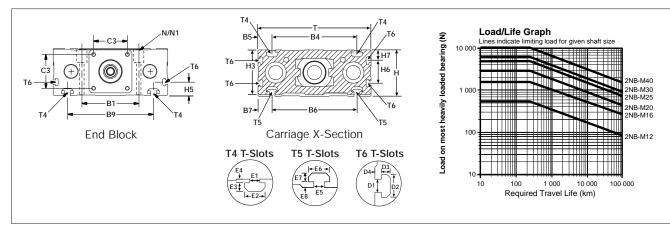
#### SuperSlide 2NB Components:

- 2 LinearRace\* End Support blocks with T-Slots for mounting ease.
- 1 T-Slot integrated carriage with 4 Super Smart open type Ball Bushing\* bearings.
- 1 Integral Ball Screw Assembly

Specifying a Thomson System: 1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number (choosing a standard length will reduce costs and speed delivery). 4.Place your order with your local authorized Thomson distributor. Part Numbering System

#### 2NB-M16-OGL-I L600





SuperSlide 2N	B System w	ith Integr	al Ball Sci	rew Asser	mbly and <sup>-</sup>	T-Slot Ca	rriage			(Dimensior	ns in mm)
Part Number	Nominal Diameter	B1	B4	B5	B6	B7	B9	D1	D2	D3	D4
2NB-M16-OGL	16										
2NB-M20-OGL	20	75	120	20	120	20	120	6	10,5	4	3

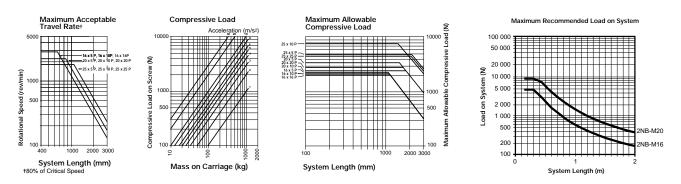
SuperSlide 2N	IB Syste	em with	Integra	I Ball Sc	rew Ass	sembly a	and T-SI	ot Carri	age			(Dim	nensions	in mm)
Part Number	E1	E2	E3	E4	E5	E6	E7	E8	Н	H3	H5	H6	H7	Т
2NB-M16-OGL														
2NB-M20-OGL	8,1	16,5	6,8	3	8,1	16,5	6,8	4,5	66	63,5	19	32	15	160

The SuperSlide has a pre-designed Maximum Acceptable Travel Rate. Calculate maximum rotational speed (rpm) by dividing your required maximum linear speed (m/s) by the corresponding system ball screw lead (m/rev). Enter the chart with the required system length and your maximum rotational speed. Select the system with a maximum acceptable travel rate curve above the plotted line.

Compressive load on the ball screw is a key factor in selecting the proper System. Using maximum load and acceleration requirements plot compressive load on the left side of the chart. Using System length and compressive load. plot the maximum allowable compressive force on the right chart. Select the System with a rated maximum compressive force above your plotted point

If you have questions concerning your system requirements, contact the Thomson Systems application engineering department

Note: Ball screw should never exceed recommended critical speed.



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





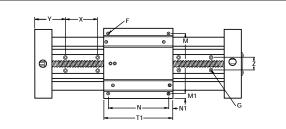
# SuperSlide<sup>\*</sup> 2DB Continuously Supported System

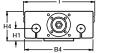
with Integral Ball Screw Assembly and Carriage

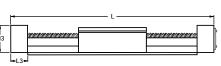
### New... Super Smart

### Ball Bushing\* Bearing...

Now Available For All Sizes







Maximum Stroke Length (without Bellows) is determined by subtracting the carriage length (T1) and 2x the end support length (L3) from the total system length.

SuperSlide 2DE	3 with Carriage a	nd Integra	al Ball Screv	N Asse	mbly						(Dimer	nsions ir	n mm)
Part Number	Ball Screw (Dia. x Lead)	Accuracy mm/300 mm	Repeatability	T1	L3	Η	H1	H2	H3	H4	В	R	Т
2DB-12-OUK-B	12 x 5 NP	<0,05	<0,05	150	38	54	28,6	49,0	60,3	66,4	66,8	17,5	155
2DB-16-OUK-D	20 x 5 NP	<0,05	<0,05	190	50	66	34,9	61,3	85,7	88,9	82,5	22,3	193

SuperSlide 2DI	B with C	arriage	and Inte	gral Ball	Screw /	Assembl	у				(D	imensions in mm)
Part Number	B2	B4	N	N1	Μ	M1	Х	Y	Z	F	G	Max. Stroke Length Without Bellows
2DB-12-OUK-B	101,6	152	130	10	135	10	150	75	25	M6	M8	L-(226)
2DB-16-OUK-D	127	178	170	10	175	9	200	100	30	M8	M10	L-(292)

For Motion Control Options refer to the Motion Control Section on page 381.

For Motor Adaptor and Motor Coupling specifications, see page 288.

For Bellows Way Covers, see page 291.

For Radial Mount Ball Screw Shaft Extenders, see page 292.

For Spring Set electric brakes, see page 304.

For Handwheels, see page 308.

SuperSli	de Sy	stem	2DB	Stan	dard	Lengt	hs			(L	ength	s in	mm)
System	450	600	750	800	900	1000	1050	1200	1400	1600	1800	Х	MAX
2DB-12												150	1200
2DB-16												200	2000

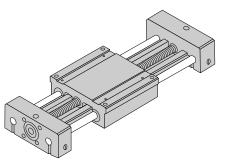
#### Custom Lengths and Delivery Information

Systems ordered in standard lengths and longer lengths in increments of (X) are typically shipped in three to four weeks. Custom length systems are available and require four to six weeks for delivery. For special requirements, please contact the Thomson **Systems** application engineering department.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.







#### SuperSlide\* 2DB Benefits:

- Used in continuously supported applications when stiffness and rigidity is required.
- Pre-aligned and preassembled for immediate installation and use.
- Designed for medium to heavy loads.
- Compact and low profile

#### SuperSlide 2DB Components:

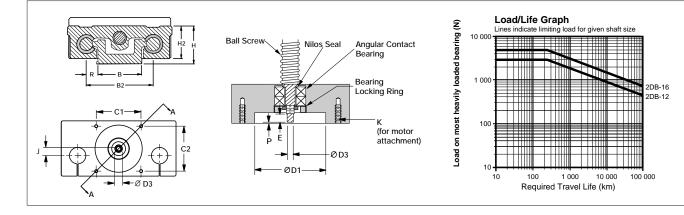
- 1 Dual LinearRace\* Rail Assembly
- 1 modular carriage with 4 open type Super Smart Ball Bushing\* Pillow blocks.
- 1 integrated ball screw assembly

#### Specifying a Thomson System:

 Determine the proper system for your load and life requirements.
 Select the part number.
 Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number (choosing a standard length will reduce costs and speed delivery).
 Place your order with your local authorized Thomson distributor.
 Part Numbering System

#### t Numbering System 2DB-12-OUK-B L600

System \_\_\_\_\_\_ L \_\_\_ L \_\_\_ L \_\_\_ L \_\_\_ System Length Designation \_\_\_\_\_\_ Ball Screw Nominal Diameter \_\_\_\_\_ Type of Carriage Type of Bearing Block \_\_\_\_\_ Type of Support

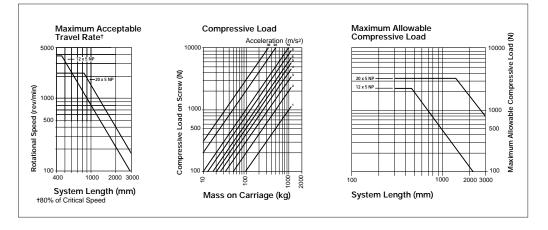


SuperSlide 2D	B with Carria	ge and Integr	al Ball Screw	Assembly			(Dimen	isions in mm)
Part Number	C1	C2	D1	D3	E	J	К	Р
2DB-12-OUK-B	47,1	47,1	54,61	6	8,5	7,62	M5 x 0,8	1,3
2DB-16-OUK-D	69,6	69,6	73,05	10	14,2	10,80	M5 x 0,8	1,3

Maximum continuous length of 2DB LinearRace support rails is 600 mm. If longer continuous one-piece LinearRace support rails are required, contact the Thomson Systems Application Engineering Department.

The SuperSlide has a pre-designed Maximum Acceptable Travel Rate. Calculate maximum rotational speed (rpm) by dividing your required maximum linear speed (m/s) by the corresponding system ball screw lead (m/rev). Enter the chart with the required system length and your maximum rotational speed. Select the system with a maximum acceptable travel rate curve above the plotted line. Compressive load on the ball screw is a key factor in selecting the proper System. Using maximum load and acceleration requirements, plot compressive load on the left side of the chart. Using System length and compressive load. plot the maximum allowable compressive force on the right chart. Select the System with a rated maximum compressive force above your plotted point. If you have questions concerning your system requirements, contact the Thomson **Systems** application engineering department.

Note: Ball screw should never exceed recommended critical speed.



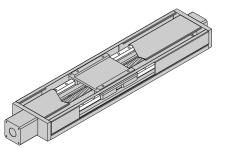
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

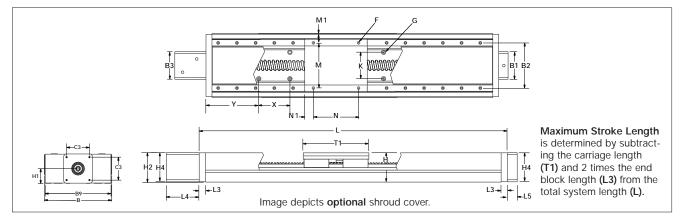




### AccuSlide<sup>\*</sup> 2HB Continuously Supported ProfileRail<sup>\*</sup> System with Integral Ball Screw Assembly

with Integral Ball Screw Assembly and Carriage





Metric AccuS	lide 2HB P	rofileRail	System wit	th Integ	ral Ball	Screw A	ssembl	y and C	arriage		(Dir	nensions	in mm)
Part	Ball	Accuracy	Repeatability	В	B1	B2	B3	B9	C3	F	G	Н	H1
Number	Screw	mm/300mm											
	(Dia. x Lead)												
2HBM10OYPG	16 x 5 P	0,025	± 0,005	100	60	70	60	105	47,15	M5	M5	60	31
2HBM10OYPH	16 x 10 P	0,025	± 0,005										
2HBM20OYPL	25 x 5 P	0,025	± 0,005	200	88	145	88	205	69,6	M10	M8	90	45
2HBM20OYPM	25 x 10 P	0,025	± 0,005										
2HBM20OYPN	25 x 25 P	0,025	± 0,005										

Metric Accu	Slide 2	2HB Pro	ofileRail	Systen	n with Ir	ntegral I	Ball Scr	ew Ass	embly a	nd Cari	riage		(Dime	ensions in mm)
Part Number	H2	H4	K Central	Μ	M1	N	N1	L3	L4	L5	T1	Х	Y	Max. Stroke Length Without Bellows
2HB-M10	61	60	35	70	15	70	15	12,5	70	26,5	100	75	37,5	L-125
2HB-M20	89	88	85	145	27,5	145	27,5	20	105	40	200	120	42,5	L-240

Metric System	n 2H	B Sta	ndar	d Ler	ngths														(	Lengtl	hs in	mm)
System	300	325	375	450	445	525	565	600	675	685	750	825	805	900	925	975	1045	1165	1285	1405	Х	MAX
2HB-M10																					75	1000
2HB-M20																					120	3000

For Motion Control Options refer to the Motion Control Section on page 381.

For Motor Coupling specifications, see page 290.

For Bellows Way Covers, see page 291.

For Shroud Covers, see pages 302 and 303.

For Limit Switch Packages, see pages 296 and 298. For Radial Mount Ball Screw Shaft extenders, see page 292.

For Spring Set electric brakes, see page 304.

For TNUT mounting hardware, see page 308.

For TNOT mounting hardware, see page 308

**Custom Lengths and Delivery Information** Systems ordered in standard lengths and longer lengths in increments of (X) are typically shipped in three to four weeks. Custom length systems are available and require four to six weeks for delivery. Lengths exceeding MAX length will require butt joints and will need 6 to 8 weeks for delivery. For special requirements, please contact the Thomson **Systems** application engineering department.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.

Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries



### AccuSlide\* 2HB Benefits:

- Used in continuously supported applications that require high stiffness and rigidity.
- Single part number is all that is required
- Equipped with high load and moment capacity AccuGlide\* ProfileRail\* System.

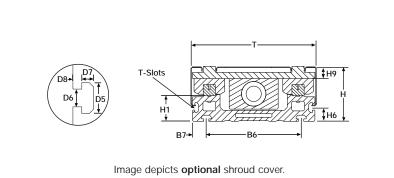
### AccuSlide 2HB Components:

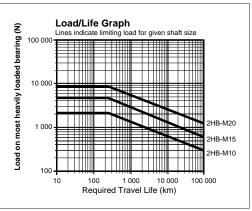
- 1 double ProfileRail System Assembly.
- 1 carriage with 4 mounting holes
- 1 Integral Ball Screw Assembly

#### Specifying a Thomson System: 1. Determine the proper system for your load and life

 Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in illimeters, as a suffix to the part number (choosing a standard length will reduce costs and speed delivery). 4.Place your order with your local authorized Thomson distributor.
 Part Numbering System





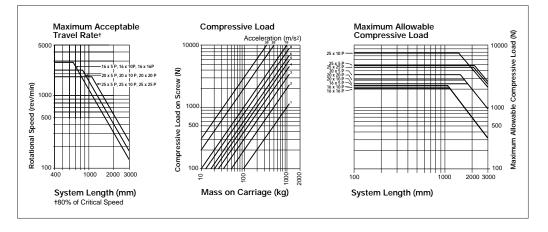


Metric AccuSI	Metric AccuSlide 2HB ProfileRail System with Integral Ball Screw Assembly and Carriage         (Dimensions in mm)														
Part Number	Nominal Diameter	D5	D6	D7	D8	B6	B7	Н	H1	H6	H9	Т			
2HB-M10	10	10,5	6	3	2,5	70	15	60	31	15	13	100			
2HB-M20	20	16,5	8,1	6	4	155	22,5	90	45	22,5	20	200			

Appropriate mounting holes can be added for mounting the base of one system to the carriage of another for x-y configurations.

The AccuSlide has a pre-designed Maximum Acceptable Travel Rate. Calculate maximum rotational speed (rpm) by dividing your required maximum linear speed (m/s) by the corresponding system ball screw lead (m/rev). Enter the chart with the required system length and your maximum rotational speed. Select the system with a maximum acceptable travel rate curve above the plotted line. Compressive load on the ball screw is a key factor in selecting the proper System. Using maximum load and acceleration requirements, plot compressive load on the left side of the chart. Using System length and compressive load, plot the maximum allowable compressive force on the right chart. Select the System with a rated maximum compressive force above your plotted point. If you have questions concerning your system requirements, contact the Thomson **Systems** application engineering department.

Note: Ball screw should never exceed recommended critical speed.



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.







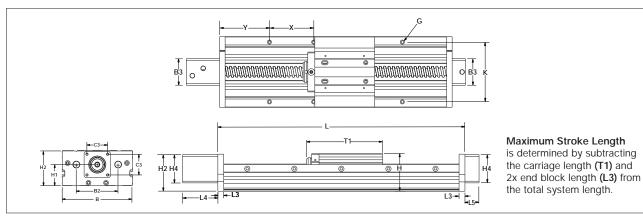
## SuperSlide<sup>\*</sup> 2RB Continuously Supported System

with Integral Ball Screw Assembly and T-Slot Carriage

### New... Super Smart

### Ball Bushing\* Bearing...

Now Available For All Sizes



SuperSlide 2RB	uperSlide 2RB System with Integral Ball Screw Assembly and T-Slot Carriage (Dimensions in mm)														
Part	Nominal	Ball	Accuracy	Repeatability	В	B2	B3	C3	G	H1					
Number	Dia.	Screw	mm/300 mm												
		(Dia. x Lead)													
2RB-M12-ODM-G	12	16x 5 P	0,025	± 0,005	130	75	60	47,15	M4	40					
2RB-M12-ODM-H	12	16x 10 P	0,025	± 0,005											
2RB-M16-ODM-I	16	20 x 5 P	0,025	± 0,005	160	95	60	47,15	M5	48					
2RB-M16-ODM-J	16	20 x 10 P	0,025	± 0,005											
2RB-M16-ODM-K	16	20 x 20 P	0,025	± 0,005											
2RB-M20-ODM	20														

SuperSlide 2RB	System wi	th Integral	Ball Screw	Assembly	and T-Slot	Carriage			(Dimension	ns in mm)	
Part Number	H2	H4	К	L3	L4	L5	T1	Base Mou	Base Mounting Holes		
								Х	Y	Stroke Length	
2RB-M12-ODM	75	60	110	9,5	70	26,5	130	75	75	L-149	
2RB-M16-ODM	79	60	135	12,5	75	31,5	160	100	100	L-185	
2RB-M20-ODM										L-(000)	

System 2RB	System 2RB Standard Lengths (Lengths in mm)														s in mm)												
System	300	375	400	450	500	525	600	675	700	750	800	825	900	975	1000	1050	1100	1125	1200	1275	1300	1350	1400	1425	1500	Х	MAX
2RB-M12																										75	2100
2RB-M16																										100	3000

For Motion Control Options refer to the Motion Control Section on page 381.

For Motor Coupling specifications, see page 290.

For Bellows Way Covers, see page 291.

For Limit Switch Packages, see pages 300-301.

For Radial Mount Ball Screw Shaft Extenders, see page 292.

For Spring Set electric brakes, see page 304.

For TNUT mounting hardware, see page 308.

Custom Lengths and Delivery Information

Systems ordered in standard lengths and longer lengths in increments of (X) are typically shipped in two to three weeks. Custom length systems are available and require three to four weeks for delivery. Lengths exceeding MAX length will require butt joints and will need 4 to 6 weeks for delivery. For special requirements, please contact the Thomson **Systems** application engineering department.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.





#### SuperSlide\* 2RB Benefits:

- Used in continuously supported applications when stiffness and rigidity is required.
- Single part number is all that is required
- T-Slot in carriage provides quick and easy mounting and removal of the workpiece.

#### SuperSlide 2RB Components:

- 1 double LinearRace\* Rail Assembly with T-Slots for mounting ease.
- 1 T-Slot integrated carriage with 4 open type Super Smart Ball Bushing\* bearings.
- 1 Integral Ball Screw Assembly

Specifying a Thomson System: 1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number (choosing a standard length will reduce costs and speed delivery). 4.Place your order with your local authorized Thomson distributor. Part Numbering System

#### 2RB-M16-ODM-I L600



10 000

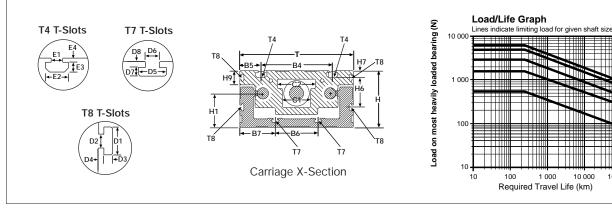
1 0 0 0

2RB-M30

2RB-M25 2RB-M20 2RB-M16

2RB-M12

100 000



SuperSlide 2R	B System w	vith Integr	al Ball Scr	ew Asser	nbly and <sup>-</sup>	T-Slot Ca	rriage			(Dimensior	is in mm)
Part Number	Nominal Diameter	B4	B5	B6	B7	D1	D2	D3	D4	D5	D6
2RB-M12-ODM	12	75	27,5	65	32,5	8,0	4,2	2,75	2	8,0	4,2
2RB-M16-ODM	16	100	30	80	40	10,5	6	3,5	2,5	10,5	6
2RB-M20-ODM	20										

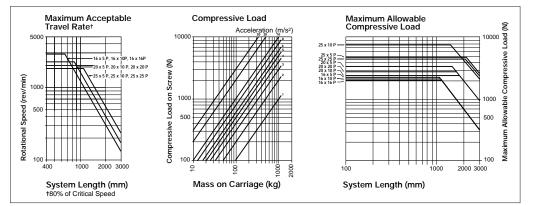
SuperSlide 2R	B Systen	n with Int	egral Bal	Screw A	ssembly	and T-Slo	ot Carria	ge		([	Dimension	s in mm)
Part Number	D7	D8	E1	E2	E3	E4	Н	H1	H6	H7	H9	Т
2RB-M12-ODM	2,75	2	7,5	13	4	3	65	40	35	7	14	130
2RB-M16-ODM	3,5	2,5	8,1	16,5	6,8	3	80	48	41,5	10	20	160
2RB-M20-ODM												

The SuperSlide has a pre-designed Maximum Acceptable Travel Rate. Calculate maximum rotational speed (rpm) by dividing your required maximum linear speed (m/s) by the corresponding system ball screw lead (m/rev). Enter the chart with the required system length and your maximum rotational speed. Select the system with a maximum acceptable travel rate curve above the plotted line.

Compressive load on the ball screw is a key factor in selecting the proper System. Using maximum load and acceleration requirements, plot compressive load on the left side of the chart.Using System length and compressive load. plot the maximum allowable compressive force on the right chart. Select the System with a rated maximum compressive force above your plotted point.

If you have questions concerning your system requirements, contact the Thomson Systems application engineering department

Note: Ball screw should never exceed recommended critical speed.



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





Systems Applications
Application
Analysis

Determining the system which best meets the demands of your application and provides optimum performance requires the evaluation of a number of variables. The accompanying form establishes basic criteria to initiate the analysis of your application. In addition, the Engineering Support Appendix has been designed with pertinent data and formulas used to specify the proper system for your application. If you have questions or special needs a Thomson systems engineer can assist you in evaluating your application and recommending a system solution.

Simply call 1-800-554-8466.	g a sjotern s	
Application Description:	Horizontal	Vertical
System Part Number:		
Quantity Required		
Weight of Load (N):		
Space Requirements (LxHxW):		
Stroke Length Requirements (mm):		
Support Requirements:	End Supported	Full Support
Maximum Velocity Requirements (m/s):		

Maximum Acceleration Requirements (m/s<sup>2</sup>):

Required Straightness of Travel Accuracy (µm/m):

Required Positioning Accuracy (µm):

Required Repeatability (µm):

Life Requirement (km):	
Cycle (km/yr):	

Environmental Considerations:

Other Design Criteria:

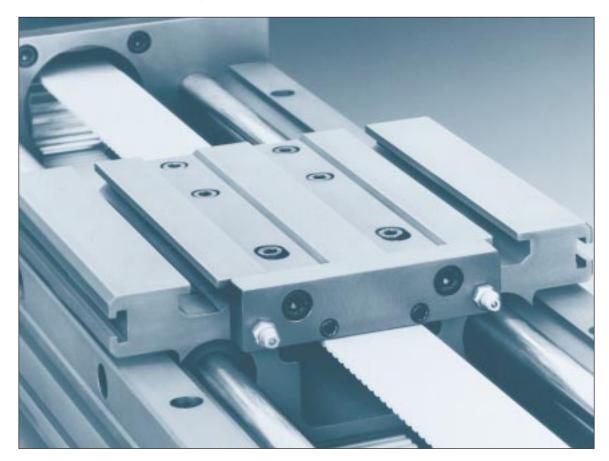
Production Time Frame:		
Company:		
Name:		
Title:		
Address:		
City:	State:	Zip:
Telephone:	Fax:	

Please Fax your Application Analysis to 516-883-9039 Attention: Application Engineering





# SuperSlide Belt Actuated Systems



# SuperSlide<sup>•</sup> Belt Actuated Systems offer:

- An end supported and continuously supported version complete with prealigned LinearRace\* ways and an integral belt drive assembly. End Supported Systems are used when spanning or bridging a gap. While Continuously Supported Systems are used when rigidity is required.
- Available with uniquely designed carriages and LinearRace assemblies with integrated T-slots for easy assembly and mounting.
- High speed and acceleration with positioning accuracy better than 0,2 mm/ 300 mm and repeatability within 0,10 mm. Improvement in system performance is realized immediately.
- Available with integrated Super Smart Ball Bushing\* bearings which provide up to six times the load capacity or 216 times the travel life of conventional linear bearing based systems.

- Anodized coating, double acting integral wipers and bellows for protection in corrosive environments. A uniquely designed lubrication system option is available for all systems.
- A precision gearhead for matching the inertia between the belt drive system payload and the servo motor. The True Planetary\* gearhead design provides torque capacity up to 28 N-m at speeds as high as 4000 rpm.
- A single part number system. All that is required to order is to specify the system nominal size and length.
- Easy adaptation to the Thomson AXI-PAK\* Motion Control system. Once the Superslide Belt Drive system has been selected simply specify a standard Thomson Motion Control package that meets your complete motion control needs.

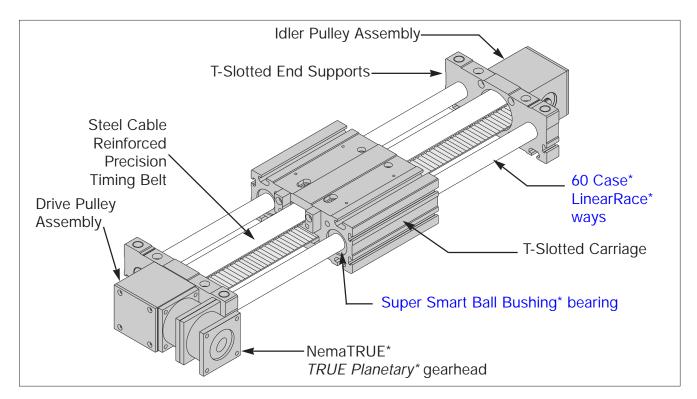
(See the Motion Control section on page 381)

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





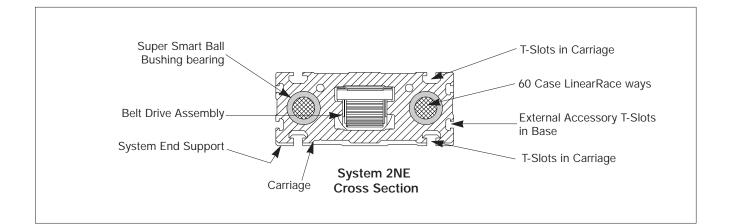
# SuperSlide\* 2NE Belt Actuated System



### SuperSlide 2NE End Supported Belt Actuated System Features:

- End Supported System
- Precision Steel Reinforced Timing Belt
- T-Slots in Carriage
- T-Slots in Base Mounting System
- Positioning Accuracy less than 0,2 mm/300 mm
- Long Travel Life
- Super Smart Ball Bushing bearings

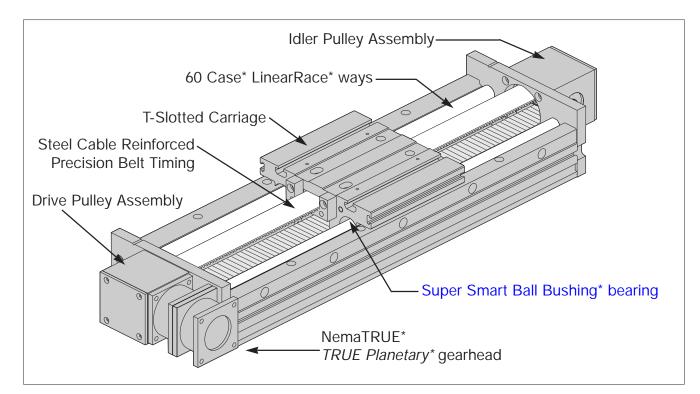
- Integral Precision Gearhead
- Double Acting Seals
- Optional Lubrication System
- Speeds in excess of 3 m/s
- Single Part Number System
- Standard NEMA Motor Mounting
- Protective Bellows Option



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



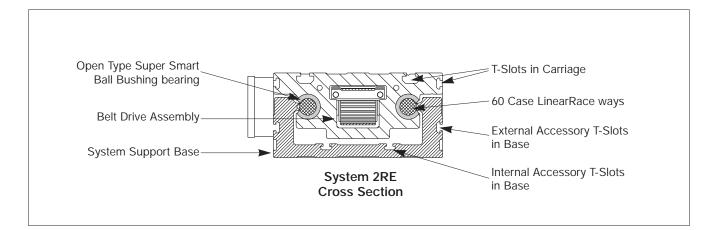
# SuperSlide\* 2RE Belt Actuated System



### SuperSlide 2RE Belt Actuated System Features:

- Continuously Supported System
- Precision Steel Reinforced Timing Belt
- T-Slots in Carriage
- T-Slots in Base Mounting System
- Positioning Accuracy less than 0,2 mm/300 mm
- Long Travel Life
- Super Smart Ball Bushing bearing

- Load Capacities up to 5446 N at 250 Km of travel life.
- Double Acting Seals
- Optional Lubrication System
- Speeds in excess of 3 m/s
- Integral Precision Gearhead
- Standard NEMA Motor Mounting
- Protective Bellows Option

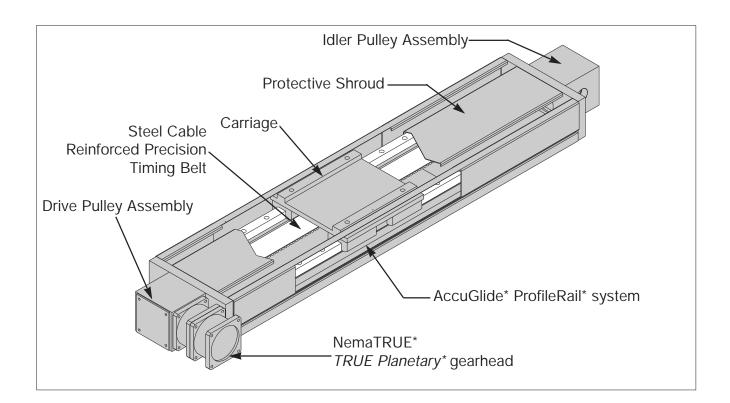


For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





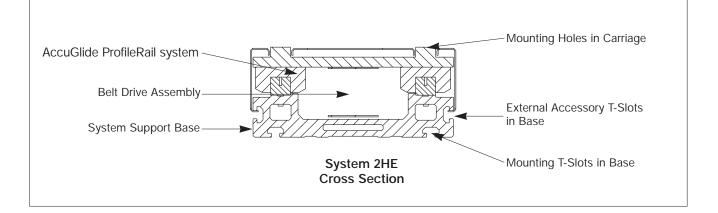
# AccuSlide\* 2HE Belt Actuated System



### AccuSlide 2HE Belt Actuated System Features:

- Continuously Supported System
- Precision Steel Reinforced Timing Belt
- Mounting holes in Carriage
- T-Slots in Base Mounting System
- Positioning Accuracy less than 0,2 mm/300 mm
- Long Travel Life
- AccuGlide ProfileRail system

- High Dynamic Moment Capacity
- Integral Full Length Wipers
- Optional Lubrication System
- Speeds up to 3 m/s
- Integral Precision Gearhead
- Standard NEMA Motor Mounting
- Optional Integral Protective Shroud



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



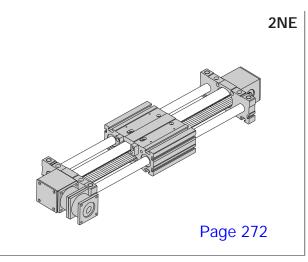


# Metric SuperSlide Belt Actuated System Solution Matrix

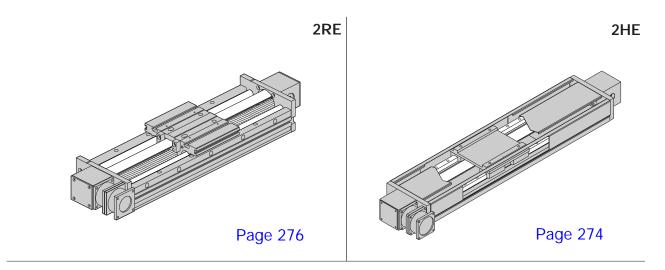
Metric SuperSlide\*

**Belt Actuated Systems** 

For End Supported Applications



For Continuously Supported Applications



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



Page 269

# SuperSlide\* Belt Actuated System

### Precision True Planetary\* gearhead



### NemaTRUE Planetary\* Precision Gearheads Torque Multiplication and Inertia Matching.

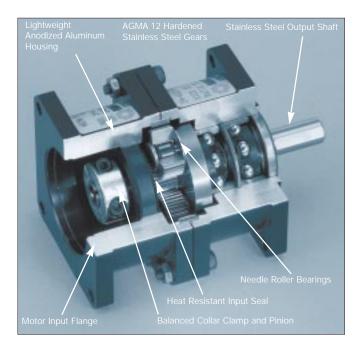
Precision True Planetary gearheads are available in ratios 1:1, 3.1, 5:1 and 10:1 providing maximum application flexibility. To specify the proper precision True Planetary gearhead all that is required is the torque, speed and inertia requirements for the belt actuated system and the AXI-PAK\* motion control system selection. True Planetary gearheads reduce the inertia reflected from the system load and allow for higher accelerations. Motor torque capacity is multiplied while accuracy is increased due to improvements in torsional stiffness.

### NemaTRUE Precision True Planetary gearheads Features:

- 13 Arc-minutes Maximum Backlash
- Long Service Life
- True Planetary gearing
- Compact Design
- Ratios Between 1:1 and 50:1
- 90% Efficient
- High Torque Capacity
- Low Inertia
- High Speed Capacity
- Single Part Number System
- Lifetime Lubrication
- Standard NEMA Motor Mounting

### NemaTRUE Precision True Planetary gearheads Materials:

- AGMA Stainless Steel Gears
- Angular Contact Ball Bearings
- Stainless Steel Output Shaft
- Lightweight Aluminum Input Housing







# SuperSlide\* Belt Driven System System Selection

Many variables influence the selection of a Linear Motion System. The best solution demands a thorough evaluation of the application, only then can design criteria be established. Issues such as envelope limitations, system load capacity, actuator load capacity, speed and acceleration, drive requirements, accuracy and repeatability, and operating environment are looked at from a broad perspective to determine the type of system, type of actuator, and whether the system need be built of special materials.

Typically, a belt actuated linear motion system is ideal for moderate precision, high load, and high-speed applications. When compared to a Ball Screw Actuated Linear Motion System, the Belt Actuated System can attain higher linear speeds in longer stroke applications. A degree of positioning accuracy, however, is sacrificed, as the belt is not capable of meeting the accuracy of that of the ball screw. Since the belt actuated is actuated through a True Planetary\* gearhead, the torque, speed, and system inertia can be matched by varying the gear ratio. If an application requires rigidity, then a fully supported system should be specified in lieu of an end supported type system. For extremely heavy-duty applications, the AccuSlide\* (2HE series) system, with its use of ProfileRail\* type Linear Guides is adept at handling normal axis, overhung, or cantilever loads of increased magnitude. In environments that are corrosive or high temperature special materials may be required and are available. Contact Application Engineering for details on special materials.

In order to determine the Belt Actuated SuperSlide System that meets the needs of your application, it is first necessary to evaluate the following detail design criteria:

- System support requirements
- System stroke length
- Maximum allowable shaft deflection
- Required travel life
- Force on the most heavily loaded bearing
- Load correction factor
- Load/Life requirements-linear bearings
- Motion (move) profile (velocity, acceleration)
- Maximum belt tooth shear strength
- Gear motor rotational speed (gear reduction)
- Torque considerations
- Size motor using torque/speed curves

A detailed explanation of the procedure for selecting a Belt Actuated Linear Motion System is given on page 342 in the Engineering Support Section.



Systems, Slides, and Stages - Metric



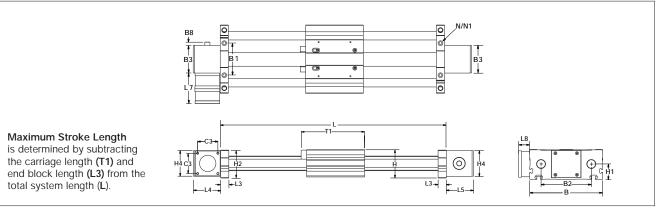
# SuperSlide<sup>\*</sup> 2NE End Supported System

with Integral Belt Drive Assembly and T-Slot Carriage

### New... Super Smart

Ball Bushing\* Bearing...

Now Available For All Sizes



SuperSlide 2	NE Syste	SuperSlide 2NE System with Integral Belt Actuated Assembly and T-Slot Carriage (Dimensions in														
Part Number	Nominal Dia.	В	B1	B2	B3	B8	C3	Н	H1	H2	H4	Max. Stroke Length				
2NE-M16-OLL-	16															
2NE-M20-OLL-	20	160	75	110	65	7,5	47,15	66	34	65	60	L-200				

SuperSlide 2	NE System	with Integral	Belt Actuat	ed Assembly	y and T-Slot	Carriage		(Dimens	sions in mm)
Part Number	L3	L4	L5	L7	L8	N Bolt	N1 Hole	T1	NEMA Size
2NE-M16-OLL-									
2NE-M20-OLL-	20	61,5	61,5	71,6	24,1	M6	11,25	160	23

System 2NE	Star	ndar	d Le	engt	hs																				(Le	ength	ns in mm)
System	300	375	400	450	500	525	600	675	700	750	800	825	900	975	1000	1050	1100	1125	1200	1275	1300	1350	1400	1425	1500	Х	MAX
2NE-M16																										75	1500
2NE-M20																										100	2000

#### Metric SuperSlide 2NE

Metric Super Silue			
System	Gear	Motor	Gearbox
Part Number	Ratio	Frame Size	Part Number
2NE-M16-OLL-A	1:1	NEMA23	NT-23-1
2NE-M16-OLL-B	3:1	NEMA23	NT-23-3
2NE-M16-OLL-C	5:1	NEMA23	NT-23-5
2NE-M16-OLL-D	10:1	NEMA23	NT-23-10
2NE-M20-OLL-A	1:1	NEMA23	NT-23-1
2NE-M20-OLL-B	3:1	NEMA23	NT-23-3
2NE-M20-OLL-C	5:1	NEMA23	NT-23-5
2NE-M20-OLL-D	10:1	NEMA23	NT-23-10

#### **Custom Lengths and Delivery Information**

Systems ordered in standard lengths and longer lengths in increments of (X) are typically shipped in two to three weeks. Custom length systems are available and require three to four weeks for delivery. For special requirements, please contact the Thomson **Systems** application engineering department.

For Motion Control Options refer to the Motion Control Section on page 381.

For Bellows Way Covers, see page 291.

For Spring Set electric brakes, see page 304.

For TNUT mounting hardware, see page 308.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.





#### SuperSlide\* 2NE Benefits:

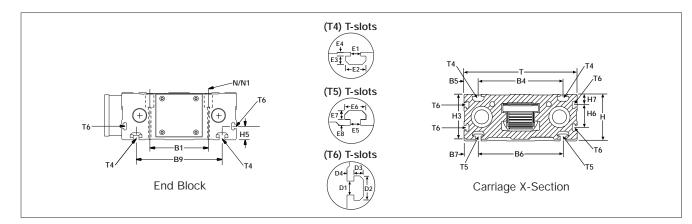
- Used in end supported applications when spanning or bridging a gap is required.
- High speed and acceleration.
- T-Slots in carriage provides quick
   and easy mounting and removal of the workpiece.

#### SuperSlide 2NE Components:

- 2 LinearRace\* End Support blocks with T-Slots for mounting ease.
  - 1 T-Slot integrated carriage with
  - 4 Super Smart Ball Bushing\* bearings.
  - 1 Integral steel cable reinforced Belt Assembly.
- 1 Integral NemaTRUE\* Precision Planetary Gearhead

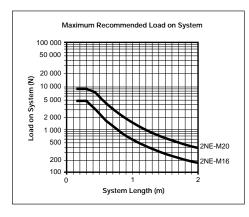
Specifying a Thomson System: 1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number (choosing a standard length will reduce costs and speed delivery). 4.Place your order with your local authorized Thomson distributor. Part Numbering System

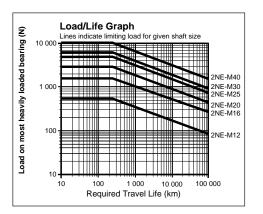




SuperSlide 2N	IE System v	vith Integ	ral Belt Ac	tuated As	ssembly a	nd T-Slot	Carriage			(Dimension	s in mm)
Part Number	Nominal Diameter	B1	B4	B5	B6	B7	B9	D1	D2	D3	D4
2NE-M16-OLL-	16										
2NE-M20-OLL-	20	75	120	20	120	20	120	6	10,5	4	3

SuperSlide 2	VE Syst	em with	n Integra	I Belt Ad	ctuated	Assemb	oly and <sup>-</sup>	T-Slot Ca	arriage			(Dim	nensions	in mm)
Part Number	E1	E2	E3	E4	E5	E6	E7	E8	Н	H3	H5	H6	H7	Т
2NE-M16-OLL-														
2NE-M20-OLL-	8,1	16,5	6,8	3,0	8,1	16,5	6,8	4,5	66	63,5	19	32	15	160



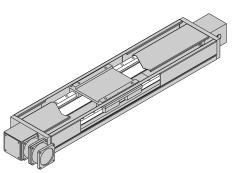


For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

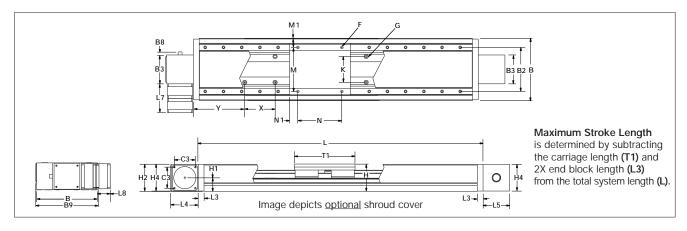




# AccuSlide<sup>\*</sup> 2HE Continuously Supported ProfileRail<sup>\*</sup> System



with Integral Belt Drive Assembly and Carriage



Metric AccuS	lide 2HE	Profile	ail Syst	em with	Integra	Belt Ac	tuated A	ssembly	and Car	riage	(D	imension	s in mm)
Part Number	Nominal Size	В	B2	B3	B8	B9	C3	F	G	Н	H1	H2	H4
2HE-M10-OZP	10	100	70	65	6,6	105	47,15	M5	M5	60	31	61	60
2HE-M20-OZP	20	200	145	95	10	205	69,6	M10	M8	90	45	89	88

Metric AccuS	lide 2HE	E Profile	Rail Sys	tem wit	h Integr	al Belt	Actuate	d Assen	nbly and	I Carriag	je	(Dim	nensions	in mm)
Part Number	Nominal Size	K Central	L3	L4	L5	L7	L8	М	M1	N	N1	T1	Х	Y
2HE-M10-OZP	10	35	12,5	61,5	61,5	71,6	54,1	70	15	70	15	100	75	37,5
2HE-M20-OZP	20	85	20	101,5	101,5	95	42,5	145	27,5	145	27,5	200	120	42,5

Metric System	m 2H	E Sta	ndar	d Ler	ngths														(	Lengt	hs in	mm)
System	300	325	375	450	445	525	565	600	675	685	750	825	805	900	925	975	1045	1165	1285	1405	Х	MAX
2HE-M10											I										75	1000
2HE-M20																					120	3000

For Motion Control Options refer to the Motion Control Section on page 381.

For Bellows Way Covers, see page 291.

For Shroud Covers, see pages 302 and 303.

For Limit Switch Packages, see pages 297 and 299.

For Spring Set electric brakes, see page 304. For TNUT mounting hardware, see page 308.

For TNUT mounting nardware, see page 308.

**Custom Lengths and Delivery Information** Systems ordered in standard lengths and longer lengths in increments of (X) are typically shipped in three to four weeks. Custom length systems are available and require four to six weeks for delivery. Lengths exceeding MAX length will require butt joints and will need 6 to 8 weeks for delivery. For special requirements, please contact the Thomson **Systems** application engineering department.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the valitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.

Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



### AccuSlide\* 2HE Benefits:

- Used in continuously supported applications that require high rigidity.
- Single part number is all that is required.
- Equipped with high load and moment capacity AccuGlide\* ProfileRail\* System.

#### AccuSlide 2HE Components:

- 1 double ProfileRail System Assembly.
- 1 carriage with 4 mounting holes.
- 1 Integral Belt Actuated Assembly.
- 1 integral NemaTRUE\* Planetary\* Precision gearhead.

Specifying a Thomson System: 1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number (choosing a standard length will reduce costs and speed delivery). 4.Place your order with your local authorized Thomson distributor. Part Numbering System



System Length Type of Gearbox Type of Carriage Type of Support

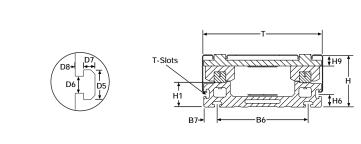
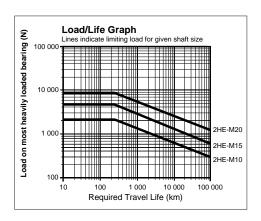


Image depicts optional shroud cover

Metric AccuSI	ide 2HE Pr	ofileRail	System v	vith Integ	ral Belt	Actuated	Assemb	oly and Ca	arriage	(E	Dimension	s in mm)
Part Number	Nominal Diameter	B6	B7	D5	D6	D7	D8	Н	H1	H6	H9	Т
2HE-M10-OZP	10	70	15	10,5	6	3,0	2,5	60	31	15	13	100
2HE-M20-OZP	20	155	22,5	16,5	8,1	6	4	90	45	22,5	20	200

Appropriate mounting holes can be added for mounting the base of one system to the carriage of another for x-y configurations.

Metric AccuSlide	2HE Belt Actuate	d System	
System Part Number	Gear Ratio	Motor Frame Size	Gearbox Part Number
Fait Number	Ratio	Fidine Size	Fait Number
2HE-M10-OZP-A	1:1	NEMA23	NT-23-1
2HE-M10-OZP-B	3:1	NEMA23	NT-23-3
2HE-M10-OZP-C	5:1	NEMA23	NT-23-5
2HE-M10-OZP-D	10:1	NEMA23	NT-23-10
2HE-M20-OZP-E	1:1	NEMA34	NT-34-1
2HE-M20-OZP-F	3:1	NEMA34	NT-34-3
2HE-M20-OZP-G	5:1	NEMA34	NT-34-5
2HE-M20-OZP-H	10:1	NEMA34	NT-34-10



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

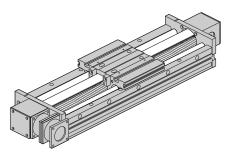




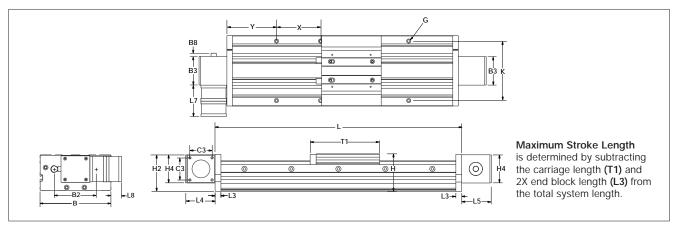
### Superslide<sup>\*</sup> 2RE Continuously Supported System

with Integral Belt Drive Assembly and T-Slot Carriage

### New... Super Smart



Ball Bushing\* Bearing... Now Available For All Sizes



SuperSlide 2	RE System v	with Integra	al Belt Act	uated Asse	mbly and 1	-Slot Carr	iage		(Dimens	ions in mm)
Part	Nominal	B	B2	B3	C3	G	H	H2	H4	K
Number	Dia.									
2RE-M12-OEM	12	130	75	65	47,15	M4	65	75	60	110
2RE-M16-OEM	16	160	95	65	47,15	M5	80	79	60	135
2RE-M20-OEM	20									

SuperSlide 2	RE System wi	th Integral Bel	t Actuated As	sembly and T-	Slot Carriage		(Dim	ensions in mm)
Part Number	L3	L4	L5	L7	T1	Base Mou	nting Hole	Max. Stroke
Number						Х	Y	Length
2RE-M12-OEM	9,5	61,5	61,5	71,6	130	75	75	L-149
2RE-M16-OEM	12,5	61,5	61,5	71,6	160	100	100	L-185
2RE-M20-OEM								

System 2RE	Star	Idar	d Le	engt	hs																				(Le	ngth	s in mm)
System	300	375	400	450	500	525	600	675	700	750	800	825	900	975	1000	1050	1100	1125	1200	1275	1300	1350	1400	1425	1500	Х	MAX
2RE-M12																										75	3000
2RE-M16																										100	3000

For Motion Control Options refer to the Motion Control Section on page 381.

For Bellows Way Covers, see page 291.

For Limit Switch Packages, see pages 300 and 301.

For Spring Set electric brakes, see page 304.

For TNUT mounting hardware, see page 308.

#### **Custom Lengths and Delivery Information** Systems ordered in standard lengths and longer lengths in increments of (X) are typically shipped in two to three weeks. Custom length systems are available and require three to four weeks for delivery. Lengths exceeding MAX length will require butt joints and will need 4 to 6 weeks for delivery. For special requirements, please contact the Thomson **Systems** application engineering department.





#### SuperSlide\* 2RE Benefits:

- Used in continuously supported applications when rigidity is required.
- High speed and acceleration.
- T-Slot in carriage provides quick and easy mounting and removal of the workpiece.

#### SuperSlide 2RE Components:

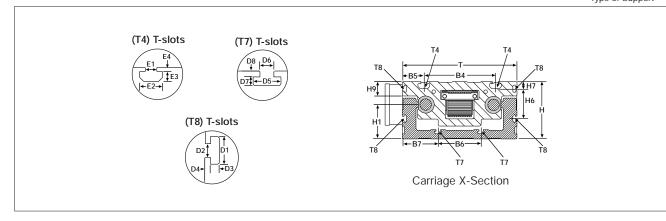
- 1 double LinearRace\* Rail Assembly with T-Slots for mounting ease.
- 1 T-Slot integrated carriage with 4 open type Super Smart Ball Bushing\* bearings.
- 1 Integral Belt Actuated Assembly.
- 1 Integral NemaTRUE\* Planetary Precision gearhead.

Specifying a Thomson System: 1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number (choosing a standard length will reduce costs and speed delivery). 4.Place your order with your local authorized Thomson distributor. Part Numbering System

#### 2RE-M16 OEM-A-L600

System Designation -Nominal Diameter -

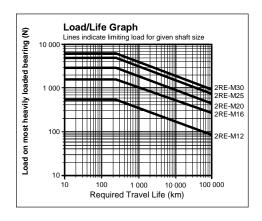
System Length - Type of Gearbox Type of Carriage Type of Support



SuperSlide 2R	SuperSlide 2RE System with Integral Belt Actuated Assembly and T-Slot Carriage											
Part Number	Nominal Diameter	B4	B5	B6	B7	D1	D2	D3	D4	D5	D6	
2RE-M12-OEM	12	75	27,5	65	32,5	8,0	4,2	2,75	2	8,0	4,2	
2RE-M16-OEM	16	100	30	80	40	10,5	6	3,5	2,5	10,5	6	
2RE-M20-OEM	20											

SuperSlide 2	SuperSlide 2RE System with Integral Belt Actuated Assembly and T-Slot Carriage											
Part Number	D7	D8	E1	E2	E3	E4	Н	H1	H6	H7	H9	Т
2RE-M12-OEM	2,75	2	7,5	13	4	3	65	40	35	7	14	130
2RE-M16-OEM	3,5	2,5	8,1	16,5	6,8	3	80	48	41,5	10	20	160
2RE-M20-OEM												

SuperSlide 2RE	SuperSlide 2RE Belt Actuated System									
System Part Number	Gear Ratio	Motor Frame Size	Gearbox Part Number							
2RE-M12-OEM-A	1:1	NEMA23	NT-23-1							
2RE-M12-OEM-B	3:1	NEMA23	NT-23-3							
2RE-M12-OEM-C	5:1	NEMA23	NT-23-5							
2RE-M12-OEM-D	10:1	NEMA23	NT-23-10							
2RE-M16-OEM-A	1:1	NEMA23	NT-23-1							
2RE-M16-OEM-B	3:1	NEMA23	NT-23-3							
2RE-M16-OEM-C	5:1	NEMA23	NT-23-5							
2RE-M16-OEM-D	10:1	NEMA23	NT-23-10							



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries

Page 277

# Systems Applications

# Application Analysis

Determining the system which best meets the demands of your application and provides optimum performance requires the evaluation of a number of variables. The accompanying form establishes basic criteria to initiate the analysis of your application. In addition, the Engineering Support Section has been designed with pertinent data and formulas used to specify the proper system for your application. If you have questions or special needs a Thomson systems engineer can assist

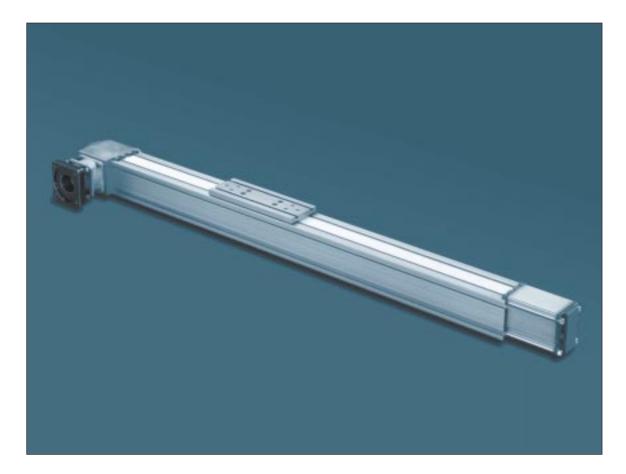
	you in evaluating your application and recommending a system solution. Simply call 1-800-554-8466.
-	

Application Description:	Horizontal	Vertical
System Part Number:		
Quantity Required		
Weight of Load (N):		
Space Requirements (LxHxW):		
Stroke Length Requirements (mm):		
Support Requirements:	End Supported	Full Support
Maximum Velocity Requirements (m/s):		
Maximum Acceleration Requirements (m/s <sup>2</sup> ):		
Required Straightness of Travel Accuracy (µm/m):		
Required Positioning Accuracy (µm):		
Required Repeatability (μm):		
Life Requirement (km):		
Cycle (km/yr):		
Environmental Considerations:		
Other Design Criteria:		
Production Time Frame:		
Company:		
Name:		
Title:		
Address:		
_ City:	State:	Zip:
Telephone:		

Please Fax your Application Analysis to 516-883-9039 Attention: Application Engineering



# Turbo Module Belt Actuated Systems



# Turbo Module\* Belt Actuated Systems offer:

- A structurally rigid design with mounting flexibility, the Turbo Module System can be used when spanning or bridging a gap or mounted continuously when maximum rigidity is required.
- Available with a uniquely designed carriage and mounting base with integrated T-slots for quick and easy multi-axis assembly and control.
- High speed and acceleration with positioning accuracy better than +/- 0,15 mm.
- Integrated AccuGlide\* ProfileRail\* Systems providing high rigidity combined with dynamic load capacities up to 56 kN and moment capacities up to 7900 Nm.

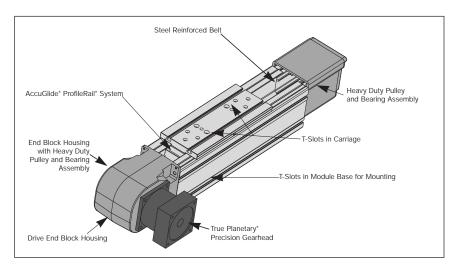
- A single point integrated lubrication system that maximizes reliability and reduces down time.
- Standard integrated True Planetary<sup>\*</sup> gearhead for speed reduction and torque multiplication. Gearhead motor mounting flanges are stocked, awaiting your motor specifications.
- A single part number system. All that is required to order is to specify the system size and length.
- Easy adaptation to industry standard servo motor systems. Refer to the Motion Control Section on page 381.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





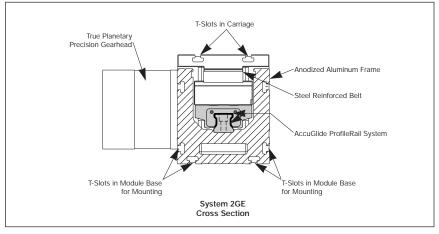
# **Turbo Module\* Belt Actuated Systems**



#### Turbo Module 2GE Belt Actuated System Features:

- Compact and Rigid Aluminum Mounting Base
- Integral Steel Reinforced Belt
- T-Slots in Carriage
- T-Slots in Base Mounting System
- Standard Built-in Gearhead
- Repeatability better than +/- 0,15 mm
- AccuGlide\* ProfileRail\* System

- Load Capacities up to 56 kN
- · Easy to install
- Integral Lubrication System
- Speeds up to 5 m/s
- Standard Motor Mounting
- Single Part Number System
- Simple or Continuous Support Capabilities



#### System Material Specifications:

- Belt Material:
- White Polyurethane Steel Cable Reinforced
- Mounting Base Material High Strength Aluminum Alloy
- ProfileRail Systems
- Hardened Bearing Quality Steel Rail Hardened Bearing Quality Steel Carriage Assembly Hardened and Precision Ground Bearing Ball Elements
- AccuTRUE\* True Planetary\* Precision Gearheads
   Activities Starl Course
- AGMA Stainless Steel Gears Tapered Roller Bearings Stainless Steel Output Shaft Stainless Steel Output Housing Light Weight Aluminum Housing
- End Support Systems High Quality Steel Toothed Pulley Heavy Duty Bearings





### Turbo Module\* 2GE Belt Actuated Systems

### True Planetary\* Gearheads



### AccuTRUE\* True Planetary Gearheads Speed reduction choices.

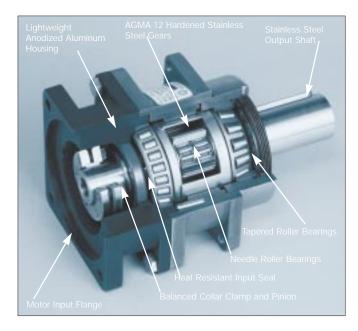
True Planetary gearheads are available in standard ratios between 1:1 and 10:1 providing maximum application flexibility. Motor torque capacity is multiplied while output speed is reduced. True Planetary gearheads reduce the inertia reflected from the system load and allow for higher accelerations. To specify the proper precision gearhead all that is required is the torque and speed requirements for the belt actuated system and your selection of a servo motor. Simply follow the step by step selection process on pages 359 through 370.

### AccuTRUE True Planetary Gear Reduction Features:

- 6 Arc-minutes Maximum Backlash
- Long Service Life
- True Planetary Gearing
- Compact Design
- Ratios Between 1:1 and 50:1
- Up to 90% Efficient
- High Torque Capacity
- Low Inertia
- High Speed Capacity
- Lifetime Lubrication
- Standard Motor Mounting

### AccuTRUE True Planetary Precision Gearhead Materials:

- AGMA Stainless Steel Gears
- Tapered Roller Bearings
- · Stainless Steel Output Shaft and Housing
- Light Aluminum Input Housing



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



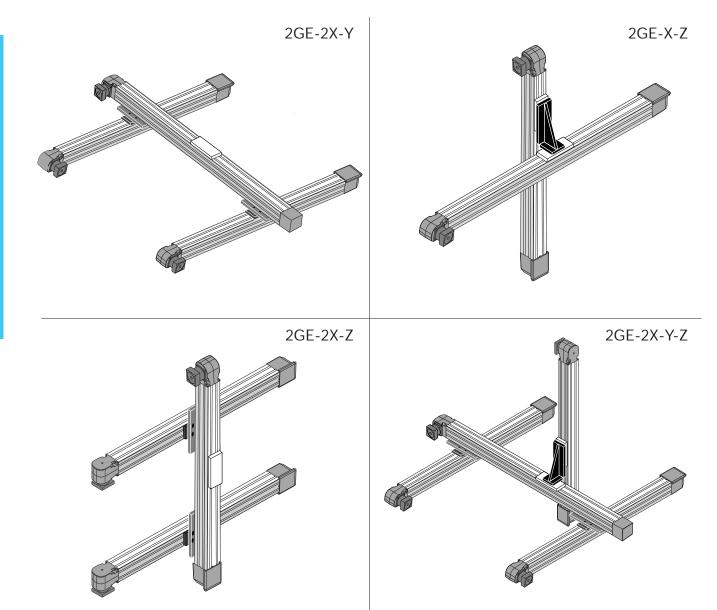


### Turbo Module 2GE Belt Actuated System



### Turbo Module\* Multi-Axis Options High Speed Multi Axis Positioning

The Turbo Module 2GE system provides the basis for multi-axis motion control. The built-in flexibility of the T-slots in the base and the carriage allow for quick and easy x-y, x-z and x-y-z assembly and positioning capability. The illustrations below provide a sampling of the types of configurations that can be achieved. In many cases a SuperSlide ball screw actuated system can be used to provide an additional axis of motion. Adapter plates can be provided for the mounting of each system. For your next multi-axis application contact Thomson Systems application engineering.



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





# Turbo Module\* Belt Actuated System Selection Criteria

Many variables influence the selection of a Linear Motion System. The best solution demands a thorough evaluation of the application, only then can design criteria be established. Issues such as envelope limitations, system load capacity, actuator load capacity, speed and acceleration, drive requirements, accuracy and repeatability, and operating environment are looked at from a broad perspective to determine the type of system, type of actuator, and whether the system need be built of special materials.

Typically, a belt driven linear motion system is ideal for moderate precision, high load, and high-speed applications. When compared to a Ball Screw Actuated Linear Motion System, the Belt Actuated System can attain higher linear speeds in longer stroke applications. A degree of positioning accuracy, however, is sacrificed, as the belt is not capable of meeting the accuracy of that of the ball screw. The Turbo Module is designed to act as its own support structure by virtue of its robust base support member and is thereby suited for applications that require gantry or overhung loads. Since the Turbo Module belt drive is actuated through a True Planetary<sup>\*</sup> gearhead, the torque, speed, and system inertia can be matched by varying the gear ratio. In environments that are corrosive or high temperature special materials may be required and are available. Contact Application Engineering for details on special materials.

In order to determine the Turbo Module Belt Actuated SuperSlide<sup>\*</sup> System that meets the needs of your application, it is first necessary to evaluate the following detail design criteria:

- System support requirements
- System stroke length
- Maximum allowable shaft deflection
- Required travel life
- Force on the most heavily loaded bearing
- Load correction factor
- Load/Life requirements-linear bearings
- Motion (move) profile (velocity, acceleration)
- Maximum belt tooth shear strength
- Gear motor rotational speed (gear reduction)
- Torque considerations
- Size motor using torque/speed curves

A detailed explanation of the procedure for selecting a Turbo Module Belt Actuated Linear Motion System is given on page 359 in the Engineering Support Section.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Systems, Slides, and Stages - Metric

Page 283

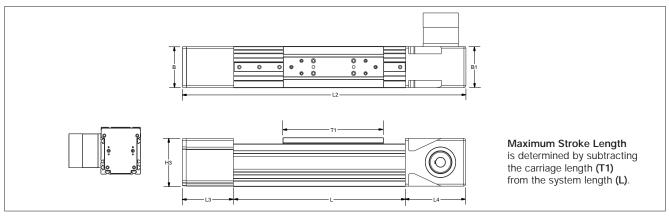
### Turbo Module 2GE Belt Actuated System

with T-Slot Integrated Carriage

### New... AccuGlide\*

### ProfileRail\* System...

Now Available in Select Sizes



(Belt Not Shown for Clarity)

•	3,												
Turbo Module*	Furbo Module* 2GE Belt Actuated System with T-Slot Integrated Carriage												
Part Number	Nominal Size	В	B1	H3	L3	L4	T1	L2 Total System Length	Max. Stroke Length				
2GE-M25-OQN	25	102	131	112	138	153	305	L+(316)	L-(305)				
2GE-M35-OQN	35	160	162	190	206	250	400	L+(456)	L-(400)				

Turbo Module	Turbo Module 2GE Belt Actuated System with T-Slot Integrated Carriage Technical Data         (Dimensions in mm)										
Part	Dyn	D	ynamic Momei	nt	Carriage	Max	Moment	of Inertia	Weight		
Number	Load Cap. (N)	Myaw (Nm)	Mroll (Nm)	Mpitch (Nm)	Mass (kg)	Length (mm)	lx (cm4)	ly (cm4)	Formula (N)		
2GE-M25-OQN	32000	3500	450	3500	4.3	3960	600	829	155,9+0,186 x L		
2GE-M35-OQN	56000	7950	1270	7950	12.5	3960	2840	3730	503,0+0,353xL		

For Motion Control Options refer to the Motion Control Section on page 381. For TNUT mounting hardware, see page 308.

System 2GE Standard Lengths (L) (Lengths in mm)													
System	410	530	610	650	770	890	930	1010	1090	1130	1250	Х	Max.
2GE-M25												120	4010
2GE-M35												160	3970

Custom Lengths and Delivery Information
Systems ordered in standard lengths and longer lengths in increments of (X) are typically shipped in
two to three weeks. Custom length systems are
available and require three to four weeks for delivery. For special requirements, please contact the
Thomson <b>Systems</b> application engineering department.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





#### Turbo Module\* 2GE Benefits:

- Used in high speed and high load applications.
- Compact and rigid design minimizes machine size.
- T-Slot in carriage provides quick and easy mounting and removal of the workpiece.

#### **Turbo Module 2GE Components:**

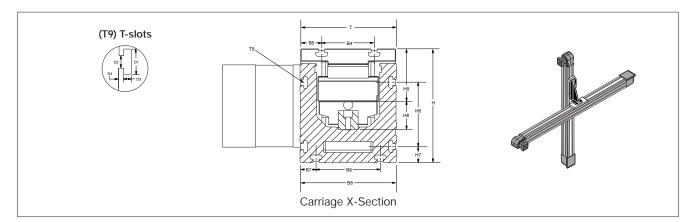
- 1 Structural Frame Assembly with standard T-Slots for mounting ease.
- 1 AccuGlide\* ProfileRail\* System Carriage assembly.
- 1 steel cable reinforced belt system including heavy duty pulleys and bearings.
- 1 Integral AccuTRUE\* True Planetary\* Precision gearhead.

Specifying a Thomson System: 1. Determine the proper system for your load and life requirements. 2. Select the part number. 3. Add the letter "L" followed by the overall length in millimeters, as a suffix to the part number (choosing a standard length will reduce costs and speed delivery). 4. Place your order with your local authorized Thomson distributor. Part Numbering System

#### 2GE-M35-OQN-N L610

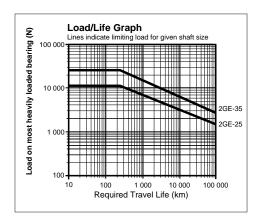
System Designation -Nominal Size

L System Length Type of Gearbox Type of Carriage Type of Support



Furbo Module 2GE Belt Actuated System with T-Slot Integrated Carriage         (Dimensions in million)											n mm)					
Part Number	Nominal Size	B4	B5	B6	B7	B8	D1	D2	D3	D4	Н	H6	H7	H8	H9	Т
2GE-M25-OQN	25	65	17,5	75	13,5	110	16,5	8,1	6,8	2,2	129	75	17,5	36	59,5	108
2GE-M35-OQN	35	90	37	110	27,5	165	20,1	10	7	6	195	110	27,5	48	90	163

Turbo Module 20	Turbo Module 2GE Gearbox Data								
System	Gear	Gearbox	Gearbox						
Part Number	Ratio	Part Number	inertia (Kg • m <sup>2</sup> )						
2GE-M25-OQN-K	1:1	AT-10-1	7,0 x 10 <sup>-2</sup>						
2GE-M25-OQN-L	3:1	AT-10-3	2,34 x 10 <sup>-3</sup>						
2GE-M25-OQN-M	6:1	AT-10-6	1,00 x 10 <sup>-3</sup>						
2GE-M35-OQN-N	1:1	AT-14-1	1,99 x 10 <sup>-1</sup>						
2GE-M35-OQN-P	6:1	AT-14-6	3,43 x 10 <sup>-3</sup>						
2GE-M35-OQN-Q	10:1	AT-14-10	2,55 x 10 <sup>-3</sup>						



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





### Systems Applications Application Analysis

Determining the system which best meets the demands of your application and provides optimum performance requires the evaluation of a number of variables. The accompanying form establishes basic criteria to initiate the analysis of your application. In addition, the Engineering Support Section has been designed with pertinent data and formulas used to specify the proper system for your application. If you have questions or special needs a Thomson systems engineer can assist

you in evaluating your application and recommending a system solution. Simply call 1-800-554-8466.

Application Description:	Horizontal	Vertical
System Part Number:		
Quantity Required		
Weight of Load (N):		
Space Requirements (LxHxW):		
Stroke Length Requirements (mm):		
Support Requirements:	End Supported	Full Support
Maximum Velocity Requirements (m/s):		
Maximum Acceleration Requirements (m/s <sup>2</sup> ):		
Required Straightness of Travel Accuracy (µm/m):		
Required Positioning Accuracy (µm):		
Required Repeatability (µm):		
Life Requirement (km):		
Cycle (km/yr):		
Environmental Considerations:		
Other Design Criteria:		
Production Time Frame:		
Company:		
Name:		
Title:		
Address:	Chata	7.
City:	State:	Zip:
Telephone:	Fax:	

Please Fax your Application Analysis to 516-883-9039 Attention: Application Engineering

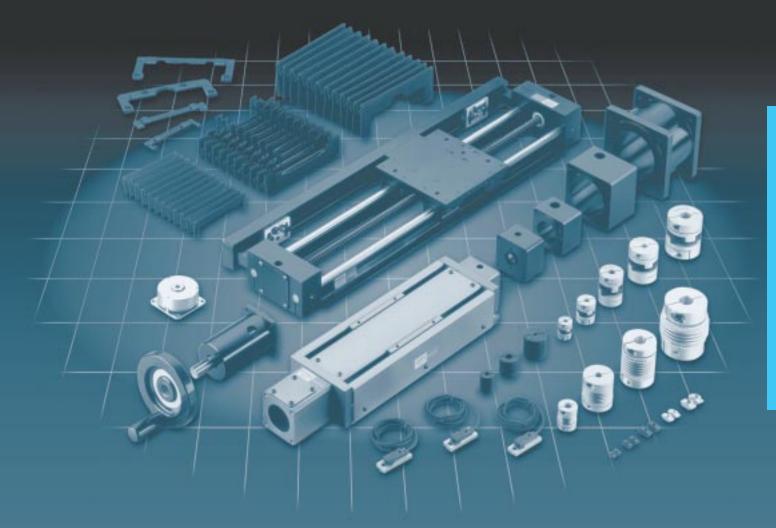




### THOMSON INDUSTRIES, INC.



Accessories for Systems, Slides & Stages, and Motion Control Products



### HARDWARE FOR YOUR APPLICATION

Motor Adaptor and Couplings
Bellows and Shroud Way Covers
Limit Switch and Sensor Packages
Electric Brakes



## www.thomsonindustries.com



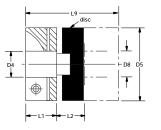
For Application Engineering assistance contact the Thomson Technical HelpLine at 1-800-554-8466. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



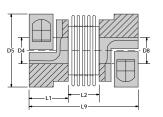
## **Couplings and Motor Adaptor Blocks**



#### Motor Couplings for Mounting NEMA frame size motors to Inch Size Systems

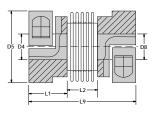


Aluminum Oldhai	Aluminum Oldham Type with Clamp Attachment (Acetal Disc)										
Part	Motor		Dimensions (in.) Maxir								
Number	Size	D5	D4	D8	L1	L2	L9	Torque (lbf-in)			
MC-OLD-12-23	NEMA 23	1.00	.250	.250	.46	.36	1.28	30.1			
MC-OLD-16-23	NEMA 23	1.00	.250	.375	.46	.36	1.28	30.1			
MC-OLD-16-34	NEMA 34	1.31	.375	.375	.59	.71	1.89	79.6			
MC-OLD-16-34 AE	NEMA 34	1.31	.375	.500	.59	.71	1.89	79.6			
MC-OLD-24-42	NEMA 42	1.63	.625	.625	.70	.60	2.00	159.3			



Stainless Steel B	Stainless Steel Bellows Type with Clamp Attachment											
Part	Motor		Dimensions (in.) Max									
Number	Size	D5	05 D4 D8 L1 L2 L9 Torque (lbf-in)									
MC-BEL-12-23	NEMA 23	.98	.250	.250	.51	.24	1.26	17.7				
MC-BEL-16-23	NEMA 23	.98	.250	.375	.51	.24	1.26	17.7				
MC-BEL-16-34	NEMA 34	1.57	.375	.375	.67	.51	1.85	88.5				
MC-BEL-16-34 AE	NEMA 34	1.57	.375	.500	.67	.51	1.85	88.5				
MC-BEL-24-42	NEMA 42	1.77	.625	.625	.47	1.54	2.48	159.3				

#### Motor Couplings for Mounting BLX Series Servo Motors to Inch Size Systems



Stainless Steel E	Bellows Type with C	lamp <i>I</i>	Attachn	nent				
Coupling	Motor		Dim	ensions	(in.)			Maximum
Part No.	Part No.	D5	D4	D8	L1	L2	L9	Torque (lbf-in)
MC324104760635	BLX232, BLX234	1.26	0.188	0.250	0.55	0.51	1.614	39.8
MC324106350635	BLX232, BLX234	1.26	0.250	0.250	0.55	0.51	1.614	39.8
MC324109530635	BLX232, BLX234	1.26	0.375	0.250	0.55	0.51	1.614	39.8
MC324112700635	BLX232, BLX234	1.26	0.500	0.250	0.55	0.51	1.614	39.8
MC456309531270	BLX341, BLX342, BLX343	1.77	0.375	0.500	0.47	0.95	2.48	159.3
MC456312701270	BLX341, BLX342, BLX343	1.77	0.500	0.500	0.47	0.95	2.48	159.3
MC667815881900	BLX421	2.60	0.625	0.748	0.77	0.79	3.07	354.0
MC667815882400	BLX422, BLX423	2.60	0.625	0.945	0.77	0.79	3.07	354.0

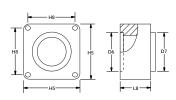
For Dimensional information and specifications of BLX series servo motors, see page 431.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



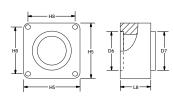


#### Motor Adaptor Blocks for mounting NEMA frame size Motors to Inch Size Systems



Motor Adaptor B	lock – Black	Anodized	Aluminum							
Part	Motor		Dimension (in.)							
Number	Size	L8	H5	H8	D6	D7				
MAB 12-23	NEMA 23	1.425	2.24	1.86	1.503	2.149				
MAB 16-23	NEMA 23	1.245	3.26	2.74	1.503	2.875				
MAB 16-34	NEMA 34	1.994	3.26	2.74	2.878	2.875				
MAB 24-42	NEMA 42	2.285	4.38	3.50	2.189	4.100				

#### Motor Adaptor Blocks for mounting BLX Series Servo Motors frame size Motors to Inch Size Systems



Motor Adaptor Block - Black Anodized Aluminum										
Motor Adaptor	Motor	Motor Dimensions (in.)								
Part No.	Part No.	L8	H5	H8	D6	D7				
MAB2DB08-BLX23	BLX232, BLX234	1.685	2.24	1.856	1.503	1.498				
MAB08/12-BLX23	BLX232, BLX234	1.59	2.24	1.856	1.503	2.148				
MAB12-BLX23	BLX232, BLX234	1.41	2.24	1.856	1.503	2.148				
MAB16-BLX23	BLX232, BLX234	1.40	3.26	2.740	1.503	2.875				
MAB16-BLX34	BLX341, BLX342, BLX343	2.40	3.26	2.740	2.878	2.875				
MAB24-BLX42	BLX421, BLX422, BLX423	3.40	4.50	3.619	4.332	4.099				

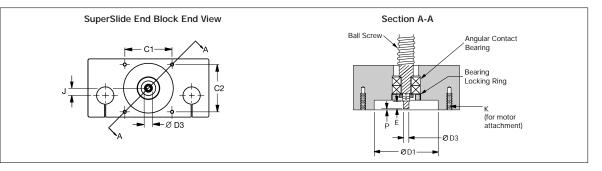
#### Motor Coupling, Motor Adaptor, Motor, and Inch Size SuperSlide Interchange Matrix

NEN	/IA frame size moto	rs		BLX series mot	ors	Used with
Coupling Part No.	Motor Adaptor Part No.	Motor Frame Size	Coupling Part No.	Motor Adaptor Part No.	Motor Part No.	SuperSlide System Part No.
MC324104760635	MAB2DB08-BLX23	NEMA23	MC324104760635	MAB2DB08-BLX23	BLX232, BLX234	2DB08
MCBEL 12-23	MAB12-23	NEMA23	MC324106350635	MAB08/12-BLX23	BLX232, BLX234	2AB08, 2CB08, 2CB12, 2DB12, 2EB08, BSA08, BSAM12
MCBEL12-23	MAB12-23	NEMA23	MC324106350635	MAB12-BLX23	BLX232, BLX234	2AB12, 2EB12, BSA12, BSAM20
MCBEL16-23	MAB16-23	NEMA23	MC324109530635	MAB16-BLX23	BLX232, BLX234	2CB16 <sup>†</sup> , 2DB16 <sup>†</sup>
MCBEL16-34	MAB16-34	NEMA34	MC456309531270	MAB16-BLX34	BLX341, BLX342, BLX343	2CB16 <sup>†</sup> , 2DB16 <sup>†</sup>
MCBEL16-34AE	MAB16-34	NEMA34	MC456312701270	MAB16-BLX34	BLX341, BLX342, BLX343	2AB16, 2EB16, BSA16
MCBEL24-42	MAB24-42	NEMA42	MC667815881900	MAB24-BLX42	BLX421	2AB24, 2EB24, BSA24
			MC667815882400	MAB24-BLX42	BLX422, BLX423	2AB24, 2EB24, BSA24

<sup>†</sup> Accessories for 2CB-16 and 2DB-16 Systems available for both NEMA 23 and NEMA 34 or BLX 23X and BLX 34X frame size motors.

## Motor Mounting Dimensions

Dimensional Information for mounting motors to Inch size Ball Screw Actuated SuperSlide\* Systems.



Part Number	Motor Size	or Size Dimensions (in.)							
Prefix	Size C1 C2 D1 D3 E J K P								
2DB08†	NEMA 23	1.75	1.25	1.50	.188	.30	.275	10-32	.05
2AB08, 2CB08, 2CB12, 2DB12, 2EB08	NEMA 23	1.86	1.86	2.15	.250	.34	.300	10-32	.05
2AB12, 2EB12	NEMA 23	1.86	1.86	2.15	.375	.56	0	10-32	.05
2CB16, 2DB16	NEMA 34	2.74	2.74	2.88	.375	.56	.425	10-32	.05
2AB16, 2EB16	NEMA 34	2.74	2.74	2.88	.500	.42	0	10-32	.05
2AB24, 2EB24	NEMA 42	3.50	3.50	4.10	.625	.59	0	1/4-20	.05

† Dimensions for the 2DB08 SuperSlide system are for lead screw actuation only.

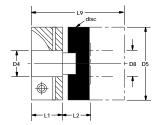
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



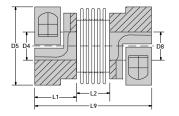


## **Metric Motor Couplings**

Motor Couplings for Mounting NEMA frame size motors to Metric Size Systems



Aluminum Oldham Type with Clamp Attachment (Acetal Disc)										
Part	Motor		Dimension (mm) Maximum							
Number	Size	D5	D4	D8	L1	L2	L9	Torque (N • m)		
MCM-OLD-08-23	NEMA 23	25,4	6,35	8	11,6	9,2	32,4	3,4		
MCM-OLD-10-23	NEMA 23	25,4	6,35	10	11,6	9,2	32,4	3,4		
MCM-OLD-14-34	NEMA 34	41,3	9,53	14	15,0	18,0	48,0	9,0		



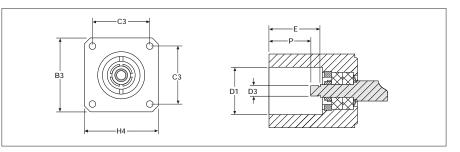
Stainless Steel Bellows Type with Clamp Attachment										
Part	Motor		Dimension (mm) Maxim							
Number	Size	D5	D4	D8	L1	L2	L9	Torque (N • m)		
MCM-BEL-08-23	NEMA 23	25	6,35	8	13	6	32	2,0		
MCM-BEL-10-23	NEMA 23	25	6,35	10	13	6	32	2,0		
MCM-BEL-14-34	NEMA 34	40	9,53	14	17	13	47	10,0		

#### Motor Couplings for Mounting BLX Series Servo Motors to Metric Size Systems

System Model	Thomson Motor Model	Motor Adaptor Block	Shaft Coupling
2RBM12	BLX23	None Required	MCM-BEL-08-23
2RBM16	BLX23 BLX34	None Required MABM34	MCM-BEL-10-23 MCM-BEL-10-34-GB
2NBM20	BLX23	None Required	MCM-BEL-10-23
	BLX34	MABM34	MCM-BEL-10-34-GB
2HBM10	BLX23	None Required	MCM-BEL-08-23
2HBM20	BLX34	None Required	MCM-BEL-14-34-GB
	BLX421	MABM42	MCM-BEL-14-421
	BLX422, BLX423	MABM42	MCM-BEL-14-422

## **Motor Mounting Dimensions**

Dimensional Information for mounting of NEMA frame size motors to Metric size Ball Screw Actuated SuperSlide\* Systems



Ball Screw Ac	Ball Screw Actuated SuperSlide									
Part	Motor	Dimension (mm)								
Number	Size	B3	C3	H4	D1	D3	E	Р		
2RB M12	NEMA 23	60,0	47,15	60,0	38,2	8,0	42,0	34,0		
2RB M16	NEMA 23	60,0	47,15	60,0	38,2	10,0	42,5	32,5		
2NB M20	NEMA 23	60,0	47,15	60,0	38,2	10,0	42,5	32,5		
2HB M10	NEMA 23	60,0	47,15	60,0	38,2	8,0	42,0	34,0		
2HB M20	NEMA 34	88,9	69,6	88,9	73,10†	14,0	66,0	52,0		

† Ø DI is for the first 5mm only; remainder is Ø 50.8mm

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.



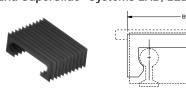


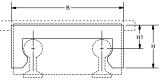
## **Protective Bellows**

#### Way Covers

#### **BEL-2AE**

For QuickSlide\* Systems 2AA, 2EA and SuperSlide\* Systems 2AB, 2EB





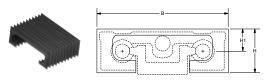
#### **BEL-2AE Moveable Protective Bellows**

Part	Nom.	Dimension (in.)								
Number	Shaft Dia.	Н	H1	В						
BEL-2AE-08	1/2	1.4	1.24	5.25						
BEL-2AE-12	3/4	2.1	1.35	6.85						
BEL-2AE-16	1	2.8	1.68	8.10						
BEL-2AE-24	11/2	4.2	2.44	11.18						

Each moveable bellows comes with 1 section of bellows and 2 pairs of Velcro<sup>®</sup> fasteners.

#### BEL-2D

For Dual Shaft Rail QuickSlide System 2DA<sup>†</sup> and SuperSlide System 2DB

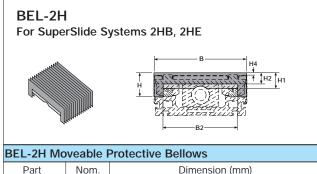


#### BEL-2D Dual Shaft Rail Bellows

DEE 20 Duul Si	iunt Run Dene	1113		
Part	Nom.	Dime	ension (in.)	
Number	Shaft Dia.	Н	H1	В
BEL-2DA-08	1/2	1.50	0.85	4.60
BEL-2DB-08	1/2	1.89	1.34	5.13
BEL-2D-12	3/4	2.406	1.437	6.000
BEL-2D-16	1	2.875	1.687	7.500

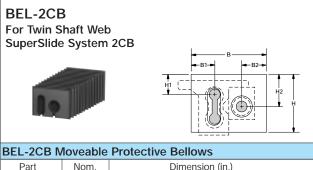
Each moveable bellows comes with 1 section of bellows and 2 mounting brackets and mounting screws.

Appropriate arrangements for afixing the Bellows at each end of the QuickSlide 2DA System are required.



i uit	NOIII.	Dimension (mm)									
Number	Sys. size	В	B2	Н	H1	H2	H4				
BEL-2H-10	10	103	81	26	11	10	0				
BEL-2H-20	20	199	167	48	30	15	5				

Each moveable bellows comes with 1 section of bellows and 2 mounting brackets and mounting screws.



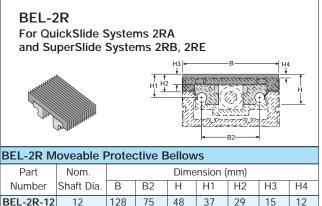
Part	Nom.		Dime				
Number	Shaft Dia.	Н	H1	H2	В	B1	B2
BEL-2CB-08	1/2	2.750	1.062	1.500	3.750	1.125	1.250
BEL-2CB-12	3/4	3.438	1.125	1.750	4.125	1.250	1.375
BEL-2CB-16	1	4.250	1.313	2.250	4.750	1.313	1.313

Each moveable bellows comes with 1 section of bellows and 2 pairs of Velcro<sup>®</sup> Fasteners.



Nom.		Dimension (mm)						
Shaft Dia.	В	B2	Н	H1	H2	H3	H4	
20	176	110	81	52	41	20	30	
20	166	110	70	38	28	15	6	
	Shaft Dia. 20	Shaft Dia.B20176	Shaft Dia.         B         B2           20         176         110	Shaft Dia.         B         B2         H           20         176         110         81	Shaft Dia.         B         B2         H         H1           20         176         110         81         52	Shaft Dia.         B         B2         H         H1         H2           20         176         110         81         52         41	Shaft Dia.         B         B2         H         H1         H2         H3           20         176         110         81         52         41         20	

Each moveable bellows comes with 1 section of bellows and 2 mounting brackets and mounting screws.



BEL-2R-12 12 128 75 48 37 29 15 BEL-2R-16 158 95 52 16 426 30 150 Each moveable bellows comes with 1 section of bellows and

2 mounting brackets and mounting screws.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





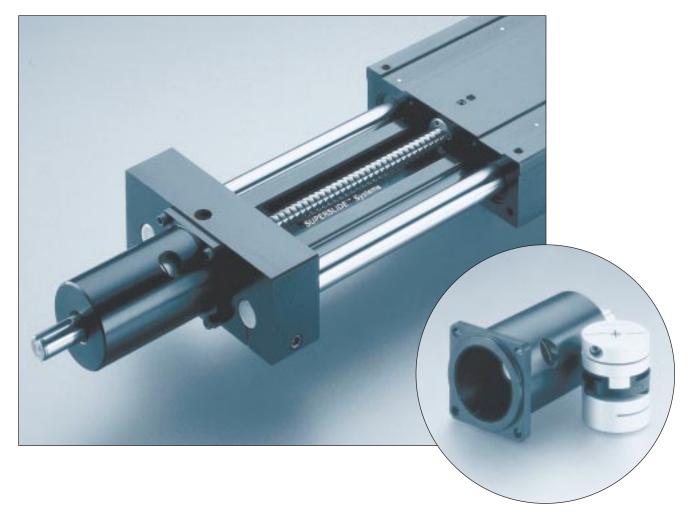
The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Veloro is a registered trademark of Veloro Industries B.V. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



10

## **Radial Mount Ball**

Ball Screw Shaft Extenders for SuperSlide\* Systems



- Allows for the mounting of actuating devices that will impart a cantilever load to the ball screw shaft extension.
- May be used with:
  - Pulley and Belt Drives
  - Hand Cranks
  - Pinion Gears

- Radial Mount\* couplings provide attachment of ball screw and extender shafts without the need for painstaking alignment procedures.
- The heavy duty cantilever torque capacity of the Radial Mount shaft extender resists ball screw stub shaft fatigue and failure.

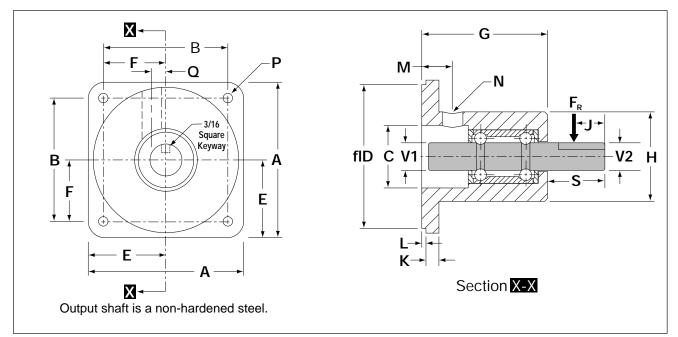
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





## **Radial Mount**

Ball Screw Shaft Extenders for SuperSlide\* Systems



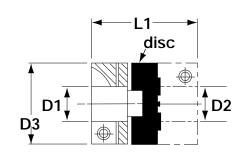
Radial Mount*	Shaft I	Extend	er Technic	al Inf	orma	ation														
Part	F <sub>R</sub> † Max.	J	Frame								Dime	nsion	s (in.)							
Number	(lbf.)	(in.)	Size	Α	В	С	D	Е	F	G	Н	К	L	Μ	Ν	Р	S	V1	V2	Q
RADMO-23A <sup>†††</sup>	120	.5	NEMA-23	2.24	1.86	1.75	2.15	1.12	.93	3.625	2.15	.25	.16	1.15	.62	.22	1.26	.626	.626	.43
RADMO-23B	120	.5	NEMA-23	2.24	1.86	1.75	2.15	1.12	.93	3.625	2.15	.25	.16	1.15	.62	.22	1.26	.626	.626	.43
RADMO-23C	120	.5	NEMA-23	2.24	1.86	1.75	2.15	1.12	.93	3.625	2.15	.25	.16	1.15	.62	.22	1.26	.626	.626	.43
RADMO-34A	120	.5	NEMA-34	3.26	2.74	1.75	2.88	1.63	1.37	3.625	3.0	.25	.16	1.2	.50	.22	1.26	.626	.626	.48
RADMO-34B	120	.5	NEMA-34	3.26	2.74	1.75	2.88	1.63	1.37	3.625	3.0	.25	.16	1.2	.50	.22	1.26	.626	.626	.48
RADMO-42A	210	1.0	NEMA-42	4.19	3.50	2.37	4.10	2.09	1.75	4.225	3.5	.38	.16	1.43	.50	.27	2.19	.747	.747	.68

<sup>†</sup> Based on a bearing life of 2 x 10<sup>8</sup> revolutions.

<sup>††</sup>Radial Mount shaft extenders are supplied with their corresponding Radial Mount Coupling.

## **Radial Mount Couplings**

Couples the SuperSlide Ball Screw shaft to the Smart Mount Shaft Extender



Radial Mour	nt Coupli	ng Technica	al Informati	on			
	Max		Dimens	ions (in.)		lload	Supplied
Part Number	Max. Torque in-Ibf.	L1	D1	D2	D3	Used with System	with Smart Mount Extender
RMC-23A <sup>TTT</sup>	80	1.89	.188	.626	1.31	2DB08	RADMO-23A
RMC-23B	80	1.89	.250	.626	1.31	2AB08, 2CB08, 2CB12, 2DB12, 2EB08, BSA08, BSAM12	RADMO-23B
RMC-23C	80	1.89	.375	.626	1.31	2AB12, 2EB12, BSA12, BSAM20	RADMO-23C
RMC-34A	80	1.89	.375	.626	1.31	2CB16, 2DB16	RADMO-34A
RMC-34B	160	2.00	.500	.626	1.63	2AB16, 2EB16, BSA16	RADMO-34B
RMC-42A	230	2.35	.625	.748	1.97	2AB24, 2EB24, BSA24	RADMO-42A

<sup>†††</sup> The RADMO-23A shaft extender is supplied with an adaptor block part number MB08-23.

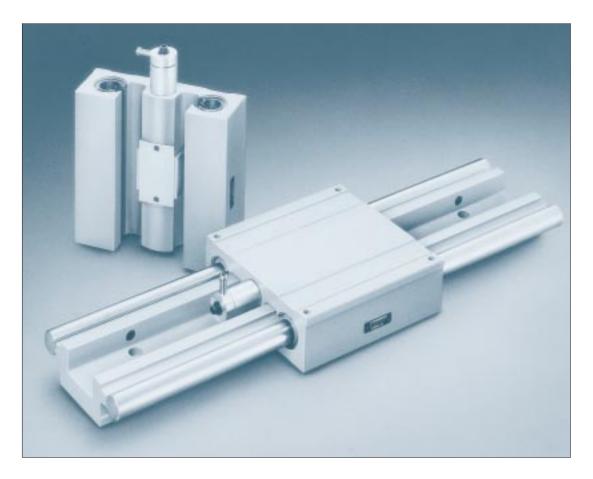
For more information, or to place an order, please contact Thomson Industries, at 1-800-55-4-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





## 2DA QuickSlide System with Brake

A manual locking mechanism for the Dual Shaft Rail System



#### 2DA QuickSlide\* System with Brake offers:

- A manual locking mechanism with infinite positioning capability.
- No carriage mounting surface deflection when the locking mechanism is activated.
- Immediate off-the-shelf availability in 1/2, 3/4 and 1 inch sizes.
- A locking mechanism that, when activated, will not apply an increase in load on the system's Ball Bushing\* bearing.
- Zero axial movement during the activation of the locking mechanism.
- A fully supported Dual Shaft assembly for maximum rigidity and unlimited travel.
- High load capacity in any direction.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

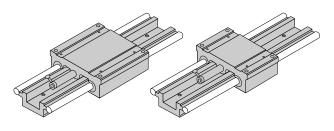


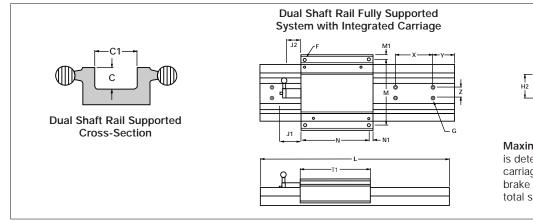


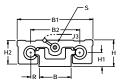
## 2DA QuickSlide<sup>\*</sup> System with Brake

### Dual Shaft Rail Fully Supported System

with Integrated Carriage and Locking Mechanism







#### Maximum Stroke Length is determined by subtracting the carriage length (T1 or T2) plus the brake handle length (J1) from the total system length.

Dual Shaft Ra	Dual Shaft Rail Fully Supported System with Integrated Carriage (Long Style)         (Dimensions in inches)												
Part	Nom.	Max.Load	Max.Load on	T1	Н	H1	H2	В	R	B1	B2	С	C1
Number	Shaft	on System <sup>(1)</sup>	One Bearing <sup>(1)</sup>										
	Dia.	(lbf)	(lbf)										
2DA-08-OOL	1/2	600	150	4.50	1.625	0.875	1.43	2.00	0.500	4.60	3.00	0.64	1.25
2DA-12-00L	3/4	1880	470	6.00	2.125	1.125	1.93	2.63	0.688	6.10	4.00	0.75	1.62
2DA-16-OOL	1	3120	780	7.50	2.625	1.375	2.44	3.25	0.875	7.60	5.00	0.99	2.00

(1) For rated travel life of 2 million inches.

Note: Manual Brake can be adjusted in order to position handle to any radial location.

Dual Shaft Rail Support Material: Aluminum Alloy Black Anodized. Standard length of one-piece Aluminum Dual Shaft Rails is 72".

Dual Shaft F	Rail Ful	ly Supp	oorted	Systen	n with	Integra	ted Ca	rriage	(Long S	Style)				(Dimensio	ons in inches)
Part	Ν	N1	M	M1	Х	Y	Z	J1	J2	J3	F	(	G	Max.	Carriage
Number												Bolt	Hole	Stroke Length	Part No.
2DA-08-OOL	4.00	0.25	4.00	0.30	4.00	2.00	0.75	1.63	1.19	0.88	#10-23	1/4	0.28	L-(6.13)	DSRC-08-SL
2DA-12-00L	5.25	0.37	5.25	0.42	6.00	3.00	1.00	1.63	1.19	1.00	1/4-20	<sup>5</sup> / <sub>16</sub>	0.34	L-(7.63)	DSRC-12-SL
2DA-16-OOL	6.75	0.37	6.75	0.42	6.00	3.00	1.25	1.63	1.19	1.00	5/16-18	3/8	0.41	L-(9.13)	DSRC-16-SL

Dual Shaft Ra	il Fully	Supported S	System with In	tegrated Carr	iage (Short Style)
Part	Nom.	T2	N2	Max.	Carriage
Number	Shaft			Stroke	Part
	Dia.			Length	No.
2DA-08-00M	1/2	3.50	3.00	L-(5.13)	DSRC-08-SM
2DA-12-00M	3/4	4.50	3.75	L-(6.13)	DSRC-12-SM
2DA-16-00M	1	6.00	5.25	L-(7.63)	DSRC-16-SM

System 2DA Standard Lengths(Lengths in inches)														
System	8″	12″	16″	18″	20″	24″	28″	30″	32″	36″	40″	42″	44″	48″
2DA-08					1									
2DA-12														

QuickSlide Br	ake Holding Force
System	Axial Holding Force (lbf.)
2DA-08	125
2DA-12	130
2DA-16	140

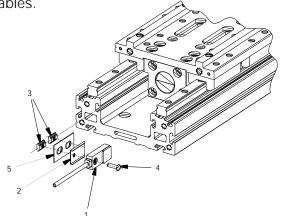
Custom Lengths and Delivery Information
Systems ordered in standard lengths and
longer lengths in increments of (X) are typically
shipped in two to three weeks. Custom length
systems are available and require three to four
weeks for delivery. For special requirements,
please contact the Thomson Systems
application engineering department.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



## Limit Switch/Sensor Package for AccuSlide\* 2HBM10 System

An inductive proximity sensor for end of travel limit and home position sensing. Standard part numbers are packages for either home positioning, end of travel limits or both home and end of travel limit sensing together. Options include NPN or PNP output types, normally closed or normally open output operations, and standard or varied frequencies. All sensors include 12-24 VDC supply voltages and 5 meter length cables.

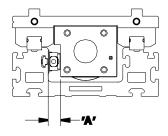


Part Number	Output Type	Output Operation	Frequency		
	Home	Sensor			
LSP2HBM10-N-1 LSP2HBM10-P-1	(1) NPN (1) PNP	(1) Normally Open (1) Normally Open	(1) Varied (1) Varied		
	End of Travel Sensors				
LSP2HBM10-N-2 LSP2HBM10-P-2	(2) NPN (2) PNP	<ul><li>(1) Normally Closed</li><li>(1) Normally Closed</li></ul>	(1) Standard (1) Standard		
Hom	Home Sensor & End of Travel Sensors				
LSP2HBM10-N-3 LSP2HBM10-P-3	(3) NPN (3) PNP	(1) N.O., (2) N.C. (1) N.O., (2) N.C.	(1) Var. (2) Std (1) Var. (2) Std		

Item	Quantity	Description
1	1	Proximity Sensor
2	1	Sensor Bracket
3	2	Tee Nut (TNUT01-M3)
4	1	Button Head Cap Screw
5	1	Shim Kit

End Plates not shown for clarity

Dimension "A"	Dimension "A"	Shim	Shim
(mm)	(in.)	Part No.	Thickness
up to 8.15 8.16-8.65 8.66-9.15 9.16-9.65	up to .320 .321340 .341360 .361380	none 22723A-02 22723A-04 22723A-02+ 22723A-04	0 .51mm (0.20") 1.02mm (0.40") 1.52mm (0.60")



End Plates not shown for clarity

Each 2HBM10 AccuSlide system is provided with access holes on each side of each end plate for passage of the sensor cable. Normal orientation of the sensor package will detract approximately 30mm from the effective stroke of the system at each end. Orientation of the sensor can be reversed so as to retain full system stroke. When Limit and Home Sensor Packages are ordered together with their respective Linear Motion System, the package is assembled to the system with their appropriate shim packs at no extra charge. When the End of Travel Limit Sensors are ordered in conjunction with the Home Position Sensor (the -3 option) the Home Sensor will be located between the Limit Sensors on the Linear Motion System.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

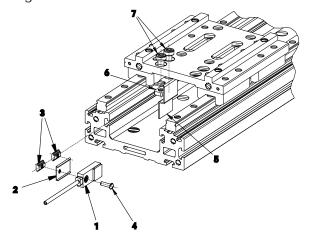




## Limit Switch/Sensor Package for AccuSlide\* 2HEM10 System

Part Number

An inductive proximity sensor for end of travel limit and home position sensing. Standard part numbers are packages for either home positioning, end of travel limits or both home and end of travel limit sensing together. Options include NPN or PNP output types, normally closed or normally open output operation and standard or varied freque All sensors include 12-24 VDC supply voltages and 5 meter length cables.



	Home Sensor				
	LSP2HEM10-N-1 LSP2HEM10-P-1	(1) NPN (1) PNP	(1) Normally Open (1) Normally Open	(1) Varied (1) Varied	
		End of Tra	vel Sensors		
	LSP2HEM10-N-2 LSP2HEM10-P-2	(2) NPN (2) PNP	<ul><li>(1) Normally Closed</li><li>(1) Normally Closed</li></ul>		
ions,	Hom	e Sensor & En	d of Travel Sensors		
encies. C	LSP2HEM10-N-3 LSP2HEM10-P-3	(3) NPN (3) PNP	(1) N.O., (2) N.C. (1) N.O., (2) N.C.	(1) Var. (2) Std (1) Var. (2) Std	

Output Type

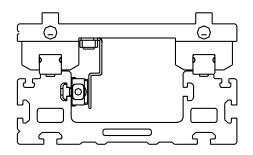
Item	Quantity	Description
1	1	Proximity Sensor
2	1	Sensor Bracket
3	2	Tee Nut (TNUT01-M3)
4	1	Button Head Cap Screw (M3)
5	1	Sensor Flag
6	1	Sensor Flag Nutplate
7	2	Low Head Cap Screw (M5)

**Output Operation** 

Frequency

End Plates not shown for clarity

Each 2HEM10 AccuSlide system is provided with access holes on each side of each end plate for passage of the sensor cable. Normal orientation of the sensor package will detract approximately 30mm from the effective stroke of the system at each end. Orientation of the sensor can be reversed so as to retain full system stroke. When Limit and Home Sensor Packages are ordered together with their respective Linear Motion System, the package is assembled to the system at no extra charge. When the End of Travel Limit Sensors are ordered in conjunction with the Home Position Sensor (the -3 option) the Home Sensor will be located between the Limit Sensors on the Linear Motion System.



End Plates not shown for clarity

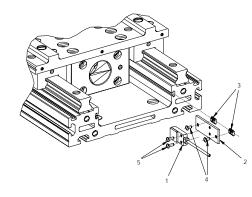
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





## Limit Switch/Sensor Package for AccuSlide\* 2HBM20 System

An inductive proximity sensor for end of travel limit and home position sensing. Standard part numbers are packages for either home positioning, end of travel limits or both home and end of travel limit sensing together. Options include NPN or PNP output types, normally closed or normally open output operations, and standard or varied frequencies. All sensors include 12-24 VDC supply voltages and 5 meter length cables.

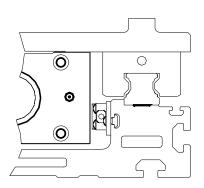


Part Number	Output Type	Output Operation	Frequency		
	Home	Sensor			
LSP2HBM20-N-1 LSP2HBM20-P-1	(1) NPN (1) PNP	(1) Normally Open (1) Normally Open	(1) Varied (1) Varied		
End of Travel Sensors					
LSP2HBM20-N-2 LSP2HBM20-P-2	(2) NPN (2) PNP	<ul><li>(1) Normally Closed</li><li>(1) Normally Closed</li></ul>			
Hom	Home Sensor & End of Travel Sensors				
LSP2HBM20-N-3 LSP2HBM20-P-3	(3) NPN (3) PNP	(1) N.O., (2) N.C. (1) N.O., (2) N.C.	(1) Var. (2) Std (1) Var. (2) Std		

Item	Quantity	Description
1	1	Proximity Sensor
2	1	Sensor Mounting Plate
3	2	Tee Nut (TNUT01-M3)
4	2	Button Head Cap Screw (M3)
5	2	Button Head Cap Screw (M3)

End Plates not shown for clarity

Each 2HBM20 AccuSlide system is provided with access holes on each side of each end plate for passage of the sensor cable. Normal orientation of the sensor package will detract approximately 30mm from the effective stroke of the system at each end. Orientation of the sensor can be reversed so as to retain full system stroke. When Limit and Home Sensor Packages are ordered together with their respective Linear Motion System, the package is assembled to the system with their appropriate shim packs at no extra charge. When the End of Travel Limit Sensors are ordered in conjunction with the Home Position Sensor (the -3 option) the Home Sensor will be located between the Limit Sensors on the Linear Motion System.



End Plates not shown for clarity

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

Accessories

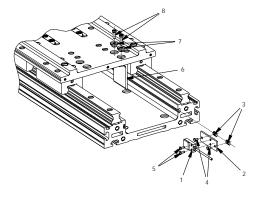




## Limit Switch/Sensor Package for AccuSlide\* 2HEM20 System

An inductive proximity sensor for end of travel limit and home position sensing. Standard part numbers are packages for either home positioning, end of travel limits or both home and end of travel limit sensing together. Options include NPN or PNP output types, normally closed or normally open output operations, and standard or varied frequencies. All sensors include 12-24 VDC supply voltages and 5 meter length cables.

Part Number	Output Type	Output Operation	Frequency		
	Home	Sensor			
LSP2HEM20-N-1 LSP2HEM20-P-1	(1) NPN (1) PNP	(1) Normally Open (1) Normally Open	(1) Varied (1) Varied		
	End of Travel Sensors				
LSP2HEM20-N-2 LSP2HEM20-P-2	(2) NPN (2) PNP	<ul><li>(1) Normally Closed</li><li>(1) Normally Closed</li></ul>			
Hom	Home Sensor & End of Travel Sensors				
LSP2HEM20-N-3 LSP2HEM20-P-3	(3) NPN (3) PNP	(1) N.O., (2) N.C. (1) N.O., (2) N.C.	(1) Var. (2) Std (1) Var. (2) Std		



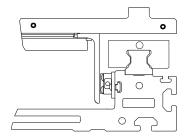
End Plates not shown for clarity

0*M5*0/

First in Linear Motion and Control Technology

Each 2HEM20 AccuSlide system is provided with access holes on each side of each end plate for passage of the sensor cable. Normal orientation of the sensor package will detract approximately 30mm from the effective stroke of the system at each end. Orientation of the sensor can be reversed so as to retain full system stroke. When Limit and Home Sensor Packages are ordered together with their respective Linear Motion System, the package is assembled to the system at no extra charge. When the End of Travel Limit Sensors are ordered in conjunction with the Home Position Sensor (the -3 option) the Home Sensor will be located between the Limit Sensors on the Linear Motion System.

Item	Quantity	Description
1	1	Proximity Sensor
2	1	Sensor Mounting Plate
3	2	Tee Nut (TNUT01-M3)
4	2	Button Head Cap Screw (M3)
5	2	Button Head Cap Screw (M3)
6	1	Sensor Flag
7	2	Hat Washer
8	2	Low Head Cap Screw (M4)



End Plates not shown for clarity

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



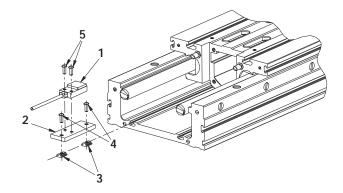
Accessories



## Limit Switch/Sensor Package for SuperSlide\* 2RBM12 and 2REM12 Systems

An inductive proximity sensor for end of travel limit and home position sensing. Standard part numbers are packages for either home positioning, end of travel limits or both home and end of travel limit sensing together. Options include NPN or PNP output types, normally closed or normally open output operations, and standard or varied frequencies. All sensors include 12-24 VDC supply voltages and 5 meter length cables.

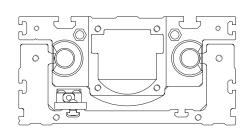
Part Number	Output Type	Output Operation	Frequency		
	Home	Sensor			
LSP2RM12-N-1 LSP2RM12-P-1	(1) NPN (1) PNP	(1) Normally Open (1) Normally Open	(1) Varied (1) Varied		
	End of Travel Sensors				
LSP2RM12-N-2 LSP2RM12-P-2	(2) NPN (2) PNP	<ul><li>(1) Normally Closed</li><li>(1) Normally Closed</li></ul>			
Hom	Home Sensor & End of Travel Sensors				
LSP2RM12-N-3 LSP2RM12-P-3	(3) NPN (3) PNP	(1) N.O., (2) N.C. (1) N.O., (2) N.C.	(1) Var. (2) Std (1) Var. (2) Std		



Item	Quantity	Description
1	1	Proximity Sensor
2	1	Sensor Mounting Plate
3	2	Tee Nut (TNUT01-M3)
4	2	Button Head Cap Screw (M3)
5	2	Button Head Cap Screw (M3)

End Plates not shown for clarity

Each 2RBM12 and 2REM12 SuperSlide system is provided with access holes on each side of each end plate for passage of the sensor cable. Normal orientation of the sensor package will detract approximately 35mm from the effective stroke of the system at each end. Orientation of the sensor can be reversed so as to retain full system stroke. When Limit and Home Sensor Packages are ordered together with their respective Linear Motion System, the package is assembled to the system at no extra charge. When the End of Travel Limit Sensors are ordered in conjunction with the Home Position Sensor (the -3 option) the Home Sensor will be located between the Limit Sensors on the Linear Motion System.



End Plates not shown for clarity

For more information, or to place an order, please contact Thomson Industries, at 1-800-55-4-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

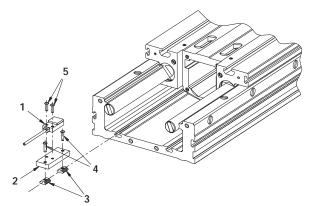




## Limit Switch/Sensor Package for SuperSlide\* 2RBM16 and 2REM16 System

An inductive proximity sensor for end of travel limit and home position sensing. Standard part numbers are packages for either home positioning, end of travel limits or both home and end of travel limit sensing together. Options include NPN or PNP output types, normally closed or normally open output operations, and standard or varied frequencies. All sensors include 12-24 VDC supply voltages and 5 meter length cables.

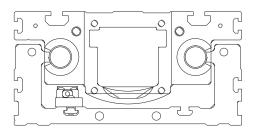
Part Number	Output Type	Output Operation	Frequency		
	Home	Sensor			
LSP2RM16-N-1 LSP2RM16-P-1	(1) NPN (1) PNP	(1) Normally Open (1) Normally Open	(1) Varied (1) Varied		
	End of Travel Sensors				
LSP2RM16-N-2 LSP2RM16-P-2	(2) NPN (2) PNP	(1) Normally Closed (1) Normally Closed			
Hom	Home Sensor & End of Travel Sensors				
LSP2RM16-N-3 LSP2RM16-P-3	(3) NPN (3) PNP	(1) N.O., (2) N.C. (1) N.O., (2) N.C.	(1) Var. (2) Std (1) Var. (2) Std		



Item	Quantity	Description
1	1	Proximity Sensor
2	1	Sensor Mounting Plate
3	2	Tee Nut (TNUT01-M3)
4	2	Button Head Cap Screw (M3)
5	2	Button Head Cap Screw (M3)

End Plates not shown for clarity

Each 2RBM16 and 2REM16 SuperSlide system is provided with access holes on each side of each end plate for passage of the sensor cable. Normal orientation of the sensor package will detract approximately 35mm from the effective stroke of the system at each end. Orientation of the sensor can be reversed so as to retain full system stroke. When Limit and Home Sensor Packages are ordered together with their respective Linear Motion System, the package is assembled to the system at no extra charge. When the End of Travel Limit Sensors are ordered in conjunction with the Home Position Sensor (the -3 option) the Home Sensor will be located between the Limit Sensors on the Linear Motion System.



#### End Plates not shown for clarity

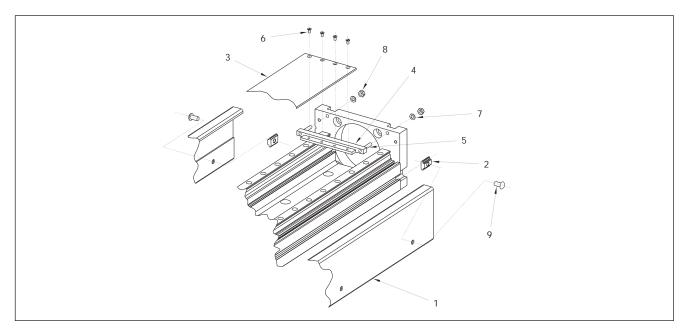
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





## Shroud Cover for AccuSlide\* 2HBM10 and 2HEM10 Systems

The AccuSlide Shroud Cover is designed to protect the AccuSlide system from contaminants and particulate matter with a minimal reduction in system stroke length. The shroud cover is a three-piece design, consisting of two side shrouds and one top shroud, each made of grey anodized aluminum. The AccuSlide system carriage top is designed with pedestal mounts so as to allow the passage of the carriage assembly without interference with the cover. This arrangement leaves two uncovered slots that run the length of the stroke. Bellows way covers are also available for full coverage of the AccuSlide system (see page 291).



Part No. ASC2HM10 x (length in mm) includes the following components:

Item	Quantity	Description
1	2	Side Shroud
2	as req'd	TNUT02-M4
3	1	Top Shroud
4	2	Top Shroud Bracket
5	4	Set Screw M3
6	8	Flat Head Screw M2
7	4	Washer
8	4	Hexagonal Nut M3
9	as req'd	Button Head Cap Screw M4

Each shroud cover for the 2HBM10 and 2HEM10 AccuSlide systems is provided with all of the necessary hardware to mount the covers. On the top shroud this includes an end mounting bracket at each end of the system with set-screws and associated nuts and washers. These set screws pull the brackets outboard in the axial direction, thus tensioning the top shroud and removing most of the sag in the cover on long axis systems. The side shrouds are attached to the system via tee nuts and button head cap screws. The screw/nut assemblies on the side shrouds are spaced every 75 mm.

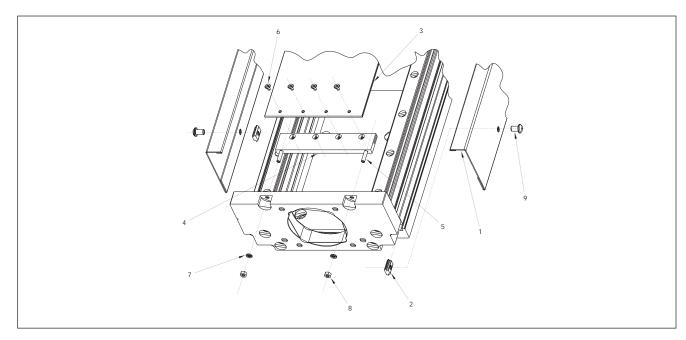
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





## Shroud Cover for AccuSlide\* 2HBM20 and 2HEM20 Systems

The AccuSlide Shroud Cover is designed to protect the AccuSlide system from contaminants and particulate matter with a minimal reduction in system stroke length. The shroud cover is a three-piece design, consisting of two side shrouds and one top shroud, each made of grey anodized aluminum. The AccuSlide system carriage top is designed with pedestal mounts so as to allow the passage of the carriage assembly without interference with the cover. This arrangement leaves two uncovered slots that run the length of the stroke. Bellows way covers are also available for full coverage of the AccuSlide system (see page 291).



Part No. ASC2HM20 x (length in mm) includes the following components:

Item	Quantity	Description
1	2	Side Shroud
2	as req'd	TNUT04-M6
3	1	Top Shroud
4	2	Top Shroud Bracket
5	4	Set Screw M4
6	8	Flat Head Screw M3
7	4	Washer
8	4	Hexagonal Nut M4
9	as req'd	Button Head Cap Screw M6

Each shroud cover for the 2HBM20 and 2HEM20 AccuSlide systems is provided with all of the necessary hardware to mount the covers. On the top shroud this includes an end mounting bracket at each end of the system with set-screws and associated nuts and washers. These set screws pull the brackets outboard in the axial direction, thus tensioning the top shroud and removing most of the sag in the cover on long axis systems. The side shrouds are attached to the system via tee nuts and button head cap screws. The screw/nut assemblies on the side shrouds are spaced every 120 mm.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





## **TEB Spring Set Electric Brakes**

For use on Ball Screw Assembly, SuperSlide and PowerSlide Linear Motion Systems



#### **Electric Brake:**

- Mounts to support end of all SuperSlide\*, PowerSlide\* and Ball Screw assembly systems
- Engages upon loss of a 24-VDC Power Supply (see TBC-7 data on page 306)
- Provides resistance to back drive rotation of ball screws due to gravitational force when power is interrupted to the brake unit
- Pre-burnished for maximum torque capacity
- Standard NEMA 23, 34 and 42
  mounting patterns for easy field retrofit
- Compact size minimizes change to overall system envelope
- Easily integrates with TBC-7 Brake Controller to offer a complete braking solution, see page 306

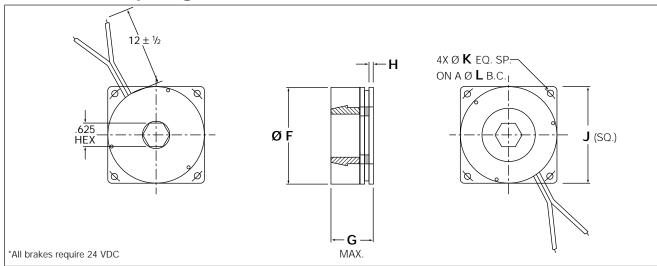
For immediate Application Engineering Assistance contact the Thomson Toll Free Helpline\*: 8 800-554-THOMSON (800-554-8466)

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

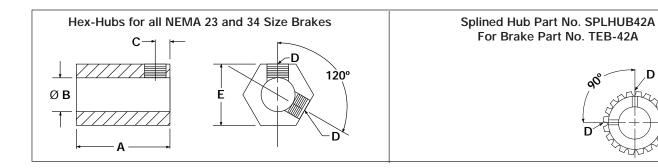




## **Thomson Spring Set Electric Brakes**



Spring Set Br	rake Data														
Electric Brake	Frame	Static Torque		-	Dii	mensio	ons (in.)		Brake Hub	Brake Adaptor	Used with System				
Part No.	Size	Torque (lbf-in.)	F	G	Н	J	К	L	HEX	Part No	Part No	Part Number			
TEB23A	NEMA 23	NEMA 23	2.25	1.10	0.11	2.25	0.22	2.625	5/8	HEXHUB23A	MB08-23	2DB08			
TEB23B	NEMA 23	NEMA 23	2.25	1.10	0.11	2.25	0.22	2.625	5/8	HEXHUB23B	None Required	2AB08, 2CB08, 2CB12, 2DB12, 2EB08, BSA08, BSDAM12			
TEB23C	NEMA 23	NEMA 23	2.25	1.10	0.11	2.25	0.22	2.625	5/8	HEXHUB23C	B23C None Required 2AB12, 2EB12, BSA12, BSAM20				
TEB23D	NEMA 23	NEMA 23	2.25	1.10	0.11	2.25	0.22	2.625	5/8	HEXHUB23D	(HUB23D None Required 2HBM10, 2RBM12				
TEB23E	NEMA 23	NEMA 23	2.25	1.10	0.11	2.25	0.22	2.625	5/8	HEXHUB23E	None Required	2NBM20, 2RBM16			
TEB23F	NEMA 23	NEMA 23	2.25	1.10	0.11	2.25	0.22	2.625	7/8	HEXHUB23F	EBA23F	2HEM10, 2NEM20, 2REM12, 2REM16			
TEB34A	NEMA 34	NEMA 34	2.25	1.10	0.11	3.25	0.22	3.875	5/8	HEXHUB34A	None Required	2DB16, 2CB16			
TEB34B	NEMA 34	NEMA 34	2.25	1.31	0.11	3.25	0.22	3.875	7/8	HEXHUB34B	None Required	2AB16, 2EB16, BSA16			
TEB34C	NEMA 34	NEMA 34	2.25	1.31	0.11	3.25	0.22	3.875	7/8	HEXHUB34C	None Required	2HBM20			
TEB34D	NEMA 34	NEMA 34	2.25	1.31	0.11	3.25	0.22	3.875	7/8	HEXHUB34D		2HEM20			
TEB42A	NEMA 42	NEMA 42	4.19	2.38	0.36	4.25	0.27	4.950	Splined	SPLHUB42A	None Required	2AB24, 2EB24, BSA24			



Brake Hub Da	Data									
Brake Hub			Dimensions			Used with System	Used with			
Part No.	А	В	С	D <sup>(1)</sup>	E	Part Number	Spring Set Brake			
HEXHUB23A	1.53 in.	3/16 in.	0.15 in.	#10-32	32 5/8 in. 2DB08					
HEXHUB23B	1.31 in.	1/4 in.	0.26 in.	#10-32	5/8 in.	2AB08, 2CB08, 2CB12, 2DB12, 2EB08, BSA08, BSDAM12	TEB23B			
HEXHUB23C	1.67 in.	3/8 in.	0.44 in.	#10-32.	5/8 in.	2AB12, 2EB12, BSA12, BSAM20	TEB23C			
HEXHUB23D	20 mm	8 mm	5 mm	M4	5/8 in.	2HBM10, 2RBM12	TEB23D			
HEXHUB23E	20 mm	10 mm	5 mm	M4	5/8 in.	2NBM20, 2RBM16	TEB23E			
HEXHUB23F	15.6 mm	12 mm	10.8 mm	M4	7/8 in.	2HEM10, 2NEM20, 2REM12, 2REM16	TEB23F			
HEXHUB34A	1.67 in.	3/8 in.	0.44 in.	#10-32	5/8 in.	2DB16, 2CB16	TEB34A			
HEXHUB34B	0.82 in.	1/2 in.	0.21 in.	#10-32	7/8 in.	2AB16, 2EB16, BSA16	TEB34B			
HEXHUB34C	32 mm	14 mm	6 mm	M5	7/8 in.	2HBM20	TEB34C			
HEXHUB34D	22 mm	15 mm	6 mm	M5	7/8 in.	2HEM20	TEB34D			
SPLHUB42A	1.66 in.	5/8 in.	0.50 in.	1/4 20	-	2AB24, 2EB24, BSA24	TEB42A			

NOTE 1: Suggested torque for hub set screws are 36 in-lb for #10-32, M4, M5, and 87 in-lb for 1/4-20. Additionally, it is suggested a serviceable thread locking compound be used.

#### For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

n



## **TBC-7 ELECTRIC BRAKE CONTROLLER**



#### Features:

- Operates Thomson's TEB series electric brakes or any 24 VDC spring set brake, 1 amp max
- Optical isolated control input
- Direct connection to any PLC, switch, relay, or computer, or CNC output.
- Black textured ABS enclosure with mounting feet, U.L. 94VO rated
- Overexcite spiking dramatically reduces brake response time
- Underexcite feature for cooler operating brake
- 115/220 VAC 50/60 Hz input, switch selectable
- Fused for protection
- Solid state design for highest reliability

The TBC-7 Brake Control/Power Supply is designed to operate most 24 VDC rated brakes. Flexible control inputs allow the brake to be switched on and off in a variety of ways:

- a 3 to 28 volt DC signal
- any dry contact switch or relay
- function as a simple power supply, switching the brake on and off with input power.

This flexibility allows the TBC-7 to interface directly to almost any PLC, switch, relay, computer, CNC, or motion controller output.

Incorporating the latest in MOSFET switching technology, the TBC-7 features overexcite/ underexcite operation. Overexcite operation applies a high voltage spike to decrease the brake's response time, while underexcite operation reduces the brake's average operating current making for a much cooler running brake. The TBC-7 may be powered by 115 VAC or 220 VAC, and is switch selectable. In addition, it has an optically isolated control input which completely eliminates noise feedback into the control system.

#### **Electrical Specifications:**

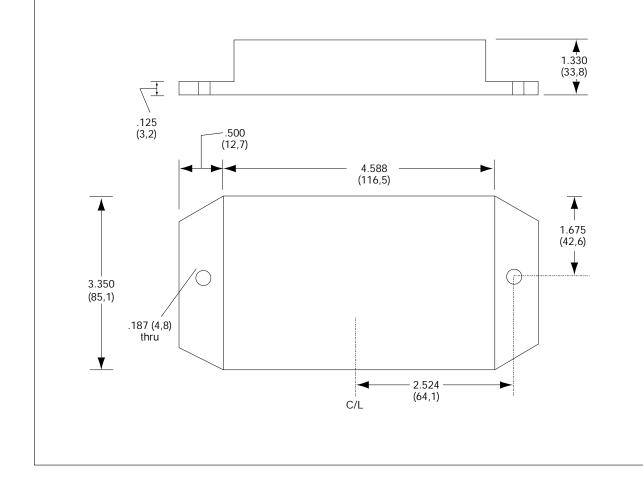
Input Power:	115/220VAC switch selectable
	50/60 Hz single phase 1 amp maximum
Output Power:	Underexcite/overexcite sequence suitable for any 24VDC
	brake rated up to 1.0 amp
Overexcite:	36VDC nominal for 200ms
Underexcite:	18VDC after overexcite complete
Control Interface:	H11AA1 type optoisolator for voltage source switching or internal pullup to own supply for dry contact switching

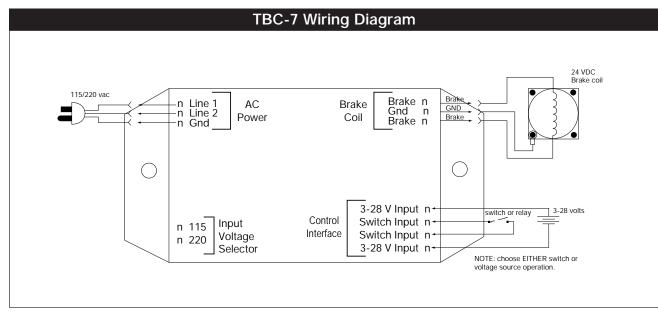
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





#### TBC-7 Dimensions



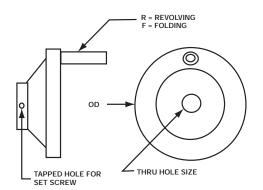


For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





## Handwheels for Manual Actuation of SuperSlide\* Systems



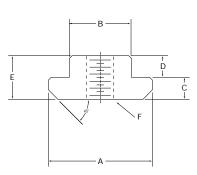
Part No.	O.D.	Thru Hole	Handle	
HW4R-188	4.0 inch	0.188 in	Revolving	
HW4R-250	4.0 inch	0.250 in	Revolving	
HW4R-375	4.0 inch	0.375 in	Revolving	
HW4R-500	4.0 inch	0.500 in	Revolving	
HW4R-625	4.0 inch	0.625 in	Revolving	
HW4R-M8	4.0 inch	8 mm	Revolving	
HW4R-M10	4.0 inch	10 mm	Revolving	
HW4R-M14	4.0 inch	14 mm	Revolving	
HW4R-747	4.0 inch	0.747 in	Revolving	

Part No.	O.D.	Thru Hole	Handle
HW4F-188 HW4F-250 HW4F-375 HW4F-500 HW4F-625 HW4F-M8 HW4F-M10 HW4F-M14 HW4F-747	4.0 inch 4.0 inch 4.0 inch 4.0 inch 4.0 inch 4.0 inch 4.0 inch 4.0 inch 4.0 inch	0.188 in 0.250 in 0.375 in 0.500 in 0.625 in 8 mm 10 mm 14 mm 0.747 in	Folding Folding Folding Folding Folding Folding Folding Folding

Part No.	O.D.	Thru Hole	Handle
HW5R-188	5.0 inch	0.188 in	Revolving
HW5R-250	5.0 inch	0.250 in	Revolving
HW5R-375	5.0 inch	0.375 in	Revolving
HW5R-500	5.0 inch	0.500 in	Revolving
HW5R-625	5.0 inch	0.625 in	Revolving
HW5R-M8	5.0 inch	8 mm	Revolving
HW5R-M10	5.0 inch	10 mm	Revolving
HW5R-M14	5.0 inch	14 mm	Revolving
HW5R-747	5.0 inch	0.747 in	Revolving

Part No.	O.D.	Thru Hole	Handle
HW5F-188	5.0 inch	0.188 in	Folding
HW5F-250	5.0 inch	0.250 in	Folding
HW5F-375	5.0 inch	0.375 in	Folding
HW5F-500	5.0 inch	0.500 in	Folding
HW5F-625	5.0 inch	0.625 in	Folding
HW5F-M8	5.0 inch	8 mm	Folding
HW5F-M10	5.0 inch	10 mm	Folding
HW5F-M14	5.0 inch	14 mm	Folding
HW5F-747	5.0 inch	0.747 in	Folding

## **T-Nuts for Mounting**



Standard T-Nu	ut Dimen	sions				(Dimen	nsions in mm)			
Part Number			Dimen	sions			Lload in conjunction with Systems			
Part Number	А	В	С	D	E	F	Used in conjunction with Systems			
TNUT-01-M3	7	4	1,75	1,25	3	M3	2RxM12, 2HxM10, 2HxM20			
TNUT-02-M4	9,5	5,5	2,25	1,75	4	M4	2NxM20, 2RxM16, 2HxM10			
TNUT-03-M4	12	7	2,5	2,5	5	M4	2RxM12			
TNUT-03-M5	12	7	2,5	2,5	5	M5	2RxM12			
TNUT-04-M4	16,5	7,9	4,8	1,2	6	M4	2NxM20, 2RxM16, 2HxM20,			
TNUT-04-M5						M5	2GEM25			
TNUT-04-M6						M6				
TNUT-05-M4	19,5	9,8	5,8	2,8	8,6	M4				
TNUT-05-M5						M5	2GEM35			
TNUT-05-M6						M6				
TNUT-05-M8						M8				

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



$$\Gamma_{\text{RMS}} = \sqrt{\frac{t_a (T_A)^2 + t_{cv} (T_{cv})^2 + t_d (T_D)^2 + t_h (T_H)^2}{t_a + t_{cv} + t_d + t_h}} \qquad (N \bullet m)$$

THOMSON INDUSTRIES, INC.

 $J_{M} \bullet i + J_{g} \bullet$ 

# ENGINEERING SUPPORT

Engineering Guide for Systems, Slides & Stages, and Motion Control

N • m

d

#### SYSTEM SIZING CALCULATIONS FOR:

- Inch size SuperSlide\* ball screw actuated systems
- Metric size SuperSlide ball screw actuated systems
- Metric size SuperSlide belt actuated systems
- Turbo Module<sup>\*</sup> belt actuated systems

 $P_a \bullet d_0$ 

1000 • 2 • i • X<sub>q</sub> • X<sub>b</sub>

 $T_L =$ 

## First in Linear Motion and Control Technology

# $\begin{array}{l} T_A \ = \ T_J + T_F + T_g + T_e \ (N \ast m) \\ T_{ev} \ = \ T_F + T_g \ast T_e \ (N \ast m) \\ T_D \ = \ T_J - T_F - T_g - T_e \ (N \ast m) \\ T_H \ = \ -T_F + T_g \ast T_e \ (N \ast m) \end{array}$

## www.thomsonindustries.com

For Application Engineering assistance contact the Thomson Technical HelpLine at 1-800-554-8466. "Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



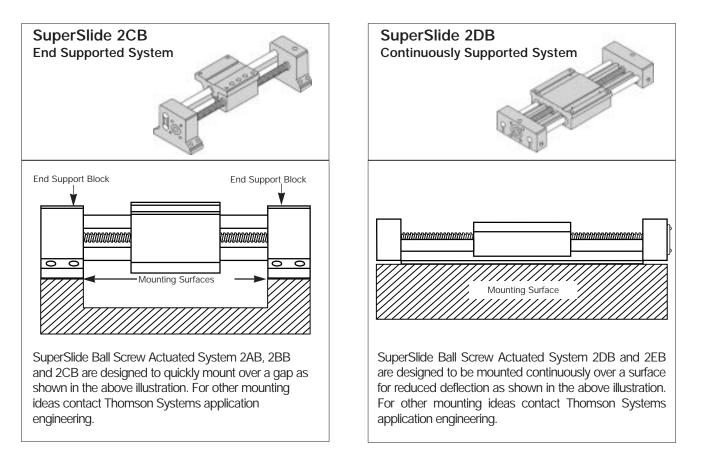
## INCH SuperSlide\* Ball Screw Actuated System System Selection

To determine the system that fits your **SuperSlide Ball Screw Actuated System** application requirements the following design criteria needs to be evaluated:

- System Support Requirements
- System Stroke Length
- Maximum Allowable Shaft Deflection
- Required Travel Life
- Force on the Most Heavily Loaded Bearing
- Load Correction Factor
- Load/Life Requirements Linear Bearings
- Load/Life Requirements Ball Screws
- Motion (Move) Profile (Velocity, Acceleration)
- Maximum Acceptable Travel Rate
- Maximum Compressive (Column) Load
- Torque Calculations
- Size Motor Using Torque/Speed Curves

After each criteria is determined, system selection will become quick and easy. The following procedure will guide you through the proper system selection.

Step 1. Based on your application needs determine the mounting support requirements.



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

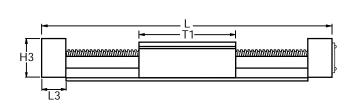




#### System Stroke Length

Step 2. Determine the **Stroke Length** ( $L_s$ ) required. The maximum **Stroke Length** ( $L_s$ ) is determined by subtracting the carriage length (T1) and twice end block lengths (L3) from the total system length (L). The application or required stroke length should not exceed this number.

 $L_{S} = L - (T1 + 2 L3)$ 



Should your application require the use of bellows way covers, it is important to recognize that the bellows will detract from the available stroke of the system. The bellows will retract to approximately 14% of the available stroke at each end of the system. The **stroke length with bellows** ( $L_{S/B}$ ) is calculated by subtracting 2 times the **stroke** ( $L_S$ ) times .14 from the **stroke** ( $L_S$ ).

 $L_{S/B} = L_S - (2 \times L_S \times .14)$ 

**Standard Length and Delivery.** For each SuperSlide Ball Screw Actuated System there is a standard length chart and delivery information that also includes the standard length increment and the maximum system length. Selecting a standard system length will minimize shipment time. Once you have selected a length that best fits your application requirements, simply determine the maximum stroke length. The required stroke length should not exceed this number. Refer to the product specification section for the standard length charts not shown.

SuperSlide System 2DB Standard Lengths													(Ler	ngth	ns ir	n ind	ches)	
System	12	16	18	20	24	28	30	32	36	40	42	44	48	54	60	72	Х	MAX
2DB-08										I							4	48
2DB-12																	6	72
2DB-16																	Б	<b>S</b>

#### Custom Lengths and Delivery Information

Systems ordered in standard lengths and longer lengths in increments of (X) are typically shipped in two to three weeks. Custom length systems are available and require three to four weeks for delivery. Lengths exceeding MAX length will require butt joints and will need 4 to 6 weeks for delivery. For special requirements, please contact the Thomson **Systems** application engineering department.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

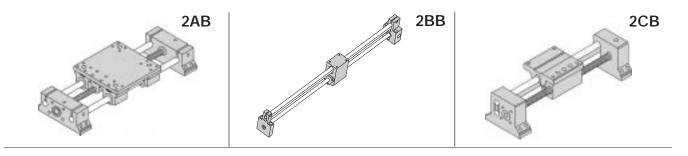


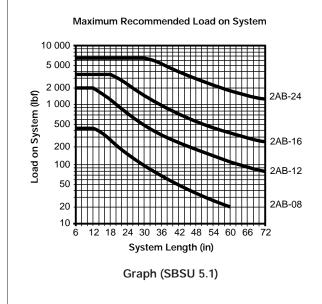


## INCH SuperSlide\* Ball Screw Actuated System End Supported System

Maximum Allowable Deflection

Step 3. Determine if the system selected meets the Maximum Allowable Deflection criteria.





In end supported applications the bearing system can withstand an enormous amount of system deflection and still run smoothly due to the universal self-aligning feature of the Super Smart Ball Bushing\* bearing. In a ball screw actuated end supported application, deflection is limited by the small amount of radial load that a ball screw assembly can withstand. Step 3 will determine if the system size and length can handle the applied load. For SuperSlide Ball Screw Actuated System 2AB there is a graph (SBSU 5.1) that gives the maximum recommended load on the system based on shaft and ball screw deflection. To determine the system that best meets your application requirements, simply enter the graph with the total load on the system and the overall system length. Select a system characteristic curve that is above or to the right of the plotted point. To determine the actual deflection see the Engineering Support Appendix, page 378.

## **Travel Life**

Step 4. Determine the Required Application Travel Life (in).

 $L_t = 2 \cdot s \cdot f \cdot L_h \cdot 60$ 

L<sub>t</sub> = required travel life (in) s = stroke (in) f = frequency (cycles/minute) L<sub>h</sub> = service life (hrs)

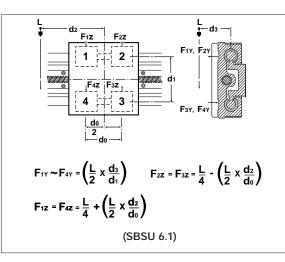
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





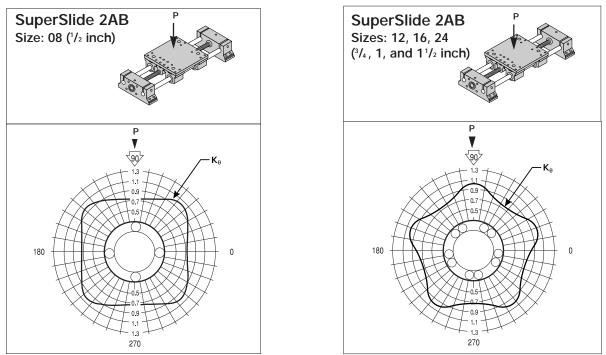
### System Loading

Step 5. Determine the **Force on the Most Heavily Loaded Bearing.** When selecting a SuperSlide Ball Screw Actuated System, it is necessary to evaluate the bearing forces that are generated based on the position of the load and its movement during application. The free body diagram (SBSU 6.1) is an example of the type of calculations that are required when determining resultant bearing forces. For other free body diagram examples see **Load Considerations** in the **Engineering Support Appendix**, page 377. The determination of the force on the most heavily loaded bearing allows you to enter the load life graph and select the system that best fits your application needs.



Step 6. Determine the **Load Correction Factor** ( $K_{\theta}$ ). The dynamic load capacity of SuperSlide Ball Screw Actuated system is determined by the orientation of the system and the direction of the resultant bearing load. To determine the load correction factor, simply enter the polar graph with the applied or resultant load direction until it intersects the polar curve. If the load correction factor is 1,0 the resultant force ( $P_{resultant}$ ) is equal to the **Force on the Most Heavily Loaded Bearing** ( $P_{max}$ ). If the direction of the resultant bearing load cannot be determined, then use the minimum K<sub>a</sub> value (0,7 for closed bearings and 0,5 for open bearings).

### Load Correction Factor Polar Charts



These Load Correction Factor Polar charts show values of  $K_{\theta}$  for load orientations on a single Ball Bushing<sup>\*</sup> bearing. Appropriate load orientation should be considered for the most heavily loaded Ball Bushing bearing.

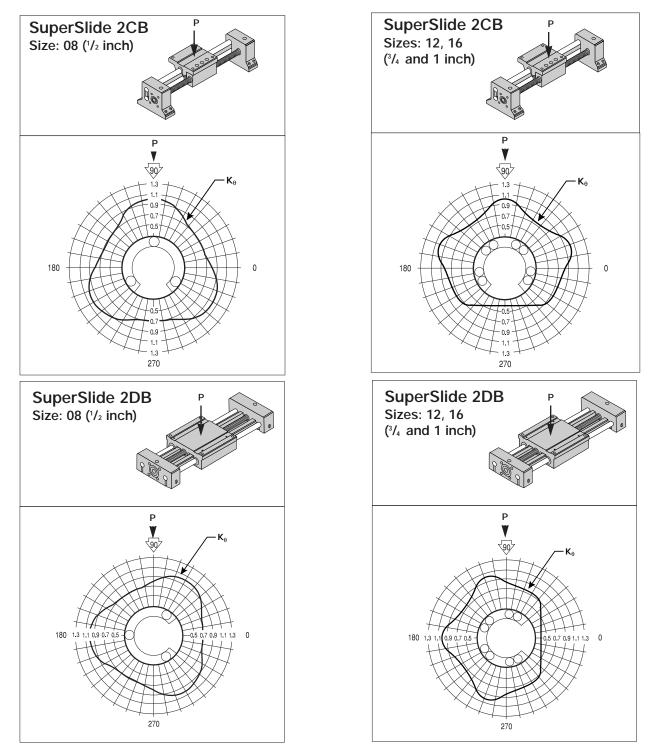
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.







Load Correction Factor Polar Charts



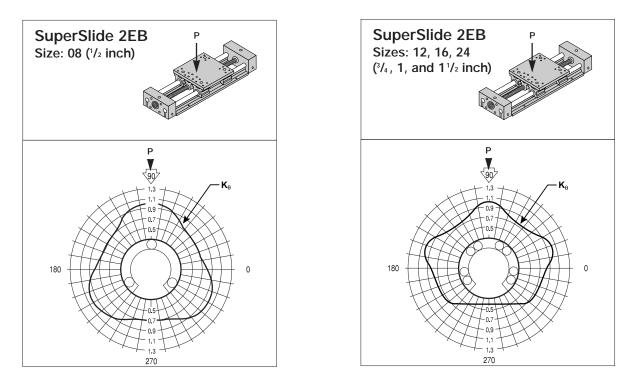
These Load Correction Factor Polar charts show values of  $K_{_{\theta}}$  for load orientations on a single Ball Bushing<sup>\*</sup> bearing. Appropriate load orientation should be considered for the most heavily loaded Ball Bushing bearing.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





Load Correction Factor Polar Charts



These Load Correction Factor Polar charts show values of  $K_{\theta}$  for load orientations on a single Ball Bushing<sup>\*</sup> bearing. Appropriate load orientation should be considered for the most heavily loaded Ball Bushing bearing.

If the Load Correction Factor is less than 1.0 the following formula should be used to determine the Corrected Force on the Most Heavily Loaded Bearing.

	P <sub>max</sub>	= Force on the Most Heavily Loaded Bearing (N)
$P_{max} = P_{resultant}$	<b>P</b> <sub>resultant</sub>	= Resultant of Externally Applied loads (N)
$\mathbf{K}_{\theta}$	$\mathbf{K}_{\mathbf{\theta}}$	= Load Correction Factor

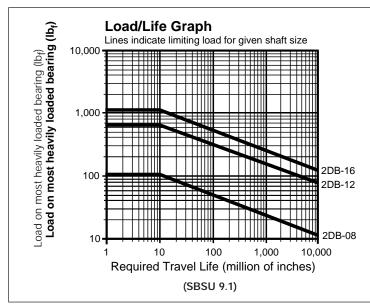
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



Page 315

## INCH SuperSlide\* Ball Screw Actuated System System Loading (continued)

Step 7. Select the system that meets the application load and life requirements.

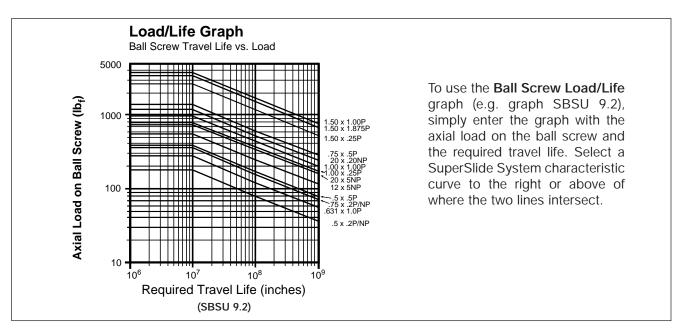


For each SuperSlide Belt Actuated System there is a graph (e.g. graph SBSU 9.1) that allows for system selection based on the Required Travel Life and the Force on the Most Heavily Loaded Bearing. To determine the system which best meets your application requirements, simply enter the graph with your Required Travel Life from step 4 and the Corrected Force on the Most Heavily Loaded Bearing from 6. Select step а system characteristic curve that is above or to the right of the plotted point.

**Note:** Use **Corrected Force on the Most Heavily Loaded Bearing** if load correction factor is less than 1.0.

## Ball Screw Load/Life

Step 8. Confirm that the **Ball Screw** in the SuperSlide selected will achieve **Load and Life requirements**. Once the SuperSlide Ball Screw Actuated System is selected refer to the Ball Screw Compatibility charts on the next two pages and select a ball screw that meets your application needs. With the ball screw axial load and the required travel life enter the graph (SBSU 9.2) below.



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





**Ball Screw and System Compatibility** 

SuperSlic														
P-Preloaded NP- Non-Preloaded									Ċ	.O	0			
SuperSlide 2	AB Bal	I Screv	N Com	patibil	ity Cha	art								
Part Number				Ball S	Screw	Diamet	ter and	Lead					Metric	:
	.50 x .20	.50 x .20	.50 x .50	.631 x 1.0	.75 x .20	.75 x .20	1.0 X .25	1.0 X 1.0	1.5 X .25	1.5 X 1.0	1.5 X 1.875	12 X 5	20 X 5	20 X 20
	NP	Р	Р	Р	NP	Р	Р	Р	Р	Р	Р	NP	NP	NP
2AB-08														
2AB-12														
2AB-12 2AB-16														

SuperSlid End Support		to the											
SuperSlide 2B	B/2CB Lead	Screv	v or Ba	all Scre	ew Act	uator	Compa	atibility	y Char	t			
Part Nu	mber		Lead S	Screw	or Ball	Screw	Diame	eter and	d Lead			Metric	
		.375 x .10 .375 x .25 .375 x .50 .375 x .75 .375 x .1.0 .50 x .20 50 x .20 .75 x .20 12 X 5 16 X 5 20 X 5											
		D	D	D	D	D	ND	D	ND	D	ND	ND	ND

	.375 X.10	.3/5 X.25	.375 X .50	.3/5 X./5	.375 X I.U	.50 x .20	50 X .20	.75 X .20	.75 x .20	12 X 5	10 X 5	20 X 5
	Р	Р	Р	Р	Р	NP	Р	NP	Р	NP	NP	NP
2BB-06												
2CB-08												
2CB-12												
2CB-16												

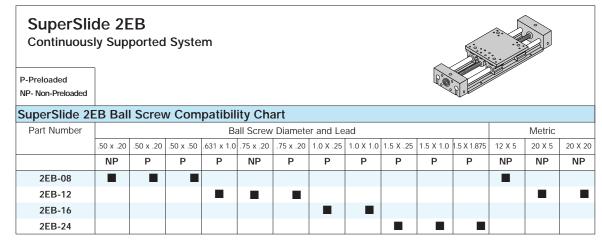
SuperSlide 2DB Continuously Supported System														
P-Preloaded														
NP- Non-Preloaded						$\nabla$								
SuperSlide 2	DB Bal	Screv	w and	Screw	Actua	tor Co	mpatil	oility C	hart					
Part Number			Le	ad Scr	ew or E	3all Sci	rew Dia	ameter	and Le	ead			Me	tric
	.375 x .1	.375 x .25	.375 x .50	.375 x .75	.375 x 1.0	.50 x .20	.50 x .20	.50 x .50	.631 x 1.0	.75 x .20	.75 x .20	.75 x.50	12 x 5	20 x 5
	Р	Р	Р	Р	Р	Р	NP	Р	Р	Р	NP	Р	NP	NP
2DB-08														
2DB-12														
2DB-16														

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries. **Engineering Support - Inch** 

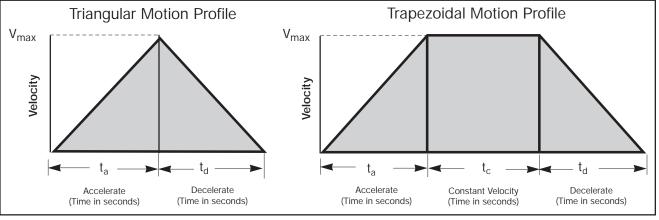
Ball Screw and System Compatibility (continued)



## Motion Profile

A typical linear ball screw actuated application normally consists of a series of motion profiles. The drive torque required to move the system should be evaluated for each motion profile. There are two basic motion profile types. The first and most simple move is a triangular motion profile which consists of two legs. The first leg is for acceleration and the second is for deceleration. The second motion profile type is trapezoidal which consists of an acceleration leg; a leg of constant velocity and a deceleration leg.

Step 9. Determine the Motion Profile that fits your application requirements. Calculate  $V_{max}$  and a.



#### Triangular Motion Profile:

Assume:  $t_a = t_d = t/2$  and  $x_a = x_d = x/2$ Then:  $V_{avg} = x/t$ 

$$V_{avg} = X/t$$
  
 $V_{max} = 2 \cdot V_{avg} = 2x/t$   
 $a = V_{max}/t_a = 4x/t^2$ 

$$a = v_{max} / l_a = 4 x / l^2$$

- Where:  $a = acceleration (in/s^2)$ 
  - d = Deceleration (in/s<sup>2</sup>)
  - x = Total Distance (in)
  - $x_a$  = Distance to Accelerate (in)
  - $x_c$  = Distance at Constant Velocity (in)
  - $x_d$  = Distance to Decelerate (in)

#### Trapezoidal Motion Profile:

Assume:  $t_a = t_c = t_d = t/3$  and  $x_a = x_d = x/4$ ,  $x_c = x/2$ 

Then: 
$$V_{avg} = x/t$$

$$V_{max} = 1.5 \cdot V_{avg}$$

$$a = -d = V_{max} / t_a = 4.5x/t^2$$

- t = Total Move Time (s)
- $t_a = Acceleration Time (s)$
- $t_c^{"}$  = Time at Constant Velocity (s)
- $t_d$  = Deceleration Time (s)
- V<sub>avg</sub> = Average Velocity (in/s)
- V<sub>max</sub> = Maximum Velocity (in/s)

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





Step 10. Determine the **Ball Screw and Motor Rotational Speed** required to move at V<sub>max</sub> for the selected SuperSlide Ball Screw Actuated system.

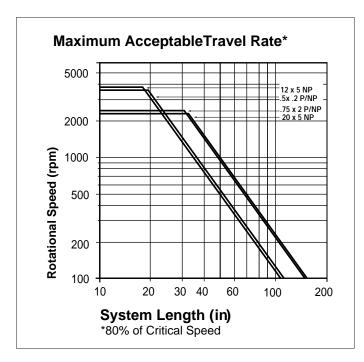
SuperSlide Ball Screw Actuated Systems are equipped with a ball screw assembly already mounted. In Some SuperSlide sizes there are multiple ball screw leads available. To determine the availability of ball screw leads for each superslide system see the Ball Screw Compatibility charts on page 317-318. To calculate the rotational speed (rpm) required to achieve V<sub>max</sub>, simply divide the linear speed (in/s) by the corresponding ball screw lead (in/rev).

 $RPM = \left(\frac{V_{max}}{P}\right) x \ 60 \ sec/min \qquad P = Ball \ Screw \ Lead \ (in/rev) \\ V_{max} = Maximum \ Linear \ Speed \ (in/s)$ 

## Maximum Acceptable Travel Rate

Step 11. Confirm the system application **Ball Screw Rotational Speed** is below the **Maximum Acceptable Travel Rate.** 

Each SuperSlide Ball Screw Actuated System has a **Maximum Acceptable Travel Rate** based on the natural frequency of the whirling vibration of the ball screw. To determine the SuperSlide system that is capable of achieving the applications speeds, simply enter the graph with the Maximum Ball Screw Rotational Speed from step 10 and the required system length. Select the SuperSlide system characteristic curve to the right or above the plotted point.



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

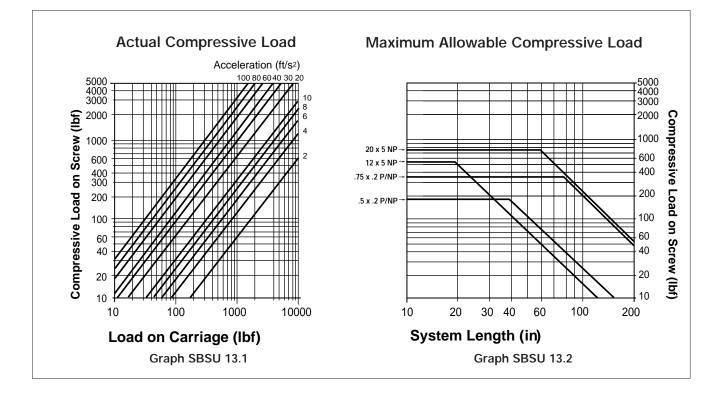
**Engineering Support - Inch** 

Page 319

Maximum Compressive Load

Step 12. Determine if the application loads on the SuperSlide exceed the maximum compressive load limits of the ball screw. Determine the **Actual Compressive Load** and the **Maximum Allowable Compressive Load**.

Graph SBSU 13.1 is used to determine the **Actual Compressive Load** on the system ball screw caused by the load on the carriage and the system acceleration. To determine the **Actual Compressive Load**, enter the graph with the load on the carriage and intersect this line with the system acceleration and locate the compressive load on the ball screw.



Graph 13.2 is used to determine the **Maximum Allowable Compressive Load** for each SuperSlide Ball Screw Actuated system. To determine the **Maximum Allowable Compressive Load** enter the graph with the **Actual Compressive Load** from (Graph 13.1) and intersect this line with the system length. Select a system with a rated maximum Compressive Load characteristic curve above or to the right of your plotted point.

Note: If the Actual Compressive Load is higher than the Maximum Allowable Compressive Load than the system size, length, load or acceleration should be reconsidered.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





#### **Torque Calculations**

Step 13. In order to size a motor for your SuperSlide system it is important to calculate the torque required to meet your application requirements with all of the parameters in mind. If you are actuating your system with a stepping motor, then a **maximum** or **peak torque** ( $T_{peak}$ ) calculation is required. **Peak torque** is usually seen at the time of maximum acceleration, however, other factors such as torque due to external forces can affect when peak torque occurs. It is important to calculate for all torque conditions (**Torque due to acceleration** ( $T_A$ ), **Torque at constant velocity** ( $T_{cv}$ ), **Torque due to deceleration** ( $T_D$ ), and **Torque required to hold at rest** ( $T_H$ )), and take that torque with the largest magnitude as the **Peak Torque** ( $T_{peak}$ ).

	$T_A = T_J + T_F + T_g + T_e \text{ (oz • in)}$ $T_{cv} = T_F + T_{g^+} T_e \text{ (oz • in)}$ $T_D = T_J - T_F - T_g - T_e \text{ (oz • in)}$ $T_H = -T_F + T_{g^+} T_e \text{ (oz • in)}$
where:	$T_J$ = Torque due to system inertia (oz • in) $T_F$ = Torque due to friction (oz • in) $T_g$ = Torque due to gravity (oz • in) $T_e$ = Torque due to external forces (oz • in)

Should you be actuating your SuperSlide system with a servo motor system then it is also necessary to calculate a Root-Mean-Square Torque ( $T_{RMS}$ ) or Continuous Torque.

$$T_{RMS} = \sqrt{\frac{t_a (T_A)^2 + t_{cv} (T_{cv})^2 + t_d (T_D)^2 + t_h (T_H)^2}{t_a + t_{cv} + t_d + t_h}}$$
 (oz • in)

where:

:  $t_a$  = time to accelerate (s)  $t_{cv}$  = time at constant velocity (s)  $t_d$  = time to decelerate (s)  $t_h$  = time at rest (s)

Step 13a. Calculate Torque due to system inertia (T<sub>J</sub>):

$$T_{J} = \underbrace{\omega}_{g \bullet t_{a}} \begin{bmatrix} J_{L} + J_{B} + J_{M} \end{bmatrix} \text{ (oz } \bullet \text{ in)}$$

where:

- w = angular velocity (rad/s)
   J<sub>L</sub> = Load inertia (oz in<sup>2</sup>)
  - $J_B = Ball \text{ or Lead Screw inertia (oz in<sup>2</sup>)}$
  - $J_{M} = Motor inertia (oz \cdot in^{2})^{(1)} (1 oz \cdot in^{2} = 386 oz \cdot in \cdot s^{2})$
  - $t_a$  = Time for acceleration (s) (from step 9)
  - $g = Acceleration due to gravity = 386 in/s^2$
- $\xi_{\text{screw}}$  = Efficiency of screw (from table on page 323)

<sup>(1)</sup> For motor inertia data see the Motion Control Section, page 431

Calculate Load inertia (JL):

$$J_{L} = \frac{(W_{c} + W_{p}) P^{2}}{(2\pi)^{2}} \qquad (oz \cdot in^{2})$$

where:

W<sub>c</sub> = Weight of the Carriage (oz) (from table on next page)
 W<sub>p</sub> = Weight of Payload (oz) (from Application Data)
 P = Lead of Ball or Lead Screw (in/rev) (from table on page 323)

$$\pi = 3.1416$$





Calculate Ball or Lead Screw inertia (J<sub>b</sub>):

$$J_{\rm B} = \frac{\pi \ {\rm L} \ \rho \ {\rm d}^4}{32} \qquad ({\rm oz} \cdot {\rm in}^2)$$

- L = Length of Ball or Lead Screw (in)
- = Density of Ball or Lead Screw = 4.48 <sup>oz</sup>/in<sup>3</sup> ρ
- = Diameter of Ball or Lead Screw (in) (from table on next page) d

Calulate angular velocity (ω):

$$\omega = \frac{2\pi V_{max}}{P} \qquad (rad/s)$$

where: V<sub>max</sub> = Maximum Linear Speed (in/s) (from step 9)

P = Lead of Ball or Lead Screw (<sup>in</sup>/<sub>rev</sub>) (from table on next page)

SuperSlic	de 2AE				SuperSli	de 2BE	3/2CB				
SuperSlide 2/	AB Ball S	Screw Ac	tuated Sys	tem Data		SuperSlide 2B	B/2CB Le	ad Screw	/Ball Screw	Act. Syste	m Data
Part Number	Nominal Dia.	Carriage Weight (oz)	Coefficient Friction Carriage	Number of Seals	Seal Drag (oz)	Part Number	Nominal Dia.		Coefficient Friction Carriage	Number of Seals	Seal Drag (oz)
2AB-08	.50	30.4	.002	8	1.6	2BB-06	.375	8.5	.002	0	_
2AB-12	.75	76.8	.002	8	2.4	2CB-08	.50	20.3	.002	4	1.6
2AB-16	1.0	128.0	.002	8	4.8	2CB-12	.75	48.0	.002	4	2.4
2AB-24	1.5	403.2	.002	8	6.4	2CB-16	1.0	100.0	.002	4	4.8
SuperSlide 2		G		tom Data	0	SuperSli					
SuperSlide 2				tem Data		SuperSlide 2	EB Ball S	Screw Ac	tuated Sys	tem Data	
Part	Nominal	Carriage	Coefficient	Number	Seal	Part	Nominal		Coefficient	Number	Seal
Number	Dia.	Weight (oz)	Friction Carriage	of Seals	Drag (oz)	Number	Dia.	Weight (oz)	Friction Carriage	of Seals	Drag (oz)
2DB-08-OUB	.50	24.5	.002	4	1.6	2EB-08	.50	30.4	.002	8	1.6

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

2.4

2.4

4.8

4.8

2EB-12

2EB-16

2EB-24

.75

1.0

1.5

76.8

128.0

403.2

.002

.002

.002



2DB-12-OUB

2DB-12-JUB

2DB-16-OUB

2DB-16-JUB

.75

.75

1.0

1.0

63.5

64.0

120.5

108.0

.002

.002

.002

.002

The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.

4

8

4

8



8

8

8

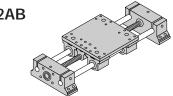
2.4

4.8

6.4

Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

SuperSlide 2AB
----------------



SuperSlide 2	SuperSlide 2AB Ball Screw Actuated System Data											
Part Number	System Nom. Dia.	Ball Screw Dia. x lead	Preload Condition	Frictional Torque oz-in <b>T</b> r <sup>†</sup>	Screw Efficiency &screw							
2AB-08-ARB-B	.50	12 mm x 5 mm	NP	6.4	0.90							
2AB-08-ARB-F	.50	.50 x .20	NP	6.4	0.90							
2AB-08-ARB-Q	.50	.50 x .50	Р	7.2	0.90							
2AB-12-ARB-D	.75	20 mm X 5 mm	NP	9.6	0.90							
2AB-12-ARB-G	.75	.75 x .20	NP	9.6	0.90							
2AB-12-ARB-L	.75	.631 x 1.0	Р	7.2	0.90							
2AB-12-ARB-U	.75	20 mm x 20 mm	NP	10.0	0.90							
2AB-16-ARB-T	1.0	1.0 x 1.0	Р	12.8	0.90							
2AB-16-ARB-H	1.0	1.0 x .25	Р	16.0	0.90							
2AB-24-ARB-J	1.5	1.5 x 1.0	Р	19.2	0.90							
2AB-24-ARB-I	1.5	1.5 x .25	Р	24.0	0.90							
2AB-24-ARB-Z	1.5	1.5 x 1.875	Р	16.0	0.90							

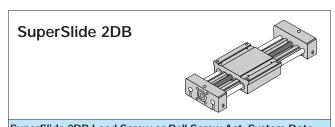
SuperSli	de 2E	BB/CB			
SuperSlide 2B	B/CB Le	ead Screw or I	Ball Screw	Act. Syst	em Data
Part Number	System Nom. Dia.	Ball Screw Dia. x lead	Preload Condition	Frictional Torque oz-in <b>T</b> r <sup>†</sup>	Screw Efficiency ξscrew
2BB-06-OTH-AA	.375	.375 x .1	Р	3 to 6	0.53
2BB-06-OTH-AB	.375	.375 x .25	Р	3 to 6	0.60
2BB-06-OTH-AC	.375	.375 x .50	Р	3 to 6	0.81
2BB-06-OTH-AD	.375	.375 x .75	Р	3 to 6	0.84

asto

 $\langle \rangle$ 

	.0.0	1070 1010		0.00	0.01
2BB-06-OTH-AD	.375	.375 x .75	Р	3 to 6	0.84
2BB-06-OTH-AE	.375	.375 x 1.0	Р	3 to 6	0.84
2CB-08-OVA-B	.75	12 mm x 5 mm	NP	6.4	0.90
2CB-08-OVA-F	.75	.50 x .20	NP	6.4	0.90
2CB-12-OVA-C	1.0	16 mm X 5 mm	Р	8.5	0.90
2CB-16-OVA-G	1.0	.75 x .20	NP	9.6	0.90
2CB-16-OVA-D	1.5	20 mm X 5 mm	NP	9.6	0.90

<sup>t</sup> Values of  $T_r$  are provided for calculation purposes. Measured values of  $T_r$  will vary with radial bearing and ball nut preload.



SuperSlide 2D	B Lead	Screw or Bal	Screw A	ct. Syster	n Data
Part Number	System Nom. Dia.	Ball Screw Dia. x lead	Preload Condition	Frictional Torque oz-in <b>T</b> r <sup>†</sup>	Screw Efficiency ξscrew
2DB-08-OUB-AA	.50	.375 x .1	Р	3 to 6	0.53
2DB-08-OUB-AB	.50	.375 x .25	Р	3 to 6	0.60
2DB-08-OUB-AC	.50	.375 x .50	Р	3 to 6	0.81
2DB-08-OUB-AD	.50	.375 x .75	Р	3 to 6	0.84
2DB-08-OUB-AE	.50	.375 x 1.0	Р	3 to 6	0.84
2DB-12-OUB-B	.75	12 mm x 5 mm	NP	6.4	0.90
2DB-12-OUB-F	.75	.50 x .20	NP	6.4	0.90
2DB-12-OUB-V	.75	.50 x .20	Р	9.6	0.90
2DB-12-JUB-Q	.75	.50 x .50	Р	7.2	0.90
2DB-16-OUB-D	1.0	20 mm x 5 mm	NP	9.6	0.90
2DB-16-OUB-G	1.0	.75 x .20	NP	9.6	0.90
2DB-16-OUB-W	1.0	.75 x .20	Р	12.4	0.90
2DB-16-OUB-L	1.0	.631 X 1.0	Р	7.2	0.90
2DB-16-OUB-R	1.0	.75 X .50	Р	8.4	0.90

SuperSlide 2EB				
uperSlide 2EB Ball Screw Actuated System Data				

SuperSlide 2EB Ball Screw Actuated System Data						
Part	System	Ball Screw	Preload	Frictional	Screw	
Number	Nom.	Dia. x lead	Condition	Torque	Efficiency	
	Dia.			oz-in	ξscrew	
				Tr⁺		
2EB-08-FTB-B	.50	12 mm x 5 mm	NP	6.4	0.90	
2EB-08-FTB-F	.50	.50 x .20	NP	6.4	0.90	
2EB-08-FTB-Q	.50	.50 x .50	Р	7.2	0.90	
2EB-12-FTB-D	.75	20 mm x 5 mm	NP	9.6	0.90	
2EB-12-FTB-G	.75	.75 x .20	NP	9.6	0.90	
2EB-12-FTB-L	.75	.631 x 1.0	Р	7.2	0.90	
2EB-12-FTB-U	.75	20 mm x 20 mm	NP	10.0	0.90	
2EB-16-FTB-T	1.0	1.0 x 1.0	Р	12.8	0.90	
2EB-16-FTB-H	1.0	1.0 x .25	Р	16.0	0.90	
2EB-24-FTB-J	1.5	1.5 x 1.0	Р	19.2	0.90	
2EB-24-FTB-I	1.5	1.5 x .25	Р	24.0	0.90	
2EB-24-FTB-Z	1.5	1.5 x 1.875	Р	16.0	0.90	

<sup>t</sup> Values of  $T_r$  are provided for calculation purposes. Measured values of  $T_r$  will vary with radial bearing and ball nut preload.

With the calculated values of Load inertia  $(J_L)$ , Ball or Lead Screw inertia  $(J_B)$ , and Angular Velocity ( $\omega$ ) you can now calculate Torque due to system inertia  $(T_J)$ :

$$T_{J} = \frac{\omega}{g \cdot t_{a}} \left[ \frac{J_{L} + J_{B} + J_{M}}{\xi_{screw}} \right] \quad (oz \cdot in)$$

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.







Step 13b. Calculate Torgue due to friction (TF)

$$\Gamma_{\rm F} = \frac{{\rm P} \cdot {\rm P}_{\rm f}}{2\pi \,\xi_{\rm SCRW}} + {\rm T}_{\rm r} \quad ({\rm oz} \cdot {\rm in})$$

where:

P = Lead of Ball or Lead Screw (in/rev) (from table on previous page)  $\pi = 3.1416$ 

 $\xi_{screw}$  = Efficiency of Ball or Lead Screw (from table on previous page)

Calculate Friction Force (Pf):

$$P_f = (W_c + W_p) \cdot m_{sys} + n \cdot D_s$$
 (oz)

 $W_c$  = Weight of Carriage (oz) (from table on page 322) where:  $W_{p} =$  Weight of Payload (oz) (from Application Data)  $\mu_{sys}$  = Coefficient of friction of carriage (from table on page 322) n = number of seals (from table on page 322)

 $D_s$  = Seal Drag (oz) (from table on page 322)

With the calculated value of Frictional Force (PF), locate Frictional Torque (Tr) (oz • in) in the appropriate table on previous page and calculate **Torque due to friction (T<sub>F</sub>)** using the formula, above.

Step 13c. Calculate **Torque due to gravity (T<sub>q</sub>)**:

$$T_{g} = \underline{P \cdot P_{g}}_{2\pi \xi_{screw}} \quad (oz \cdot in)$$

P = Lead of Ball or Lead Screw (<sup>in</sup>/<sub>rev</sub>) (from table on previous page) where:  $\pi = 3.1416$ 

 $\xi_{screw}$  = Efficiency of Ball or Lead Screw (from table on previous page)

Calculate Gravity Force (Pn):

$$P_{q} = (W_{c} + W_{p}) SIN \theta \qquad (oz)$$

where:

 $W_c$  = Weight of Carriage (oz) (from table on page 322)  $W_p$  = Weight of Payload (oz) (from Application Data)  $\theta$  = Angle from horizontal (for horizontal  $\theta$  = 0°; vertical  $\theta$  = 90° for upstroke,  $\theta = 270^{\circ}$  for downstroke)

With the calculated value of Gravity Force (Pq), the torque due to gravity (Tq) can be calculated using the formula, above.

Step 13d. Calculate Torque due to external forces (Te):

$$T_{e} = \frac{P \cdot P_{e}}{2\pi \xi_{screw}} \qquad \text{(oz \cdot in)}$$

where:

P = Lead of Ball or Lead Screw (in/rev) (from table on previous page)  $\pi = 3.1416$ 

 $\xi_{\text{screw}}$  = Efficiency of Ball or Lead Screw (from table on previous page)

The value of external force(s) (P<sub>e</sub>) (oz) must be calculated or estimated from the application specifications. Any outside forces that have a component that acts along the axis of the Superslide system should be included as an external force (Pe) (oz).

With the calculated or estimated value of external force (Pe) the Torque due to external forces (Te) can be calculated using the formula, above.





Step 13e. Calculate **Peak Torque (T<sub>peak</sub>)**, the largest of the following:

Torque due to acceleration (T<sub>A</sub>):

 $T_A = T_J + T_F + T_g + T_e \text{ (oz } \cdot \text{ in)}$ where:  $T_J = \text{Torque due to system inertia (oz } \cdot \text{ in)} \text{ (from step 13a)}$ 

 $T_F$  = Torque due to friction (oz • in) (from step 13b)  $T_a$  = Torque due to gravity (oz • in) (from step 13c)

 $T_e$  = Torque due to external forces (oz • in) (from step 13d)

Torque at constant velocity (T<sub>cv</sub>):

 $T_{cv} = T_F + T_a + T_e$  (oz • in)

Torque due to deceleration (T<sub>D</sub>):

 $T_D = T_J - T_F - T_a - T_e$  (oz • in)

Torque required to hold at rest (T<sub>H</sub>):

 $T_H = -T_F + T_q + T_e$  (oz • in)

Step 13f. Calculate Root-Mean-Square Torque (T<sub>RMS</sub>) or Continuous Torque:

$$T_{RMS} = \sqrt{\frac{t_a (T_A)^2 + t_{cv} (T_{cv})^2 + t_d (T_D)^2 + t_h (T_H)^2}{t_a + t_{cv} + t_d + t_h}}$$
 (oz•in)

where:  $T_{A}$ ,  $T_{CV}$ ,  $T_{D}$ , and  $T_{H}$  are from step 13e.

t<sub>a</sub> = time to accelerate (s)
 t<sub>cv</sub> = time at constant velocity (s)
 t<sub>d</sub> = time to decelerate (s)
 t<sub>h</sub> = time at rest (s)

#### Speed vs Torque

Step 14. Determine the proper TMC-1000 motor selection. Plot **Peak Torque (T**<sub>peak</sub>) against the **Required Motor Speed** from step 10 and enter the Motor Speed vs. Torque graph (Graph SBSU 19.1). If the plotted point is below the curve for intermittent duty, then you have made a proper selection. Now plot **Continuous Torque (T**<sub>RMS</sub>) against the **Required Motor Speed** from step 10 and enter the graph again. If the plotted point is below the curve for continuous duty, then you have made a proper selection. If either of the plotted points fall above their respective curve then either a larger frame motor or a speed reducing gearhead must be employed. Check mounting flange availability when increasing the motor frame size. See the example at the bottom of the next page if you choose to employ a speed reducing gearhead.

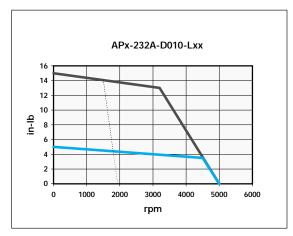
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





#### Motor Speed vs. Torque Curve

Graph SBSU 19.1 is an example of a speed vs. torque curve for a NEMA 23 motor from the Motion Control section. BLX Series motors are available in standard NEMA frame sizes 23, 34 and 42 and can be combined with either a one, two, three or four axis controller. To determine the motor speed vs. torgue curve that best suits the application and for a continuation of features and specifications refer to the Motion Control section, page 371.





#### Speed vs. Torque Curve with Gearhead

There is an increased torgue capability when using a gearhead. The use of a gearhead also requires the motor to run at a higher speed. Gearheads are available in standard NEMA frame sizes 23, 34 and 42 and in ratios 1:1, 3:1; 5:1 and 10:1 (other ratios are available). To determine the motor speed vs. torque curve that best suits the application and for a continuation of features and specifications refer to the Motion Control section, page 371.

#### To determine motor speed, use the following formula:

$$RPM = \frac{V_{max} \cdot 60 \cdot i}{P}$$

- where:  $V_{max}$  = maximum linear speed (in/s) (from step 9)
  - P = lead of Ball or Lead screw (in/rev) (from table on page 323)
  - i = gearhead ratio





# SuperSlide\* Ball Screw Actuated System **System Selection**

To determine the SuperSlide Ball Screw Actuated System that best fits your application requirements, the following design criteria will be evaluated:

- System Support Requirements
- System Stroke Length
- Maximum Allowable Shaft Deflection
- Required Travel Life

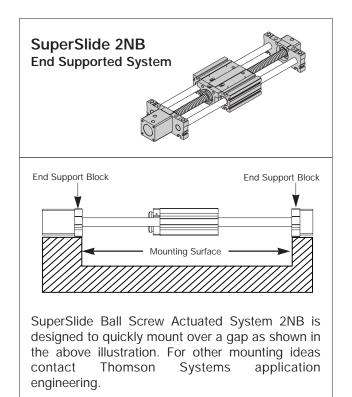
**METRIC** 

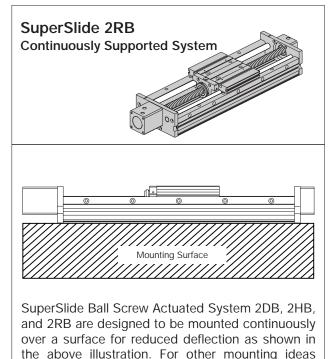
- Force on the Most Heavily Loaded Bearing
- Load Correction Factor
- Load/Life Requirements-Linear Bearings

- Load/Life Requirements-Ball Screws
- Motion (Move) Profile (Velocity, Acceleration)
- Maximum Acceptable Travel Rate
- Maximum Compressive (Column) Load
- Torgue Calculations
- Size Motor Using Torque/Speed Curves

After each criteria is determined system selection will become quick and easy. The following procedure will guide you through the proper system selection.

Step 1. Based on your application needs determine the mounting support requirements.





contact Thomson Systems application engineering.

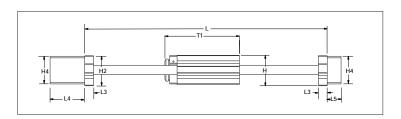
#### For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





System Travel Lengths

Step 2. Determine the **Stroke Length (L<sub>s</sub>).** For each SuperSlide Ball Screw Actuated System the maximum **Stroke Length (L<sub>s</sub>)**can easily be determined. The following example describes how Maximum Stroke Length is calculated. By subtracting the carriage length **(T1)** and two times the end block length **(L3)** from the total system length **(L)** the Maximum Stroke Length is determined. The application or required stroke length should not exceed this number.



 $L_{S} = L - (T1 + 2 L3)$ 

Should your application require the use of bellows way covers, it is important to recognize that the bellows will detract from the available stroke of the system. The bellows will retract to approximately 14% of the available stroke at each end of the system. The **stroke length with bellows** ( $L_{s/B}$ ) is calculated by subracting 2 times the **stroke** ( $L_s$ ) times .14 from the **stroke** ( $L_s$ ).

 $L_{S/B} = L_{S} - (2 \times L_{S} \times .14)$ 

**Standard Length and Delivery.** For each SuperSlide Ball Screw Actuated System there is a standard length chart and delivery information that also includes the standard length increment and the maximum system length. Selecting a standard system length will minimize shipment time. Once you have selected a length that best fits your application requirements, simply determine the maximum stroke length. The required stroke length should not exceed this number. Refer to the product specification section for the standard length charts not shown.

System 2RE	3 Sta	anda	ard	Leng	gths																				(Le	ength	is in mm)
System	300	375	400	450	500	525	600	675	700	750	800	825	900	975	1000	1050	1100	1125	1200	1275	1300	1350	1400	1425	1500	Х	MAX
2RB-M12																										75	2100
2RB-M16															I											100	3000

Custom Lengths and Delivery Information Systems ordered in standard lengths and longer lengths in increments of (X) are typically shipped in two to three weeks. Custom length systems are available and require three to four weeks for delivery. Lengths exceeding MAX length will require butt joints and will need 4 to 6 weeks for delivery. For special requirements, please contact the Thomson **Systems** application engineering department.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

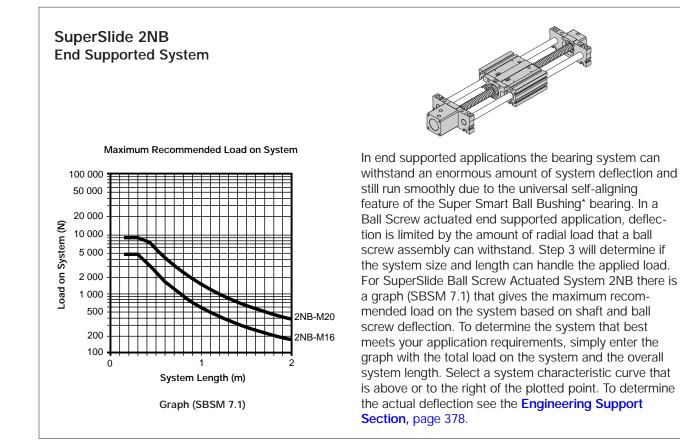
Engineering Support - Metric





#### Maximum Allowable Deflection End Supported Systems

Step 3. For end supported systems, determine if the system selected meets the **Maximum Allowable Deflection** criteria.



#### **Travel Life**

Step 4. Determine the Required Travel Life (km).

$$L_{t} = 2 \cdot s \cdot f \cdot L_{h} \cdot 60$$

$$L_{t} = required travel life (km)$$

$$s = stroke (mm)$$

$$f = frequency (cycles/minute)$$

$$L_{h} = service life (hrs)$$

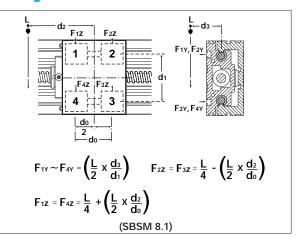
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



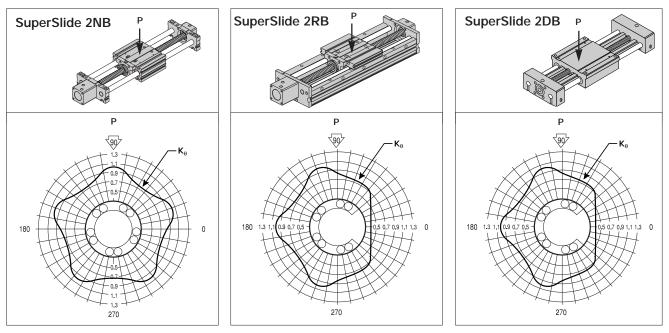
Page 329

#### System Loading

Step 5. Determine the **Force on the Most Heavily Loaded Bearing.** When selecting a SuperSlide Ball Screw Actuated System, it is necessary to evaluate the bearing forces that are generated based on the position of the load and its movement during application. The free body diagram (SBSM 8.1) is an example of the type of calculations that are required when determining resultant bearing forces. For other free body diagram examples see **Load Considerations** in the **Engineering Support Section**, page 377. The determination of the force on the most heavily loaded bearing allows you to enter the load life graph and select the system that best fits your application needs.



Step 6. Determine the **Load Correction Factor** ( $K_{\theta}$ ). The dynamic load capacity of the SuperSlide Ball Screw Actuated system is determined by the orientation of the system and the direction of the resultant bearing load. To determine the load correction factor, simply enter the polar graph with the applied or resultant load direction until it intersects the polar curve. If the load correction factor is 1,0 the resultant force ( $P_{resultant}$ ) is equal to the **Force on the Most Heavily Loaded Bearing** ( $P_{max}$ ). If the direction of the resultant bearing load cannot be determined, then use the minimum  $K_{\theta}$  value (0,7 for closed bearings and 0,5 for open bearings).



These Load Correction Factor Polar charts show values of  $K_{\theta}$  for load orientations on a single Ball Bushing<sup>\*</sup> bearing. Appropriate load orientation should be considered for the most heavily loaded Ball Bushing bearing.

If the Load Correction Factor is less than 1,0 the following formula should be used to determine the **Corrected Force on the Most Heavily Loaded Bearing**.

$$P_{max} = \underbrace{P_{resultant}}_{K_{\theta}}$$

$$P_{max} = Force on the Most Heavily Loaded Bearing (N)$$

$$P_{resultant} = Resultant of Externally Applied loads (N)$$

$$K_{\theta} = Load Correction Factor$$

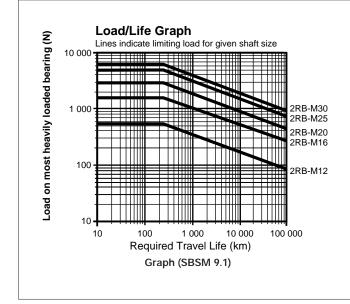
Note: AccuSlide\* 2HB has a load correction factor in all directions of 1,0.





#### METRIC SuperSlide\* Ball Screw Actuated System Load and Life Requirements

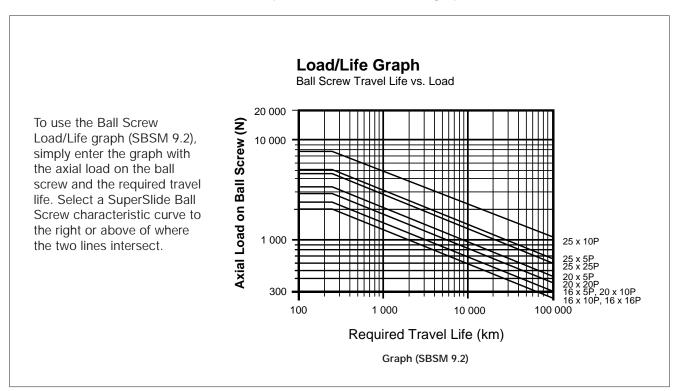
Step 7. Select the system that meets the application Load and Life Requirements.



For each SuperSlide Ball Screw Actuated System there is a graph (SBSM 9.1) that allows for system selection based on the **Required Travel Life** and the **Force on the Most Heavily Loaded Bearing**. To determine the system which best meets your application Load and Life requirements, simply enter the graph with your **Required Travel Life** from step 4 and the **Corrected Force on the Most Heavily Loaded Bearing** from step 6. Select a system characteristic curve that is above or to the right of the plotted point.

**Note:** Use **Corrected Force on the Most Heavily Loaded Bearing** if load correction factor is less than 1,0.

Step 8. Confirm that the Ball Screw in the SuperSlide selected will achieve **Load and life Requirements**. Once the SuperSlide Ball Screw Actuated System is selected refer to the **Ball Screw Compatability Charts** on the next page and select a ball screw that meets your application needs. With the Ball Screw axial load and the required travel life enter the graph below.



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





#### **Ball Screw Compatibility**

To determine the availability of ball screw diameters and leads for each SuperSlide system see the Ball Screw Compatibility charts below.

SuperS End Sup P-Preload NP- Non-Prel	port			m		en e				
SuperSlid	e 21						<u> </u>		t	
Part Number		В	all S	crew	Dian	neter	and L	ead		
	12 x 5	12 x 10	16 x 5	16 x 10	20 x 5	20 x 10	20 x 20	25 x 5	25 x 10	25 x 25
Preload	Р	Р	Р	Р	Р	Р	Р	Р	Р	Р
2NB-M16										
2NB-M20										

Supers Continue				ted S	ystei	m		J.		
P-Preload						00		2		
NP- Non-Prel	oad					- a	20			
SuperSlid	e 20	)B Ba	all S	crew	Con	npatil	oility	Char	rt	
Part Number		В	all S	crew	Dian	neter	and L	ead		
	12 x 5	12 x 10	16 x 5	16 x 10	20 x 5	20 x 10	20 x 20	25 x 5	25 x 10	25 x 25
Preload	NP	Р	Р	Р	NP	Р	Р	Р	Р	Р
2DB-12										
2DB-16										

AccuS Continuc				ed S	ystei	m	ß			
P-Preload							)	/	/	
NP- Non-Prelo	bad					0				
AccuSlide	2H	в Ва	ll Sc	rew (	Com	patib	ility C	hart	t	
Part Number		В	all S	crew	Diar	neter	and L	ead		
	12 x 5	12 x 10	16 x 5	16 x 10	20 x 5	20 x 10	20 x 20	25 x 5	25 x 10	25 x 25
Preload	Р	Р	Р	Р	Р	Р	Р	Р	Р	Р
2HB-M10										
2HB-M20										

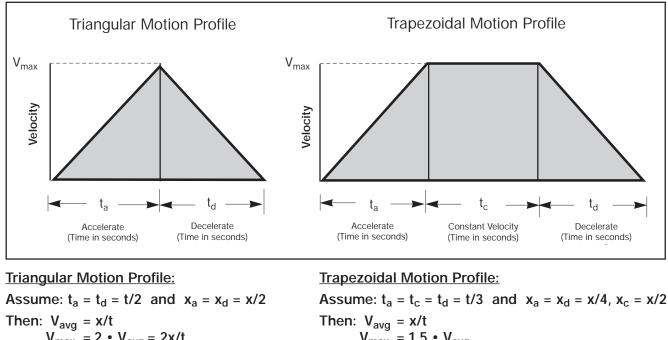
Supers Continuc				ed S	yste	m				
NP- Non-Prel	oad					<u>O</u>	0.0			
SuperSlid	e 2F	RB Ba	all So	crew	Con	npatik	oility	Char	t	
Part Number			Ball	Scre	w Di	amete	er and	d Lea	nd	
	12 x 5	12 x 10	16 x 5	16 x 10	20 x 5	20 x 10	20 x 20	25 x 5	25 x 10	25 x 25
Preload	Р	Р	Р	Р	Р	Р	Р	Р	Р	Р
2RB-M12										
2RB-M16										



## METRIC SuperSlide\* Ball Screw Actuated System Motion Profile

A typical linear ball screw actuated application normally consists of a series of motion profiles. The drive torque required to move the system should be evaluated for each motion profile. There are two basic motion profile types. The first and most simple move is a triangular motion profile which consists of two legs. The first leg is for acceleration and the second is for deceleration. The second motion profile type is trapezoidal which consists of an acceleration leg; a leg of constant velocity and a deceleration leg.

Step 9. Determine the Motion Profile that fits your application requirements. Calculate V<sub>max</sub> and a.



Step 10. Determine the **Ball Screw and Motor Rotational Speed** required to move at  $V_{max}$  for the selected SuperSlide Ball Screw Actuated system.

SuperSlide Ball Screw Actuated Systems are equipped with a ball screw assembly already mounted. In some Superslide sizes there are multiple ball screw leads available. To determine the availability of ball screw leads for each SuperSlide system see the **Ball Screw Compatibility** charts on page 332. To calculate the rotational speed (rpm) required to achieve  $V_{max}$  simply divide the linear speed (m/s) by the corresponding ball screw lead (mm/rev).

 $RPM = \left(\frac{Vmax}{P}\right) x \ 1000 \ mm/m \ x \ 60 \ sec/min \qquad P = Ball \ Screw \ Lead \ (mm/rev)$ 

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

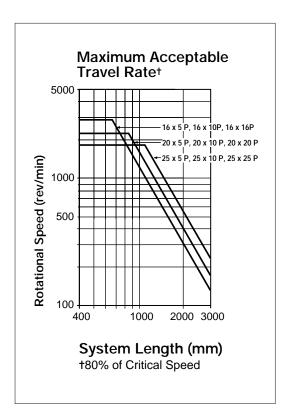




Maximum Acceptable Travel Rate

Step 11. Confirm the system application Maximum Ball Screw Rotational Speed is below the Maximum Acceptable Travel Rate.

Each SuperSlide Ball Screw Actuated System has a **Maximum Acceptable Travel Rate** based on the natural frequency of the whirling vibration of the ball screw. To determine the SuperSlide system that is capable of achieving the applications speeds, simply enter the graph with the **Maximum Ball Screw Rotational Speed** from step 10 and the required system length. Select the SuperSlide system characteristic curve to the right or above the plotted point.



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

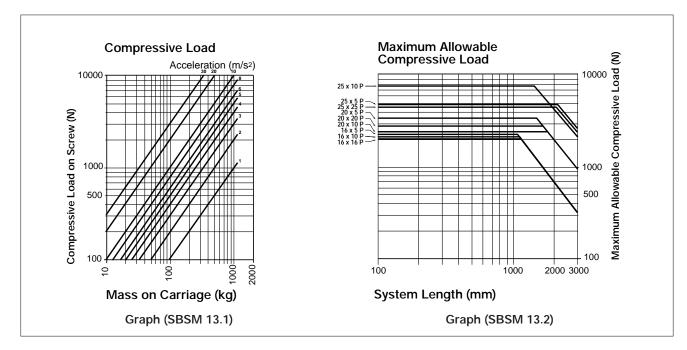




Maximum Compressive Load

Step 12. Determine if the application loads on the SuperSlide exceed the maximum compressive load limits of the ball screw. Determine the **Actual Compressive Load** and the **Maximum Allowable Compressive Load**.

Graph SBSM13.1 is used to determine the **Actual Compressive Load** on the system ball screw caused by the load on the carriage and the system acceleration. To determine the **Actual Compressive Load**, enter the graph with the mass on the carriage and intersect this line with the system acceleration and locate the compressive load on the ball screw.



Graph SBSM13.2 is used to determine the **Maximum Allowable Compressive Load** for each Superslide Ball Screw Actuated system. To determine the **Maximum Allowable Compressive Load**, enter the graph with the **actual compressive load** from (Graph 13.1) and intersect this line with the system length. Select a system with a rated maximum compressive load characteristic curve above or to the right of your plotted point.

Note: If the Actual Compressive Load is higher that the Maximum Allowable Compressive Load than the system size, length, load or acceleration should be reconsidered.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



Page 335

#### **Torque Calculations**

Step 13. In order to size a motor for your SuperSlide Ball Screw Actuated system it is important to calculate the torque required to meet your application requirements with all of the parameters in mind. If you are actuating your system with a stepping motor, then a maximum or peak torque (Tpeak) calculation is required. Peak torque is usually seen at the time of maximum acceleration, however, other factors such as torque due to external forces can affect when peak torque occurs. It is important to calculate for all torque conditions (Torque due to acceleration ( $T_A$ ), Torque at constant velocity ( $T_{CV}$ ), Torque due to deceleration ( $T_D$ ), and Torque required to hold at rest (T<sub>H</sub>)), and take that torque with the largest magnitude as the Peak Torque (Tpeak).

where:

 $T_J$  = Torque due to system inertia (N • m)  $T_F$  = Torque due to friction (N • m)  $T_g$  = Torque due to gravity (N • m)  $T_e$  = Torque due to external forces (N • m)

 $\begin{array}{rcl} T_{A} &=& T_{J} + T_{F} + T_{g} + T_{e} & (N \cdot m) \\ T_{cv} &=& T_{F} + T_{g} + T_{e} & (N \cdot m) \\ T_{D} &=& T_{J} - T_{F} - T_{g} - T_{e} & (N \cdot m) \\ T_{H} &=& -T_{F} + T_{g} + T_{e} & (N \cdot m) \end{array}$ 

Should you be actuating your Superslide system with a servo motor system then it is also necessary to calculate a Root-Mean-Square Torque (T<sub>RMS</sub>) or Continuous Torque.

$$T_{RMS} = \sqrt{\frac{t_a (T_A)^2 + t_{cv} (T_{cv})^2 + t_d (T_D)^2 + t_h (T_H)^2}{t_a + t_{cv} + t_d + t_h}}$$
 (N • m)

where:

- $t_a$  = time to accelerate (s) t<sub>cv</sub> = time at constant velocity (s)
- $t_d$  = time to decelerate (s)
- $t_h = time at rest (s)$

Step 13a. Calculate Torque due to system inertia (T<sub>1</sub>):

$$T_{J} = \underbrace{\omega}_{\mathbf{q} \bullet \mathbf{t}_{a}} \begin{bmatrix} \mathbf{J}_{L} + \mathbf{J}_{B} + \mathbf{J}_{M} \\ \underline{\xi}_{screw} \end{bmatrix} \quad (N \bullet m)$$

where:

- $\omega$  = angular velocity (rad/s)  $J_L = Load inertia (N \cdot m^2)$ 
  - $J_B = Ball Screw inertia (N \cdot m^2)$

 $J_{M} = Motor inertia (N \cdot m^{2})^{(1)} (1 g \cdot cm^{2} = 10^{-8} N \cdot m^{2})$ 

- $t_a = Time$  for acceleration (s) (from step 9)
- $g = Acceleration due to gravity = 9.81 m/s^2$

 $\xi_{\text{screw}}$  = Efficiency of Ball Screw = 90%

<sup>(1)</sup> For motor inertia data see the Motion Control Section, page 431

Calculate Load inertia (JL):

$$J_{L} = \frac{(W_{c} + W_{p}) (P/1000)^{2}}{(2\pi)^{2}}$$
 (N • m<sup>2</sup>)

 $W_c$  = Weight of the Carriage (N) (from table on next page) where:  $W_p = Weight of Payload (N) (from Application Data)$ P = Lead of Ball or Lead Screw (mm) (from table on page 338)  $\pi = 3.1416$ 





Calculate Ball or Lead Screw inertia (J<sub>B</sub>):

 $J_{\rm B} = \frac{\pi \ {\rm L} \ \rho \ (d/1000)^4}{32} \qquad ({\rm N} \cdot {\rm m}^2)$ 

L = Length of Ball Screw (m)

 $\rho$  = Density of Ball Screw = 76,400 N/m<sup>3</sup>

d = Diameter of Ball Screw (mm) (from table on next page)

Calulate angular velocity (ω):

 $\omega = \frac{2\pi \text{ Vmax}}{(\text{P}/1000)} \quad (\text{rad/S})$ 

where: V<sub>max</sub> = Maximum Linear Speed (m/s) (from step 9) P = Lead of Ball Screw (mm) (from table on next page)

SuperSli						SuperSl		G			20
SuperSlide 2	1			ystem Da		SuperSlide 2				ystem Dat	
Part	System	Carriage	Carriage	Number	Seal	Part	System	Carriage	Carriage	Number	Seal
Number	Size	Weight	Friction	Of Seels	Drag	Number	Size	Weight	Friction	Of Seels	Drag
		(N)	Coefficient	Seals	(N)			(N)	Coefficient	Seals	(N)
2NB-M16	16		0,002	8	0,7	2DB-12	12	16,7	0,002	4	0,7
2NB-M20	20	22,6	0,002	8	1,2	2DB-16	16	34,3	0,002	4	1,2
AccuSlic						SuperSl					
AccuSlide 2	NB Ball	Screw Ac	tuated Sy	stem Data	а	SuperSlide 2	2RB Ball	Screw A	ctuated Sy	stem Dat	а
Part Number	System Size	Carriage Weight (N)	Carriage Friction Coefficient	Number of Seals	Seal Drag (N)	Part Number	System size	Carriage Weight (N)	Carriage Friction Coefficient	Number of Seals	Seal Drag (N)
2HB-M10	10	3,9	0,003	4	0,9	2RB-M12	12	8,8	0,002	8	0,5
2HB-M20	20	26,5	0,003	4	7,0	2RB-M16	16	16,7	0,002	8	0,7

With the calculated values of Load inertia  $(J_L)$ , Ball or Lead Screw inertia  $(J_B)$ , and Angular Velocity ( $\omega$ ) you can now calculate Torque due to system inertia  $(T_J)$ :

$$T_{J} = \frac{\omega}{\mathbf{g} \cdot \mathbf{t}_{a}} \left[ \frac{\mathbf{J}_{L} + \mathbf{J}_{B} + \mathbf{J}_{M}}{\xi_{\text{screw}}} \right] \quad (N \cdot m)$$

Step 13b. Calculate Torque due to friction (TF)

$$T_{F} = \frac{(P/1000)}{2\pi \xi_{screw}} \bullet P_{f} + T_{r} \quad (N \bullet m)$$

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





SuperSlide	e 2NB			SuperSlide	e 2DB		
SuperSlide 2NE	Ball Sc	rew Act. Sy	stem Data	SuperSlide 2DE	Ball Sc	rew Act. Sy	stem Data
Part Number	Nominal Dia.	Ball Screw Dia.x lead (mm)	Frictional Torque N-m <b>7</b> r †	Part Number	System Dia.	Ball Screw Dia.x lead (mm)	Frictional Torque N-m <i>T</i> r †
2NB-M20-OGL-I	20	20 X 5	0,1	2DB-12-OUK-B	12	12 x 5	0,05
2NB-M20-OGL-J 2NB-M20-OGL-K	20 20	20 X 10 20 X 20	0,1 0,1	2DB-16-OUK-D	16	20 x 5	0,07
AccuSlide	e* 2HB			SuperSlide	e 2RB		
AccuSlide	e* 2HB			SuperSlide	e 2RB		
AccuSlide			em Data	SuperSlide SuperSlide 2RB		rew Act. Sys	Stem Data
		w Act. Syste	m Data Frictional Torque N-m $T_r$ †				stem Data Frictional Torque N-m T <sub>r</sub> †
AccuSlide 2HB Part	Ball Scre Nominal Size 10	w Act. Syste Ball Screw Dia.x lead (mm) 16 x 5	Frictional Torque N-m <i>T</i> r † 0,09	SuperSlide 2RB	Ball Scr Nominal Dia.	Ball Screw Dia.x lead (mm) 16 x 5	Frictional Torque N-m
AccuSlide 2HB Part Number 2HB-M10-OYP-G 2HB-M10-OYP-H	Ball Scre Nominal Size 10 10	w Act. Syste Ball Screw Dia.x lead (mm) 16 x 5 16 x 10	Frictional Torque N-m <b>T</b> r † 0,09 0,09	SuperSlide 2RB Part Number 2RB-M12-ODM-G 2RB-M12-ODM-H	Ball Scr Nominal Dia.	Ball Screw Dia.x lead (mm) 16 x 5 16 x 10	Frictional Torque N-m <i>T</i> r † 0,09 0,09
AccuSlide 2HB Part Number 2HB-M10-OYP-G	Ball Scre Nominal Size 10	w Act. Syste Ball Screw Dia.x lead (mm) 16 x 5	Frictional Torque N-m <i>T</i> r † 0,09	SuperSlide 2RB Part Number 2RB-M12-ODM-G	Ball Scr Nominal Dia.	Ball Screw Dia.x lead (mm) 16 x 5	Frictional Torque N-m <i>T</i> r † 0,09

<sup>†</sup> Values of  $T_r$  are provided for calculation purposes. Measured values of  $T_r$  will vary with radial bearing and ball nut preload.

where: P = Lead of Ball Screw (mm) (from table above)  

$$\pi$$
 = 3.1416  
 $\xi_{screw}$  = Efficiency of Ball Screw = 90%

Calculate Friction Force (P<sub>f</sub>):

$$P_f = (W_c + W_p) \bullet \mu_{sys} + n \bullet D_s (N)$$

where:

 $W_c$  = Weight of Carriage (N) (from table on previous page)  $W_p$  = Weight of Payload (N) (from Application Data)  $\mu_{sys}$  = Coefficient of friction of carriage (from table on previous page)

n = number of seals (from table on previous page)

 $D_s$  = Seal Drag (N) (from table on previous page)

With the calculated value of Frictional Force ( $P_F$ ), locate Frictional Torque ( $T_r$ ) (N • m) in the appropriate table above and calculate Torque due to friction  $(T_F)$  from the formula on the previous page.

Step 13c. Calculate **Torque due to gravity (T**<sub>a</sub>):

 $T_{g} = \frac{(P/1000)}{2\pi \xi_{screw}} \bullet P_{g}$ (N • m) P = Lead of Ball Screw (mm) (from table above) where:  $\pi = 3.1416$  $\xi_{screw}$  = Efficiency of Ball Screw = 90%





Calculate Gravity Force (Pg):

$$P_q = (W_c + W_p) SIN \theta$$
 (N)

where:  $W_c$  = Weight of Carriage (N) (from table on page 337)  $W_p$  = Weight of Payload (N) (from Application Data)  $\theta$  = Angle from horizontal (for horizontal  $\theta$  = 0°; vertical  $\theta$  = 90° for upstroke,  $\theta$  = 270° for downstroke)

With the calculated value of Gravity Force ( $P_g$ ) (N), the torque due to gravity ( $T_g$ ) can be calculated from the formula on the previous page.

Step 13d. Calculate Torque due to external forces (Te):

$$T_{e} = \frac{(P/1000)}{2\pi \xi_{screw}} \cdot P_{e} \quad (N \cdot m)$$
where: P = Lead of Ball Screw (mm/rev) (from table on previous page)  
 $\pi = 3.1416$   
 $\xi_{screw} = Efficiency of Ball Screw = 90\%$ 

The value of external force(s) ( $P_e$ ) (N) must be calculated or estimated from the application specifications. Any outside forces that have a component that acts along the axis of the Superslide system should be included as an external force ( $P_e$ ) (N).

With the calculated or estimated value of external force ( $P_e$ ) the Torque due to external forces ( $T_e$ ) can be calculated using the formula, above.

Step 13e. Calculate Peak Torque (Tpeak), the largest of the following:

Torque due to acceleration (T<sub>A</sub>):

$$T_A = T_J + T_F + T_g + T_e (N \cdot m)$$

where:  $T_J$  = Torque due to system inertia (N • m) (from step 13a)  $T_F$  = Torque due to friction (N • m) (from step 13b)  $T_g$  = Torque due to gravity (N • m) (from step 13c)  $T_e$  = Torque due to external forces (N • m) (from step 13d)

Torque at constant velocity (T<sub>cv</sub>):

$$T_{cv} = T_F + T_a + T_e (N \cdot m)$$

Torque due to deceleration (T<sub>D</sub>):

$$T_D = T_J - T_F - T_a - T_e$$
 (N • m)

Torque required to hold at rest  $(T_H)$ :

$$T_{H} = -T_{F} + T_{q} + T_{e} (N \cdot m)$$

Step 13f. Calculate Root-Mean-Square Torque (T<sub>RMS</sub>) or Continuous Torque:

$$T_{RMS} = \sqrt{\frac{t_a (T_A)^2 + t_{cv} (T_{cv})^2 + t_d (T_D)^2 + t_h (T_H)^2}{t_a + t_{cv} + t_d + t_h}} (N \cdot m)$$

where:  $T_{A'} T_{CV'} T_{D'}$  and  $T_H$  are from step 13e.

 $t_a$  = time to accelerate (s)  $t_{cv}$  = time at constant velocity (s)

- $t_d$  = time to decelerate (s)
- $t_{h}$  = time at rest (s)

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



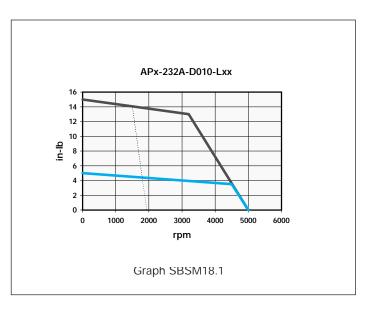


## METRIC SuperSlide\* Ball Screw Actuated System Speed vs Torque

Step 14. Determine the proper motor selection. Plot **Peak Torque (T**<sub>peak</sub>) against the **Required Motor Speed** from step 10 and enter the Motor Speed vs. Torque graph (SBSM 18.1). If the plotted point is below the curve for intermittent duty, then you have made a proper selection. Now plot **Continuous Torque (T**<sub>RMS</sub>) against the **Required Motor Speed** from step 10 and enter the graph again. If the plotted point is below the curve for continuous duty, then you have made a proper selection. If either of the plotted points fall above their respective curve then either a larger frame motor or a speed reducing gearhead must be employed. Check mounting flange availability when increasing the motor frame size. See the example at the bottom of this page if you choose to employ a speed reducing gearhead.

#### Motor Speed vs. Torque Curve

Graph SBSM18.1 is an example of a speed vs. torque curve for a NEMA 23 motor from the Motion Control section. BLX Series motors are available in standard NEMA frame sizes 23, 34 and 42 and can be combined with either a one, two, three or four axis controller. To determine the motor speed vs. torque curve that best suits the application and for a continuation of features and specifications refer to the Motion Control section, page 381.



Speed vs. Torque Curve with Gearhead

There is an increased torque capability when using a gearhead. The use of a gearhead also requires the motor to run at a higher speed. Gearheads are available in standard NEMA frame sizes 23, 34 and 42 and in ratios 1:1, 3:1, 5:1 and 10:1. (other ratios are available). To determine the motor speed vs. torque curve that best suits the application and for a continuation of features and specifications refer to the Motion Control section, page 381.

To determine motor speed, use the following formula:

$$_{\text{RPM}} = \frac{V_{\text{max}} \cdot 60000 \cdot i}{P}$$

where:  $V_{max}$  = maximum linear speed (m/s) (from step 9)

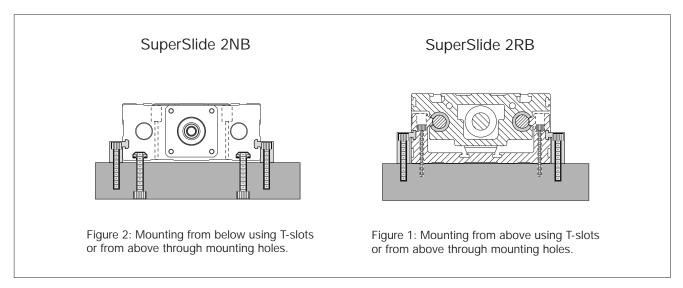
- P = lead of Ball Screw (mm/rev)
- i = gearhead ratio (from Application Data)



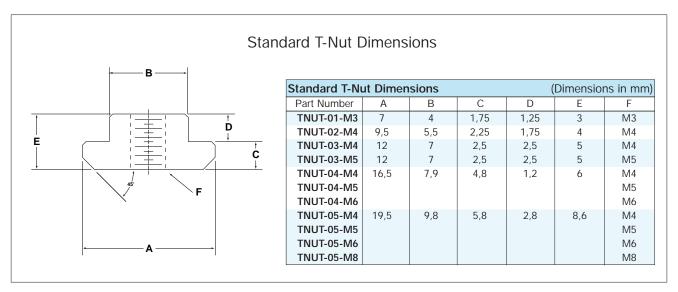


#### System Mounting

The SuperSlide 2NB and 2RB Ball Screw Actuated Systems can be mounted using the T-nuts and T-slots from above with clamping fixtures as shown below. In addition, SuperSlide Ball Screw Actuated Systems 2NB and 2RB can be mounted using the bolt down attachment holes found in each end block (System 2NB) or system support base (System 2RB). For other mounting fixity contact Thomson Systems Application Engineering.



#### **T-Nuts for Mounting**



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





#### **System Selection**

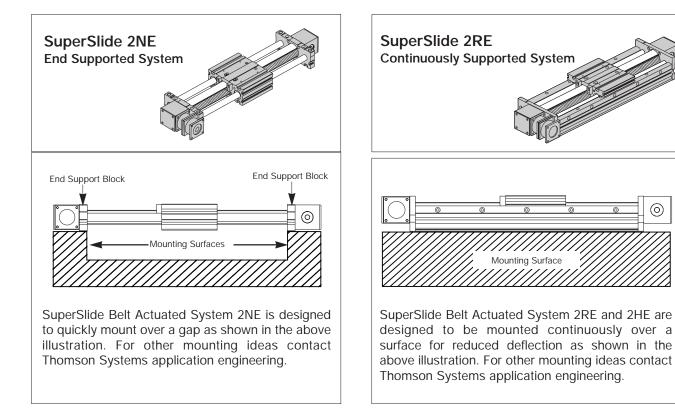
To determine the system that fits your SuperSlide Belt Actuated System application requirements the following design criteria needs to be evaluated:

- System Support Requirements
- System Stroke Length
- Maximum Allowable Shaft Deflection
- Required Travel Life
- Force on the Most Heavily Loaded Bearing Torque Calculations
- Load Correction Factor

- Load/Life Requirements Linear Bearings
- Motion (Move) Profile (Velocity, Acceleration)
- Maximum Belt Tooth Shear Strength
- Gear Motor Rotational Speed (Gear Reduction)
- Size Motor using Torque/Speed Curves

After the above are determined, the system selection will become guick and easy. The following procedure will guide you through the proper system selection.

Step 1. Based on your application needs determine the Mounting Support Requirements. Will the application require end or continuous support?



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

Engineering Support - Metric





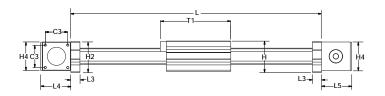
 $\bigcirc$ 

Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries

#### System Travel Lengths

Step 2. Determine the **Stroke Length (L**<sub>s</sub>). For each SuperSlide Belt Actuated System, the maximum **Stroke Length (L**<sub>s</sub>) can easily be determined. By subtracting the carriage length **(T1)** and two times end block length **(L3)** from the total system length **(L)** the maximum stroke length is determined. The application or required stroke length should not exceed this number.

$$L_{S} = L - (T1 + 2 L3)$$



Should your application require the use of bellows way covers, it is important to recognize that the bellows will detract from the available stroke of the system. The bellows will retract to approximately 14% of the available stroke at each end of the system. The **stroke length with bellows (L**<sub>S/B</sub>) is calculated by subtracting 2 times the **stroke (L**<sub>S</sub>) times .14 from the **stroke (L**<sub>S</sub>).

$$L_{S/B} = L_{S} - (2 \times L_{S} \times .14)$$

**Standard Length and Delivery.** For each SuperSlide Belt Actuated System there is a standard length chart and delivery information that also includes the standard length increment and the maximum system length. Selecting a standard system length will minimize shipment time. Once you have selected a length that best fits your application requirements, simply determine the maximum stroke length. The required stroke length should not exceed this number.

System 2NE S	Star	dar	d Le	engt	hs																				(Len	igths	; in mm)
System	300	375	400	450	500	525	600	675	700	750	800	825	900	975	1000	1050	1100	1125	1200	1275	1300	1350	1400	1425	1500	Х	MAX
2NE-M16																										75	1500
2NE-M20															1											100	2000

**Custom Lengths and Delivery Information** Systems ordered in standard lengths and longer lengths in increments of (X) are typically shipped in two to three weeks. Custom length systems are available and require three to four weeks for delivery. Lengths exceeding MAX length will require butt joints and will need 4 to 6 weeks for delivery. For special requirements, please contact the Thomson Systems application engineering department.

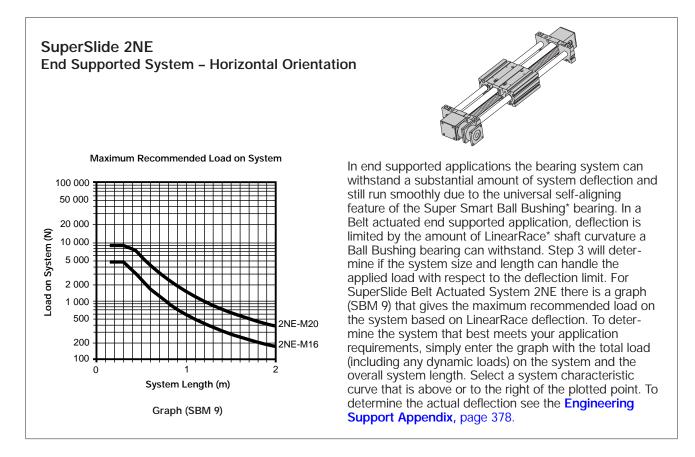
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



Page 343

#### System Deflection

Step 3. For end supported systems, determine if the system selected meets the **Maximum Allowable Deflection** criteria.



#### **Travel Life**

Page 344

Step 4. Determine the Required Travel Life (km).

$$L_{t} = \frac{2 \cdot s \cdot f \cdot L_{h} \cdot 60}{10^{6}}$$

$$L_{t} = required travel life (km)$$

$$s = stroke (mm)$$

$$f = frequency (cycles/minute)$$

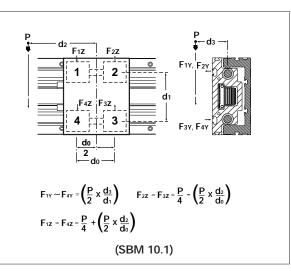
$$L_{h} = service life (hrs)$$

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

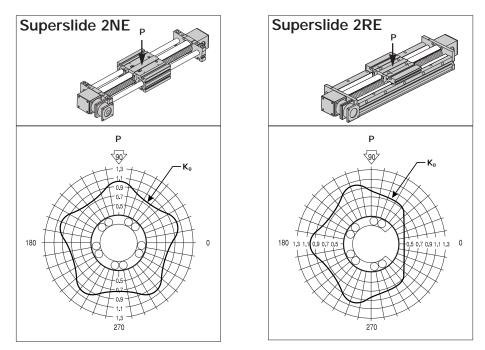


#### System Loading

Step 5. Determine the **Force on the Most Heavily Loaded Bearing.** When selecting a SuperSlide Belt Actuated System, it is necessary to evaluate the bearing forces that are generated based on the position of the load and its movement during application. The free body diagram (SBM 10.1) is an example of the type of calculations that are required when determining resultant bearing forces. For other free body diagram examples see **Load Considerations** in the **Engineering Support Appendix**, page 377. The determination of the force on the most heavily loaded bearing allows you to enter the load life graph and select the system that best fits your application needs.



Step 6. Determine the Load Correction Factor ( $K_{\theta}$ ). The dynamic load capacity of SuperSlide Belt Actuated system is determined by the orientation of the system and the direction of the resultant bearing load. To determine the load correction factor, simply enter the polar graph with the applied or resultant load direction until it intersects the polar curve. If the load correction factor is 1,0 the resultant force ( $P_{resultant}$ ) is equal to the Force on the Most Heavily Loaded Bearing ( $P_{max}$ ). If the direction of the resultant bearing load cannot be determined, then use the minimum  $K_{\theta}$  value (0,7 for closed bearings and 0,5 for open bearings.)



These Load Correction Factor Polar charts show values of  $K_{\theta}$  for load orientations on a single Ball Bushing<sup>\*</sup> bearing. Appropriate load orientation should be considered for the most heavily loaded Ball Bushing bearing.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





If the Load Correction Factor is less than 1,0 the following formula should be used to determine the Corrected Force on the Most Heavily Loaded Bearing.

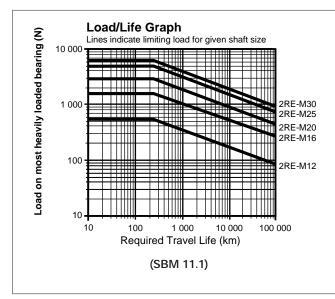
$$P_{max} = \frac{P_{resultant}}{K_{\theta}}$$

 $\begin{array}{l} P_{max} = \mbox{ Force on the Most Heavily Loaded Bearing (N)} \\ P_{resultant} = \mbox{ Resultant of Externally Applied loads (N)} \\ K_{\theta} = \mbox{ Load Correction Factor} \end{array}$ 

Note: AccuSlide\* 2HE has a load correction factor in all directions of 1,0.

### Load and Life Requirements

Step 7. Select the system that meets the application load and life requirements.



For each SuperSlide Belt Actuated System there is a graph (SBM 11.1) that allows for system selection based on the **Required Travel Life** and the **Force on the Most Heavily Loaded Bearing**. To determine the system which best meets your application requirements, simply enter the graph with your **Required Travel Life** from step 4 and the **Corrected Force on the Most Heavily Loaded Bearing** from step 6. Select a system characteristic curve that is above or to the right of the plotted point.

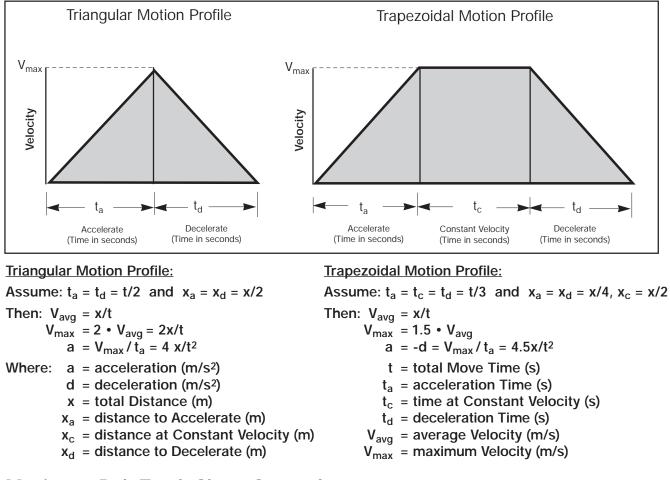
**Note:** Use **Corrected Force on the Most Heavily Loaded Bearing** if load correction factor is less than 1,0.



#### **Motion Profile**

A typical linear belt actuated application normally consists of a series of motion profiles. The actuated torque required to move the system should be evaluated for each motion profile. There are two basic motion profile types. The first and most simple move is a triangular motion profile which consists of two legs. The first leg is for acceleration and the second is for deceleration. The second motion profile type is trapezoidal which consists of an acceleration leg, a leg of constant velocity and a deceleration leg.

Step 8. Determine the Motion Profile that fits your application requirements. Calculate  $V_{max}$  and a.



#### Maximum Belt Tooth Shear Strength

Step 9. Calculate the Total Axial Forces on the system belt and determine whether they are within the limits of the Belt Pre-Tension Force and Maximum Allowable Tooth Shear of the belt. The Total Axial System Belt Force (P<sub>s</sub>) is the summation of External Force (P<sub>a</sub>), Acceleration Force (P<sub>a</sub>) and Frictional Force (P<sub>f</sub>).

$$P_s = P_e + P_a + P_f$$

Step 9a. Determine the External Axial Forces (P<sub>a</sub>). External axial forces seen by the Superslide Belt Actuated system can be the result of application forces such as stretching fabric in a textile application or compressing boxing in a packaging application. In a vertical application, the external force is the addition of gravity acting on the payload. In those vertical applications the motor must be mounted above the load on the carriage.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



Page 347

#### Maximum Belt Tooth Shear Strength (continued)

Step 9b. Determine the **Acceleration force (P<sub>a</sub>).** To overcome the inertia generated by the payload, the carriage assembly and the belt force due to acceleration must be evaluated.

$$P_a = a \cdot (W_c + W_p + (W_b \cdot L \cdot 2))$$

Belt Pre-

Tension

Force (N)

225

780

Belt Pre-

Tension

Force (N)

225

780

Maximum

Axial Force, Belt (N)

485

817

Maximum

Axial Force,

Belt (N)

485

817

a =  $V_{max} / t_a = \frac{4.5 \cdot x}{t^2}$  = linear acceleration (m/s<sup>2</sup>) (from step 8)

 $W_c$  = carriage Weight (N) (from table below)  $W_p$  = weight of Payload (N) (from Application Data)

 $W_{\rm p}$  = weight of Payload (N) (norm application Data  $W_{\rm b}$  = weight of Belt (N/m) (from table below)

Coefficient

Friction

Carriage

0,002

0,002

Coefficient

Friction

Carriage

0,002

0,002

Number

of Seals

8

8

Number

of Seals

8

8

Seal

Drag

(N)

0,7

1,2

Seal

Drag

(N)

0,5

0,7

 $g = acceleration due to gravity = 9,81 m/s^2$ 

SuperSlide 2NE Belt Actuated System Data

Carriage

Weight

(N)

22,6

SuperSlide 2RE Belt Actuated System Data

Carriage

Weight

(N)

8,8

16.7

Belt

Weight

(N/m)

0,4

1,12

Belt

Weight

(N/m)

0,4

1,12

SuperSlide 2NE

Nominal

Dia.

16

20

Nominal

Dia.

12

16

AccuSlide\* 2HE

SuperSlide 2RE

Part

Number

2NE-M16

2NE-M20

Part

Number

2RE-M12

2RE-M16

V<sub>max</sub> = maximum velocity (m/s) (from Step 8)

- t<sub>a</sub> = acceleration time (s)
- $x_a$  = distance to accelerate (m)
- L = overall length of system (m)
- x = total distance (m)
- t = total move time (s)

Step 9c. Determine the **Frictional Force (P<sub>f</sub>)**. The total Frictional force is the sum of the payload and carriage weight times the system coefficient of friction plus the additional seal drag.

$$P_{f} = [\mu_{sys} \bullet (W_{p} + W_{c}) + n \bullet D_{s}]$$

W<sub>p</sub>= payload weight (N)

- W<sub>c</sub>= carriage weight (N) (see table at left)
- μ<sub>sys</sub>= system coefficient of friction (see table at left)
- D<sub>S</sub>= seal Drag (N) (see table at left)
  - n= number of seals (see table at left)

In the case of vertical axis orientation, this  $\mathbf{P}_{\mathbf{f}}$  term may be omitted.

Step 9d. Calculate **Total Axial System Belt Force (P**<sub>s</sub>):

$$P_s = P_e + P_a + P_f$$

					JUP			
AccuSlide	2HE Be	It Actuat	ed Syst	tem Data				
Part Number	Nominal Size	Carriage Weight (N)	Belt Weight (N/m)	Coefficient Friction Carriage	Number of Seals	Seal Drag (N)	Belt Pre- Tension Force (N)	Maximum Axial Force, Belt (N)
2HE-M10	-	3,9	0,4	0,003	4	0,9	225	485
2HE-M20	20	26,5	1,75	0,003	4	7,0	1260	1488

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.

Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries



Step 9e. Compare the calculated Total Axial System Belt Force (Ps) with the Belt Pre-Tension Force in the tables on the previous page. If the calculated value exceeds the Pre-Tension Force in the table then the application parameters or the size of the system should be reconsidered, as the possibility exists that the belt could go into a slackened condition causing slippage on the pulley. In no case should the Total Axial Belt Force (Ps) ever exceed the Maximum Axial Force for the belt in the tables on the previous page.

#### Maximum Belt Tooth Shear Capacity

Step 10. It is also important to check that the application parameters are within the limits of the Belt Tooth Shear Capacity.

SuperS	lide 2NE							
SuperSlide	2NE Belt Act	uated System	Data					
Part	Nominal	Pitch Circle	Lead	Number of	Belt	Belt	Standard	Maximum
Number	Dia.	Diameter	(mm/rev.)	Effective	Width	Pitch	Gear	Axial
		(mm)		Teeth	(mm)	(mm)	Ratios	Force (N)
2NE-M16	16	26,74	84	12	20	3	1:1, 3:1, 5:1, 10:1	485
2NE-M20	20	35,01	110	11	32	5	1:1, 3:1, 5:1, 10:1	817

AccuSli	ide* 2HE							)
AccuSlide 2	HE Belt Actu	ated System	Data					
Part Number	Nominal Size	Pitch Circle Diameter (mm)	Lead (mm/rev.)	Number of Effective Teeth	Belt Width (mm)	Belt Pitch (mm)	Standard Gear Ratios	Maximum Axial Force (N)
2HE-M10 2HE-M20	10 20	26,74 47,75	84 150	12 12	20 50	3 5	1:1, 3:1, 5:1, 10:1 1:1, 3:1, 5:1, 10:1	485 1488

SuperS	ilide 2RE							
SuperSlide	2RE Belt Act	uated System	Data					
Part Number	Nominal Dia.	Pitch Circle Diameter (mm)	Lead (mm/rev.)	Number of Effective Teeth	Belt Width (mm)	Belt Pitch (mm)	Standard Gear Ratios	Maximum Axial Force (N)
2RE-M12 2RE-M16	12 16	26,74 35,01	84 110	12 11	20 32	3 5	1:1, 3:1, 5:1, 10:1 1:1, 3:1, 5:1, 10:1	485 817

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





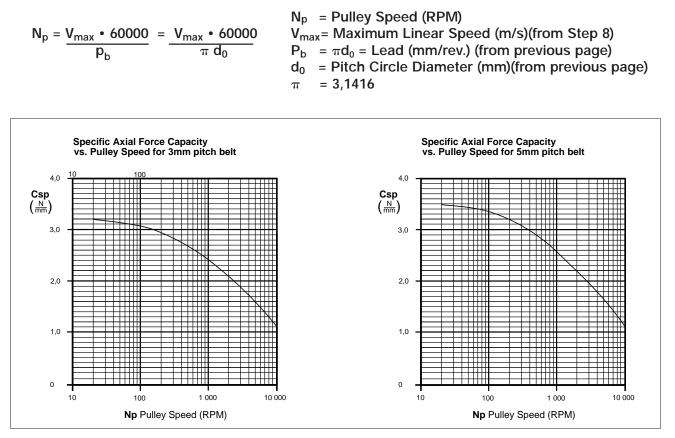
the		
	Page	3

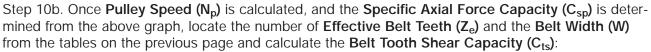
Maximum Belt Tooth Shear Capacity (continued)

The formula for calculating Belt Tooth Shear Capacity (Cts) is as follows:

C<sub>ts</sub> = C<sub>sp</sub> • Z<sub>e</sub> • W C<sub>sp</sub> = Specific Axial Force Capacity (N/mm) Z<sub>e</sub> = Number of Effective Belt Teeth (from previous page) W = Belt Width (mm) (from previous page)

Step 10a. The  $C_{sp}$  value is taken from the above graphs. Enter the graph for the appropriate **Belt Pitch** with the **Pulley Speed** ( $N_p$ ) calculated as follows:





#### $C_{ts} = C_{sp} \cdot Z_e \cdot W$

Step 10c. Compare the **Belt Tooth Shear Force Capacity (C**<sub>ts</sub>) with the calculated **Maximum Axial System Belt Force (P**<sub>s</sub>) from step 9d. If the calculated value for P<sub>s</sub> exceeds the maximum allowable capacity from step 10b, the application parameters or the size of the system must be reconsidered.

#### $C_{ts} > P_s$

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





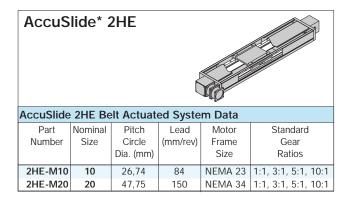
#### **Speed Requirements**

Rotational vs. Linear

Step 11. Determine the Motor Rotational Speed required to move at  $V_{max}$  for all system ratios.

The SuperSlide Belt Actuated System is equipped with a Thomson Micron True Planetary<sup>\*</sup> Precision Gearhead already mounted. Each gearhead ratio (greater than 1:1) provides an increase in output torque and requires the motor to operate at a higher speed.

SuperSlide 2NE					Super	Slide 2	2RE				
SuperSlid	e 2NE B	elt Actua	ted Syste	em Data		SuperSlid	e 2RE B	elt Actua	ted Syste	em Data	
Part	Nominal	Pitch	Lead	Motor	Standard	Part	Nominal	Pitch	Lead	Motor	Standard
Number	Dia.	Circle	(mm/rev)	Frame	Gear	Number	Dia.	Circle	(mm/rev)	Frame	Gear
		Dia. (mm)		Size	Ratios			Dia. (mm)		Size	Ratios
2NE-M16	16	26,74	84	NEMA 23	1:1, 3:1, 5:1, 10:1	2RE-M12	12	26,74	84	NEMA 23	1:1, 3:1, 5:1, 10:1
2NE-M20	20	35,01	110	NEMA 23	1:1, 3:1, 5:1, 10:1	2RE-M16	16	35,01	110	NEMA 23	1:1, 3:1, 5:1, 10:1



Calculate the Maximum Motor Speed ( $N_{max}$ ) at the system Maximum Linear Speed ( $V_{max}$ ) from Step 8 using the following formula:

$$N_{max} = \frac{V_{max} i}{p_{b}}$$

 $V_{max}$ = Maximum Linear Speed (m/s) i = Gear Ratio  $d_0$  = Pitch Circle Diameter (mm) (from tables above)  $p_b = \pi d_0$  = Lead (mm/rev.) (from tables above)  $\pi$ = 3,1416

or with unit conversions and constants:

$$N_{max} = \frac{V_{max} \cdot i \cdot (1000 \text{mm/m}) \cdot (60 \text{ sec/min})}{\pi d_0} = \frac{V_{max} \cdot i \cdot (19 \text{ 100})}{d_0} \text{ (RPM)}$$

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





**Torque Calculations** 

Step 12. In order to size a motor for your SuperSlide Belt Actuated system it is important to calculate the torque required to meet your application requirements with all of the parameters in mind. If you are actuating your system with a stepping motor, then a maximum or peak torgue (T<sub>peak</sub>) calculation is required. Peak torgue is usually seen at the time of maximum acceleration, however, other factors such as torque due to external forces can affect when peak torque occurs. It is important to calculate for all torque conditions (Torque due to acceleration (T<sub>A</sub>), Torque at constant velocity (T<sub>cv</sub>), Torque due to deceleration ( $T_D$ ), and Torque required to hold at rest ( $T_H$ )), and take that torque with the largest magnitude as the **Peak Torque (T<sub>peak</sub>)**.

- $T_A = T_J + T_F + T_g + T_e (N \bullet m)$  $T_{cv} = T_F + T_g + T_e (N \cdot m)$  $T_D = T_J - T_F - T_g - T_e (N \cdot m)$   $T_H = -T_F + T_g + T_e (N \cdot m)$ where:  $T_J$  = Torque due to system inertia (N • m)  $T_F$  = Torque due to friction (N • m)  $T_g$  = Torque due to gravity (N • m)  $T_e$  = Torque due to external forces (N • m)
- Should you be actuating your SuperSlide system with a servo motor system then it is also necessary to calculate a Root-Mean-Square Torque (T<sub>RMS</sub>) or Continuous Torque.

$$T_{RMS} = \sqrt{\frac{t_a (T_A)^2 + t_{cv} (T_{cv})^2 + t_d (T_D)^2 + t_h (T_H)^2}{t_a + t_{cv} + t_d + t_h}}$$
 (N • m)

where:

 $t_a$  = time to accelerate (s)  $t_{cv}$  = time at constant velocity (s)  $t_d$  = time to decelerate (s)  $t_{h}$  = time at rest (s)

Step 12a. Calculate Torque due to system inertia (T<sub>1</sub>):

$$T_{J} = \left[\frac{1000 \cdot 2 \cdot a}{d_{0}}a\right] \cdot \left[\frac{J_{p}}{i^{2} \cdot \xi_{g}} + J_{M} \cdot i + J_{g} \cdot i\right] + T_{L} \qquad (N \cdot m)$$

and

$$T_{L} = \frac{P_{a} \cdot d_{0}}{1000 \cdot 2 \cdot i \cdot \xi_{g} \cdot \xi_{b}} \qquad (N \cdot m)$$

where:

 $T_L$  = Torque due to payload (N • m) a = required linear acceleration (m/s<sup>2</sup>) (from step 8)

- $d_0$  = pulley pitch circle diameter (mm) (from table on next page)
- $J_p$  = drive pulley inertia (Kg m<sup>2</sup>) (from table on next page)
- $J_M = motor inertia (K_g \cdot m^2)^{(1)} (g \cdot cm^2 = K_g \cdot m^2 x 10^{-7})$   $J_g = gearbox inertia (K_g \cdot m^2) (from table on next page)$  i = gearbox ratio (from Application Data)
- $\xi_q$  = gearbox efficiency = 90%
- $\xi_{b}^{\tilde{s}} = \bar{b}elt efficiency = 90\%$
- $P_a = acceleration$  force (N)
- <sup>(1)</sup> For motor inertia data see the **Motion Control Section**, page 431.





# Engineering Support - Metric

## METRIC SuperSlide\* Belt Actuated System

Calculate acceleration force (P<sub>a</sub>) (N)

$$P_a = \frac{a \cdot (W_c + W_p + W_B \cdot L \cdot 2)}{g}$$
(N)

 $W_c$  = weight of carriage (N) (from table below)  $W_p$ = weight of payload (N) (from application data)  $W_B$ = weight of belt (N/m) (from table below) L= overall system length (m) a= required linear acceleration (m/s<sup>2</sup>) (from step 8) g= acceleration due to gravity = 9,81 m/s<sup>2</sup>

SuperSlide 2NE								
SuperSlid	e 2NE B	elt Actuat	ed System	Data				
Part Number	System Size	Pitch Circle Diameter (mm)	Pulley inertia (kg • m <sup>2</sup> )	Carriage Weight (N)	Belt Weight (N/m)			
2NE-M16	16	26,74	7,3 x 10 <sup>-6</sup>		0,4			
2NE-M20	20	35,01	3,02 x 10 <sup>-5</sup>	22,6	1,12			

SuperSlide 2NE								
System Part Number	Gear Ratio	Motor Frame Size	Gearbox Part Number	Gearbox inertia (Kg•m²)				
2NE-M16-OLL-A	1:1	NEMA23	NT-23-1	8,14 x 10-4				
2NE-M16-OLL-B	3:1	NEMA23	NT-23-3	7,82 x 10 <sup>-4</sup>				
2NE-M16-OLL-C	5:1	NEMA23	NT-23-5	2,58 x 10 <sup>-4</sup>				
2NE-M16-OLL-D	10:1	NEMA23	NT-23-10	1,61 x 10 <sup>-4</sup>				
2NE-M20-OLL-A	1:1	NEMA23	NT-23-1	8,14 x 10 <sup>-4</sup>				
2NE-M20-OLL-B	3:1	NEMA23	NT-23-3	7,82 x 10 <sup>-4</sup>				
2NE-M20-OLL-C	5:1	NEMA23	NT-23-5	2,58 x 10-4				
2NE-M20-OLL-D	10:1	NEMA23	NT-23-10	1,61 x 10 <sup>-4</sup>				

Juper	Silde	[								
SuperSlid	le 2RE B	elt Actuat	ed System	Data						
Part	System	Pitch	Pulley	Carriage	Belt					
Number	Size	Circle	inertia	Weight	Weight					
		Diameter	(kg • m <sup>2</sup> )	(N)	(N/m)					
	(mm)									
2RE-M12	12	26,74	7,3 x 10 <sup>-6</sup>	8,8	0,4					
2RE-M16	16	35,01	3,02 x 10 <sup>-5</sup>	16,7	1,12					

AccuSlide* 2HE								
AccuSlide	e 2HE Be	It Actuate	d System D	Data				
Part NumberSystem SizePitch Circle Diameter (mm)Pulley inertiaCarriage Weight (N)Belt Weight (N/m)								
2HE-M10	10	26,74	7,3 x 10 <sup>-6</sup>	3,9	0,4			
2HE-M20	20	47,75	1,54x 10 <sup>-4</sup>	26,5	1,75			

SuperSlide 2RE							
System	Gear	Motor	Gearbox	Gearbox			
Part Number	Ratio	Frame Size	Part Number	inertia (Kg•m²)			
2RE-M12-OEM-A	1:1	NEMA23	NT-23-1	8,14 x 10 <sup>-4</sup>			
2RE-M12-OEM-B	3:1	NEMA23	NT-23-3	7,82 x 10 <sup>-4</sup>			
2RE-M12-OEM-C	5:1	NEMA23	NT-23-5	2,58 x 10 <sup>-4</sup>			
2RE-M12-OEM-D	10:1	NEMA23	NT-23-10	1,61 x 10 <sup>-4</sup>			
2RE-M16-OEM-A	1:1	NEMA23	NT-23-1	8,14 x 10 <sup>-4</sup>			
2RE-M16-OEM-B	3:1	NEMA23	NT-23-3	7,82 x 10 <sup>-4</sup>			
2RE-M16-OEM-C	5:1	NEMA23	NT-23-5	2,58 x 10 <sup>-4</sup>			
2RE-M16-OEM-D	10:1	NEMA23	NT-23-10	1,61 x 10 <sup>-4</sup>			

AccuSlide 2HE				
System	Gear	Motor	Gearbox	Gearbox
Part Number	Ratio	Frame Size	Part Number	inertia (Kg•m²)
2HE-M10-OZP-A	1:1	NEMA23	NT-23-1	8,14 x 10 <sup>-4</sup>
2HE-M10-OZP-B	3:1	NEMA23	NT-23-3	7,82 x 10 <sup>-4</sup>
2HE-M10-OZP-C	5:1	NEMA23	NT-23-5	2,58 x 10 <sup>-4</sup>
2HE-M10-OZP-D	10:1	NEMA23	NT-23-10	1,61 x 10 <sup>-4</sup>
2HE-M20-OZP-E	1:1	NEMA34	NT-34-1	4,9 x 10 <sup>-3</sup>
2HE-M20-OZP-F	3:1	NEMA34	NT-34-3	4,51 x 10 <sup>-3</sup>
2HE-M20-OZP-G	5:1	NEMA34	NT-34-5	1,39 x 10 <sup>-3</sup>
2HE-M20-OZP-H	10:1	NEMA34	NT-34-10	7,56 x 10 <sup>-4</sup>

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



SuperSlide 2RF

The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

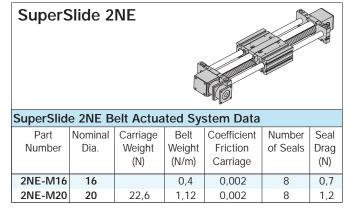
Page 353

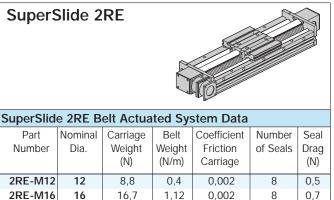
Calculate Torque due to payload (T<sub>L</sub>):

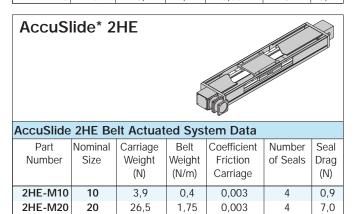
$$T_{L} = \frac{P_{a} \cdot d_{0}}{1000 \cdot 2 \cdot i \cdot \xi_{g} \cdot \xi_{b}}$$
 (N · m)

Calculate Torque due to system inertia (T<sub>J</sub>) :

$$T_{J} = \left[\frac{1000 \cdot 2 \cdot a}{d_{0}}\right] \cdot \left[\frac{J_{p}}{i^{2} \cdot \xi_{g}} + J_{M} \cdot i + J_{g} \cdot i\right] + T_{L} \quad (N \cdot m)$$







For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





Step 12b. Calculate **Torque due to Friction (T<sub>F</sub>)** :

$$T_{F} = \left[\frac{d_{0}}{1000 \cdot 2}\right] \cdot \left[\frac{P_{f}}{i \cdot \xi_{g} \cdot \xi_{b}}\right]$$

and

 $P_{f} = (W_{p} + W_{c}) \cdot \mu_{sys} + n \cdot D_{s}$ 

where:

 $P_f$  = Force due to Friction (N)  $W_p$  = Weight of Payload (N) (from Application Data)

- $W_c$  = Weight of Carriage (N) (from table on previous page)
- $\mu_{svs}$  = Coefficient of friction of carriage (from table on previous page)
  - n = Number of seals (from table on previous page)
  - D<sub>s</sub> = Seal Drag (N) (from table on previous page)
  - d<sub>0</sub> = Pulley pitch circle diameter (mm) (from table on page 353)
  - i = Gearbox ratio (from Application Data)
  - $\xi_{g}$  = Gearbox efficiency = 90%
  - $\xi_{\rm b}$  = Belt efficiency = 90%

First calculate Force due to friction ( $P_f$ ) and with this value calculate Torque due to friction ( $T_f$ ) using the formula, above.

Step 12c. Calculate Torque due to gravity (Tg):

$$T_{g} = \begin{bmatrix} d_{0} \\ 1000 \cdot 2 \end{bmatrix} \cdot \begin{bmatrix} P_{g} \\ i \cdot \xi_{g} \cdot \xi_{b} \end{bmatrix}$$
(N · m)  
$$P_{g} = (W_{p} + W_{c}) SIN\theta$$
(N)

and

where: 
$$P_{\alpha}$$
 = Force due to Gravity (N)

 $W_{p}^{*}$  = Weight of Payload (N) (from Application Data)

 $W_c$  = Weight of Carriage (N) (from table on previous page)

 $\theta$  = Angle from horizontal (for horizontal  $\theta$  = 0°, vertical  $\theta$  = 90° for upstroke  $\theta$  = 270° for downstroke)

 $d_0$  = Pulley pitch circle diameter (mm) (from table on page 353)

- i = Gearbox ratio (from Application Data)
- $\xi_g$  = Gearbox efficiency = 90%
- $\xi_{b}$  = Belt efficiency = 90%

First calculate Force due to gravity  $(P_g)$  and with this value calculate Torque due to gravity  $(T_g)$  using the formula, above.

Step 12d. Calculate **Torque due to external forces (T<sub>e</sub>):** 

$$T_{e} = \left[ \frac{d_{0}}{1000 \cdot 2} \right] \cdot \left[ \frac{P_{e}}{i \cdot \xi_{g} \cdot \xi_{b}} \right]$$
 (N · m)

where:

- d<sub>0</sub> = Pulley pitch circle diameter (mm) (from table on page 353)
- i = Gearbox ratio (from Application Data)
- $\xi_g$  = Gearbox efficiency = 90%
- $\xi_{\rm b}$  = Belt efficiency = 90%





The value of external force(s) ( $P_e$ ) (N) must be calculated or estimated from the application specifications. Any outside forces that have a component that acts along the axis of the Superslide system should be included as an **external force** ( $P_e$ ) (N).

With the calculated or estimated value of external force ( $P_e$ ), the Torque due to external force ( $T_e$ ) can be calculated from the formula on the previous page.

Step 12e. Calculate Peak Torque (Tpeak), the largest of the following:

Torque due to acceleration (T<sub>A</sub>):

 $T_A = T_J + T_F + T_g + T_e (N \cdot m)$ 

where:

re:  $T_J$  = Torque due to system inertia (N • m) (from step 12a)  $T_F$  = Torque due to friction (N • m) (from step 12b)  $T_g$  = Torque due to gravity (N • m) (from step 12c)  $T_e$  = Torque due to external forces (N • m) (from step 12d)

Torque at constant velocity (T<sub>cv</sub>):

$$T_{cv} = T_F + T_q + T_e (N \cdot m)$$

Torque due to deceleration (T<sub>D</sub>):

$$T_D = T_J - T_F - T_a - T_e$$
 (N • m)

Torque required to hold at rest (T<sub>H</sub>):

$$T_H = -T_F + T_q + T_e$$
 (N • m)

Step 12f. Calculate Root-Mean-Square Torque (T<sub>RMS</sub>) or Continuous Torque:

$$T_{RMS} = \sqrt{\frac{t_a (T_A)^2 + t_{cv} (T_{cv})^2 + t_d (T_D)^2 + t_h (T_H)^2}{t_a + t_{cv} + t_d + t_h}} (N \cdot m)$$

where:

 $t_a$  = time to accelerate (s)  $t_{cv}$  = time at constant velocity (s)  $t_d$  = time to decelerate (s)  $t_h$  = time at rest (s)

 $T_{A}$ ,  $T_{CV}$ ,  $T_{D}$ , and  $T_{H}$  are from step 12e.



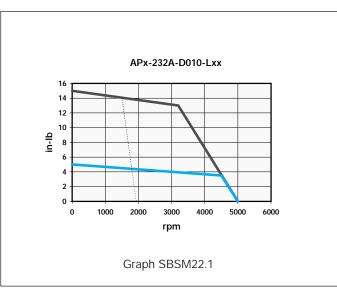


#### Speed vs Torque

Step 13. Determine the proper motor selection. Plot **Peak Torque (T**<sub>peak</sub>) against the **Required Motor Speed** from step 11 and enter the Motor Speed vs. Torque graph. (See the Motion Control Section, page 381). If the plotted point is below the curve for intermittent duty, then you have made a proper selection. Now plot **Continuous Torque (T**<sub>RMS</sub>) against the **Required Motor Speed** from step 11 and enter the graph again. If the plotted point is below the curve for continuous duty, then you have made a proper selection. If either of the plotted points fall above their respective curve then either a larger frame motor or a different gear ratio gearbox must be employed. Check mounting flange availability when increasing the motor frame size. Use of a system with a gearbox with a different gear ratio entails recalculating steps 11 and 12 with the new gear ratio in mind.

#### Motor Speed vs. Torque Curve

Graph SBSM22.1 is an example of a Speed vs. Torque curve for a NEMA 23 motor from the Motion Control section. BLX Series motors are available in standard NEMA frame sizes 23, 34 and 42 and can be combined with either a one, two, three or four axis controller. To determine the motor speed vs. torque curve that best suits the application and for a continuation of features and specifications refer to the Motion Control section, page 381.



To determine motor speed, use the following formula:

Motor RPM =  $\frac{V_{max} \cdot 60 \cdot i}{(P_B/1000)}$ where:  $V_{max}$  = maximum linear speed (m/s) (from step 8) i = gearhead ratio (from Application Data)

 $P_B$  = belt lead (mm)(from table in step 10)





#### **System Mounting**

The SuperSlide Belt Actuated System can be mounted using the T-nuts and T-slots from above with clamping fixtures and below as shown below. In addition, SuperSlide Belt Actuated System can also be mounted using the bolt down attachment holes found in each end block (System 2NE) or system support base (System 2RE). For other mounting fixity contact Thomson Systems Application Engineering.

SuperSlide 2NE

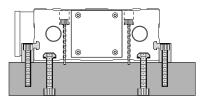


Figure 1: Mounting from below using T-slots or from above through mounting holes.

#### **T-Nuts for Mounting**

SuperSlide 2RE

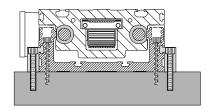
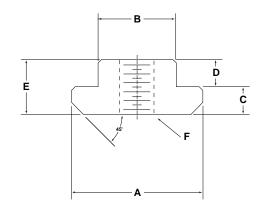


Figure 2: Mounting from above using T-slots or from above through mounting holes.



Daut Nicerala au	Α		Standard T-Nut Dimensions (Dimension								
Part Number	A	В	С	D	E	F					
TNUT-01-M3	7	4	1,75	1,25	3	M3					
TNUT-02-M4	9,5	5,5	2,25	1,75	4	M4					
TNUT-03-M4	12	7	2,5	2,5	5	M4					
TNUT-03-M5	12	7	2,5	2,5	5	M5					
TNUT-04-M4	16,5	7,9	4,8	1,2	6	M4					
TNUT-04-M5						M5					
TNUT-04-M6						M6					
TNUT-05-M4	19,5	9,8	5,8	2,8	8,6	M4					
TNUT-05-M5						M5					
TNUT-05-M6						M6					
TNUT-05-M8						M8					

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



#### Standard T-Nut Dimensions

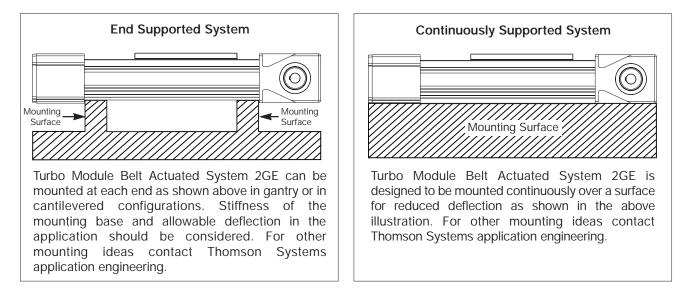
## METRIC Turbo Module\* Belt Actuated System

#### **System Selection**

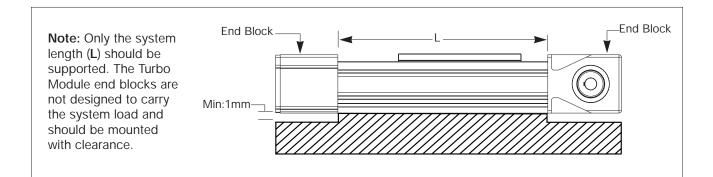
To determine the **Turbo Module Belt Actuated System** that best fits the application requirements the following design criteria should be evaluated:

- System Support Requirements
- System Stroke Length
- Maximum Allowable System Deflection
- Required Travel Life
- Force on the Most Heavily Loaded Bearing
- Load/Life Requirements Linear Bearings
- Motion (Move) Profile (Velocity, Acceleration)
- Maximum Belt Tooth Shear Strength
- Gear Motor Rotational Speed (Gear Reduction)
- Torque Calculations
- Size Motor using Torque/Speed Curves

Step 1. Based on your application needs determine the **Mounting Support Requirements**. Will the application require end or continuous support?



#### Note: For multi-axis application mounting and specifications contact the Thomson Systems Application Engineering Department



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

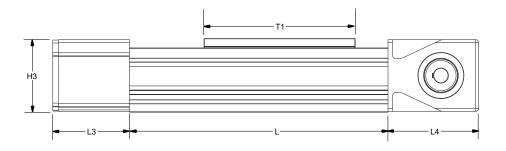


The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Page 359

### System Travel Lengths

Step 2. Determine the **Maximum Stroke Length**. For each Turbo Module Belt Actuated System, the Maximum Stroke Length can easily be determined. By subtracting the carriage length **(T1)** from the total system length **(L)** the maximum stroke length is determined. The application or required stroke length should not exceed this number.



**Standard Length and Delivery**. For each Turbo Module Belt Actuated System there is a standard length chart and delivery information that also includes the standard length increment and the maximum system length. Selecting a standard system length will minimize shipment time. Once you have selected a length that best fits your application requirements, simply determine the Maximum stroke length. The required stroke length should not exceed this number.

System 2GE Standard Lengths (L) (Lengths in mm)											mm)		
System	410	530	610	650	770	890	930	1010	1090	1130	1250	Х	Max.
2GE-M25												120	4010
2GE-M35												160	3970

Custom Lengths and Delivery Information
Systems ordered in standard lengths and longer lengths in increments of (X) are typically shipped in
two to three weeks. Custom length systems are available and require three to four weeks for delivery. For special requirements, please contact the Thomson <b>Systems</b> application engineering department.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

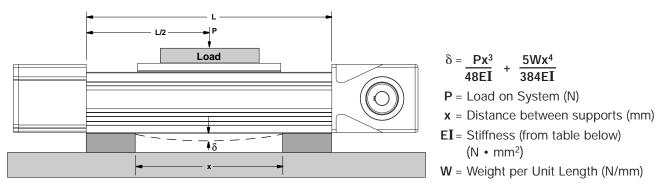




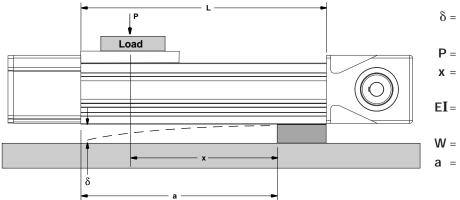
### **System Deflection**

Step 3. Determine the Turbo Module **System Deflection**. The Turbo Module 2GE is designed for the most stringent motion control requirements. Due to its unique structure, the Turbo Module can be mounted on simple or cantilevered supports. To maximize system reliability maximum system deflection should be considered in any simply supported application. Calculate deflection ( $\delta$ ) using one of the following formulae for the appropriate system support condition:

Step 3a. The end or simply supported case – deflection at center.



Step 3b. The cantilevered case - deflection at end.



- $\delta = \frac{Px^3}{3EI} + \frac{Wa^4}{8EI}$
- P = Load on System (N)
- EI = Stiffness (from table below) (N • mm<sup>2</sup>)
- W = Weight per Unit Length (N/mm)
- a = Unsupported length of base (mm)

Turbo	Turbo Module 2GE Turbo Module 2GE Belt Actuated System Data											
Turbo Mo	dule 2G	E Belt Ac	tuated Sys	stem Data								
Part	Nominal	Momer	nt of Inertia	Stiffn	iess	Unit Weight	Weight of	Weight of				
Number	Size		1		1		Motor End	Support End				
		I <sub>xx</sub>	l I <sub>yy</sub>	EIxx	EIyy	W	Block Assy.	Block Assy.				
		(mm <sub>4</sub> )	(mm <sub>4</sub> )	(N•mm <sub>2</sub> )	(N•mm <sub>2</sub> )	(N/mm)	(N)	(N)				
2GE-M15	15											
2GE-M25	25	5.76 X 10 <sup>6</sup>	8.23 X 10 <sup>6</sup>	3.97 X 10 <sup>11</sup>	5.67 X 10 <sup>11</sup>	0,186	93,2	20,6				
2GE-M35	35	2.84 X 10 <sup>7</sup>	3.73 X 10 <sup>7</sup>	1.96 X 10 <sup>12</sup>	2.57 X 10 <sup>12</sup>	0,353	270,6	109,8				

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





### **Travel Life**

Step 4. Determine the Required Travel Life (km).

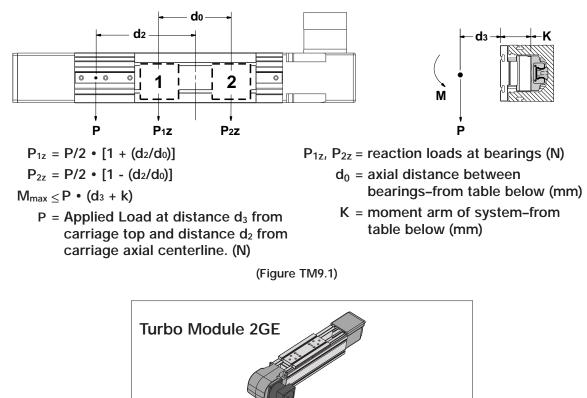
$$L_{t} = \frac{2 \cdot s \cdot f \cdot L_{h} \cdot 60}{10_{6}}$$

L<sub>t</sub> = required travel life (km) s = stroke (mm) f = frequency (cycles/minute) L<sub>h</sub> = service life (hrs)

### System Loading

Step 5. Determine the Force on the Most Heavily Loaded Bearing.

When selecting a Turbo Module Belt Actuated System, it is necessary to evaluate the bearing forces that are generated based on the position of the load and its movement during application. The free body diagram (figure TM9.1) is an example of the type of calculations that are required when determining resultant bearing forces. For other free body diagram examples see **Load Considerations** in the **Engineering Support Appendix**, page 377. The determination of the force on the most heavily loaded bearing allows you to enter the load life graph and select the system that best fits your application needs.



Turbo Module	2GE Belt A	Act. System Data (	Dimensions in mm)						
Part	Nominal	do	K						
Number	Size	(mm)	(mm)						
2GE-M15	15								
2GE-M25	25	219	59,5						
2GE-M35	35	284	90,0						

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

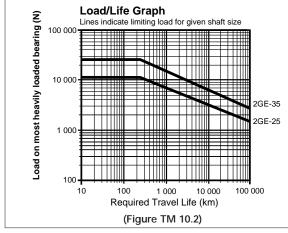
Page 362





### Load and Life Requirements

Step 6. Selecting the system that meets load and life requirements.

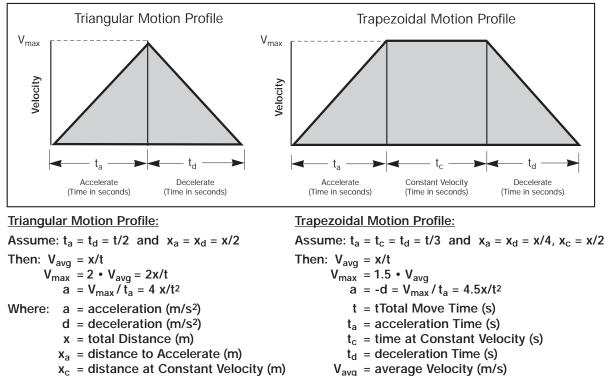


For each Turbo Module Belt Actuated System there is a graph (figure TM10.2) that allows for system selection based on the **Required Travel Life** and the **Force on the Most Heavily Loaded Bearing**. To determine the system which best meets your application requirements, simply enter the graph with your required travel life from step 4 and the load on the most heavily loaded bearing from step 5. Select a system with a characteristic curve that is above or to the right of the plotted point.

### **Motion Profile**

A typical linear belt actuated application normally consists of a series of motion profiles. The drive torque required to move the system should be evaluated for each motion profile. There are two basic motion profile types. The first and most simple move is a triangular motion profile which consists of two legs. The first leg is for acceleration and the second is for deceleration. The second motion profile type is trapezoidal which consists of an acceleration leg, a leg of constant velocity and a deceleration leg.

Step 7. Determine the Motion Profile that fits your application requirements. Calculate Vmax and a.



 $x_d$  = distance to Decelerate (m)  $V_{max}$  = maximum Velocity (m/s)

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





### Maximum Belt Tooth Shear Strength

Step 8. Calculate the **Total Axial Forces** on the system belt and determine whether they are within the limits of the **Belt Pre-Tension Force** and **Maximum Allowable Tooth Shear** of the belt. The **Total Axial System Belt Force (P<sub>s</sub>)** is the summation of **External Force (P<sub>e</sub>)**, **Acceleration Force (P<sub>a</sub>)**, and **Frictional Force (P<sub>f</sub>)**.  $P_{s} = P_{e} + P_{a} + P_{f}$ 

Step 8a. Determine the **External Axial Forces** ( $P_{e}$ ). External axial forces seen by the Turbo Module Belt Actuated system can be the result of application forces such as stretching fabric in a textile application or compressing boxing in a packaging application. In a vertical application, the external force is the addition of gravity acting on the payload. In those vertical applications the motor must be mounted above the load on the carriage.

Turbo Mo	Turbo Module 2GE										
Turbo Module	2GE Belt	Actuated	System	Data							
Part	Nominal	Carriage	Belt	Carriage	Seal	Number	Belt Pre	Maximum			
Number	Size	Weight	Weight	Friction	Drag	of	Tension	Axial Force,			
		(N)	(N/m)	Coefficient	(N)	Seals	Force (N)	Belt (N)			
2GE-M15	15			0,003	2,8	2					
2GE-M25	25	42,07	2,75	0,003	7,5	2	2250	3307			
2GE-M35	35	122,58	7,80	0,003	18,0	2	5400	9234			

Step 8b. Determine the **Acceleration force (P<sub>a</sub>).** To overcome the inertia generated by the payload, the carriage assembly and the belt force due to acceleration must be evaluated.

$$P_a = a \cdot (W_c + W_p + (W_b \cdot L \cdot 2))$$

a = V<sub>max</sub> / t<sub>a</sub> =  $\frac{4.5 \cdot x}{t^2}$  = linear acceleration (m/s<sup>2</sup>) (from step 7)

W <sub>c</sub> = carriage Weight (N)	Vmax = maximum velocity (m/s) (from Step 8)
W <sub>p</sub> = Weight of Payload (N)	$t_a$ = acceleration time (s)
W <sub>b</sub> = Weight of Belt (N/m)	x <sub>a</sub> = distance to accelerate (m)
g = acceleration due to gravity = $9,81 \text{ m/s}^2$	L = overall length of system (m)
	x = total distance (m)
	t = total time (s)

Step 8c. Determine the **Frictional Force** ( $P_f$ ). The total Frictional force is the sum of the payload and carriage mass times the system coefficient of friction plus the additional seal drag.

$$P_{f} = [\mu_{sys} \bullet (W_{p} + W_{c}) + n \bullet D_{s}]$$

W<sub>p</sub> = payload weight (N) (from Application Data)

D<sub>S</sub> = seal Drag (N) (see table above) n = number of seals (see table above)

 $W_c$  = carriage weight (N) (see table above)  $\mu_{svs}$  = system coefficient of friction (see table above)

Step 8d. Calculate Total Axial System Belt Force (Ps): Ps = Pe + Pa + Pf

Step 8e. Compare the calculated **Total Axial System Belt Force (P**<sub>s</sub>**)** with the **Belt Pre-Tension Force** in the tables above. If the calculated value exceeds the **Pre-Tension Force** in the table then the application parameters or the size of the system should be reconsidered, as the possibility exists that the belt could go into a slackened condition causing slippage on the pulley. In no case should the **Total Axial Belt Force (P**<sub>s</sub>**)** ever exceed the **Maximum Axial Force** for the belt in the tables above.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





### Maximum Belt Tooth Shear Capacity

Step 9. It is also important to check that the application parameters are within the limits of the **Belt Tooth Shear Capacity**.

Turbo Module 2GE										
Turbo Module	2GE Belt	Actuated System	em Data							
Part Number	Nominal Size	Pitch Circle Diameter (mm)	Lead (mm/rev.)	Number of Effective Teeth	Belt Width (mm)	Belt Pitch (mm)	Standard Gear Ratios	Maximum Axial Force (N)		
2GE-M15	15									
2GE-M25	25	92,31	290	12	50	10	1:1, 3:1, 6:1	3307		
2GE-M35	35	140,06	440	11	75	20	1:1,6:1,10:1	9234		

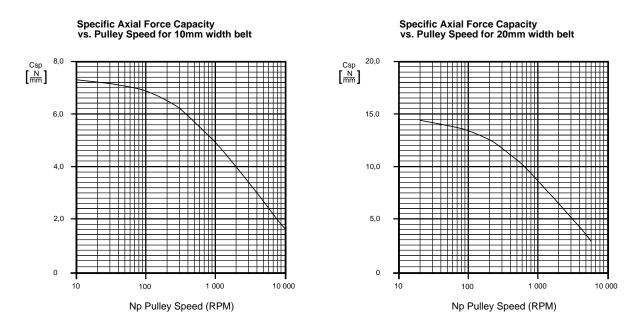
The formula for calculating Belt Tooth Shear Capacity (Cts) is as follows:

$$C_{ts} = C_{sp} \cdot Z_e \cdot W$$

C<sub>sp</sub> = specific Axial Force Capacity (N/mm)
 Z<sub>e</sub> = number of Effective Belt Teeth (from table above)
 W = belt Width (mm) (from table above)

Step 9a. The  $C_{sp}$  value is taken from the graphs below. Enter the graph for the appropriate **Belt Pitch** with the **Pulley Speed** ( $N_p$ ) calculated as follows:

 $N_{p} = \underbrace{V_{max} \cdot 60000}_{p_{b}} = \underbrace{V_{max} \cdot 60000}_{\pi d_{0}}$ (RPM)  $N_{p} = \underbrace{V_{max} \cdot 60000}_{p_{b}} = \underbrace{V_{max} \cdot 60000}_{\pi d_{0}}$ (RPM)  $M_{p} = pulley Speed (RPM)$  $V_{max} = maximum Linear Speed (m/s) (from step 7)$  $d_{0} = pitch Circle Diameter (mm) (from tables above)$  $p_{b} = \pi d_{0} = Lead (mm/rev.) (from tables above)$  $\pi = 3,1416$ 



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





Step 9b. Once **Pulley Speed** ( $N_p$ ) is calculated, and the **Specific Axial Force Capacity** ( $C_{sp}$ ) is determined from the graph on the previous page, locate the number of **Effective Belt Teeth** ( $Z_e$ ) and the **Belt Width** (W) from the tables on the previous page and calculate the **Belt Tooth Shear Capacity** ( $C_{ts}$ ):

$$C_{ts} = C_{sp} \cdot Z_e \cdot W$$

Step 9c. Compare the **Belt Tooth Shear Force Capacity** ( $C_{ts}$ ) with the calculated **Total Axial System Belt Force** ( $P_s$ ) from step 8e. If the calculated value exceeds the maximum allowable capacitiy from step 9c, the application parameters or the size of the system must be reconsidered.

Cts>Ps

### **Speed Requirements**

Rotational vs. Linear

Step 10. Determine the Motor Rotational Speed required to move at  $V_{max}$  for all system ratios.

The Turbo Module Belt Actuated System is equipped with an AccuTRUE\* Planetary Precision Gearhead already mounted. Each gearhead ratio (greater than 1:1) provides an increase in output torque and requires the motor to operate at a higher speed.

Turbo Module 2GE									
Turbo Modu	ile 2GE Be	elt Actuated	d System Da	ita					
Part	Nominal	Pitch	Lead	Standard					
Number	Size	Circle	(mm/rev)	Gear					
		Dia. (mm)		Ratios					
2GE-M15	15								
2GE-M25	25	92,31	290	1:1, 3:1, 6:1					
2GE-M35	35	140,06	440	1:1, 6:1,10:1					

Calculate the Maximum Motor Speed ( $N_{max}$ ) at the system Maximum Linear Speed ( $V_{max}$ ) from Step 7. using the following formula:

$$N_{max} = \frac{V_{max}}{p_b}i$$

 $\begin{array}{l} V_{max} = Maximum \ Linear \ Speed \ (m/s) \\ i = Gear \ Ratio(input/output) \\ d_0 = Pitch \ Circle \ Diameter \ (mm) \ (from \ table \ above) \\ p_b = \ \pi d_0 = Lead \ (mm/rev.) \ (from \ table \ above) \\ \pi = 3,1416 \end{array}$ 

or with unit conversions and constants:

$$N_{max} = \frac{V_{max} \cdot i \cdot (1000 \text{mm/m}) \cdot (60 \text{ sec/min})}{\pi d_0} = \frac{V_{max} \cdot i \cdot (19 \text{ 100})}{d_0} \text{ (RPM)}$$

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





### **Torque Calculations**

Step 11. In order to size a motor for your Turbo Module Belt Actuated system it is important to calculate the torque required to meet your application requirements with all of the parameters in mind. A **maximum** or **peak torque** ( $T_{peak}$ ) calculation is required. **Peak torque** is usually seen at the time of maximum acceleration, however, other factors such as torque due to external forces can affect when peak torque occurs. It is important to calculate for all torque conditions (**Torque due to acceleration** ( $T_A$ ), **Torque at constant velocity** ( $T_{cv}$ ), **Torque due to deceleration** ( $T_D$ ), and **Torque required to hold at rest** ( $T_H$ )), and take that torque with the largest magnitude as the **Peak Torque** ( $T_{peak}$ ).

> $T_A = T_J + T_F + T_g + T_e (N \cdot m)$   $T_{cv} = T_F + T_g + T_e (N \cdot m)$   $T_D = T_J - T_F - T_g - T_e (N \cdot m)$  $T_H = -T_F + T_g + T_e (N \cdot m)$

where:

- $T_F = Torque due to friction (N \cdot m)$
- $T_g$  = Torque due to gravity (N m)
- $T_e$  = Torque due to external forces (N m)

 $T_{J}$  = Torque due to system inertia (N • m)

It is also necessary to calculate a Root-Mean-Square Torque (T<sub>RMS</sub>) or Continuous Torque.

$$T_{RMS} = \sqrt{\frac{t_a (T_A)^2 + t_{cv} (T_{cv})^2 + t_d (T_D)^2 + t_h (T_H)^2}{t_a + t_{cv} + t_d + t_h}}$$
 (N • m)

where:

- $t_{cv}$  = time at constant velocity (s)
- $t_d$  = time to decelerate (s)

 $t_a$  = time to accelerate (s)

t<sub>h</sub> = time at rest (s)

Step 11a. Calculate Torque due to system inertia (T<sub>J</sub>):

$$T_{J} = \left[\frac{1000 \cdot 2 \cdot a}{d_{0}}\right] \cdot \left[\frac{J_{p}}{i^{2} \cdot \xi_{g}} + J_{M} \cdot i + J_{g} \cdot i\right] + T_{L} \qquad (N \cdot m)$$

and

$$T_{L} = \frac{P_{a} \cdot d_{0}}{1000 \cdot 2 \cdot i \cdot \xi_{g} \cdot \xi_{b}} \qquad (N \cdot m)$$

where:

T<sub>L</sub> = torque due to payload (N ⋅m)

- a = required linear acceleration (m/s<sup>2</sup>) (from step 7)
- d<sub>0</sub> = pulley pitch circle diameter (mm) (from table on next page)
- $J_p$  = drive pulley inertia (Kg m<sup>2</sup>) (from table on next page)
- $J_{M}^{-}$  = motor inertia (Kg m<sup>2</sup>)<sup>(1)</sup> (g cm<sup>2</sup> x 10<sup>-6</sup> = Kg m<sup>2</sup>)
- $J_g$  = gearbox inertia (Kg m<sup>2</sup>) (from table on next page)
- i = gearbox ratio (from Application Data)
- $\xi_q$  = gearbox efficiency = 90%
- $\xi_{\rm b}$  = belt efficiency = 90%
- $P_a$  = acceleration force (N)
- <sup>(1)</sup> For motor inertia data refer to technical information for your Motion Control System, page 431.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





Calculate acceleration force (P<sub>a</sub>) (N)

$$P_a = a \cdot (W_c + W_p + W_B \cdot L \cdot 2)$$
(N)

W<sub>c</sub> = weight of carriage (N) (from table on next page)

 $W_p$  = weight of payload (N) (from application data)  $W_B$  = weight of belt (N/m) (from table on next page)

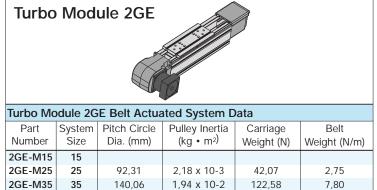
L = overall system length (m)

a = required linear acceleration  $(m/s^2)$ 

 $9 = acceleration due to gravity = 9,81 m/s^2$ 

Calculate **Torque due to payload (T<sub>1</sub>)**:

$$T_{L} = \frac{P_{a} \cdot d_{0}}{1000 \cdot 2 \cdot i \cdot \xi_{g} \cdot \xi_{b}} \qquad (N \cdot m)$$



Turbo Module 2GE Gearbox Data									
System Part Number	Gear Ratio	Gearbox Part Number	Gearbox inertia (Kg • m <sup>2</sup> )						
2GE-M25-OQN-K	1:1	AT-10-1	7,0 x 10 <sup>-2</sup>						
2GE-M25-OQN-L	3:1	AT-10-3	2,34 x 10 <sup>-3</sup>						
2GE-M25-OQN-M	6:1	AT-10-6	1,00 x 10 <sup>-3</sup>						
2GE-M35-OQN-N	1:1	AT-14-1	1,99 x 10 <sup>-1</sup>						
2GE-M35-OQN-P	6:1	AT-14-6	3,43 x 10 <sup>-3</sup>						
2GE-M35-OQN-Q	10:1	AT-14-10	2,55 x 10 <sup>-3</sup>						

Calculate Torque due to system inertia (T<sub>J</sub>) :

$$T_{J} = \left[\frac{1000 \cdot 2 \cdot a}{d_{0}}\right] \cdot \left[\frac{J_{p}}{i^{2} \cdot \xi_{g}} + J_{M} \cdot i + J_{g} \cdot i\right] + T_{L} \qquad (N \cdot m)$$

Step 11b. Calculate Torque due to Friction (T<sub>F</sub>) :

$$T_{F} = \left[\frac{d_{0}}{1000 \cdot 2}\right] \cdot \left[\frac{P_{f}}{i \cdot \xi_{g} \cdot \xi_{b}}\right]$$

and

$$P_{f} = (W_{p} + W_{c}) \bullet \mu_{sys} + n \bullet D_{s}$$

where:

 $P_f$  = force due to Friction (N)

 $W_p$  = weight of Payload (N) (from Application Data)  $W_c$  = weight of Carriage (N) (from table on next page)

- $\mu_{sys}$  = coefficient of friction of carriage (from table on next page)
  - n = number of seals (from table on next page)
- $D_s$  = seal Drag (N) (from table on next page) d<sub>0</sub> = pulley pitch circle diameter (mm) (from table on next page)
  - i = gearbox ratio (from Application Data)
- $\xi_g$  = gearbox efficiency = 90%
- $\xi_{\rm b}$  = belt efficiency = 90%

First calculate Force due to friction (P<sub>f</sub>) and with this value calculate Torque due to friction (T<sub>f</sub>) using the formula, above.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





Turbo N	Turbo Module 2GE											
Turbo Modu			ted Syst									
Part	Nominal	Carriage	Belt	Coefficient	Number	Seal						
Number	Size	Weight	Weight	Friction	of Seals	Drag						
		(N)	(N/m)	Carriage		(N)						
2GE-M15	15											
2GE-M25	25	42,07	2,75	0,003	2	7,5						
2GE-M35	35	122,58	7,80	0,003	2	18						

Step 11c. Calculate Torque due to gravity (Tg):

$$T_{g} = \left[\frac{d_{0}}{1000 \cdot 2}\right] \cdot \left[\frac{P_{g}}{i \cdot \xi_{g} \cdot \xi_{b}}\right]$$
 (N · m)

and

 $P_{q} = (W_{p} + W_{c}) SIN\theta$ (N)

where:

 $P_{\alpha}$  = Force due to Gravity (N)

- $W_p^g$  = Weight of Payload (N) (from Application Data)  $W_c$  = Weight of Carriage (N) (from table above)
  - $\theta$  = Angle from horizontal (for horizontal  $\theta$  = 0°, vertical  $\theta$  = 90° for upstroke  $\theta$  = 270° for downstroke

First calculate Force due to gravity ( $P_{\alpha}$ ) and with this value calculate Torque due to gravity ( $T_{\alpha}$ ) using the formula, above.

Step 11d. Calculate Torque due to external forces (T<sub>e</sub>):

$$T_{e} = \left[\frac{d_{0}}{1000 \cdot 2}\right] \cdot \left[\frac{P_{e}}{i \cdot \xi_{g} \cdot \xi_{b}}\right]$$
 (N · m)

where:

 $d_0$  = Pulley pitch circle diameter (mm) (from table on previous page)  $\xi_g = \text{Gearbox ratio (from Application Data)}$ 

- $\xi_{\rm b}$  = Belt efficiency = 90%

The value of external force(s) ( $P_e$ ) (N) must be calculated or estimated from the application specifications. Any outside forces that have a component that acts along the axis of the Turbo Module system should be included as an external force (P<sub>e</sub>) (N).

With the calculated or estimated value of external force ( $P_e$ ), the Torque due to external forces ( $T_e$ ) can be calculated from the formula above.

Step 11e. Calculate Peak Torque (Tpeak), the largest of the following:

Torque due to acceleration  $(T_{A})$ :

$$T_A = T_J + T_F + T_g + T_e (N \cdot m)$$

where:  $T_{J}$  = Torque due to system inertia (N • m) (from step 11a)

 $T_F$  = Torque due to friction (N • m) (from step 11b)

 $T_g =$  Torque due to gravity (N • m) (from step 11c)  $T_e =$  Torque due to external forces (N • m) (from step 11d)

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





### METRIC Turbo Module<sup>\*</sup> Belt Actuated System

Torque at constant velocity  $(T_{cv})$ : $T_{cv} = T_F + T_g + T_e (N \cdot m)$ Torque due to deceleration  $(T_D)$ : $T_D = T_J - T_F - T_g - T_e (N \cdot m)$ Torque required to hold at rest  $(T_H)$ : $T_H = -T_F + T_g + T_e (N \cdot m)$ 

Step 11f. Calculate Root-Mean-Square Torque (T<sub>RMS</sub>) or Continuous Torque:

$$T_{RMS} = \sqrt{\frac{t_a (T_A)^2 + t_{cv} (T_{cv})^2 + t_d (T_D)^2 + t_h (T_H)^2}{t_a + t_{cv} + t_d + t_h}} (N \cdot m)$$

where:

 $T_{A'} T_{CV'} T_{D'}$  and  $T_{H}$  are from step 11e.

 $t_a$  = time to accelerate (s)  $t_{cv}$  = time at constant velocity (s)  $t_d$  = time to decelerate (s)

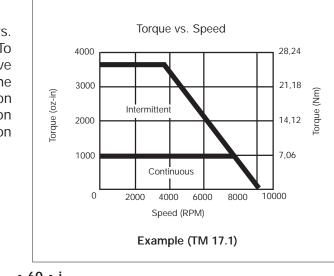
t<sub>h</sub> = time at rest (s)

### Speed vs Torque

Step 12. Determine the proper Servo motor selection. Plot **Peak Torque (T**<sub>peak</sub>) against the **Required Motor Speed** from step 10 and enter the Motor Speed vs. Torque graph (Graph TM 17.1). If the plotted point is below the curve for intermittent duty, then you have made a proper selection. Now plot **Continuous Torque (T**<sub>RMS</sub>) against the **Required Motor Speed** from step 10 and enter the graph again. If the plotted point is below the curve for continuous duty, then you have made a proper selection. If either of the plotted points fall above their respective curve then either a larger frame motor or a different gear ratio gearbox must be employed. Check mounting flange availability when increasing the motor frame size. Use of a system with a gearbox with a different gear ratio entails recalculating steps 10 and 11 with the new gear ratio in mind.

### Motor Speed vs. Torque Curve

Graph TM 17.1 is an example of a Speed vs. Torque curve for a typical DC Servo motor. To determine the motor Speed vs. Torque curve that best suits your application a review of the application parameters with our Application Engineers and your selection of a motion control system will be required. See the Motion Control Section, page 381.



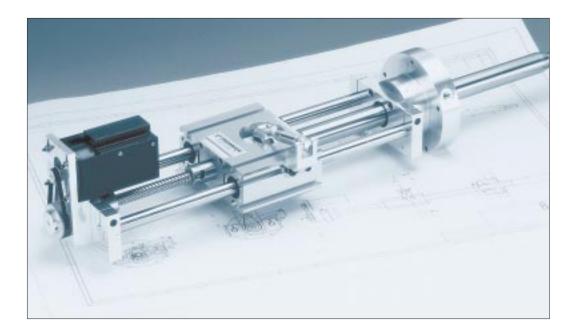
Motor RPM =  $\frac{V_{max} \cdot 60 \cdot i}{(P_B/1000)}$ 

where:  $V_{max}$  = maximum linear speed (m/s) (from step 7) i = gearhead ratio (from Application Data)  $P_B$  = belt lead (mm) (from table in step 9a)

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



# **Engineering Support Appendix**



Evaluating your needs and providing you with the information to make the system selection that's right for you.

Thomson Linear Motion Systems have been designed to fit a broad spectrum of linear motion applications. From light to heavy loads from short stroke to nearly infinite length from modular to completely integrated units, our Systems are built to meet your needs. Unactuated or actuated with ball screws or belts in both inch and metric sizes, we provide a complete solution to your Linear Motion requirements.

This support section includes the basic engineering data and formulae to determine deflection, load-life relationships, free body diagrams, and material specifications needed to select the proper system for your design needs.

Each section of the catalog is preceded with a concise selection section designed to be a road map to your Linear Motion Solution. Each section concludes with an Application Analysis required for a proper system selection. Simply fax your Application Analysis to Thomson Application Engineering at 1-516-883-9039 and receive quick, accurate answers to your selection questions.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





### Engineering Support Choosing A Thomson Linear Motion System

Many variables influence the selection of a Linear Motion System. The best solution demands a thorough evaluation of the design application. Only then can the design criteria be established.

The following basic design criteria should be considered when selecting a linear motion system:

- system support requirements
- system stroke length
- system deflection
- envelope limitations
- system load capacity
- actuator load capacity
- speed and acceleration
- drive requirements
- accuracy and repeatability
- environment

If your application has special requirements, they should be added to the list of criteria.

### Calculating Bearing and Inner Race Size

The factors which influence bearing size are **maximum load on a single bearing** and **total travel life**. Calculating stroke length and duty cycle will provide an accurate travel life requirement.

Applied load and travel life are related through the following formula:

Life =  $(C/F)^3 \times 10^7$  (in) =  $(C/F)^3 \times 250$  (km)

where:

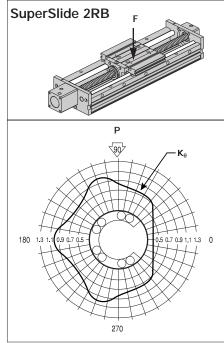
- c = dynamic load rating of the Super Smart Ball bushing\* bearing
- F = applied load

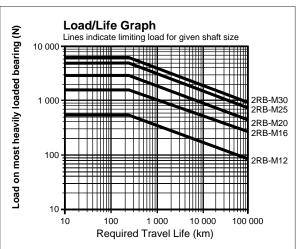
Thomson Super Smart Ball bushing bearings will provide 10 million inches or 250 km of travel life at their rated load capacities, and extended life under reduced load. The load/life graph provides a quick evaluation of bearing performance based on maximum load on a single bearing and travel life requirements.

To determine your bearing/inner race size, plot your maximum load on the most heavily loaded bearing and required travel life. If the plotted point occurs **above** a bearing performance

curve, specify the next largest size System.

It is also important to keep in mind that the orientation of load can effect the load carrying capacity of the Ball Bushing bearing. For this reason polar graphs are provided in each system selection section. The force on the must heavily loaded bearing used in the Load/Life graph should be the quotient of the resultant applied load and the  $K_{\theta}$  value from the polar graph.





### Determining Stroke, System Length, Envelope.

A primary consideration for your application will be the maximum stroke required. Each Thomson System dimension chart lists the formula for maximum stroke and a pre-calculated summation of components which limit the stroke.

Maximum Stroke Length is determined by subtracting the carriage length (T1 or T2) and 2 times the end support block length (L3), where necessary, from the total system length (L). For systems requiring protective bellows, consult the appropriate selection section for stroke reduction formulae. Thomson systems are supplied in a variety of standard lengths which vary with System type and size. A standard length chart has been provided which accompanies each System's technical data. Standard lengths require shorter lead times and are more economical.

**Custom lengths** are available in most linear motion systems. Careful consideration and evaluation of design criteria should occur before specifying a custom length System. Contact the Thomson **Systems** application engineering department for assistance in addressing custom requirements.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.

Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries



### **Engineering Support** Lubrication, Materials and Part Number Specifications

Thomson Linear Motion Systems are pre-lubricated with a rust preventative oil. This process is designed to inhibit the corrosion of the steel components within the system during transport.

Available upon special request, LinearLube\* lubricant can be applied to the ball tracks of the Ball Bushing\* bearings. This specially formulated lubricant provides optimum performance for most applications. LinearLube is a synthetic lubricant utilizing suspended Teflon<sup>®</sup> in a specially formulated base compound.

LinearLube provides excellent performance characteristics in a wide range of applications. It is FDA listed, non-polluting, noncorrosive. LinearLube will not stain and adheres tightly to parts, forming a water resistant barrier and airtight seal against contaminant's.

LinearLube reduces overall maintenance and extends service intervals, which helps decrease your maintenance costs.

- · Maintains properties in operating temperatures from -65°F to 450°F
- U.S.D.A. Rated H1 (Non-Toxic)
- · Inhibits wear, rust, and corrosion
- Will not oxidize in use
- 100% water resistant

\*LinearLube is an NLGI Grade II class material which contains PTFE (Teflon®) particles suspended in a specially compounded base.

All Thomson Ball Bushing bearings require a small amount of grease or oil to operate. For most applications, lubricant is recommended to prevent wearing and rusting of the bearing surfaces. When linear speeds are high, a light oil should be used and the bearing should be prevented from running dry for a prolonged period of time.

A medium to heavy oil or light grease has greater adhesion properties that afford longer bearing protection and minimize sealing problems. The numerous built-in pockets in the Ball Bushing bearing retainer allow grease to be stored for an extended period of time. Though not generally recommended, in some lightly loaded, low speed and highly contaminated applications, Ball Bushing bearings have been used without lubrication. For these types of applications contact Thomson application engineering.

#### Specifying a Thomson linear motion system.

Thomson linear motion systems are specified quickly and easily with a single part number. When you have evaluated your linear motion requirements and selected a System which best meets your criteria, review the System part

number, System length, and any special options to generate a single order number.

Custom lengths or special requirements should be reviewed with the Thomson systems application engineering department.

#### System Replacement Components

Replacement components form systems are available from Thomson. Assure the accuracy and repeatability of your system by specifying a -XS after the component part number.

**Thomson Linear Motion systems** are designed and manufactured through advanced processes with high grade materials chosen for their strength, durability, and hardness. The following is a comprehensive list of the materials utilized throughout Thomson systems.

Ball Bushing Bearing	
Components	Material
Super Smart Ball Bushing* bearings	
<ul> <li>Sleeve and Retainers</li> </ul>	Thomson Engineered Plastic <sup>††</sup>
Bearing Plates	Hardened Bearing Steel
• Balls	Chrome Alloy Steel
Seals	Synthetic Rubber
Pillow Block Housing	Aluminum Alloy†
Supports	
Type ASB End Support	Aluminum Alloy†
Type SB End Support	Iron
Type SRA Rail Support	Aluminum Alloy†
Twin Shaft End Support	Aluminum Alloy†
Twin Shaft Web End Support	Aluminum Alloy†
<ul> <li>Integrated End Support</li> </ul>	Aluminum Alloy†
Dual Shaft Support Rail	Aluminum Alloy†
Inner Race (60 Case™ Shafting)	Case Hardened High Carbon Steel
Carriage	
Universal Carriage	Aluminum Alloy†
Twin Shaft Carriage	Aluminum Alloy†
Twin Shaft Web Carriage	Aluminum Alloy†
<ul> <li>Modular Dual Shaft Carriage</li> </ul>	Aluminum Alloy†
<ul> <li>Integrated Dual Shaft Carriage</li> </ul>	Aluminum Alloy†
†Custom Black Anodized for inch size systems Custom Grey Anodized for metric size systems Custom system lengths may require black paint to p Assemblies and Shaft support Rails. If a specific su	

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

Systems application engineering department.

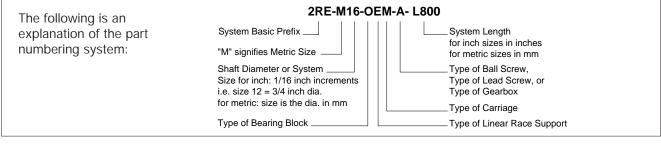


The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. <sup>®</sup> Teflon is a registered trademark of E.I. DuPont de Nemours & Company.





### Part Number Specifications



### **Coefficient of Friction and Seal Drag**

### **Coefficient of Friction**

The coefficient of friction of Thomson Ball Bushing<sup>\*</sup> bearings ranges from 0.001 to 0.004. There are two components of the coefficient of friction, the rolling or operating friction and the static or breakaway friction.

### **Coefficient of Rolling Friction**

The rolling coefficient of friction is measured by the force required to operate the Ball Bushing at a constant rate of travel. The formula for determining frictional resistance during operation is as follows:

#### $P_f = P x f_r$

where:  $P_f$  = Frictional resistance (lbf)

- **P** = Resultant of externally applied loads (lbf)
- $\mathbf{f}_{\mathbf{r}}$  = Coefficient of rolling friction

The following table describes the coefficient of rolling friction of Ball Bushing bearings operating on Thomson 60 Case\* LinearRace\*. These values are grouped according to the number of ball circuits in each bearing. Friction coefficients are constant among bearings having three and four ball circuits, but slightly less for bearings with five or six ball circuits. A dry Ball Bushing bearing has the lowest coefficient of friction due to the complete absence of lubricant surface tension effects. Values for grease lubrication ranges from 100% greater in the smaller sizes to 20% to 50% greater in the larger sizes. Oil lubrication

#### Ball bushing Bearing coefficients of rolling friction (f,)

	5	5			5	•	14	
Bearing I.D.	Number of Ball	Condition of		Load in % of Rolling Load Rating (for 2,000,000 inches of travel)				
	Circuits	Lubrication	125%	100%	75%	50%	25%	
1/4", 3/8"		No Lube	.0011	.0011	.0012	.0016	.0025	
1/2", 5/8"	3 & 4	Grease Lube	.0019	.0021	.0024	.0029	.0044	
8 mm		Oil Lube	.0022	.0023	.0027	.0032	.0045	
<sup>3</sup> / <sub>4</sub> ", 1"		No Lube	.0011	.0011	.0012	.0024	.0033	
12, 16 mm	5	Grease Lube	.0018	.0019	.0021	.0024	.0033	
		Oil Lube	.0020	.0021	.0023	.0027	.0036	
1 <sup>1</sup> / <sub>4</sub> "		No Lube	.0011	.0011	.0012	.0014	.0019	
thru 4″	6	Grease Lube	.0016	.0016	.0017	.0018	.0022	
20 thru 40 mm		Oil Lube	.0011	.0011	.0012	.0013	.0018	
<sup>5</sup> / <sub>8</sub> " thru		No Lube	.0011	.0011	.0012	.0013	.0019	
1 <sup>1</sup> / <sub>2</sub> "	10	Grease Lube	.0014	.0014	.0015	.0016	.0019	
12 thru 40 mm		Oil Lube	.0016	.0016	.0017	.0019	.0025	

(medium/heavy, viscosity 64 cs @  $100^{\circ}$ F) achieves frictional values slightly higher than those for grease lubrication.

### **Coefficient of Static Friction**

The coefficient of static or breakaway friction is measured by the force required to initiate Ball Bushing bearing movement. The formula used to determine static frictional resistance is:

$$P_f = P x f$$

where:  $f_o = Coefficient of static friction$ 

Ball bushing	Bearing	coefficients	of static	friction (	(f_)
Dali bushing	Dearing	coenicients	UI Static	inction (	( <sup>1</sup> 0)

	<u> </u>			- 0-
Load in % of Rolling Load Rating				
125%	100%	75%	50%	25%
.0028	.0030	.0033	.0036	.0040

The values for the coefficient of static friction or breakaway friction are not measurably affected by the number of ball circuits in the bearing or by the lubrication condition.

#### Seal Drag

Another variable that affects the frictional resistance in a Ball Bushing bearing system is seal drag. When seals are used to retain lubricant or to prevent entry of foreign particles, frictional resistance must be taken into account for determining total frictional drag. In applications where contamination is minimal, the seals can be removed to reduce frictional drag. In highly contaminated applications, seals, wipers and or scrapers are used to minimize the ingress of contamination into the bearing. This protective measure adds to the frictional drag of the bearing system. There is a fine line between minimizing frictional drag and maximizing contaminant protection which is controlled by the addition or removal of seals, wipers or scrapers. In applications that require low frictional drag in highly contaminated environments, contact Thomson application engineering.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.

Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



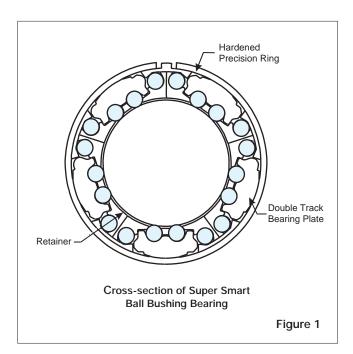
# Engineering Support Super Smart Ball Bushing Bearing

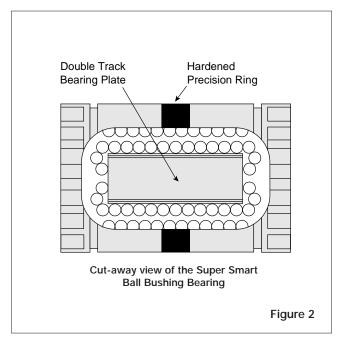
The new Super Smart Ball Bushing\* bearing represents a major advancement in linear bearing technology worldwide. The Super Smart Ball Bushing bearing offers twice the load capacity or eight times the travel life of the industry standard Thomson Super Ball Bushing bearing. An enormous technological breakthrough, considering the Super Ball Bushing Bearing already offers three times the load capacity or twentyseven times the travel life of conventional linear bearings.

### Technologically Advanced Design

The load carrying component of the Super Smart Ball Bushing bearing is the combination four hardened and precision ground, bearing quality steel components (Figures 1 & 2).

The first component is the steel outer ring, which allows the bearing to maintain its diametrical fit-up even when installed in a housing that is slightly out-ofround. The unique ring design also allows for bearing adjustment and the removal of diametrical clearance. The second component is the precision ground double track bearing plate that provides twice the load capacity and features universal self-alignment.





The third component is the rolling element. Each Super Smart Ball Bushing utilizes precision ground balls manufactured to the highest quality standards for roundness and sphericity. The result is maximum load capacity, travel life and performance.

The last component is the 60 Case<sup>\*</sup> LinearRace<sup>\*</sup> that acts as the inner race to the Super Smart Ball Bushing Bearing. Each 60 Case LinearRace is manufactured to the highest quality standards for roundness, straightness, surface finish and hardness. Roundness is held under eighty millionths of an inch ( $2\mu$ m); straightness to .002 inches per foot (0,050mm per 0,3m); surface finish under twelve microinch and hardness between 60-65 HRC. The combination of inner and outer race or 60 Case LinearRace and Super Smart Ball Bushing bearing provides the basis for the RoundRail Advantage.

#### The RoundRail Advantage

The RoundRail Advantage is the inherent ability of Super Smart Ball Bushing bearing system to accommodate torsional misalignment (caused by inaccuracies in carriage or base machining or by machine deflection) with little increase in stress to bearing components. Installation time and cost are minimized and system performance is maximized.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

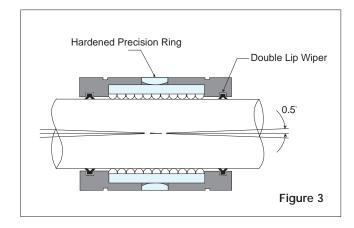




# Engineering Support Super Smart Ball Bushing Bearing

### Universal Self-Alignment

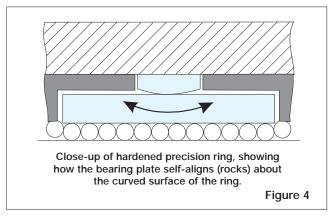
The bearing plate of the Super Smart Ball Bushing<sup>\*</sup> Bearing is designed with many unique and technologically advanced features. The Universal Self-Alignment feature assures that the Super Smart Ball Bushing Bearing will achieve maximum performance regarding load capacity, travel life, smooth operation and coefficient of friction. The three components that make up universal self-alignment are **Rock**, **Roll** and **Yaw**.

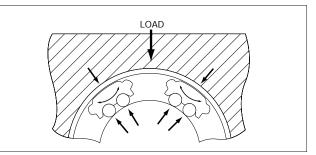


### Rock

The bearing plate is designed to rock 0.5° about the hardened precision ground outer ring (Figures 3 & 4). This self-aligning feature allows the Super Smart Ball Bushing bearing to absorb misalignment caused by inaccuracies in housing bore alignment or 60 Case LinearRace deflection.

This rocking capability provides smooth entry and exit of the precision balls into and out of the load zone assuring a constant low coefficient of friction. By compensation for misalignment, each bearing ball in the load carrying area is uniformly loaded providing maximum load capacity.





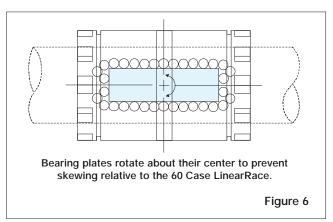
Close-up of double track bearing plates showing how they self-align (roll) to evenly distribute the load on each of their two ball tracks.

Figure 5

### Roll

The second key design feature of the Super Smart Ball Bushing bearing plate is its ability to **Roll**. The bearing plate is designed with the radius of its outer surface smaller than the inside radius of the precision outer ring (Figure 5). This allows the bearing plate to compensate for torsional misalignment and evenly distribute the load on each of its two ball tracks. The roll component assures maximum load capacity and travel life.

#### Yaw



The shape formed by the **Rock** and **Roll** features allows the Super Smart Ball Bushing bearing plate to rotate about its center (Figure 6). This allows the Super Smart Ball Bushing bearing to absorb skew caused by misalignment. The result is a constant low coefficient of friction and maximum bearing performance.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





### Load Considerations

When designing a linear motion system, it is necessary to consider the effect the variables of operation will have on performance.

The following examples demonstrate how the position of the load and the center of gravity can influence the system selection. When evaluating your application, review each of the forces acting on your system and determine the System best for your needs.

$$F_{1Z} = \frac{L}{4} + \left(\frac{L}{2} \times \frac{d_2}{d_0}\right) - \left(\frac{L}{2} \times \frac{d_3}{d_1}\right)$$

$$F_{2Z} = \frac{L}{4} - \left(\frac{L}{2} \times \frac{d_2}{d_0}\right) - \left(\frac{L}{2} \times \frac{d_3}{d_1}\right)$$

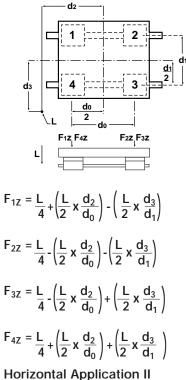
$$F_{3Z} = \frac{L}{4} - \left(\frac{L}{2} \times \frac{d_2}{d_0}\right) + \left(\frac{L}{2} \times \frac{d_3}{d_1}\right)$$

$$F_{4Z} = \frac{L}{4} + \left(\frac{L}{2} \times \frac{d_2}{d_0}\right) + \left(\frac{L}{2} \times \frac{d_3}{d_1}\right)$$

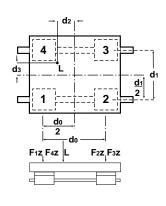
1.

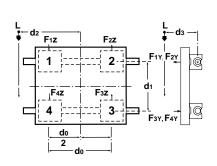
### Horizontal Application I

At the time of movement with uniform velocity or at the time of stop.



### At the time of movement with uniform velocity or at the time of stop.



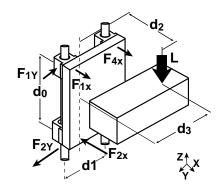


- $F_{1Y} \sim F_{4Y} = \left(\frac{L}{2} x \frac{d_3}{d_1}\right)$  $F_{1Z} = F_{4Z} = \frac{L}{4} + \left(\frac{L}{2} \times \frac{d_2}{d_0}\right)$
- $F_{2Z} = F_{3Z} = \frac{L}{4} \left(\frac{L}{2} \times \frac{d_2}{d_0}\right)$

**Side Mounted Application** At the time of movement with uniform velocity or at the time of stop.

### Terms

- $d_0$  = distance between centerlines of pillow blocks (in) or (mm)
- $d_1$  = distance between centerlines of shafts (in) or (mm)
- $d_2$  = distance from centerline of carriage to load action point (in) or (mm)
- $d_3$  = distance from centerline of carriage to load action point (in) or (mm)
- F<sub>NX</sub>= Force in the X-axis direction (lb<sub>f</sub>) or (N)
- F<sub>NY</sub>= Force in the Y-axis direction (lb<sub>f</sub>) or (N)
- **F**<sub>NZ</sub>= Force in the **Z**-axis direction (lb<sub>f</sub>) or (N)



$$F_{1X} \sim F_{4X} = \frac{L}{2} \times \frac{d_2}{d_0}$$

$$F_{1Y} \sim F_{4Y} = \frac{L}{2} \times \frac{d_3}{d_0}$$

$$F_{1X} + F_{4X} \sim F_{2X} + F_{3X}$$

### $F_{1Y} + F_{4Y} \sim F_{2Y} + F_{3Y}$

#### **Vertical Application**

At the time of movement with uniform velocity or at the time of stop. At the time of start and stop, the load varies because of inertia.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.



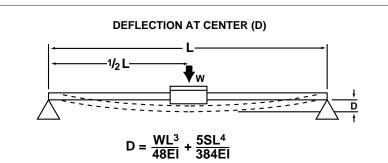


When a Linear Motion System is used in an end supported configuration it is important to ensure that system deflections at the bearing locations are kept within performance limitations.

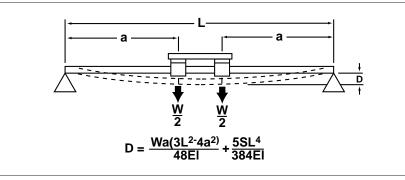
These equations give the deflection at the center of an end supported system. Systems with continuous 60 Case\* LinearRace\* support are not subject to the same types of deflection.

For more detailed information of the deflection characteristics of Thomson linear motion products contact application engineering.

Cimply Cupported	$( \cap C \cap \cap )$	LincorDooo	with One Dleek
Simply Supported	60 Case	LinearRace	WITH ONE BLOCK



Simply Supported 60 Case LinearRace with Two Blocks



### LEGEND

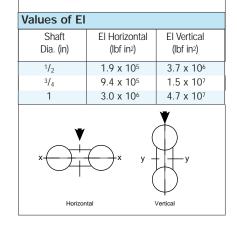
- D = Deflection (in) or (mm)
- $W = Load (Ib_f) or (mm)$
- L = Length of unsupported 60 Case LinearRace (in) or (mm)
- a = Distance to first bearing with carriage at center position (in) or (mm)
- $S = Unit weight of LinearRace (Ib_f/in) or (N/mm)$
- $E = Modulus of Elasticity (lb_f/in^2) or (N/mm^2)$
- I = Moment of inertia of area through diameter of LinearRace (in<sup>4</sup>) or (mm<sup>4</sup>)

### For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

60 Case Line	earRace Stiffr	ness and Wei	ghts		
	Inch Size			Metric Size	
Diameter (in)	EI (Ib <sub>f</sub> • in <sup>2</sup> )	Weight (lb <sub>f</sub> / in)	Diameter (mm)	EI (N • mm²)	Weight (N/mm)
1/4	5.8 x 10 <sup>3</sup>	0.014	8	3,83 x 10 <sup>7</sup>	0,0038
3/8	2.9 x 104	0.031	12	1,94 x 10 <sup>8</sup>	0,0087
1/2	9.2 x 104	0.055	16	6,12 x 10 <sup>8</sup>	0,0154
5/ <sub>8</sub>	2.3 x 10⁵	0.086	20	1,50 x 10 <sup>9</sup>	0,0240
3/4	4.7 x 10⁵	0.125	25	3,65 x 10 <sup>9</sup>	0,0379
1	1.5 x 10 <sup>6</sup>	0.222	30	7,57 x 10 <sup>9</sup>	0,0542
1 <sup>1</sup> / <sub>4</sub>	3.6 x 10 <sup>6</sup>	0.348	40	2,39 x 10 <sup>10</sup>	0,0968
1 <sup>1</sup> / <sub>2</sub>	7.5 x 10 <sup>6</sup>	0.500			

Deflection for Twin Shaft Web System

Since the Twin Shaft Web rail has different stiffness depending on its orientation, an appropriate El value must be used based upon the direction of loading. Select the orientation of your load from the figure below and then use the appropriate El value in the deflection equation.







### Engineering Support 60 Case LinearRace Specifications

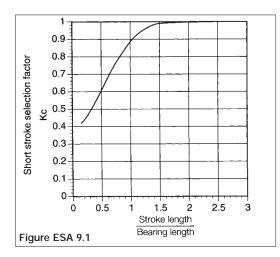
Thomson 60 Case\* LinearRace\* provides the inner race for Thomson Ball bushing bearings. All 60 Case LinearRace is manufactured to extremely close tolerances for surface finish, roundness, hardness and straightness to provide long service life with reduced maintenance.

#### Specifications:

Hardness: Surface Finish: Roundness: Straightness: Length Tolerance	HRC 60-65 12R <sub>a</sub> microinch (R <sub>a</sub> 0,30 $\mu$ m) 80 millionths of an inch (2 $\mu$ m) Standard001 inch per foot (0,050mm per 0,3m) (.002 in or 0,050mm TIR) Special0005 inch per foot (0,025mm per 0,3m) cumulative (.001 in or 0,025mm TIR) Standard +/030 (+/-0,75mm) for diameters up to 1 1/2 inch or 40mm. Special length tolerances available.
Chamfer:	Standard chamfer on diameters up to 1 inch or 25mm is .030 x 45' or 0.8mm x 45' and .060 x 45' or 1,6mm x 45' for diameters larger than 1 inch or 25mm.
Tensile Strength:	Case: 335,000 psi, Core: 100,000 psi 2,31 GPa 0,69 GPa
Yield Strength:	Case: 250,000 psi, Core: 75,000 psi 1,72 GPa 0,52 GPa

#### Short Stroke Applications

In applications when the stroke length is short, the life of the shaft is shorter than that of the Ball Bushing bearing. In short stroke applications, the required dynamic load capacity must be multiplied by the factor  $K_C$  found on Figure ESA 9.1.



### **Application Tips**

### Two Ball Bushing Bearings per 60 Case LinearRace When using the Super Smart, Super or Precision Steel

Ball Bushing bearing it is recommended that two Ball Bushings bearings be used on each 60 Case Linear Race. This will assure system stability as well optimum performance. If envelope constraints prohibit the use of two Ball Bushing bearings per 60 Case LinearRace contact application engineering.

#### Ball Bushing Bearing Spacing v. 60 Case LinearRace Spacing

In parallel 60 Case LinearRace applications, the ratio of 60 Case LinearRace spacing to Ball Bushing bearing spacing should always be less than three to one. This will assure a constant breakaway and operating friction.

#### 60 Case LinearRace Parallelism

In most applications the maximum acceptable out of parallelism condition is .001 inch (0,025 mm) over the entire full system length. In applications where preload is present a closer 60 Case LinearRace parallelism is recommended.

### Measuring 60 Case LinearRace Alignment

Methods for establishing or checking 60 Case LinearRace straightness and parallelism depends on the accuracy required. Lasers, collimator or alignment telescopes can be used for very precise applications, while accurate levels, straight edges, micrometers and indicators will suffice for the majority of applications which have less stringent accuracy requirements.

#### Access for Lubrication

Thomson Super Smart and Super Ball Bushing Pillow blocks in inch sizes are equipped with either an oil lubrication fitting or a 1/4-28 access hole for lubrication. To use the oil fitting simply insert a lubrication device into the oil nipple by depressing the spring loaded ball. The 1/4-28 tapped hole is a standard size for most grease and lubrication fittings. Simply install the lubrication fitting of your choice and it is ready for immediate use. super Ball Bushing Pillow blocks in sizes .250 through .500 inch diameter are equipped with oil lubrication fittings. Super Ball Bushing pillow blocks in sizes .625 inch and above and all Super smart Ball Bushing Pillow Blocks are equipped with a 1/4-28 access for lubrication.

Super smart Ball Bushing Bearing pillow blocks in metric sizes are provided with an M6 x 0,1 access for lubrication. Simply install the appropriate lubrication fitting and it is ready for immediate use.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.





# Systems Applications Application Analysis

Determining the system which best meets the demands of your application and provides optimum performance requires the evaluation of a number of variables. The accompanying form establishes basic criteria to initiate the analysis of your application. In addition, the Engineering Support Appendix has been designed with pertinent data and formulas used to specify the proper system for your application. If you have guestions or special needs a Thomson systems engineer can assist

you in evaluating your application and recommending a system solution. Simply call 1-800-554-8466.

Application Description:	Horizontal	Vertical
System Part Number:		
Quantity Required:		
Weight of Load (lbs) or (N):		
Space Requirements (LxHxW):		
Stroke Length Requirements (in) or (mm):		
Support Requirements:	End Supported	Full Support
Maximum Velocity Requirements (in/s) or (m/s):	· · ·	
Maximum Acceleration Requirements (in/s <sup>2</sup> ) or (m/s <sup>2</sup> ):		
Required Straightness of Travel Accuracy (in/ft) or (µm/300mm):		
Required Positioning Accuracy (in) or (µm):		
Required Repeatability (in) or (µm):		
Life Requirement (in) or (km):		
Cycle (in/yr) or (km/yr):		
Environmental Considerations:		
Other Design Criteria:		
Production Time Frame:		
Company:		
Name:		
Title:		
Address:		
City: State:		Zip:
Telephone: Fax:		
Please Fax your Application Analysis to 516-883-9039	Attention: Application	n Engineering

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at systems@thomsonmail.com.

Engineering Support Appendix





## THOMSON INDUSTRIES, INC. **MOTION CONTROL SOLUTION** Engineering Guide for Motion Control

• Easy to Specify; Complete Solutions • Easy to Install; Plug & Play



www.thomsoncontrol.com

For Application Engineering assistance contact the Thomson Technical HelpLine at 1-800-554-8466. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Page 381

### MOTION CONTROL SOLUTION GUIDE PRODUCT SUMMARY









#### TMC-2000 MOTION CONTROLLER

- High performance, stand alone, multi axis servo and stepper motor controller
- Performs point to point motion, linear and circular interpolation, contouring, electronic gearing, electronic cam, and jogging
- Powerful yet simple instruction set supports multitasking, user variables and arrays, arithmetic and logic functions, position latch, event triggers, error handling and more.
- Servo Setup Kit\* software for Windows<sup>®</sup> provides communications, program editing, tuning and diagnostics
- All optoisolated I/O

#### AXI-PAK\* Complete Servo Axis Packages

Page 397

Page 385

- A complete servo axis that operates either with a motion controller or as a smart stand alone drive
- Includes a matched BLX brushless motor, OMNIDRIVE\* digital servo drive, professionally molded cables, OMNI LINK\* setup software, and documentation for a fast and worry free installation
- The latest technology and most rugged design for a high performance industrial quality turn key motion control solution

#### **OMNIDRIVE Digital Servo Drives**

Page 413

- Fully digital "smart" brushless servo amplifier with integrated power supply
- Configurable for analog input, step and direction, serial link, encoder follower, electronic gearing.
- Indexing option for stand alone positioning capabilities
- Available in 0.5, 1, 2, 3, 7.5, and 15 kW continuous power ratings
- Included OMNI LINK setup and diagnostic software

#### **BLX Brushless Servo Motors**

Page 43

- Superior magnetic and thermal design gives exceptional performance and the highest torque per frame size
- Standard IP65 sealing, MS style fluid tight connectors, oversize bearings, and thermal switch ensure a long and worry free service life
- A variety of frame sizes and winding configurations are available to suit your precise application needs
- Internal bearing mounted commutating encoder provides precision and reliability
- Available with planetary gearheads and internal brakes

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.





### MOTION CONTROL SOLUTION GUIDE TABLE OF CONTENTS

TMC-2000 Multi-axis Motion Controller
Description
Software
Command Summary
Programming/Application Examples
Specifications
Connection Pinouts
Dimensions
Accessories and Ordering Information

AXI-PAK* Servo Axis Packages	
Modes of Operation	
Description	
Indexing Option	
Speed-Torque Curves	
Dimensions and Specifications, and Accessories	
Ordering Information	

OMNIDRIVE* Digital Servo Drives	
Features	
OMNI LINK* (software)	
Indexing Options	
Specifications	
Connector Pinouts	
Dimensions	
Accessories	

BLX Brushless Servo Motors
BLX 23 Series.       432 - 433         BLX 34 Series.       434 - 435         BLX 42 Series.       436 - 437
BLX 60 Series
Application Examples

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



### MOTION CONTROL SOLUTION GUIDE RECOMMENDED PRODUCT APPLICATION GUIDE

	TMC-2000 motion controller and non-indexing AXI-PAK* servo axis packages	Indexing AXI-PAK servo axis packages	Non-indexing AXI-PAK servo axis packages
single axis, point to point positioning	✓	<b>√</b>	
multi-axis, point to point positioning	1	1	
multi-axis, linear and circular interpolation	✓	1	
contouring	1	✓	
electronic gearing	✓	✓	1
torque control	✓	<b>√</b>	1
analog position control	✓	1	J
control by PLC I/O	1	1	except for positioning
control by another stepper card (step/dir)			1
control by another servo card (+/- IOV)			1
control by a host PC	✓	✓	except for positioning
electronic cam	1	1	1
encoder following	✓	<b>√</b>	1
electronic gearing	1	1	1
torque control	✓	<b>√</b>	1
analog position control	1	J	5
serial port control	✓	1	1
auto program execute	1	✓	except for positioning

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.





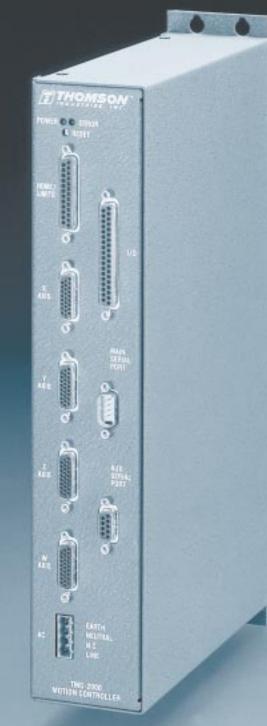
### **TMC-2000 MOTION CONTROLLER**

**The TMC-2000** is a packaged high performance multi-axis motion controller designed for stand alone operation. It is capable of controlling I - 4 axes of servo or stepper motors independently, coordinated (linear and circular interpolation) or synchronized to external events. Flexible inputs and outputs allow interfacing to a wide variety of industrial sensors, relays, or PLCs. A powerful yet easy to use instruction set allows solving any motion control problem quickly and easily.

Windows<sup>®</sup> based support software allows quick program editing, system setup and tuning. Programs may be permanently stored in memory and automatically executed upon power up.

### **F**EATURES

- Controls 1-4 axes of servo and/or stepper motors
- Stand alone operation with automatic program execution upon power up
- Various modes of motion include point to point, linear and circular interpolation, contouring, electronic gearing, electronic cam, and jogging
- 2 serial RS-232/RS-422 communication ports
- 32 bit microprocessor gives high performance servo control through: Full digital PID control with feed forward; S-curve profiling with accel, velocity, and position changes on the fly; and auxiliary encoder inputs for dual loop and backlash compensation
- Enhanced I/O including: 8 optoisolated digital inputs
   8 optoisolated digital outputs
   Dedicated reset and abort inputs and error output
   7 analog inputs
   72 additional OPTO-22 compatible I/O option
- Dedicated limit and home inputs (optoisolated)
- Servo Setup Kit<sup>®</sup> for Windows<sup>®</sup> software provides: communications, program editing, various auto and manual tuning methods, motion and I/O diagnostics
- Multitasking allows up to 4 programs running simultaneously



- Compact industrial enclosure
- 110V/220V operation
- Powerful, yet simple two letter instruction set supports: 254 user variables and 8000 array elements; arithmetic and logic functions; high speed position latch; and, event triggers and sophisticated error handling

Page 385



For Application Engineering assistance contact the Thomson Technical HelpLine at 1-800-554-8466. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

### THE TMC-2000 MOTION CONTROLLER

#### MODES OF MOTION

The **TMC-2000** supports various modes of motion to allow solving any motion problem.

**Fully independent positioning** allows each axis to follow its own prescribed profile regardless of any other axis motion. Linear interpolation is supported for any combination of axes and provides coordinated motion along any prescribed vector path.

**Circular interpolation** allows circular moves and arc segments between any pair of axes.

**Coordinated motion** allows the following of a two dimensional path consisting of a continuous vector feed of an infinite number of linear and arc segments, while maintaining a constant vector speed. A third axis can be commanded to remain tangent to the path.

**Contouring mode** allows the user to completely define any arbitrary position trajectory which is useful when specialized computer generated trajectories must be followed. Position increments over a time interval are specified. An automatic recording feature allows the controller to learn and play back this path.

**Electronic gearing** allows any number of axes to be electronically geared to one master axis or external encoder and gear ratio may be changed on the fly. Electronic cam mode allows synchronizing axes with a master axis according to a user defined table, point by point along the motion cycle, for repetitive periodic operations such as flying shears and rotating knives.

**Jogging** allows any axis to move at a constant speed for an indefinite time.

All motion may be **synchronized with outside** events through the controller's I/O, and motion profiles may be smoothed through the use of **S-Curve** velocity profiling.

#### **I/O**

The TMC-2000 comes standard with 8 uncommitted digital inputs, 8 uncommitted digital outputs, and dedicated home, forward and reverse travel limits for each axis. There are also dedicated reset and abort inputs and an error output. All of the I/O is optoisolated. Additionally, 7 analog inputs are standard. Up to 72 more I/O points (OPTO-22 compatible) are optionally available.

#### PROGRAMMING

The TMC-2000 has a powerful yet intuitive and simple programming language allowing complex and demanding applications to be solved quickly. Programming is BASIC-like and instructions consist of two letter commands such as BG for Begin and SP for Speed. The command set includes commands for defining motion profiles, configuring your system, handling I/O, checking status, and tuning the axes. Conditional instructions, subroutines, and jump statements allow the building of a complete



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.





machine control program. Use of the arithmetic and logic functions and the flexibility of 254 user defined symbolic variables allow writing complete self contained application programs. Multiple arrays may contain up to 8000 elements to capture real time data for teach modes or data collection. Programs can be controlled by event triggers, timers, and definable input interrupts And the controller's multitasking capabilities allow up to 4 independent or related programs to run simultaneously. Programs, arrays, and variables can be stored in nonvolatile memory and programs may be set for automatic execution upon power up.

Programming can be performed with the controller's own internal editor and can be quickly entered and edited with any dumb terminal or PC. However, you'll probably prefer using the supplied Servo Setup Kit\* Windows® based software. Servo Setup Kit will allow you to edit, upload and download your programs. A terminal mode allows direct communication with the controller. Tuning the axes is simplified through an advanced assortment of autotuning and manual tuning methods. Built in scope and plotting capabilities allow graphical representation of position, velocity, position error, motor command, system response, and many other parameters. All system configuration parameters may be viewed and set.

#### COMMUNICATIONS

The TMC-2000 has two RS-232 serial communication ports which also can be configured as RS-422. Baud rates from 300 to 38.4k bps can be used with or without handshaking. Up to 8 controllers may be daisy chained together for control by a single host computer or by each other. Because all instructions are simple 2 letter ASCII commands, most any PLC, computer, or controller with a serial port can communicate with the TMC-2000.

#### SERVO PERFORMANCE

The controller supports up to 4 axes of servo and step motors. High performance operation is ensured through a fast servo update rate, 16 bit DAC motor command, and a fully digital PID filter with velocity and acceleration feedforward and integration limits. S-Curve velocity profiling with different acceleration and deceleration rates is supported along with the ability to change position, velocity, and acceleration on the fly. Each axis may utilize an auxiliary encoder for automatic dual loop damping and backlash compensation. And for those applications where a potentiometer or other sensor is used for feedback, the controller can close the loop around the analog inputs.

#### SAFETY FEATURES AND ERROR HANDLING

Prudent design of any piece of machinery dictates consideration of unexpected problems. The TMC-2000 has both software and hardware limits. The axes may be configured for automatic shut-off on excessive error. Dedicated optoisolated inputs are provided for Abort and Reset. And, sophisticated error handling may be employed through user definable error and limit routines. THE TMC-2000 MOTION CONTROLLER DESCRIPTION

# APPLICATIONS XYZ systems General Automation Specialty Machinery Pick and Place Dispensing Laser & Water Jet Cutting Welding Robots Food Processing **Coil Winding** Metalworking Packaging Machinery Material Handling Web Synchronization **Tension** Control Printing and Labeling and more!

Motion Control

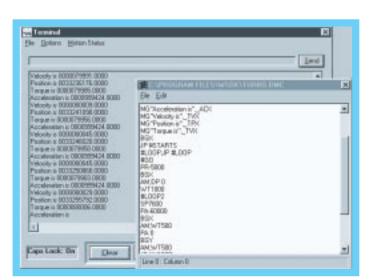
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.





### TERMINAL

For programming, development, troubleshooting, or operation, use the built in terminal for direct interaction with the controller. The program editor may be launched from here to edit, save, upload, download, and print your programs. You also may create a log file to capture all activity for later review.



### TUNING

Choose from one of five tuning routines that best suits your application. You can completely hands off auto-tune or, if you prefer, interact by specifying a crossover frequency, gain, or damping. Either way, the resulting system response is displayed.



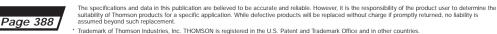
### **STORAGE SCOPES**

You can create up to four channels of storage to capture important parameters for any combination of axes. View critical signals such as commanded position, actual position, position error, motor command, auxiliary encoder, and I/O levels. Adjust the trigger method, sample time, trace colors, grid types, values, min/max levels, and more.

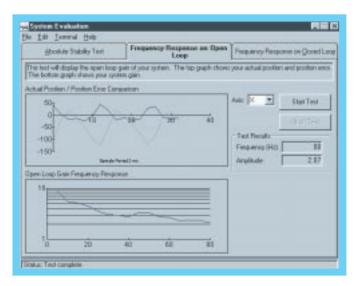
1Score	250mm	1 38	apés 🗍	4 Scopes	Contraces	Foop
1196100				Find Booper		
1170600				N . Actual	Position	1.2
IT THE COURSE				Tacen	Nomal	
INTERC	-	-	-	Second Scoper		
\$	10	60	-	Di	Ente	1.2
al				Zion	Monnal	
				Third Scope	The second	
		*********		X Control	nded Postian	
				Zeom	Montal	
10790013				Fouth Scope	-	
107380				X Toque		
IPTORO			ND I	Zee	Morrial	-
Bdg: protocol gives a				Conversed String		1
			a a a a a a	240		_
200			10000	F Stop Alter Sco	ce Canaletes	
-		-			Collecting	

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.

**Motion Control** 

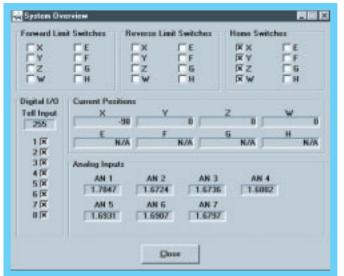






### SYSTEM EVALUATION

Evaluate the servo performance though an absolute stability test, step response test, or frequency response on either the open-loop or closed loop response. Check for problems with gain or damping and get a graphical look at the responsiveness of your system.



Asia Information	general internation			
	3.80	YAD	TAIR	WAlle
Asturi Foellon	0003807670	0000000000	00000000000	0000000000
Terterence Pastian	0002594203	80800000000	0000000000	0000000000
Dual Encoder Position	0000000000	000000000	0000000000	0000000000
Latched Pastian	0000000000	0000000000	00000000000	BOBOBOBOBO
Position Error	-00000000022	8000000000	00000000000	0000000000
Bap Cade	000	-004	004	004
Switcher: Anis in Nation	1	0	D	0
Induted: Auto Byter Exceeds Byter Limit	0	0.	0	0
Switches: Hatur Off	0			
Iwbhes Unastned	D	0	0	0
Switches: Parvierd Limit Inactive	3	1.	4	1
Toolstwo. Heverse Laid Ioadive	-+	+	1	; t
Sydistee: Hone	1		1	1
Switches Latered	4	+	1	1
Torque	1.5154	0.0000	8.0000	0.0000
Yelooffy	80000754	0000000	8000000	0000000

### SYSTEM OVERVIEW

A quick overview of the state of important system variables such as encoder positions, digital and analog I/O status, limit and home switch states.

### SYSTEM INFORMATION

A detailed listing of all system parameters can be viewed for diagnostic or troubleshooting purposes. Check the status of error codes, motion related variables, all I/O, limit switches and more.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.





### THE TMC-2000 MOTION CONTROLLER COMMAND SUMMARY

#### AS At Speed DA **Deallocate Arrays** MOTION **STATUS** AT After Time DE Define Dual AB Abort Motion RP **Encoder Position** AV After Vector AC Acceleration Distance DL Download RL BG **Beain Motion** EA Choose ECAM DM **Dimension Arrays** SC CD Contour Data Master DP **Define Position** TΒ CM Contour Mode EB Enable CAM ED Edit Mode TC CR Circle FG Engage ECAM EI Enable Interrupts TD CS Clear Motion CAM Cvcle EM EO Echo Off Sequence TE Command LS List ΤI DC Deceleration EN End Program MO Motor Off DT Contour Time TP CAM Interval and EP MT Motor Type Define Interval Starting Point TR ES Ellipse Scaling OB Output Bit EQ Disengage ECAM TS Find Edge OP **Output Port** FE ECAM Table Entry ET TT PF **Position Format** FI Find Index ΗX Halt Execution TV QU GA Master Axis for Upload Array JP Jump to Location Gearing JS QD Download Array Jump to Subroutine ERROR AND LIMITS GR Gear Ratio RA **Record Array** MC After In Position BL HM Home RC Record MF After Motion -IP Increment Position **Forward Direction** RD Record Data ER JG Jog Mode MG Message RI Interrupt Mask FL LE Linear Interpolation MR After Motion -RS Reset End **Reverse Direction** OE SB Set Bit LI Linear Interpolation NO No Operation UI User Interrupt Distance Return from Error RE **EDITOR** UL Upload Linear Interpolation LM Subroutine VF Variable Format mode FD RI Return from PA Position Absolute <return> Save Line Interrupt **CONTROL FILTER** PR Position Relative TW Timeout for In <cntrl> P Previous Line SETTINGS Position SP Speed <cntrl> | Insert Line DV Damping for Dual WC Wait for Contour ST Stop <cntrl> D Delete Line Loop Data ΤN Tangent <cntrl> Q Quit Editor Acceleration FA WT Wait VA Vector Acceleration Feedforward XO **Execute Program** VD Vector Deceleration FV Velocity Feedforward **ARITHMETIC FUNCTIONS** ZS Zero Subroutine VE Vector Sequence GN Gain Stack @SIN Sine End IL Integrator Limit **@COM** Complement VM **Coordinated Motion** Smoothing Time GENERAL IT @COS Cosine Mode Constant -CONFIGURATION @ABS Absolute Value VR Vector Speed Ratio Independent AF Analog Feedback VP Vector Position **@FRAC** Fraction Portion KD Derivative AL Arm Latch Constant VS Vector Speed @INT Integer Portion BN ΚI Integrator Constant Burn @RND Round Burn Program Proportional BP KP **@SQR** Square Root PROGRAM FLOW Constant BV **Burn Variables** @IN AD After Distance KS Stepper Smoothing CB Clear Bit @AN Constant AI After Input Configure Com Port CC + OF Offset MF After Motion-CE Configure Encoder Forward Direction \_ SH Servo Here Type \* After Motion-AM TL **Torque Limit** CI Communication Complete Sample Time Interrupt TM AP After Absolute & Configure Switches CN VT Smoothing Time Position Constant - Vector and Stepper After Relative AR () CO Configure Outputs ZR 7ero Distance

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

THOM50N First in Linear Motion and Co ntrol Tech

Parentheses

**Return Digital Input** 

**Return Analog Input** 

Add

Subtract

Multiply

Divide

And

Or

Report Command

Position

Stop Code

Tell Status

Tell Error

Tell Input

Trace

Tell Position

**Tell Switches** 

Tell Torque

**Tell Velocity** 

Limit

Limit

Error Limit

Off on Error

Edit Mode

**Reverse Software** 

Forward Software

Report Latch

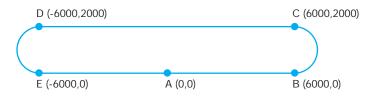
Tell Error Code

Tell Dual Encoder

### Example #I: Coordinated Motion

Applications such as dispensing, machining, welding, and water jet cutting often require coordinated motion amongst a set of XY axes. This code sample shows typical straight line and circular motion.

### Motion Path for XY



Instruction	Interpretation
#M	Label
VM XY	Specify XY plane
<b>VP6000,0</b>	Move to point B
CR 1000,270,180	Move to point C
VP -6000,2000	Move to point D
CR 1000,90,180	Move to point E
VP 0,0	Return to point A
VE	End of path
VS 20000	Vector speed
VA 100000	Vector acceleration
VD 100000	Vector deceleration
BGS	Start motion
EN	End program

### Example #2: Inputs and Outputs

On machines, inputs and outputs are often used to read sensors, turn on equipment, or handshake with other controllers. This code sample waits for an input, performs motion, and sets an output to notify a PLC. Additionally, the speed of the motion is set proportional to an analog input, which could be wired to a potentiometer or some type of sensor.

Instruction	Interpretation
#CYCLE	Label
PA 50000	Specify position
AI1	Wait for input 1
A=@AN[1]	Read analog input 1
V=A*2500	Scale voltage to desired speed
SP V	Update feedrate
BGX	Start motion
AMX	Wait for completion of move
SB1	Turn on output 1
PA 0	Specify return position
BGX	Start motion
AMX	Wait for completion of move
CB1	Turn off output 1
JP#CYCLE	Repeat the cycle

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.





### Example #3: Loops and Variables

Machines often need to repeat a cycle a certain number of times. This code sample shows how a variable, V1, can be used to create a counter. The motion cycles back and forth, each time incrementing the counter. When 10 cycles are complete, the program ends.

Instruction	Interpretation
#MAIN	Label
V1=1	Set counter variable to 1
#LOOP	Label for loop
PA 25000	Set move distance
BG X	Begin move
AM X	Wait for move completion
PA 0	Set move distance
BG X	Begin move
AM X	Wait for move completion
V1=V1+1	Increment cycle counter
JP #LOOP,	
V1<10	Loop until counter = 10
EN	Program end

### Example #4: Electronic Gearing

Some applications require axes to follow another master encoder in a synchronized or geared configuration. In this example, three rotating dies repetitively stamp material traversing on a conveyor. It is important that the dies rotate at the same surface speed as the material. When the operator presses the start switch, the axes rotate and cycle the dies by following the conveyor motor. The gear ratio is set by an operator depending on the size of the die.

Instruction	Interpretation
#MAIN	Label
IN"Enter die size", A	Prompt operator for die size
A=A*3.33	Scale gear ratio as required
GAW	Designate W as master (conveyor) axis
<b>JG</b> ,4000	Start conveyor running
#CYCLE	Label
AI1	Wait for start switch
GR A,A,A	Start stamping by setting ratios for X, Y, and Z
AI2	Wait for stop switch
GR 0,0,0	Stop stamping by disabling gearing
JP #CYCLE	

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.

**Motion Control** 



SERVO	
Number of axes	4 axes, any combination of servo and stepper
Feedback	Incremental encoder, single ended or differential. Can also use analog voltage
	from potentiometer or transducer
Servo Loop Update Time	500 μs
Position Accuracy	+/-1 quadrature count
Position Range	+/-2147483647 counts per move; automatic rollover and no limit in jog
	or vector modes
Velocity Accuracy: Long Term	Phase-locked, better than .003%
Short Term	System dependent
Velocity Range	Up to 8,000,000 counts/sec
Velocity Resolution	2 counts/sec
Accel/Decel Range Motor Command Resolution	1024 to 67,107,840 counts/s <sup>2</sup> 16-bit or 0.0003V
Block Execution Time	In contour mode, up to 1000 (moves)/sec with full trajectory generation
Synchronization	All axes in the same unit are perfectly synchronized and share the same servo
Synchronization	cycle. Multiple controllers may share the same synchronization signal and be
	perfectly synchronized in the same servo cycle
Position Capture Accuracy	25µs with optoisolation, 0.1µs bypassed optoisolation
Gear Ratio	+/- 127.9999
Step Pulse Frequency	2,000,000 pulses/sec maximum
PROGRAMMING	
Number of Variables	254
Variable Range	+/-2 billion
Variable Resolution	1 • 10 <sup>-4</sup>
Array Size	8000 elements in up to 30 arrays
Program Size	1000 lines x 80 characters
INPUTS / OUTPUTS	
General Purpose Inputs	8 uncommitted optoisolated, open collector 28V@ 25mA max
General Purpose Outputs	8 uncommitted optoisolated, open collector 28V@ 25mA max
General Purpose Analog Inputs	7 +/- 10V, 12 bit resolution
Limit Inputs	Dedicated forward and reverse limit inputs for each axis, optoisolated
Home Inputs	Dedicated home input for each axis, optoisolated
Other	Reset input, Abort input, and Error output
ELECTRICAL	
Servo ACMD Amplifier Command	+/-10 Volts analog signal. Resolution 16-bit, .0003 Volts. 3 mA maximum
Encoder A+,A-,B+,B-,IDX+,IDX-	TTL compatible, but can accept up to +/-12 Volts. Quadrature phase
	on CHA,CHB. Can accept single-ended (A+,B+ only) or differential
	(A+,A-,B+,B-). Maximum A, B edge rate: 8 MHz. Minimum IDX pulse width: 120 nsec.
Stepper Pulse	TTL (0-5 Volts) level at 50% duty cycle.
	2,000,000 pulses/sec maximum frequency
Stepper Direction	TTL (0-5 Volts)
Uncommitted Inputs, Limits,	
Home, Reset and Abort Inputs	2.2K ohm in series with optoisolator. Requires at least 1 mA for on. Can accept
	up to 28 Volts without additional series resistor. Above 28 Volts requires additional resistor.
AN[1] thru AN[7] Analog Inputs	Standard configuration is +/-10 Volt. 12-Bit Analog-to-Digital converter.
OUT[1] thru OUT[8] Outputs	Optoisolated, open collector
Available Power For External Devices	+ 5V 1.5 A
	+12V 750 mA
	-12V 200 mA
COMMUNICATIONS	
Number of Communication Ports	2 serial RS-232 (can be configured for RS-422)
Speed	300, 1200, 4800, 9600, 19200, 38400 bps
Handshaking	Hardware or none

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Page 393

### RS-232 Main Serial Port

Type: 9 pin male D sub
Function
CTS – output Transmit Data – output Receive Data – input RTS – input Ground CTS – output RTS – input CTS – output No connect/ or 5V or sample clock with jumpers

RS-232 – Auxiliary	Serial
Port Connector	

Connector Type: 9 pin female D sub				
Pin	Function			
1 2 3 4 5 6 6 7 8 9	CTS - input Transmit Data - input Receive Data - output RTS - output Ground CTS - input RTS - output CTS - input SV / or no connect or sample clock with jumpers			
*RS-232 ports can be configured for RS-422 by factory				

### AC Power Connector

Connector Type: 4 position Phoenix screw terminal				
Pin	Function			
LINE N.C. NEUTRAL EARTH	Hot wire of AC power cord – black Do not connect (used for key) Return of AC power cord – white Chassis ground – green			

### X, Y, Z, W Axis Connectors

Connector Type: 26 pin high density female D sub, one per axis Function Pin # 1 enc A+ 2 enc Aenc B+ 3 4 enc B-5 enc I+ 6 enc I-7 enc gnd 8 enc 5V 9 enc shield 10 amp cmd 11 amp enable 12 amp PWM/step 13 amp sign/dir 14 amp enable Vx 15 stepper mode enable amp gnd 17 18 amp shield 16, 23 gnd 24 +5V +12V 26 25 -12V 19,20,21,22 N.C.

### I/O Connector

Connector Type: 37 pin female D sub

Pin	Function	Pin	Function	Pin	Function	Pin	Function
28,17	Controller	34	input 1 (latch X)	2	output 1	25	analog 2
	supplied 5V	15	input 2 (latch Y)	21	output 2	7	analog 3
10,11,	Controller	33	input 3 (latch Z)	3	output 3	26	analog 4
29,30,	supplied	14	input 4 (latch W)	22	output 4	8	analog 5
36	Ground	32	input 5	4	output 5	27	analog 6
16,35	User isolated	13	input 6	23	output 6	9	analog 7
	inputs	31	input 7	5	output 7	19	abort input
	Vcc INCOM	12	input 8	24	output 8	37	error output
1,20	User isolated			6	analog 1	18	reset input
	outputs ground				-		

### HOME/LIMITS Connector

Connector Type: 25 pin female D sub					
Pin	Function	Pin	Function		
	Controller supplied 5V	5	Y + limit		
18,19,20	),21 Controller supplied	6	Y - limit		
22,23,24	1,25 ground	7	Y home		
1,14	User isolated inputs	8	Z + limit		
	Vcc, LSCOM	9	Z - limit		
2	X + limit	10	Z home		
3	X - limit	11	W + limit		
4	X home	12	W - limit		
		13	W home		

#### Auxiliary Encoder Connector J3

Connector Type: 20 pin male ribbon header. It is internally mounted and noted as J3. Remove side cover for access.

Pin	Function	Pin	Function	Pin	Function
1	Sample	8	B+Aux Z	15	B-Aux X
	clock	9	A-Aux Z	16	B+Aux X
2	Synch	10	A+Aux Z	17	A-Aux X
3	B-Aux W	11	B-Aux Y	18	A+Aux X
4	B+Aux W	12	B+Aux Y	19	5 Volt
5	A-Aux W	13	A-Aux Y	20	Ground
6	A+Aux W	14	A+Aux Y		
7	B-Aux Z				

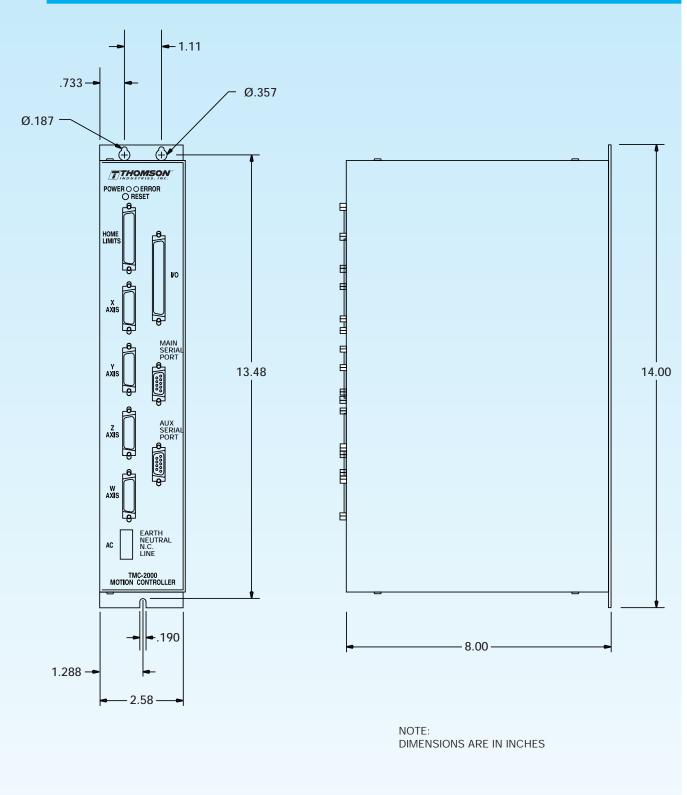
### For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.

Motion Control



### THE TMC-2000 MOTION CONTROLLER DIMENSIONS

### MOTION CONTROLLER



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.
\* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

**Motion Control** 

## **Ordering Information**

TMC 2004-CO4 axis Motion Controller

### Accessories

19260A TMC-2000 manual. Note: one manual is included with each controller.

21365B Cable for direct connection of the TMC-2000 motion controller to any OMNIDRIVE\* digital servo drive or AXI-PAK\* servo axis package. 36" length

21210B Cable, same as above 21365B, with the addition of a separate pigtail to access all signals of the OMNIDRIVE that are unused by the TMC-2000 motion controller.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.





# A THOMSON AXI-PAK

servo axis package is the simplest way to a high performance and cost effective servo solution. An AXI-PAK is a tested and proven combination of a BLX brushless servo motor, an OMNIDRIVE\* digital servo drive, and the required cables all under a single part number. Pre-engineered and pre-matched components ensure optimized performance and take the guesswork and worry out of compatibility and installation issues. We put it together so you can put it to work.

An AXI-PAK can operate as a smart stand alone drive, or if the application requires it, can easily connect to a motion controller (such as in coordinated multi-axis systems). As a smart digital drive, it can be configured to operate in torque, velocity, or position modes. It can accept the standard +/- IOV analog command signal from a motion control card, digital commands from a host computer via its serial link, or step and direction inputs and function as a high performance alternative to a stepper drive. Its programmable I/O and preset speeds allow it to be used as a variable speed drive. It can even follow a master encoder with electronic gearing.

AXI-PAK servo axis packages are also available in an indexing version capable of executing up to eight different position moves initiated by the digital I/O as well as a user defined homing routine. This indexing option eliminates the need for a separate motion control card in many applications.

### FEATURES

- A turnkey motor and drive package
- Operates with a motion controller or as a smart stand alone drive
- Four motor frame sizes to fit your requirements
- Continuous torque ratings from 4.2 to 280 in-lb, peak torque ratings from 11.0 in-lb to 840 in-lb
- Includes all cabling
- Digital drives operate in torque, velocity, or position modes
- High torque maintenance free brushless servo motors feature IP65 sealing, MS style fluid tight connectors, oversize bearings, and a winding thermal switch and internal 2000 (8000 count) line commutating encoder
- Simple one cable connection to TMC-2000 controller for complex or multi axis applications
- All components carry UL, cUL, and CE approvals
- Off-the-shelf delivery





For Application Engineering assistance contact the Thomson Technical HelpLine at 1-800-554-8466. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



### CONTROL BY SERVO OR STEPPER CONTROLLER

Use an AXI-PAK servo axis package without indexing for direct control by any servo or stepper controller. Either a +/- 10V torque/velocity command or step and direction signals may be used as a command source. Ideal for use with the TMC-2000 multi-axis controller.



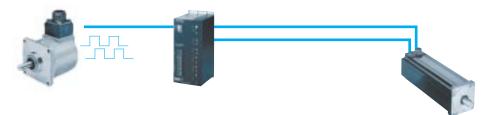
### STAND ALONE BASIC POSITIONING

For basic point to point positioning applications, the AXI-PAK with servo axis package indexing option allows the drive to execute up to eight different position moves initiated by the drive's digital I/O. In many cases, a separate motion control card is not needed. Connect to your I/O card, PLC, or switch panel for a simple solution



### SLAVE TO A MASTER ENCODER

Any AXI-PAK servo axis package can use an incremental encoder source as a command signal. This feature can be used to have an AXI-PAK follow a master encoder or even another AXI-PAK. Multiple axes can be a slave to a master without requiring a multi-axis controller or a gantry configuration can be easily implemented. The gear ratio of this electronic gearing feature is easily set in OMNILINK\* setup software.



### CONTROL BY HOST THROUGH SERIAL INTERFACE

An AXI-PAK servo axis package can be controlled through its host command language via its serial interface port. In this way, a PC, PLC, or any host computer may constantly change all parameters including acceleration, velocity, move distance, and I/O configuration. This gives the AXI-PAK maximum flexibility.



In general, an AXI-PAK without indexing is used when a separate servo or stepper controller (such as the TMC-2000) is utilized. The indexing option is required to give the AXI-PAK basic stand alone positioning capabilities.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.





# **OMNIDRIVE – Power and Flexibility**

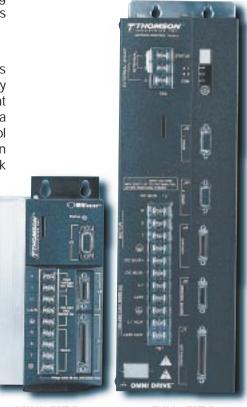
The heart of every AXI-PAK servo axis package is an OMNIDRIVE\* digital servo drive. Available in both full size and mini versions, this fully digital drive is suitable for a myriad of motion control applications. With the optional indexing functionality, it makes an ideal stand

alone positioner for basic point to point motion. Without the indexing option, it is a high performance drive using a command source from a servo or stepper motion controller (such as the TMC-2000), PLC, master encoder, or host computer.

**Communications** are provided through an RS-232/RS-485 serial port (2 ports on full size drive). OMNI LINK\* software running on your PC is used for quick point and click configuration.

Various **Modes of Operation** are possible including analog torque, velocity, and position, digital preset velocity or torque, master encoder follower with electronic gearing, step/dir input, and serial commands from a host computer. The indexing option adds eight preset positions as well as homing.

**Precise Motor Control** of brushless motors is provided through fully digital position, velocity, and current loops. Sine wave commutation via encoder feedback, special control algorithms, and latest generation IGBT power modules ensure peak performance and reliability. **Fully Digital Design** provides the ultimate in performance, features, and functionality as well as providing a system that is stable over time and temperature



MINI SIZE

FULL SIZE

The **Indexing Option** extends the drives functionality by allowing up to eight different move profiles initiated by the digital I/O as well as a user defined homing routine.

Flexible I/O is user definable. Inputs can be set as: various enable and preset selects, start index, start home, fault reset, drive mode select, mode override, and more. Outputs can be set as: in position or speed window, in motion, sequence complete, various fault indicators, home status, and more. Analog outputs can reproduce important voltage, current, error, and feedback signals.

**Power Ratings** are 0.5, 1, and 2 kW for the mini version and 1, 2, 3, 7.5, and 15 kW for the full size version. Full size drives add a 24V user I/O supply and internal regeneration resistor.

Page 399



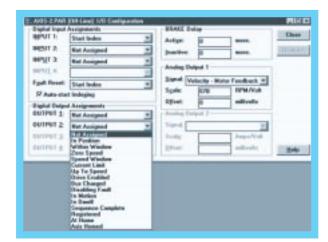


### OMNI LINK\* Setup Software

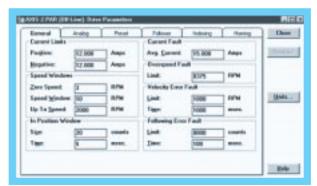
Every AXI-PAK servo axis package comes with OMNI LINK software, a Windows<sup>®</sup> based interface tool for setup, configuration, and diagnostics. OMNI LINK software provides a complete graphical interface to the drive with absolutely no programming language to learn. A drive is configured by simply clicking on the appropriate option box or entering values in existing fields. A variety of intuitive screens guide you through configuration, signal monitoring, and diagnostics.



With just a click, the drive can be configured for a wide variety of operational modes (torque, velocity, position, step/dir, follower, etc.) Communications parameters may be set for single or multi-drop operation.



Digital inputs can be configured for homing, reset, enable, indexing, and more. Digital outputs may be defined for various signals as well. Analog outputs may be set for a variety of position, velocity, current, voltage and error signals.



Although an AXI-PAK package comes pre-configured for its motor, there may be times where an application requires special settings. The Drive Parameters screen may be used to set current limits, error limits, scaling, offsets, and more.

Ingent Carnet: D Phone	
Scale: Auto Scale - Aware	
Offect E 808 Aways	
Cheanal II	
leavet Filter Detput	
Sigales 1.000 - Ampt	
Offset  0.808 Ampr	
C Shee B for Harksonial	
Sample Period	
Dete: 12.5 + mace.	
Trapper	
Made: Cestinates Tripper	
Louis R. B.	

All important drive signals may be plotted realtime using the oscilloscope utility. Additional windows allow a numerical display of all signals as well as error codes, status codes, fault history, tuning parameters, and more.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.

**Motion Control** 



### Indexing Option

When not using an AXI-PAK servo axis package in conjunction with a separate motion controller, you'll likely be interested in the indexing option. This indexing capability allows an AXI-PAK to act as a simple controller for basic point-to-point positioning applications. Using the OMNI LINK\* setup software, the drive may be configured for up to eight different position moves (indexes) initiated by the drive's digital I/O. As the OMNI LINK software only requires you to enter parameters in existing fields, there is no programming language to learn. The moves may be incremental (a distance relative to the current position), absolute (a distance relative to home

position), or registration (a distance relative to the registration sensor input). Velocity, acceleration, and move distance may be specified for each index, as well as a batch count that will automatically repeat any index a specified number of times. A dwell time between moves also may be set. Through an "action when complete" setting, each index may be linked to any other for automatic subsequent execution. And for those cases where a host computer is employed, an infinite number of moves may be executed by sending parameter information to the drive via the serial interface. The indexing option also includes a user defined homing routine.

Eerend	Availag	1 Pe	of Follow	1 Jad	ealing Hundry	0	hese "
Index 2				-		1 16	
Modec	Incenerda	4 . 21	Hup Dist	0	COURSE!	- 15	****
Distance	1808	counts	Velocity	1806	RPM		
Butch Count	7	1	Acceleration	580	RPM/sec.		
Deat	250	-	Deceleration	560	BPM/sec.		
Action pedar	and when o	implete:	Execute Index 1	-		10	đ4.,
Index 1							
Mode	Absolute		Hap Dist.	1	in and		
Pusilos:	5406	mante	Velocity	5400	18PM		
Balch Count	1	1	Acceleration	580	HPM/sec.		
Dwell .	0	mener.	Decelesation	1403	HPM/sec.		
Action pedar	and other or	-	Store		-	1.0	lele 1

#### No Programming Language to Learn!

Up to eight indexes are defined using OMNI LINK setup software with a simple point and click. Absolute, relative, and registration moves are supported. Moves are initiated by the drive's digital I/O.



#### **User Defined Homing Routine**

You can home to a sensor switch and/or encoder marker, as well as set homing speed and acceleration, and enter an offset distance. Homing may begin automatically upon drive enable or through an assignable input.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.





### A Motor Built To Last

Each AXI-PAK servo axis package includes a Thomson BLX Series brushless servo motor. There are four frame sizes of motors available, each with a variety of winding configurations that are an engineered match to the OMNIDRIVE\* servo drive. This high performance, industrial quality motor is built to last. Brushless construction, oversize lifetime lubricated bearings, MS style fluid tight connectors, IP65 sealing, and a winding thermal switch ensure a long and trouble free life in the harshest and most challenging applications. An internally mounted 2000 line encoder (8000 counts) with integral commutation sensors and its own bearing system provides the precision and resolution for your high performance application.



- Maintenance free brushless construction
- High energy rare earth magnets
- Standard IP65 for washdown environments
- MS style connectors for durability
- Internal winding thermal switch
- UL and cUL recognized

### The Right Cables

"The devil is in the details" – a saying quite appropriate for such a seemingly simple item as cabling. Experienced engineers and technicians know very well that properly built cables make the difference in getting a machine up and running quickly – and keeping it running. That is why Thomson has tooled up to provide you with professionally molded, high quality cable assemblies that just drop in, saving you time and worry. Our cables incorporate features such as 360° shielding of both cable and connectors for EMC compliance, UL approved oil and chemical resistant cable, and fully molded connector housings with integral strain reliefs. Each AXI-PAK includes all cables for a quick, complete and trouble-free installation.



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.





# AXI-PAK\* SERVO AXIS PACKAGE DESCRIPTION



# Your choice: AXI-PAK with mini size drive or with full size drive

### Choose the Mini Size when:

- power levels are from 0.5kW to 2kW
- space is a premium
- a more cost effective solution is needed
- any application requires a feature rich, high performance, digital servo drive

### Choose the Full Size when:

- power levels are from 1kW to 15 kW
- internal shunt is needed for fast deceleration and high inertia applications
- the most flexibility is required by a second serial port and a few extra I/O
- any application requires a feature rich, high performance, digital servo drive

The majority of features and performance are common to both size drives. However, some important differences are noted below.

Mini and Full Size [	Drive Comparison	
	Mini	Full
Size	roughly 1/4 of full size	see p.46-50
Power Output	0.5, 1.0, 2.0 kW	1.0, 2.0, 3.0, 7.5, 15 kW
Command sources and operational modes	Same	Same
Setup Software	Same	Same
Connectors/Cables	Same	Same
Indexing option available	yes	yes
I/O power supply	requires external 12-24V source	internal 24V supply
Regenerative shunt	external kit	internal
Digital Inputs/Outputs	3 inputs, 2 outputs	4 inputs, 4 outputs
Serial Ports	1	2
Front Panel Status Display	no	yes



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.





### AXI-PAK with Mini Size Drive

Axis Package PN	St	ont. all que	Ra	ont. ted que	Speed at Cont. Rated Torque	Peak Tor	Stall que		Rated que	Speed at Peak Rated Torque	Motor Model Included	Drive Model Included
	in-lb	Nm	in-lb	Nm	rpm	in-lb	Nm	in-lb	Nm	rpm		
APx-232A-DM005-Lxx	4.5	0.51	3.5	0.40	4500	12.3	1.39	11.0	1.24	3500	BLX232A2E000	ODM-005
APx-232A-DM010-Lxx	5.0	0.56	3.5	0.40	4500	15.0	1.69	13.0	1.47	3200	BLX232A2E000	ODM-010
APx-234A-DM005-Lxx	4.2	0.47	3.4	0.38	5700	12.0	1.36	11.2	1.27	5000	BLX234A2E000	ODM-005
APx-234A-DM010-Lxx	8.3	0.94	8.0	0.90	5700	24.0	2.71	22.0	2.49	5050	BLX234A2E000	ODM-010
APx-234A-DM020-Lxx	10.0	1.13	8.0	0.90	5600	30.0	3.39	27.0	3.05	4800	BLX234A2E000	ODM-020
APx-341B-DM005-Lxx	16.0	1.81	14.5	1.64	2100	48.0	5.42	43.0	4.86	1500	BLX341B2E000	ODM-005
APx-342A-DM010-Lxx	17.9	2.02	17.0	1.92	4100	53.6	6.05	48.0	5.42	3000	BLX342A2E000	ODM-010
APx-342A-DM020-Lxx	30.0	3.39	25.5	2.88	4000	90.0	10.2	81.0	9.15	2950	BLX342A2E000	ODM-020
APx-343A-DM010-Lxx	26.9	3.04	25.0	2.82	3100	80.0	9.04	72.0	8.13	2550	BLX343A2E000	ODM-010
APx-343A-DM020-Lxx	39.0	4.41	34.4	3.89	3000	119.0	13.4	105	11.9	2200	BLX343A2E000	ODM-020
APx-421B-DM010-Lxx	51.0	5.76	47.0	5.31	1400	146.0	16.5	140	15.8	1000	BLX421B2M000	ODM-010
APx-421B-DM020-Lxx	54.0	6.10	50.0	5.65	1400	162.0	18.3	150	16.9	1000	BLX421B2M000	ODM-020
APx-422A-DM020-Lxx	50.0	5.65	44.0	4.97	3000	159.0	18.0	142	16.0	2300	BLX422A2M000	ODM-020
APx-423B-DM020-Lxx	103	11.6	93.0	10.5	1400	303.0	34.2	271	30.6	1000	BLX423B2M000	ODM-020

# AXI-PAK with Full Size Drive

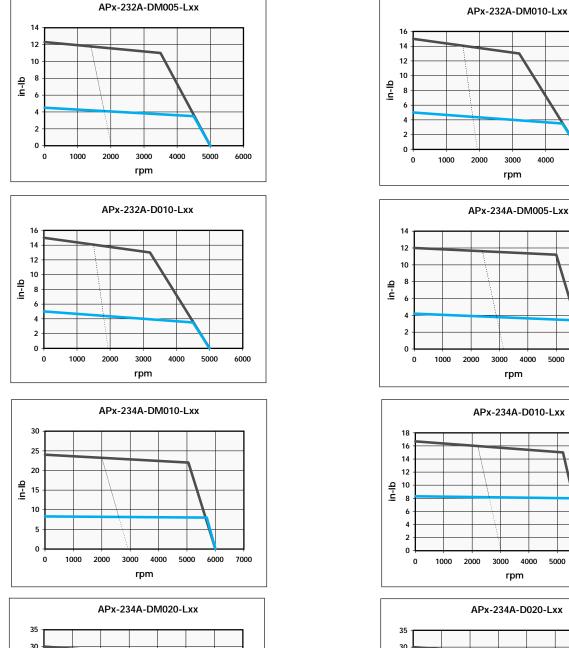
Axis Package PN	St	ont. all que	Ra	ont. ted que	Speed at Cont. Rated Torque		Stall que		Rated que	Speed at Peak Rated Torque	Motor Model Included	Drive Model Included
	in-lb	Nm	in-lb	Nm	rpm	in-lb	Nm	in-lb	Nm	rpm		
APx-232A-D010-Lxx	5.0	0.56	3.5	0.40	4500	15.0	1.69	13.0	1.47	3200	BLX232A2E000	OD-010
APx-234A-D010-Lxx	8.3	0.94	8.0	0.90	5600	16.7	1.88	15.0	1.69	5200	BLX234A2E000	OD-010
APx-234A-D020-Lxx	10.0	1.13	8.0	0.90	5600	30.0	3.39	27.0	3.05	4800	BLX234A2E000	OD-020
APx-341B-D010-Lxx	16.0	1.81	14.5	1.64	2100	48.0	5.42	43.0	4.86	1500	BLX341B2E000	OD-010
APx-342A-D010-Lxx	17.9	2.02	17.0	1.92	4100	35.7	4.04	33.0	3.73	3550	BLX342A2E000	OD-010
APx-342A-D020-Lxx	30.0	3.39	25.5	2.88	4000	71.4	8.07	64.0	7.23	3200	BLX342A2E000	OD-020
APx-342A-D030-Lxx	30.0	3.39	25.5	2.88	4000	90.0	10.2	81.0	9.15	2950	BLX342A2E000	OD-030
APx-343A-D010-Lxx	26.9	3.04	25.0	2.82	3100	54.7	6.2	50.0	5.65	2800	BLX343A2E000	OD-010
APx-343A-D020-Lxx	39.0	4.41	34.4	3.89	3000	105	11.9	94.0	10.6	2300	BLX343A2E000	OD-020
APx-343A-D030-Lxx	39.0	4.41	34.4	3.89	3000	119	13.4	105	11.9	2200	BLX343A2E000	OD-030
APx-421B-D010-Lxx	51.0	5.76	47.0	5.31	1400	101	11.4	93.0	10.5	1200	BLX421B2M000	OD-010
APx-421B-D020-Lxx	54.0	6.10	50.0	5.65	1400	162	18.3	150	16.9	1000	BLX421B2M000	OD-020
APx-422A-D020-Lxx	50.0	5.65	44.0	4.97	3000	103	11.6	90.0	10.2	2700	BLX422A2M000	OD-020
APx-422A-D030-Lxx	80.0	9.04	69.1	7.81	3000	159	18.0	137	15.5	2700	BLX422A2M000	OD-030
APx-422A-D075-Lxx	83.0	9.38	69.1	7.81	3000	245	27.7	215	24.3	2400	BLX422A2M000	OD-075
APx-423A-D030-Lxx	81.0	9.15	72.0	8.13	3000	147	16.6	138	15.6	2700	BLX423A2M000	OD-030
APx-423A-D075-Lxx	116	13.1	96.8	10.9	3000	348	39.3	308	34.8	2300	BLX423A2M000	OD-075
APx-423B-D020-Lxx	103	11.6	93	10.5	1400	204	23.0	181	20.5	1200	BLX423B2M000	OD-020
APx-423B-D030-Lxx	116	13.1	104	11.8	1400	295	33.3	280	31.6	1050	BLX423B2M000	OD-030
APx-602B-D030-Lxx	170	19.2	152	17.2	1350	340	38.4	306	34.6	1100	BLX602B2M000	OD-030
APx-602B-D075-Lxx	210	23.7	190	21.5	1400	630	71.2	570	64.4	1000	BLX602B2M000	OD-075
APx-603A-D075-Lxx	235	26.6	220	24.9	2200	490	55.4	450	50.8	1800	BLX603A2M000	OD-075
APx-603A-D150-Lxx	280	31.6	238	26.9	2150	840	94.9	750	84.7	1200	BLX603A2M000	OD-150

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.

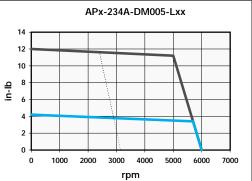


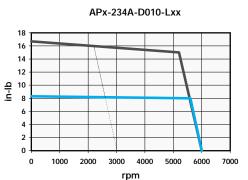


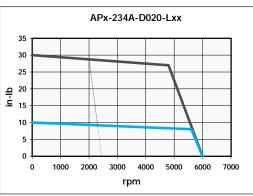
#### Peak, 230 VAC -- Continuous, 230 VAC ---- 115 VAC



2000 3000 4000 5000 6000 rpm







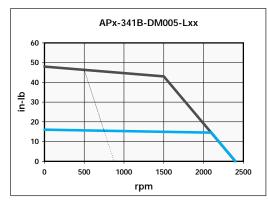
30 25 . . . . . 15 10 5 0 2000 3000 4000 5000 6000 7000 0 1000 rpm

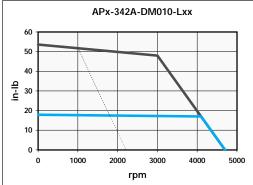
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.

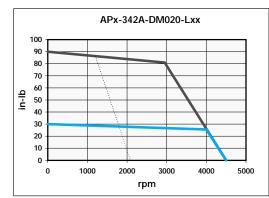


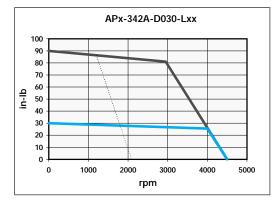
**23 FRAME AXI-PAK** 

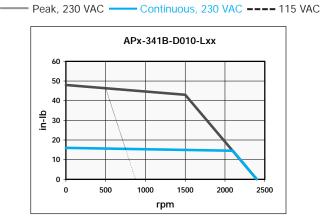


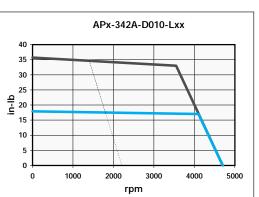


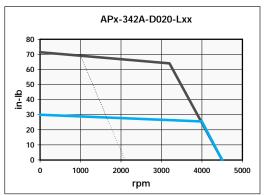


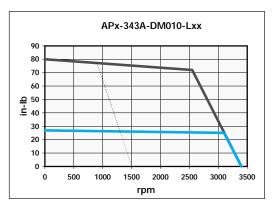








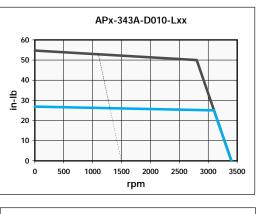


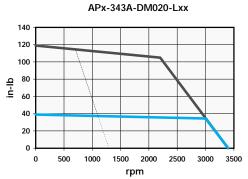


For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.

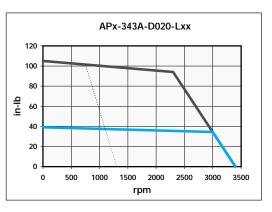


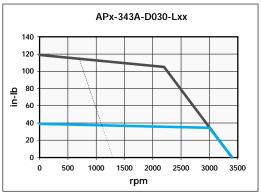








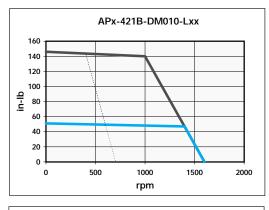


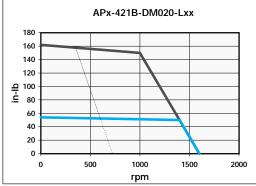


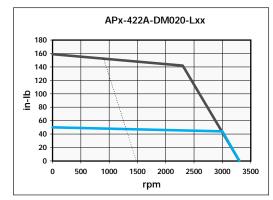
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.

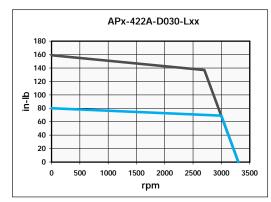


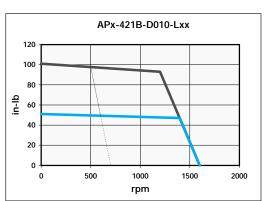


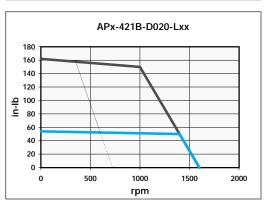


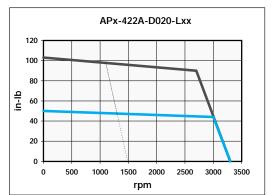


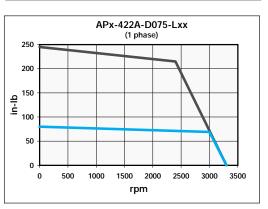










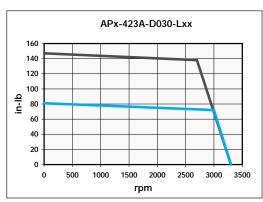


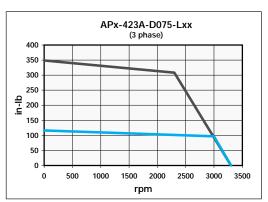
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.

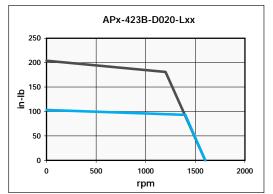
**Motion Control** 

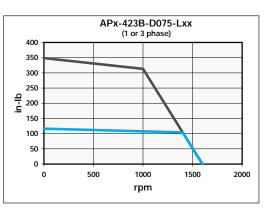


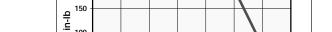
Peak, 230 VAC Continuous, 230 VAC











**42 FRAME AXI-PAK** 

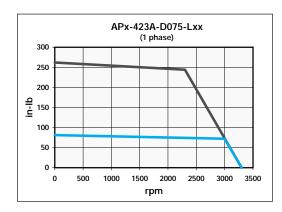
250

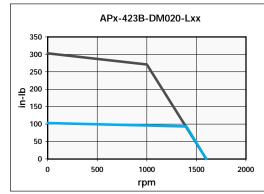
200

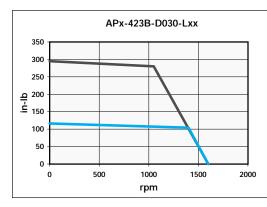
E 100 50 0 500 1000 1500 2000 2500 3000 3500 rpm

APx-422A-D075-Lxx

(3 phase)



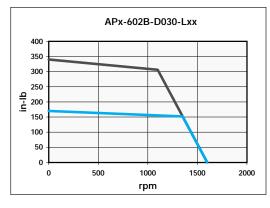


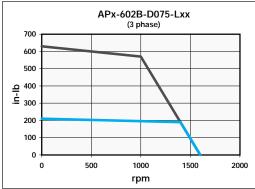


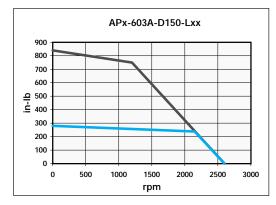
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



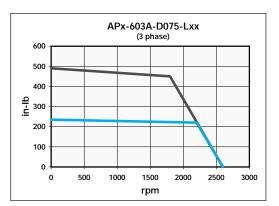








APx-602B-D075-Lxx (1 phase) 600 500 400 in-lb 300 200 100 0 0 500 1000 1500 2000 rpm



**Motion Control** 

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.





Peak, 230 VAC Continuous, 230 VAC

### **Dimensions and Specifications**

For details on motors used in an AXI-PAK servo axis package, see the BLX Brushless Motor section starting on page 53.

For details on Servo Drives used in an AXI-PAK servo axis package, see the OMNIDRIVE\* section starting on page 35.

### Accessories

#### **Touchpad TP-OOI**

The optional Touchpad gives you the convenience of OMNI LINK\* software in the palm of your hand. The Touchpad plugs into the RS-232/RS-485 port on the drive. One Touchpad communicates with all drive types. The Touchpads can be left attached to the drive for constant operator use, or in a toolbox to be used as needed. The Touchpad is the best solution for maintenance technicians and engineers troubleshooting and testing on the floor.

Touchpad commands are entered by pressing a single key or combination of keys. Two modes of operation are available. Display mode allows you to move through the touchpad command tree to each parameter. Modify mode allows you to monitor and change each parameter. Most parameters can be modified or viewed while the drive is running or disabled.



AXI-PAK\* SERVO AXIS PACKAGE

ACCESSORIES

**TOUCHPAD TP-OOI** 

#### Cables

Professionally molded, high quality cable assemblies just drop in, saving you time and worry. Our cables incorporate features such as 360° shielding of both cable and connectors for EMC compliance, UL approved oil and chemical resistant cable, and fully molded connector housings with integral strain reliefs.

21365B	Cable for direct connection of any AXI-PAK servo axis pack-
	age to the TMC-2000 motion controller. 36" length
212100	Cable, come as above 2124ED with the addition of a congrete

- 21210B Cable, same as above 21365B with the addition of a separate pigtail to access all signals of the OMNIDRIVE digital servo drive that are unused by the TMC-2000 motion controller.
- 21380B10 Serial interface cable for connection to a PC or any RS-232/RS-485. 10ft. length. Note: one serial interface cable is included in each AXI-PAK servo axis package.
- 21468B-xx J1 interface cable. Available in lengths of 10 ft (xx=10) and 25 ft (xx=25). Note: one 10 ft cable is included in each AXI-PAK with indexing.

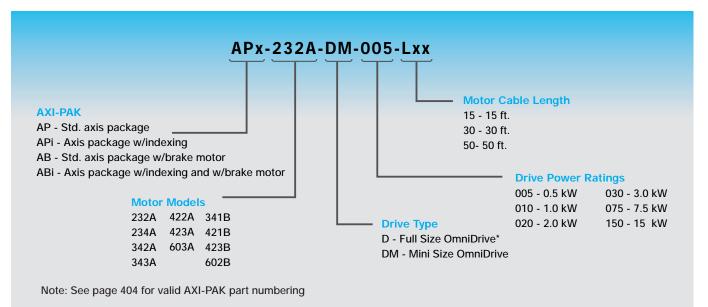
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.





### AXI-PAK\* SERVO AXIS PACKAGE ORDERING INFORMATION

# **Ordering Information**



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



**Motion Control** 



# **OMNIDRIVE\* DIGITAL SERVO DRIVE**



# The Thomson **OMNIDRIVE** line of digital brushless servo drives delivers the high performance and reliability required for any motion control application. Available

in continuous output power ratings from O.5 kW to I5 kW, an OMNIDRIVE digital servo drive flexibility allows it to be configured for various command sources for operation with a separate motion controller, PLC, or as a stand alone drive or positioner. The setup, operation, and control of an OMNIDRIVE is just a point and click away with full featured Windows® based OMNI LINK\* software or the available touchpad. There is no programming language to learn.



### **F**EATURES

- High performance microcontroller technology provides fully digital velocity, position, and current loop control as well as motor commutation
- Software configurable for various modes including analog velocity and torque, encoder follower, step/direction, preset velocities, and serial commands
- Indexing versions are capable of storing multiple move profiles for basic stand alone positioning applications
- Includes OMNI LINK Windows<sup>®</sup> based setup software – no programming language to learn!
- Output power ratings from 0.5kW to 15kW
- User configurable optically isolated I/O
- Available in both space saving mini and full size versions



For Application Engineering assistance contact the Thomson Technical HelpLine at 1-800-554-8466. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



#### A Fully Digital Design Gives Unrivaled Functionality and Performance

OMNIDRIVE digital servo drives incorporate high performance microcontrollers giving the features, flexibility, performance, and ease of use only possible in a fully digital design. An OMNIDRIVE can be configured to control a brushless servo motor in conjunction with a separate motion controller, PLC, or as a stand alone drive or positioner. All aspects of configuration, adjustments, and diagnostics are done completely in software. Current, velocity, and position loops are controlled digitally, as well as motor commutation. Intelligent Power Module (IPM) technology based on the latest generation IGBTs provides the highest possible reliability. Brushless motors are controlled with a pulse width modulated (PWM) sine wave in a smooth and efficient method utilizing feedback from a motor mounted encoder. Onboard electrically erasable programmable read only memory (EEPROM) stores all motor and configuration parameters to ensure reliability and repeatability over time and temperature.

#### **Multiple Command Sources**

- +/- 10V analog input for torque, velocity, or position modes
- Step/Direction input or step up/step down with electronic gearing for a high performance replacement for step motors
- Auxiliary master encoder input with electronic gearing
- Eight preset torques or speeds selected via the digital inputs
- Basic positioning capability through eight preset move profiles and a homing routine (indexing version only)
- RS-232/RS-485 serial host command language control for unlimited torque, velocity, position, and configuration control
- Command source and mode of operation may be changed during operation by toggling of an input

#### An Easy to Use Package

All sizes of the OMNIDIVE digital servo drive share the same connectors for commonality. All connector locations are clearly marked on the front panel. Electronics and power supplies are fully enclosed in a single panel mounted package, eliminating the need for external transformers.

#### Host Command Language

A serial port provides the connection for the OMNIDRIVE to PCs, PLCs, or other smart systems that can communicate via a RS-232/RS-485 interface. The host command language is a rich serial command set which allows real time control of multiple drives up to 32 addresses. The command language gives remote access to all OMNIDRIVE parameters and functions.

#### Flexible I/O

Optically isolated digital inputs and outputs work with 12-24VDC and are user definable for various functions.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.





### OMNIDRIVE\* DIGITAL SERVO DRIVE FEATURES

#### Inputs may be configured as:

drive mode select integrator inhibit follower enable forward enable reverse enable mode override preset/index select start index define home start homing fault reset registration sensor

#### Outputs may be configured as:

in position within window zero speed speed window current limit up to speed drive enabled bus charged disabling fault in motion in dwell sequence complete registered at home



# OMNIDRIVE Mini and OMNIDRIVE Full Size

To satisfy the widest range of application requirements, OMNIDRIVE digital servo drivers are available in a full size version as well as a reduced size mini version.



#### Choose the Mini Size when:

- power levels are 0.5kW to 2kW
- space is a premium
- a more cost effective solution is needed
- any application requires a feature rich, high performance, digital servo drive

#### Choose the Full Size when:

- power levels are 1kW to 15 kW
- internal shunt is needed for fast deceleration and high inertia applications
- the most flexibility is required by a second serial port and a few extra I/O
- any application requires a feature rich, high performance, digital servo drive

#### **Multiple Protection Features**

Multiple protection circuits monitor all critical parameters so in the unlikely event of trouble, your system shuts down safely and predictably. OMNI LINK\* software provides a fault history which stores error messages allowing you to easily troubleshoot what went wrong. OMNIDRIVE digital servo drives self-protect from input over/under voltage, phase to phase and phase to ground short circuit, overcurrent, drive and motor overtemperature, motor overspeed, and various other errors. Additionally, watchdog timers provide additional protection.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.





## OMNIDRIVE Mini Compact Frame, Digital Servo Drives (ODM)

- Continuous output power ratings of 0.5kW, 1kW, 2kW available
- Large scale integration with custom ASICs and IPMs for performance and reliability
- Superior performance in a package 1/4 the size of most drives
- On board electrically erasable programmable read only memory (EEPROM)
- 115 to 240 VAC single phase input power
- Phase to phase and phase to ground short circuit protection
- Sinusoidal current control
- DC bus available externally for power leveling
- Scalable motor encoder output
- 4 dedicated I/O with 5 selectable optically isolated digital I/O
- 1 analog input for external current limiting
- 1 analog output for variable monitoring or torque sharing
- Serial port for RS-232/RS-485 for host communications
- Internally shielded output filters for electromagnetic compatibility
- UL and cUL listed, and CE marked
- Flash memory for easy upgrades
- Wireless construction for reliability
- User selectable command source configuration



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.







# OMNIDRIVE Full Size Full Featured Digital Servo Drives (OD)

- Continuous output power ratings of 1kW, 2kW, 3kW, 7.5kW, 15kW available
- Advanced multi-processor design for all digital current, velocity and position loops
- On board electrically erasable programmable read only memory (EEPROM)
- 115 to 240 VAC input power single phase (for OD-075 and OD-150 max power with 3 phase)
- Phase to phase and phase to ground short circuit protection
- Internal power supplies including a 24 V I/O supply, only AC line required
- Sinusoidal current control
- Removable personality module to store setup parameters
- Large scale integration with custom ASICs and IPMs for performance and reliability
- Flash memory for easy upgrades
- DC bus available externally for power leveling
- Scalable motor encoder output
- 4 dedicated I/O with 8 selectable optically isolated digital I/O
- 2 analog input for external current limiting
- 2 analog output for variable monitoring or torque sharing
- 2 serial ports for RS-232/RS-485 host communications
- Internally shielded output filters for electromagnetic compatibility
- Wireless construction for reliability
- Internal or external resistive shunt
- UL and cUL listed, and CE marked

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.

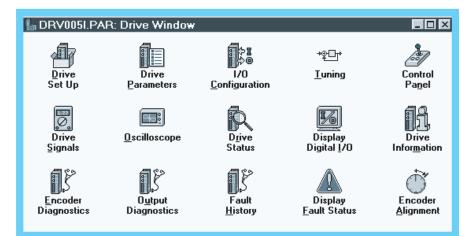


# OMNI LINK SOFTWARE

A powerful Windows<sup>®</sup> based setup and operation software package allows the user to fully exploit OMNIDRIVE digital servo drive features specific to each application. Program tasks are organized for easy setup, control and maintenance. A context sensitive, on-line help file provides immediate assistance every step of the way. Operation is simplified by a series of logically arranged setup screens. Files can be stored and printed for on-line or off-line modification or back-up. Diagnostic tools ease system integration. System tuning and debugging is added with on-screen

dual channel digital oscilloscope and drive signals. OMNI LINK contains a complete Host Command Language reference library for setting up the drives to be controlled via host computer or PLC.

### OMNI LINK Servo Setup Software



- The Drive Window is the main window for performing functions. It becomes active after communications are established or the software enters the off-line mode.
  - The Drive Set Up window displays the basic parameter set required to connect with a servo system. This window, along with the Drive Parameters and I/O Configuration windows, defines the necessary drive parameters for an application.

leive and Mer	or Selection	Devu Nores			Christ
yave Type:	20.028				
Anter Model	BLOODIDAD A	Otivo Camranio	okone		. CANNER
pendian Mo		8 Delo, No Parit	y, 18kapi		11
Analog Vela Analog Ten		Baud Rate: Dave Address	9608	*	Maler Enconators
Analog Pau Procet Volo Procet Lorg	cities	Notor Encoder Owput Signal	Divide by 1	-	
Followst M	natur Encoder top / Direction	Advanced Control	1	-	
	top Up / Step Dears	Spilate Rate	208 piec	*	
"ladoging		Motor Direction:	Perward + CW		
spenation Mos	de Quereda	C Disable PWM	Switching		
Analog Volux	ily logat 🛛	I Dates CODE	OM to Frankey Set		their

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.

Page 418

**Motion Control** 





Named States	vision and a second	_	BPAKE De	lay		-
NPUT II	<b>Drive Mode Select</b>		Action	Ne	man:	Clase
NEUT 2.	Registration Seasor	+	inactive:	1	ININC.	Enstor
NPUTE	Ordina Home	7		-	_	-
NPUI 4	Stat Hawing		Anolog Du			
fgalt Reset:	Fault Roset	1		osition - Mot	er Feedback	
C Auto-ster	Indexing	_	Spale	815	cousts/Vall	
Depilol Owper	Assignments		Offset.	8	milivate	
DUTPUT 1:	In Position	-	Analog Da	par2		
DUTPUT 2	Up To Speed	-	Signel D	unuel - Dorse	nand 2	
DUTPUT 2	In Motos		Scola	2.800	Amps/Voll	
DUTPUT &	Sequence Complete		Offert.	1	milivata	timbr.

Taning Mode			Gain Control		Close
"Normal Day	e Operation		C Valacity	# Position	Carter
AutoTune				14.98	Bestere
Manuel Turs			1 <sub>6</sub>		
Monand Turs	e (Preskien S	kep)	친 그	1	Stat
lato Tane Cer	bream		Ed	25.78	-
listings:	800088	counts	21	1 1	2848
Rep Cerrent	1.823	Anpo	100	34	Edats
Autor Disection	0		1 1	4	Cant
D-Direction				3.32	Scope On
" Forgard Oal			AL		

Chansel A	
Jopat Canest-R-Phase	
Scale: Auto Scale Amps	
Offset 0.888 Amps	
Chassel B	
lepst. Filter Output	
Sgale: 1.000 - Awps	
Offunt E.000 Amps	
Use B for Herizontal	
Sample Period	
Jime: 12.5 · moot.	
Trigger	
Moder Continuous Trigger	
Level 0.8	

- The I/O Configuration window routes signals from digital inputs, assigns drive signals to digital or analog outputs, and sets both active and inactive BRAKE delays. This window, along with the Drive Set Up and the Drive Parameters windows, define the necessary drive parameters for an application.
- The Tuning window displays the connected drive's velocity and position servo loop gains. It provides various means for tuning the servo loops and monitoring drive performance.
- The Control Panel window is used as a set up and testing tool to verify that the drive is functioning.
- The Oscilloscope window, along with the Drive Signals window, display the values of selected drive signals in the connected drive.
- The Encoder Diagnostics window is used for diagnosing encoder problems. It is used to display the count from the motor encoder, the resolution and the position of the encoder index. If the drive's Operation Mode is set to Step/Direction or Step Up/Step Down, it also displays the count from the master input. If the drive's Operation Mode is set to Master Encoder, it also displays the count from the master encoder, the resolution and the position of the encoder index.
- The Output Diagnostics window provides controlled outputs for verification of analog and digital output signals. When this window is opened, the drive firmware enters a special mode where the outputs are controlled by this window, rather than by the state of the drive.
- The Fault History window displays the faults that are stored in the drive's nonvolatile memory. The fault list is arranged from the most recent to the least recent.
- The Fault Status window displays the state of various potential fault sources. Faults which are active appear "lighted." Refer to the troubleshooting guide in the Hardware and Installation Manual for determining the cause and appropriate actions.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.



### **INDEXING OPTION**

When not using an AXI-PAK\* digital servo drive in conjunction with a separate motion controller, you'll likely be interested in the indexing option. This indexing capability allows an AXI-PAK to act as a simple controller for basic point to point positioning applications. Using the OMNI LINK\* setup software, the drive may be configured for up to eight different position moves (indexes) initiated by the drive's digital I/O. As the OMNI LINK software only requires you to enter parameters in existing fields, there is no programming language to learn. The moves may be incremental (a distance relative to the current position), absolute (a distance relative to home position) or registration

(a distance relative to the registration sensor input). Velocity, acceleration, and move distance may be specified for each index, as well as a batch count that will automatically repeat any index a specified number of times. A dwell time between moves may also be set. Through an "action when complete" setting, each index may be linked to any other for automatic subsequent execution. And for those cases where a host computer is employed, an infinite number of moves may be executed by sending parameter information to the drive via the serial interface. The indexing option also includes a user defined homing routine.

interio	Animp	- Pas	d Falses		samp Honis		Cleve
adas <u>6</u>						1	
Wade:	la marca	ted in	Fag Dist	1	- Arrestin	-	Erriver
lainer.	1000	amonto	Webselly-	7008	1216		
Salah Dearth	9	1	Asselection	500	IPM/mi		
beet.	214	mere:	<b>Eventuation</b>	MO	FFW/sec.		
Action parlos	and when	complete:	Execute Index 1	-			2441
index 1							
Wade:	Albeidute	*	Prog. 1914	1	- reality		
Peaking	5006	counts	Walacity:	300	FEW		
Arab Lower:	1	-	Acodisation:	300	RPM/usc.		
lard	6	1	Encoderation:	500	1PH/sec		
And and percent	and adams	mandate D	Sing	-	-	-	104

#### No Programming Language to Learn!

Up to eight indexes are defined using OMNI LINK setup software with a simple point and click. Absolute, relative, and registration moves are supported. Moves are initiated by the drive's digital I/O.

Home Type: T Home to Sense() how Markes T Home to Marker T Home to Sense Hate start Homey on Endols S Deartime T Action T Action	Russ Deletion Russing Schools AcceleDeced Effect Manu-	N08	RPM RPM/sec.	Bernen
kono Senesi Back-off "Agtion	Rome Dontine:	E	countries	

#### **User Defined Homing Routine**

You can home to a sensor switch and/or encoder marker, as well as set homing speed and acceleration, and enter a offset distance. Homing may begin automatically upon drive enable or through an assignable input.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.





#### SERIAL COMMUNICATION PORT (ALL DRIVES)

RS-232, Four wire RS-485 1200-19200 Baud rate Maximum 32 drives connected for multiple drive addressing

### INTERNAL POWER SUPPLY SPECIFICATIONS

OD-010/020/030/075	Min	Max	Max Output Current
24 Vdc power supply	21.6	26.4	500 mA
5 Vdc power supply	4.75	5.25	250 mA

#### ENVIRONMENTAL

Operating Temperature	-5°C to 55°C
Humidity	5% to 90% non-condensing
Altitude	1500m/5000ft
Vibration	10 to 2000 Hz at 2g
Shock	15g 11msec half sine

#### 0D-010/020/030/075/150 I/0 (FULL SIZE)

4 Digital INPUTS
4 Digital OUTPUTS
Dedicated Digital ENABLE Input
Dedicated Digital FAULT RESET
Dedicated BRAKE and DRIVE READY Relay Outputs
2 External Current Limit Analog Input 0–10 volt
2 User Set Analog Output +/-10 v
Encoder Output Scalable by 1, 1/2, 1/4, 1/8

#### ODM-005/010/020 I/0 (MINI SIZE)

3 Selectable Digital INPUTS
2 Selectable Digital OUTPUTS
Dedicated Digital ENABLE Input
Dedicated Digital FAULT RESET
Dedicated BRAKE and DRIVE READY Relay Outputs
1 External Current Limit Analog Input 0–10 volt
1 User Set Analog Output +/-10 v
Encoder Output Scalable by 1, 1/2, 1/4, 1/8

#### **SELECTABLE I/O**

Inputs and outputs are configurable in software as follows:

Selectable Outputs	Selectable Inputs
In Position	Drive Mode Select
Within Window	Integrator Inhibit
Zero Speed	Forward Enable
Speed Window	Follower Enable
Current Limit	Reverse Enable
Up to Speed	Operation Mode Override
Drive Enabled	Preset Select 0–7
Bus Charged	Start Index
Disabling Fault	Define Home
In Motion	Remove Command Offset
In Dwell	Registration Sensor
Sequence Complete	
Registered	
At Home	

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Page 421

### OMNIDRIVE\* DIGITAL SERVO DRIVE SPECIFICATIONS

	ODM-005	ODM-010	ODM-020
Peak Output	7.5 Amps	15 Amps	30 Amps
Current (Amps)			
Continuous Output	2.5 Amps	5 Amps	10 Amps
Current (Amps)	2.0 / 11103	5 7 inp3	10 Millips
	0.5.1114		0.1111
Continuous Output	0.5 kW	1 kW	2 kW
Power (kW)			
Continuous Input	5	9	18
Current (Amps)			
Input Voltage	100 to 240 VAC	100 to 240 VAC	100 to 240 VAC
and Frequency	47-63 Hz	47-63 Hz	47-63 Hz
Velocity Loop	300 Hz	300 Hz	300 Hz
Bandwidth Maximum			
Weight Lbs (kg)	3.7 (1.68)	4.5 (2.03)	4.4 (2.0)

# FULL SIZE

	OD-010	OD-020	OD-030	OD-075	OD-075	OD-150
				Single Phase Input	Three Phase Input	Three Phase Input
Peak Output Current (Amps)	10 Amps	20 Amps	30 Amps	50 Amps	75 Amps	150 Amps
Continuous Output Current (Amps)	5 Amps	10 Amps	15 Amps	15 Amps	35 Amps	65 Amps
Continuous Output Power (kW)	1 kW	2 kW	3 kW	3 kW	7.5 kW	15 kW
Continuous Input Current (Amps)	19	28	28	28	30	46
Input Voltage and Frequency	100-240 VAC 47-63 Hz					
Velocity Loop Bandwidth Maximum	400 Hz					
Weight Lbs (kg)	12.8 (5.80)	14 (6.36)	14.3 (6.48)	21.3 (9.67)	21.3 (9.67)	31 (14.06)

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.





Chnl I+ Chnl I-

# OD-010, OD-020, OD-030, OD-075, and OD-150

|--|

J4 and	J5-Serial Port	J3 - Aux	iliary Port	<b>J2</b> -	Encoder		
Pin	Function	Pin	Function	Pin	Function	Pin	Function
1 2 3 4 5 6 7 8 9	RCV +         RS-485           RCV         RS-232           XMT         RS-232           XMT +         RS-485           COM         Reserved           RCV -         RS-485           XMT -         RS-485           Reserved         RS-485           Reserved         RS-485	Duplicates	J1 pins 1–26	1 2 3 4 5 6 7 8 9 10	Encoder Pwr Encoder Com Encoder Pwr Encoder Com Encoder Pwr Sense + Encoder Pwr Sense - Mtr Encdr Input Chnl A+ Mtr Encdr Input Chnl B+ Mtr Encdr Input Chnl B+ Mtr Encdr Input Chnl B-	11 12 13 14 15 16 17 18 19 20	Mtr Encdr Input Ch Mtr Encdr Input Ch Hall Effect A Hall Effect B Hall Effect C Absolute Position Reserved Reserved Thermal Switch + Thermal Switch -

#### JI - Controller

Pin	Function	Pin	Function	Pin	Function	Pin	Function
1	Encoder +5V DC	14	Auxiliary Chnl A+	27	+I Limit	40	Reserved
2	Encoder Com	15	Auxiliary Chnl A-	28	Analog Com	41	Reserved
3	Encoder +5V DC	16	Auxiliary Chnl B+	29	-I Limit	42	Selectable Output 1
4	Encoder Com	17	Auxiliary Chnl B-	30	Analog Output 1	43	Selectable Output 2
5	External +24 VDC	18	Auxiliary Chnl I+	31	Analog Output 2	44	Selectable Output 3
6	External 24V COM	19	Auxiliary Chnl I-	32	Selectable Input 1	45	Selectable Output 4
7	Mtr Output Chnl A+	20	Drive Enable	33	Selectable Input 2	46	Reserved
8	Mtr Output Chnl A-	21	Fault Reset	34	Selectable Input 3	47	Reserved
9	Mtr Output Chnl B+	22	Analog Cmnd +	35	Selectable Input 4	48	Reserved
10	Mtr Output Chnl B-	23	Analog Cmnd -	36	Reserved	49	Brake Enable +
11	Mtr Output Chnl I+	24	Drive Ready +	37	Reserved	50	Brake Enable -
12	Mtr Output Chnl I-	25	Drive Ready -	38	Reserved		
13	Isolated 24V Com	26	Isolated +24 VDC	39	Reserved		

# ODM-005, ODM010 and ODM-020

### J5 - Serial Port

J2 - Encoder

Ρ	in Function	Pin Function	Pin Function
1 2 3 4 5 6 7 8 9	RCV - RS-485	<ol> <li>Encoder +5V Pwr</li> <li>Encoder VCOM</li> <li>Encoder +5V Pwr</li> <li>Encoder VCOM</li> <li>Reserved</li> <li>Reserved</li> <li>Mtr Encdr Input Chnl A+</li> <li>Mtr Encdr Input Chnl A-</li> <li>Mtr Encdr Input Chnl B+</li> <li>Mtr Encdr Input Chnl B-</li> </ol>	<ul> <li>11 Mtr Encdr Input Chnl I+</li> <li>12 Mtr Encdr Input Chnl I-</li> <li>13 Hall A</li> <li>14 Hall B</li> <li>15 Hall C</li> <li>16 Absolute Position</li> <li>17 Reserved</li> <li>18 Reserved</li> <li>19 Thermal Switch +</li> <li>20 Thermal Switch -</li> </ul>
JI	- Controller		

#### **Pin Function Pin Function Pin Function Pin Function** Auxiliary Chnl A+ +I Limit Encoder +5VDC 14 27 40 Reserved Encoder COM Auxiliary Chnl A-Analog Com Reserved 2 15 28 41 Auxiliary Chnl B+ Auxiliary Chnl B-Encoder +5VDC 29 -I Limit Selectable Output 1 3 42 16 4 Encoder COM 17 30 Reserved 43 Selectable Output 2 Auxiliary Chnl I+ 5 External +24 VDC 18 31 Analog Output 1 44 Reserved Auxiliary Chnl I-External 24VCOM 45 Reserved 19 Selectable Input 1 6 32 7 Mtr Encdr Output Chnl A+ 20 Drive Enable 33 Selectable Input 2 46 Reserved Mtr Encdr Output Chnl A-Selectable Input 3 8 21 Fault Reset 34 47 Reserved Reserved Mtr Encdr Output Chnl B+ 22 Analog Cmnd + 35 9 48 Reserved 10 Mtr Encdr Output Chnl B-23 Analog Cmnd -36 Reserved 49 Brake Enable + Mtr Encdr Output Chnl I+ 24 37 Reserved 50 Drive Ready + Brake Enable -11 Mtr Encdr Output Chnl I-12 25 Drive Ready -38 Reserved 13 External 24V Com 26 External +24 VDC 39 Reserved

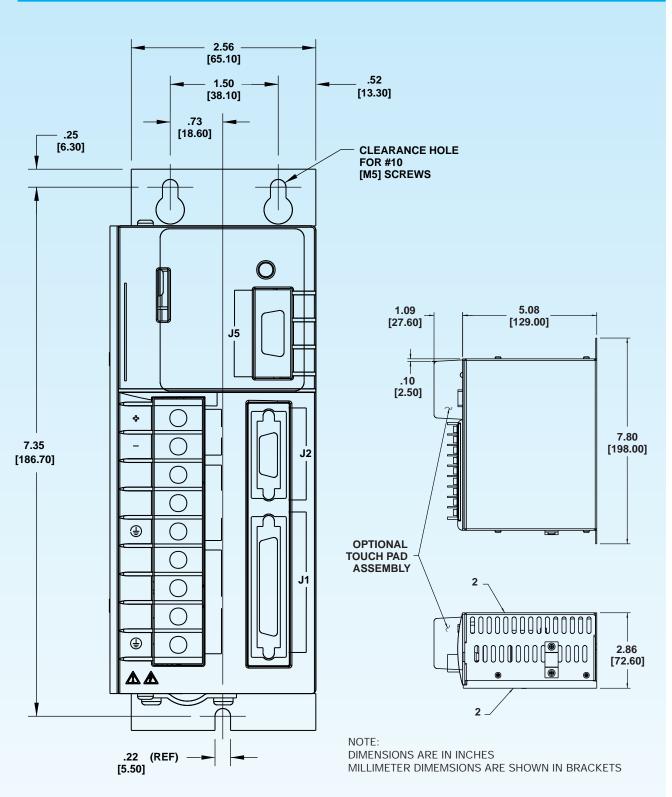
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries

Page 423

# **ODM-005**

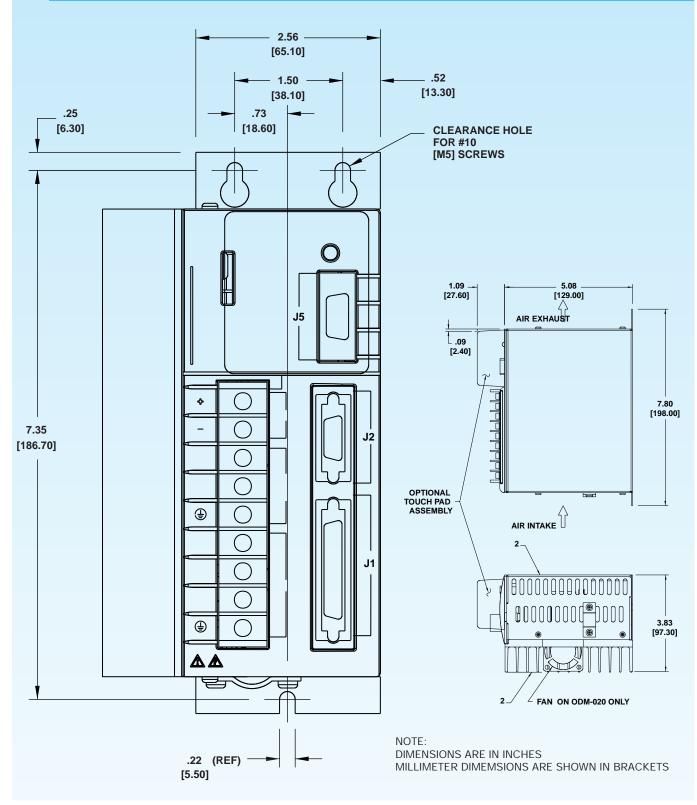


For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.





# ODM-OIO AND ODM-O20



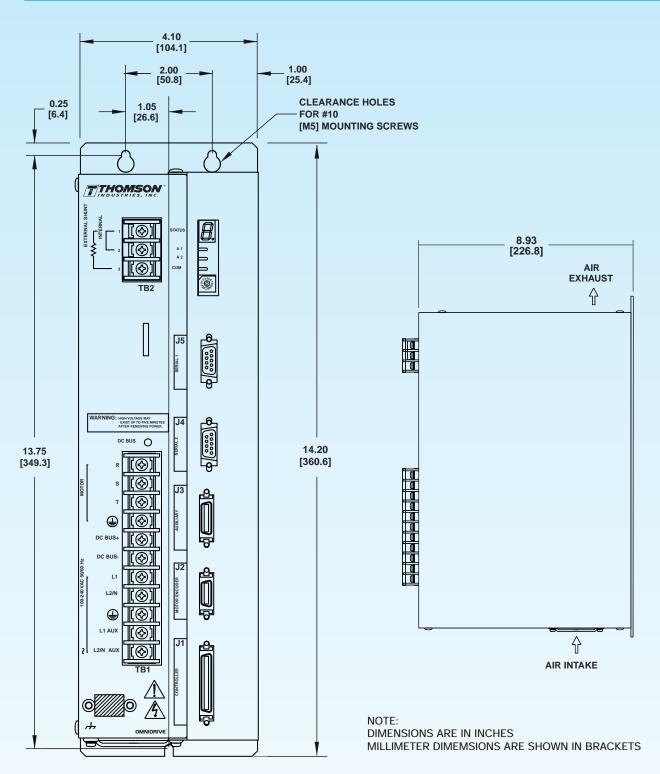
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Page 425

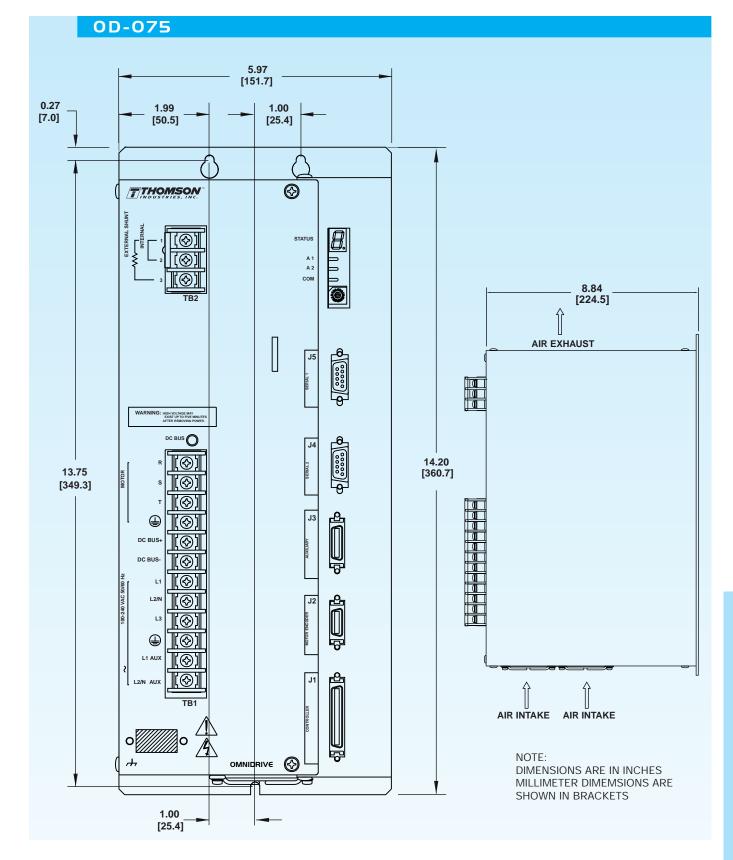
# OD-010, OD-020 AND 0D-030



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.

Page 426





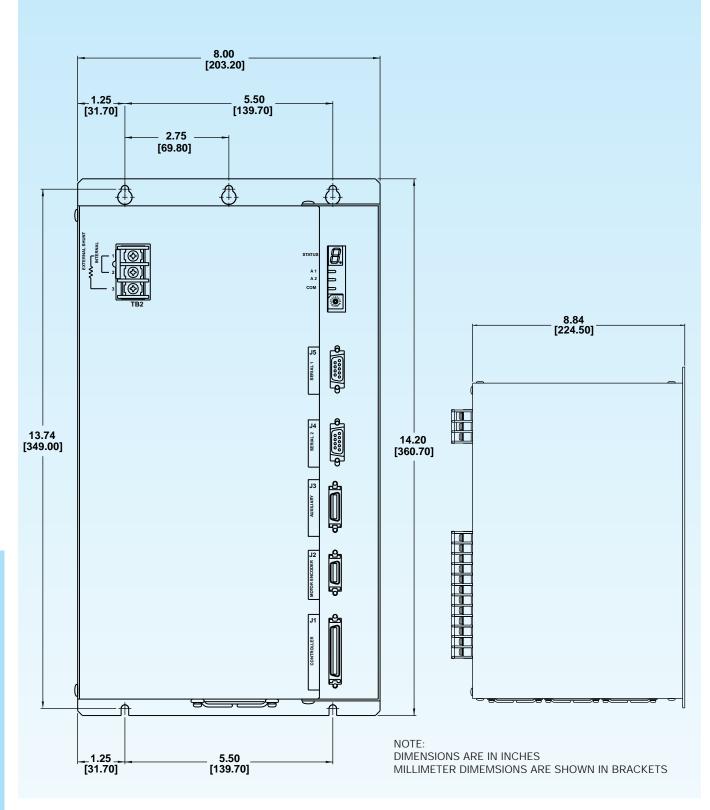
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Page 427

# 0D-150

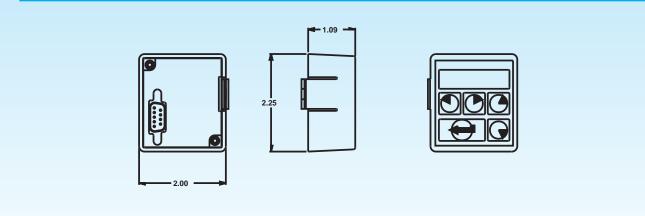


For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.

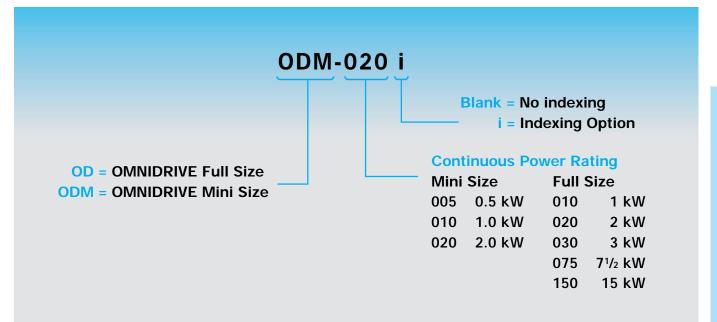
Page 428



# **TOUCHPAD TP-00I**



# Ordering Information: OmniDrive Digital Servo Drive



For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Page 429



### TouchPad P/N TP-OOI

The optional Touchpad gives you the flexibility and power of OMNI LINK\* software in the palm of your hand. The Touchpad plugs into the RS-232/RS-485 port on the drive. One Touchpad communicates with all drive types. The Touchpads can be left attached to the drive for constant operator use or in a toolbox to be used as needed. The Touchpad is a convenient solution for maintenance technicians and engineers troubleshooting and testing on the floor.

Touchpad commands are entered by pressing a single key or combination of keys. Two modes of operation are available. Display mode allows you to move through the touchpad command tree to each parameter. Modify mode allows you to monitor and change each parameter. Most parameters can be modified or viewed while the drive is running or disabled.



### CABLES

Professionally molded, high quality cable assemblies just drop in, saving you time and worry. Our cables incorporate features such as 360° shielding of both cable and connectors for EMC compliance, UL approved oil and chemical resistant cable, and fully molded connector housings with integral strain reliefs.

21209B-xx	Power/feedback cable for all BLX23 motors w/o brake
21305B-xx	Power/feedback cable for all BLX23 motors w/ brake
21207B-xx	Feedback cable for all BLX 34, 42, 60 motors
21290B-xx	Power cable for BLX 34x, 421, 422 motors w/o brake
21206B-xx	Power cable for BLX 34x, 421, 422 motors w/ brake
21208B-xx	Power cable for BLX 423, 60x motors w/o brake
21306B-xx	Power cable for BLX 423, 60x motors w/ brake
21210B	OMNIDRIVE to TMC-2000 interface w/breakout
21365B	OMNIDRIVE to TMC-2000 interface
21380B10	RS232 serial cable, 10 ft
21468B-xx	J1 interface pigtail, xx= 10 ft. or 25 ft. only

xx = standard cable length designator, 15=15ft, 30=30ft, 50=50ft except for 21468B-xx which is 10ft or 25ft only.



#### AXI-PAK\* Servo Axis Packages

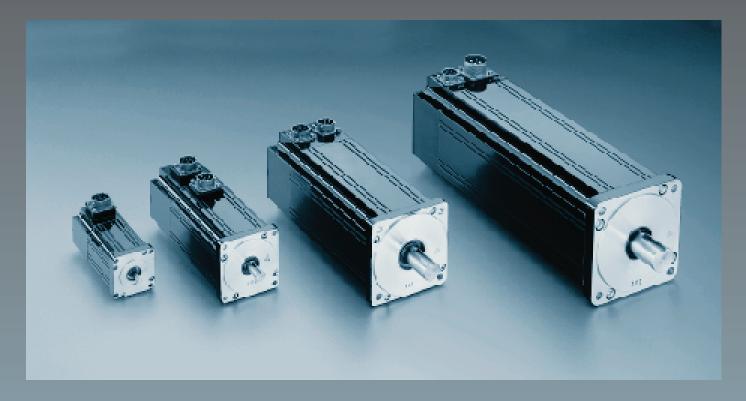
Thomson Industries engineered AXI-PAK servo axis packages are proven combinations of OMNIDRIVE digital dervo drives, BLX servo motors and cabling designed to deliver the best performing, lowest cost solutions for the widest variety of applications. See page 431 for details.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.

**Motion Control** 



# **BLX BRUSHLESS SERVO MOTORS**



**The BLX** Series of brushless servo motors are industrial quality motors designed for high performance and durability. A superior magnetic and thermal design gives exceptional performance and the highest torque per frame size. A wide variety of frame sizes and winding configurations are available to suit your application needs.

BLX servo motors are built to last. Brushless construction and lifetime lubricated bearings eliminate all maintenance issues. Standard IP65 sealing, MS style fluid tight connectors, oversize bearings, and a winding thermal switch ensure a long and worry-free service life in the harshest and most challenging applications.

For a complete motor control solution, BLX motors are available with matched OMNIDRIVE\* digital servo drives and pre-made cables for a quick, easy and trouble-free installation.

### FEATURES

- Four frame sizes to fit your requirements
- High energy magnets for extremely high torque
- Maintenance free brushless construction
- Standard IP65 sealing for wash down environments
- MS style connectors for durability
- Internal 2000 line (8000 count) commutating encoder

- Internal thermal switch
- UL and cUL recognized
- Optional internal 24VDC brake
- Optional Thomson Micron True Planetary\* gearheads
- Available matching OMNIDRIVE digital servo drives and pre-made cables
- Off-the-shelf delivery



PARAMETER	SYMBOL	UNITS	BLX232A	BLX234A
Rated Power (1)(2)	Pr	Нр	0.22	0.47
		Kw	0.16	0.36
Speed at Rated Power	N rated	rpm	4000	5000
Max Operating Speed (1)	N max	rpm	5000	6500
Continuous Stall Torque (2)	Тс	in-lb	5	10
	10	Nm	0.56	1.12
Peak Torque	Тр	in-lb	15	30
	. P	Nm	1.7	3.36
Rotor Inertia (4)	Jm	lb-in-s <sup>2</sup>	0.000097	0.000184
		Kg-m <sup>2</sup>	0.0000109	0.0000207
Weight	W	lb	3	3.7
5		Kg	1.3	1.68
Number of Poles	-	-	4	4
Torque Constant, sinewave				
(line-line) (3)	Kt	in-lb/A	1.81	1.81
		Nm/A	0.204	0.204
Voltage Constant	Ke	V <sub>rms</sub> /Krpm	18.2	17.8
(line-line)				
		V <sub>rms</sub> /rad/sec	0.174	0.17
Resistance (cold)	Rc	ohm	8.4	3.1
(line-line)				
Resistance (hot)	Rh	ohm	12.6	4.65
(line-line)				
Inductance	L	mH	11.6	5.1
(line-line)				
Peak Current (3)	Ip	А	8.28	18
Continuous Current (3)	lc	А	2.76	6

NOTES:

- 1. With 230VAC drive line input voltage.
- 2. 25°C ambient, motor mounted on a 8"x8"x1/2" aluminum heat sink and the lower of 155°C winding or 100°C encoder temperature.
- 3. Peak value of a sinusoidal waveform.
- 4. Add brake inertia if applicable.

COMMENTS:

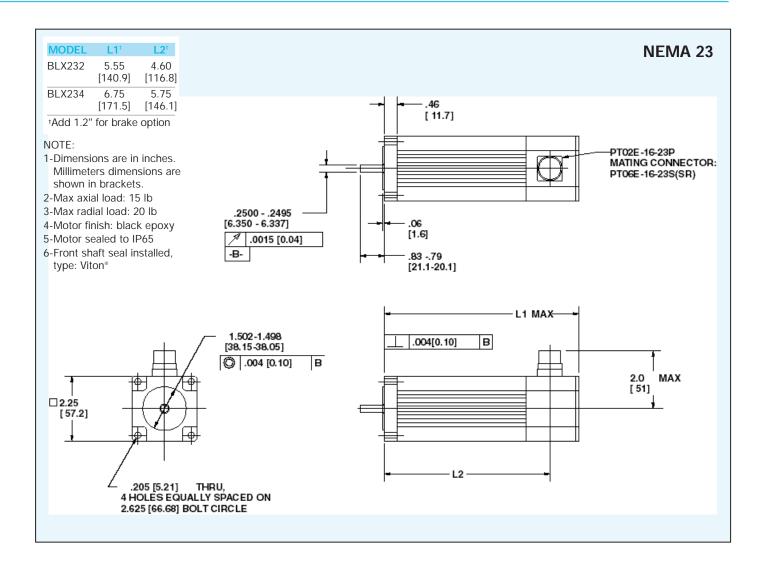
- a) Thermostat in stator windings will open if winding temperature exceeds 155°C.
- b) Above data represent typical values. Actual performance is dependent on amplifier, controller, and system installed.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.





# Motor/Encoder/Therm/Brake Connector PTO2E-I6-23P

Pin	Function	Pin	Function
Т	ENC GROUND	L	HALL CH V\
E	ENC +5VDC	Y	HALL CH W
F	ENC CH A	М	HALL CH W\
U	ENC CH A\	N	GND/CABLE SHIELD
G	ENC CH B	S	THERM
V	ENC CH B\	R	THERM
Н	ENC CH Z	D	GND
W	ENC CH Z\	А	MOTOR PHASE R
J	HALL CH U	В	MOTOR PHASE S
К	HALL CH U\	С	MOTOR PHASE T
Х	HALL CH V	Р	BRAKE (+) 🔒 DIODE
		Z	BRAKE (-) IN4007

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Viton' is a registred trademark of E. I. DuPont de Nemours & Company. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Page 433

PARAMETER	SYMBOL	UNITS	BLX341B	BLX342A	BLX343A
Rated Power (1)(2)	Pr	Нр	0.55	1.62	1.96
		Kw	0.41	1.20	1.46
Speed at Rated Power	N rated	rpm	2400	4000	3600
Max Operating Speed (1)	N max	rpm	3000	5000	4100
Continuous Stall Torque (2)	Tc	in-lb	16.0	30	39
		Nm	1.81	3.4	4.4
Peak Torque	Тр	in-lb	48.0	90	117
		Nm	5.43	10.2	13.2
Rotor Inertia (4)	Jm	lb-in-s <sup>2</sup>	0.000615	0.000991	0.00137
		Kg-m <sup>2</sup>	0.0000693	0.0001116	0.000154
Weight	W	lb	8.3	9.3	14.6
		Kg	3.8	4.2	6.6
Number of Poles	-	-	6	6	6
Torque Constant, sinewave (line-line) (3)	Kt	in-Ib/A	7.65	3.91	5.58
		Nm/A	0.864	0.442	0.63
Voltage Constant (line-line)	Ke	V <sub>rms</sub> /Krpm	75.2	36.6	55
		V <sub>rms</sub> /rad/sec	0.72	0.35	0.53
Resistance (cold) (line-line)	Rc	ohm	15.4	1.5	1.9
Resistance (hot) (line-line)	Rh	ohm	23.1	2.25	2.85
Inductance (line-line)	L	mH	39.6	5.1	7.5
Peak Current (3)	lp	А	6.57	25.2	21.75
Continuous Current (3)	lc	А	2.19	8.4	7.25

#### NOTES:

- 1. With 230VAC drive line input voltage.
- 2. 25°C ambient, motor mounted on a 8"x 8"x 1/2" aluminum heat sink and the lower of 155°C winding or 100°C encoder temperature.
- 3. Peak value of a sinusoidal waveform.
- 4. Add brake inertia if applicable.

COMMENTS:

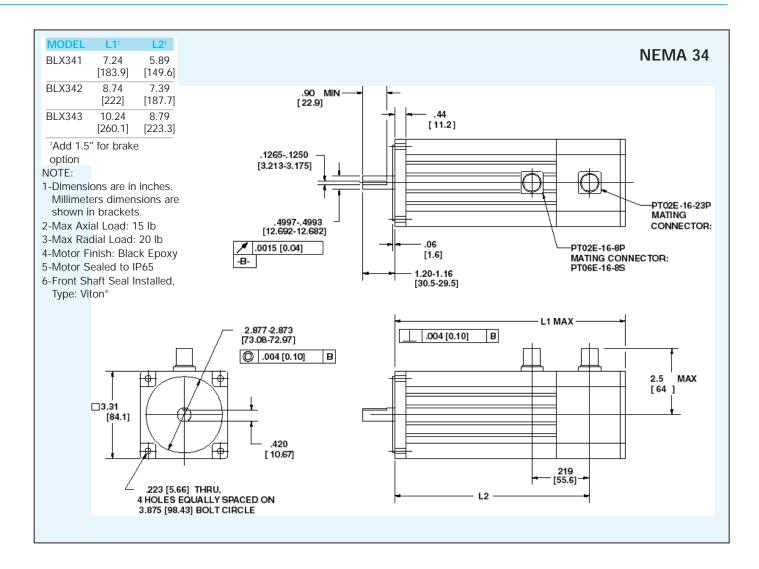
- a) Thermostat in stator windings will open if winding temperature exceeds 155°C.
- b) Above data represent typical values. Actual performance is dependent on amplifier, controller, and system installed.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.





# Encoder/Therm Connector PTO2E-I6-23P

Pin	Function	Pin	Function
т	ENC GROUND	L	HALL CH V\
Е	ENC +5VDC	Y	HALL CH W
F	ENC CH A	М	HALL CH W\
U	ENC CH A\	N	GND/CABLE SHIELD
G	ENC CH B	S	THERM
V	ENC CH B\	R	THERM
Н	ENC CH Z	D	GND
W	ENC CH Z\	А	NO CONNECTION
J	HALL CH U	В	NO CONNECTION
K	HALL CH U\	С	NO CONNECTION
Х	HALL CH V	Р	NO CONNECTION
		Z	NO CONNECTION

# Motor/Brake Connector PTO2E-I6-8P

Pin	Function
A	MOTOR PHASE R
В	MOTOR PHASE S
С	MOTOR PHASE T
D	PE GND
E	BRAKE SHLD
F	BRAKE (+) 🔒 DIODE
G	BRAKE (-) IN4007
Н	NO CONNECTION

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Viton's a registered trademark of E. I. DuPont de Nemours & Company. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



PARAMETER	SYMBOL	UNITS	BLX421B	BLX422A	BLX423A	BLX423B
Rated Power (1)(2)	Pr	Нр	1.2	3.3	4.6	2.0
		Kw	0.88	2.5	3.4	1.8
Speed at Rated Power	N rated	rpm	1500	3000	3000	1500
Max Operating Speed (1)	N max	rpm	2100	4200	4200	2100
Continuous Stall Torque (2)	Тс	in-lb	54.0	83	116.2	116.2
		Nm	6.1	9.3	13.1	13.1
Peak Torque	Тр	in-lb	162.0	249	348.6	348.6
		Nm	18.3	27.9	39.3	39.3
Rotor Inertia (4)	Jm	lb-in-s <sup>2</sup>	0.0035	0.0066	0.0095	0.0095
		Kg-m <sup>2</sup>	0.00039	0.00074	0.00107	0.00107
Weight	W	lb	20	26.4	37	37
		Kg	9.1	12	16.8	16.8
Number of Poles	-	-	6	6	6	6
Torque Constant, sinewave	Kt	in-lb/A	11.16	5.66	5.58	11.16
(line-line) (3)						
		Nm/A	1.26	0.64	0.64	1.28
Voltage Constant	Ke	V <sub>rms</sub> /Krpm	110	55.0	55.0	110
(line-line)						
		V <sub>rms</sub> /rad/sec	1.05	0.525	0.525	1.05
Resistance (cold)	Rc	ohm	3.3	0.4	0.27	1.1
(line-line)						
Resistance (hot)	Rh	ohm	4.95	0.6	0.4	2.25
(line-line)						
Inductance	L	mH	24.4	21.8	2	8.1
(line-line)						
Peak Current (3)	lp	А	15.18	46.2	64.5	32.4
Continuous Current (3)	lc	А	5.06	15.4	21.5	10.8

#### NOTES:

- 1. With 230VAC drive line input voltage.
- 25°C ambient, motor mounted on a 10"x 10"x 1/2" aluminum heat sink and the lower of 155°C winding or 100°C encoder temperature.
- 3. Peak value of a sinusoidal waveform.
- 4. Add brake inertia if applicable.

COMMENTS:

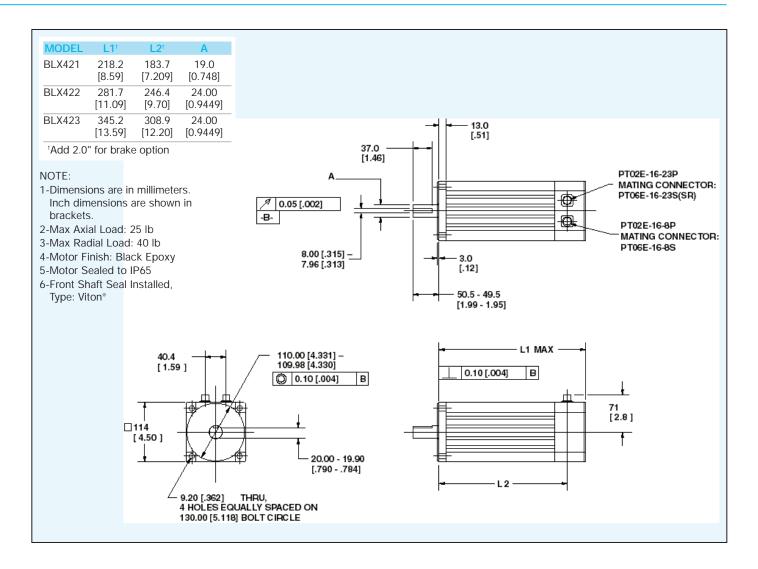
- a) Thermostat in stator windings will open if winding temperature exceeds 155°C.
- b) Above data represent typical values. Actual performance is dependent on amplifier, controller, and system installed.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.





#### Encoder/Therm Connector PTO2E-I6-23P

Pin	Function	Pin	Function
т	ENC GROUND	L	HALL CH V\
Е	ENC +5VDC	Y	HALL CH W
F	ENC CH A	М	HALL CH W\
U	ENC CH A\	N	GND/CABLE SHIELD
G	ENC CH B	S	THERM
V	ENC CH B\	R	THERM
Н	ENC CH Z	D	GND
W	ENC CH Z\	А	NO CONNECTION
J	HALL CH U	В	NO CONNECTION
К	HALL CH U\	С	NO CONNECTION
Х	HALL CH V	Р	NO CONNECTION
		Z	NO CONNECTION

# Motor/Brake Connector PTO2E-I6-8P

Pin	Function
А	MOTOR PHASE R
В	MOTOR PHASE S
С	MOTOR PHASE T
D	PE GND
Е	BRAKE SHLD
F	BRAKE (+) 🔒 DIODE
G	BRAKE (-) 🗳 IN4007
Н	NO CONNECTION

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. Viton's a registered trademark of E. I. DuPont de Nemours & Company. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



PARAMETER	SYMBOL	UNITS	BLX602B	BLX603A
	STINDOL	ONITS	DEX002D	DEX003A
Rated Power (1)(2)	Pr	Нр	4.5	9.1
		Kw	3.4	6.8
Speed at Rated Power	N rated	rpm	1500	2400
Max Operating Speed (1)	N max	rpm	1750	2700
Continuous Stall Torque (2)	Тс	in-lb	210	280
		Nm	23.7	31.5
Peak Torque	Тр	in-lb	630	840
		Nm	70.8	94.4
Rotor Inertia (4)	Jm	lb-in-s <sup>2</sup>	0.0016	0.0276
		Kg-m <sup>2</sup>	0.00212	0.00307
Weight	W	lb	51	64
		Kg	23.1	29
Number of Poles	-	-	6	6
Torque Constant, sinewave	Kt	in-Ib/A	12.0	7.11
(line-line) (3)				
		Nm/A	1.35	0.8
Voltage Constant	Ke	V <sub>rms</sub> /Krpm	1.1	0.669
(line-line)				
		V <sub>rms</sub> /rad/sec	0.72	0.13
Resistance (cold)	Rc	ohm	1.08	0.2
(line-line)				
Resistance (hot)	Rh	ohm	12.6	4.65
(line-line)				
Inductance	L	mH	6.1	1.4
(line-line)				
Peak Current (3)	lp	А	54.5	122
Continuous Current (3)	lc	А	18.2	40.7

NOTES:

- 1. With 230VAC drive line input voltage.
- 2. 25°C ambient, motor mounted on a 12" x 12" x 1/2" aluminum heat sink and the lower of 155°C winding or 100°C encoder temperature.
- 3. Peak value of a sinusoidal waveform.
- 4. Add brake inertia if applicable.

COMMENTS:

- a) Thermostat in stator windings will open if winding temperature exceeds 155°C.
- b) Above data represent typical values. Actual performance is dependent on amplifier, controller, and system installed.

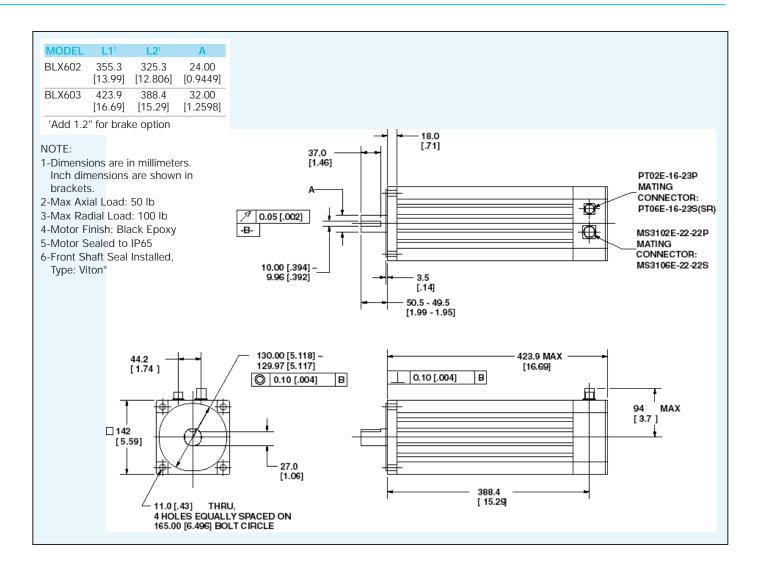
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement.

\* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.





# Encoder/Therm Connector PTO2E-I6-23P

Pin	Function	Pin	Function
т	ENC GROUND	L	HALL CH V\
E	ENC +5VDC	Y	HALL CH W
F	ENC CH A	М	HALL CH W\
U	ENC CH A\	N	GND/CABLE SHIELD
G	ENC CH B	S	THERM
V	ENC CH B\	R	THERM
Н	ENC CH Z	D	GND
W	ENC CH Z\	А	NO CONNECTION
J	HALL CH U	В	NO CONNECTION
К	HALL CH U\	С	NO CONNECTION
Х	HALL CH V	Р	NO CONNECTION
		Z	NO CONNECTION

# Motor/Brake Connector PTO2E-I6-8P

Pin	Function			
А	MOTOR PHASE R			
В	MOTOR PHASE S			
С	MOTOR PHASE T			
D	PE GND			
E	BRAKE SHLD			
F	BRAKE (+) 🖪 DIODE			
G	BRAKE (-) IN4007			

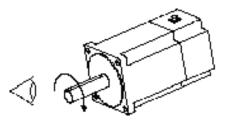
For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.

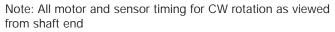


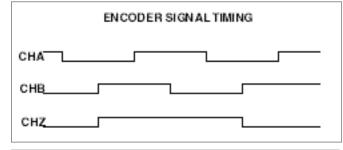
The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond sterior replacement. Viton's a registered trademark of E. I. DuPont de Nemours & Company. Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



# **BLX BRUSHLESS SERVO MOTORS** COMMON SPECS

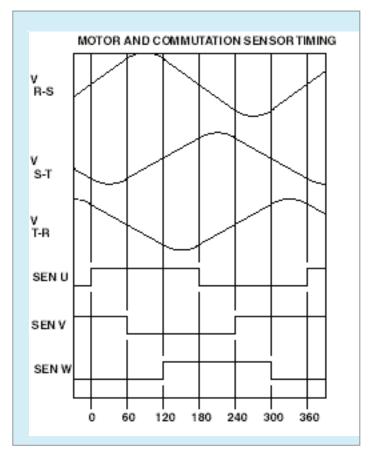


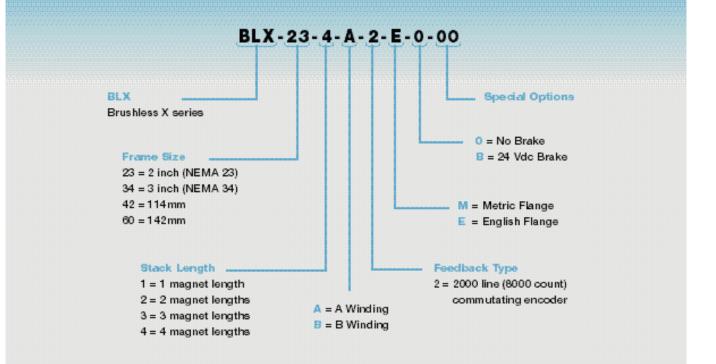




#### **ENCODER NOTES**

- 1. Resolution = 2000 lines/rev. (8000 counts)
- 2. Power Supply = 5VDC±5%, 200mA max.
- 3. Output circuit is 26LS31 differential line driver, 20mA max sink/source
- 4. Commutation sensors in encoder have differential outputs.





For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.

**Motion Control** 

specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the bility of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is med beyond such replacement. nie sp suitabil



Trademark of Thomson Industries. Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries

# Application: Draw and cut to length Rolling Dies

# **Application Description**

Flat stock clamped to a positioning stage is drawn through two rolling dies which form the material into a profile. At the end of a pre-determined stroke length, the clamp releases, the slide retracts, and the material is cut off. The material is once again clamped and the action repeats. The actual cutoff and clamping mechanisms are located on a Thomson belt driven linear motion slide which is energized by outputs from the drives. The length of the material must be altered as required for the job.

# Requirements

- One axis stand alone capability
- Configurable I/O
- On the floor programmability

# The Solution

(1) APi-421B-DM020-L15 AXI-PAK\* digital servo drive package with indexing(1) TP-001 Touchpad

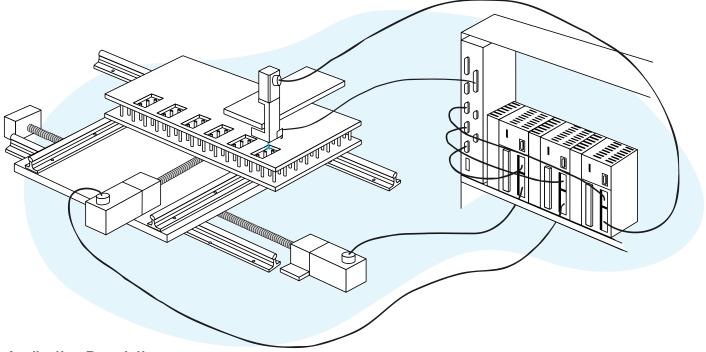
A Thomson Industries AXI-PAK drive/motor combination with indexing capability and touch pad has been selected to satisfy this application. The drive's programmable outputs are configured to fire when moves are complete thus initiating the clamp and cut operations. The touch pad allows the move lengths, speeds, accelerations, etc. to be set on the factory floor without a separate computer. The drive is homed automatically upon power up.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.



The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Page 441



#### **Application Description**

Sheet stock, which has been clamped in place on an X-Y table, will be guided under the head of a focusing beam laser. As these pre-programmed patterns are being traced, any height deviations of the sheet metal with respect to the laser head will jeopardize the integrity and accuracy of the cut. This condition will be compensated for by a sensor attached to the laser head mounted on the Z axis.

#### Requirements

- Three axis control, smooth motion, high accuracy
- Stand alone operation
- · Linear and circular Interpolation, and contouring
- Analog inputs
- Multi-tasking capabilities
- User defined I/O

# The Solution

- (1) TMC-2004-CO multi-axis motion controller
- (2) AP-342A-DM020-L15 AXI-PAK\* servo axis packages for X and Y
- (1) AP-232A-DM005-L15 AXI-PAK servo axis packages for Z

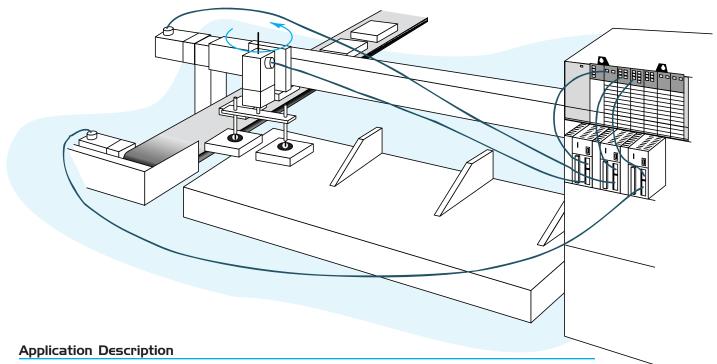
Thomson Industries TMC-2004-CO multi-tasking controller has been selected to control three AXI-PAK servo axis packages. The controller provides coordinated motion between the X and Y axes while, at the same time closing a position loop around the Z axis and the analog input to which the height sensor is connected. The cut progresses smoothly and accurately as the controller processes these two programs simultaneously, while having the additional capability to run two more programs, for a total capacity of four. These two additional programs can be used to monitor laser beam quality and/or safety devices located on the machine.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.





# **Application: Offload transfer line**



Automate a material transfer process by integrating assembly workstations and the necessary linear and rotary motion stages into one machine. All motion is to be coordinated with an existing PLC. Finished assemblies will be sensed and picked on a first in first out basis and transferred to an offload conveyor which will index as necessary. Product is then forwarded to a packaging station.

# Requirements

- Smooth, quick motion
- High reliability
- · High-speed indexing for increased throughput
- Interface with a PLC
- Accurate position control
- Non-volatile memory for move profiles

# The Solution

(3) APi-234A-DM010-L15 AXI-PAK\* digital servo drive packages with indexing

Three Thomson Industries AXI-PAK digital servo drive packages have been selected. Each will use its indexing capability to execute up to 8 preset move profiles while communicating with the PLC through user defined I/O. Finished assemblies are placed in "out" boxes by their respective assemblers and sensed by the PLC. A Thomson linear motion belt driven slide, controlled by an AXI-PAK, will be directed to the out box. The rotary stage indexes as required and pneumatics make the pick. Product is then transferred to the offload conveyor, which indexes ahead as necessary. The process repeats itself, with the PLC sequencing a total of 24 move profiles provided by the Thomson drives.

For more information, or to place an order, please contact Thomson Industries, at 1-800-554-THOMSON, Fax: 1-800-445-0329, or E-mail at motioncontrol@thomsonmail.com.

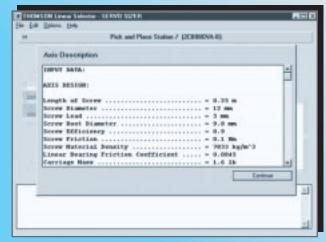


The specifications and data in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. "Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Page 443

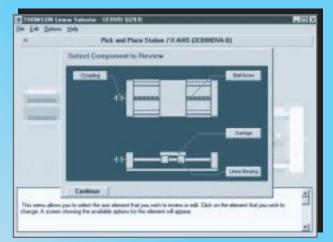
# Servo FREE Sizing Software

Selecting the right servo solution has never been easier or more accurate. Thomson servo sizing software gives you the exact part number(s) for the solution to your motion control application. Ballscrew (leadscrew), belt drive, and direct drive configurations are supported. If using a Thomson linear motion system, simply choose the part number from a list box and all system parameters are automatically entered. You can also design your own system with Thomson components or your own. Then, specify your move profile and the suitable AXI-PAK\* engineered servo axis packages are listed.

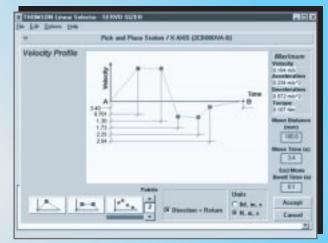


In addition to the program's rich graphical output both on screen and printed, tabulated values are available for all design parameters, move profile, torque requirements, and chosen motion control components.

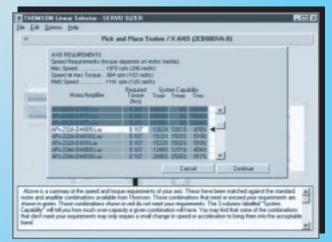
# Call 1-800-55-4-THOMSON for your FREE copy of Thomson servo sizing software



If using a Thomson system, simply enter its part number to have all system parameters automatically entered. You may also design your own system using Thomson components or your own/generic components. Screw, belt, and direct driven systems are supported.



Your move profile is easily entered in a graphical way. Simply drag the profile as desired and all values are updated. Triangular, trapezoidal, or complex multispeed/acceleration/deceleration moves are supported.



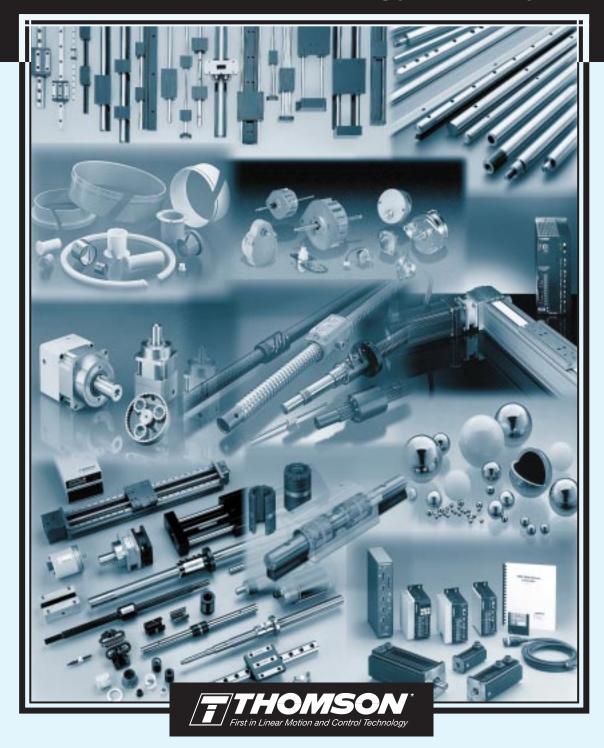
Actual AXI-PAK servo axis package part numbers are generated for a matched motor-drive-cable solution. All available solutions are listed with the suitable packages highlighted. Torque margins are displayed for convenience.







# Free from the Thomson Technology Library



It's as easy as checking a box. Make sure your Thomson Engineering Library is up to date.



# Linear Bearings & Components (Inch)



# ADVANCED LINEAR MOTION TECHNOLOGY GUIDE

144-page guide includes specifications of all linear 144-page guide includes specifications of all linear Ball Bushing\* bearings, pillow blocks and support rails. Also featured are the new Super Smart Ball Bushing\* bearings, Super Ball Bushing\* bearings and RoundWay\* linear roller bearings. Literature No. 01-00-000-6001-03

# Linear Bearings & Components (Metric)



# ADVANCED LINEAR MOTION METRIC PRODUCTS

A 66-page comprehensive catalog provides A to-page completensive catalog provides information and specifications on advanced linear motion metric products. These include Super Smart Ball Bushing bearings, Smart MultiTrac Ball Bushing\* bearings and Smart Rail\* linear guides. Literature No. 01-50-000-6001-02

# Thomson 60 Case



# THOMSON 60 CASE LINEARRACE SHAFTING CATALOG

60-page catalog describing the features, benefits and technical specifications of the complete line of 60 Case\* LinearRace\* shafting. Engineering templates are provided for ease of ordering. Literature No. 02-00-000-6001

# **Thomson Saginaw**



# ADVANCED LINEAR ACTUATOR GUIDE

This 92-page technology guide is a complete source of information on high performance Thomson Saginaw\* ball screws, including rolled thread assemblies, precision ground assemblies and ball splines. Also included are product descriptions, applications, specifications, design and selection criteria and mounting instructions.

Literature No. 06-00-000-6001-02

# **Thomson Saginaw**



# PERFORMANCE PAK ACTUATORS-ENGINEERING AND SELECTION GUIDE

This 28-page catalog describes the Thomson Saginaw\* Performance Pak, PPA\*, actuators and accessories for commercial, institutional and industrial linear actuation. PPA's combine the efficiency of a ball screw with an electric motor for a ready-to-install positioning system. Includes complete engineering and selection data and application examples.

Literature No. 09-00-000-6001-01

# **Thomson Saginaw**



# EXPERT BALL SCREW RECONDITIONING FOR ANY DESIGN OR MAKE

Brochure describes ball screw repair services from Thomson Saginaw that can save a customer up to 90% of the cost of a new ball screw. Topics include repair capabilities, inspection procedures, and special programs such as emergency repairs, train-ing seminars, and preventive maintenance. Brochure also includes information on how a ball screw operates and what causes damage and wear. Literature No. 06-16-000-6400-01

# Thomson Micron\*



# TRUE PLANETARY GEARHEAD SELECTION GUIDE AND ENGINEERING CATALOG

Complete engineering data and selection guide for True Planetary\* gearheads and position feedback transducers.

Literature No. 10-00-000-6001

# **Thomson Micron**



# **GEARHEAD EXPRESS**

Gearhead Express\* ships True Planetary\* gearheads within 24 hours-the fastest delivery of planetary gearheads available from any industry source. The program offers two precision classes; high precision DuraTrue\* gearheads and Ultra precision UltraTrue\* gearheads. Both gearhead product groups mount with the error-free Redimount\* motor mounting curtor system

Literature No. 10-08-000-6001

# **Thomson Airpax Mechatronics**

# PRODUCT SELECTION AND ENGINEERING GUIDE

- Features the largest and most powerful capability per size in the industry and: Ideal for valve actuators, fluid displacement pumps, copiers, printers, fax machines, paper feed devices, character positioning devices, climate con-trol, and fluid flow-rate management Customization to meet your precise design needs Fast powerful meets positioning

- Fast, powerful, precise positioning
   Large selection of permanent magnet stepper motors from 15mm to 60mm
   Pioneer in digital linear actuator (DLA) technology

Literature No. 12-00-000-6001

# Linear Motion Solutions

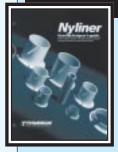


# LINEAR GUIDES, SYSTEMS, SLIDES & STAGES AND MOTION CONTROL SOLUTION GUIDE

450-page guide permits quick selection of standard off-the-shelf linear motion systems and accessories. Easy to use, it presents inch and metric systems sep-arately and has special sections on motion control, accessories and engineering support. Using the graphs, formulas and illustrations included through-out, complete systems can be designed, specified and ordered with a single part number. Literature No. 99-40-000-6100



# **Molded Products**



# NYLINER BEARING DESIGNER'S GUIDE

20-page design guide for Nyliner engineered polymer bearings includes easy-to-use technical and selection data, specification and application guidelines. Special section included on Nyliner Plus\* bearings. They are composed of advanced thermoplastics for increased PV ratings and operation at higher temperature and lower friction. Literature No. 04-00-000-6001-03

# Thomson Precision Ball



#### THOMSON PRECISION BALL CATALOG

A 22-page catalog covers standard and custom precision balls, guaranteed to meet ABMA standards. Available in chrome and stainless steel and many special materials-and in 0.005" to 1" diameters, in grades 3-1000. The catalog also features a full-line of balls in ferrous, non-ferrous and ceramic materials: from 0.0525 in.; and in Grades 10-1000.

Literature No. 07-00-000-6001-02

# Systems



#### LINEAR MOTION SYSTEMS FOR SEMICONDUCTOR PROCESSING

This brochure presents an overview of Thomson linear motion systems, both pre-engineered, off-the-shelf designs and currently engineered custom designs for proprietary equipment. Typical applications in the semiconductor industry include wafer processing and inspection, wafer furnaces, robotic wafer arms, transport and flat panel display processing. Literature No. 03-00-000-6402

# Systems



# THOMSON LINEAR MOTION SYSTEMS FOR PACKAGING MACHINERY

This brochure shows 1-to 4-axis modular servo systems complete with motors and controls. These systems reduce product development time and time-to-market for new packaging equipment with such applications as width adjustment, stretch wrapping and fluid dispensing. The components of these systems are stocked for quick assembly, matching of motors and controls, shipment and ease of in-plant operation. Literature No. 03-00-000-6403

# Corporate



#### WHY YOU SHOULD SPECIFY THOMSON LINEAR MOTION PRODUCTS

When buying linear motion products you want to get the very best. This brochure explains why you should specify Thomson products. Thomson products offer the highest loads, longest life, and the most advanced features and benefits available in the world. Thomson offers 10,000 standard offthe-shelf linear motion products.

Literature No. 99-00-000-6416-01

# Corporate



#### **INFORMATION BY FAX!**

A simple one-page brochure that explains how to use the LinearFax\* technical data system. Lists the product information available through this service. Literature No. 99-00-000-6401

# Corporate



#### THE WORLD'S MOST COMPLETE LINEAR MOTION & CONTROL LINE

An eight-page brochure featuring a listing of Thomson's linear motion products. Included are brief descriptions of each product line. Literature No. 99-00-000-6430



THOMSON INDUSTRIES, INC. 2 Channel Drive • Port Washington, NY 11050 USA 2 (800) 554-8466 • Fax: 1 (800) 445-0329 E-mail: thomson@thomsonmail.com \*Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

Download literature from www.thomsonindustries.com

or literature by fax: LinearFax\* 1-800-554-THOMSON



# FAX ALL REQUESTS TO **516-944-1045** (in UK **0800 9751001**) To request, simply check the box next to the literature listing and enter the quantity desired.

All requests filled within 72 hours after receipt of form.

QTY

LINEAR MOTION SYSTEMS	QT
Linear Motion & Control Solutions Catalog CT Literature No. 99-40-000-6100	
Advanced Linear Motion Systems	
Product Overview CT Literature No. 03-00-000-6005-03	
Thomson Linear Motion Systems	
for Semiconductor Processing	
CT Literature No. 03-00-000-6402	
Thomson Linear Motion Systems for Packaging Machinery	
<b>CT</b> Literature No. 03-00-000-6403	
MicroStage* Systems	
TB Literature No. 03-55-000-6001 Motion Control Solutions Catalog	
<b>CT</b> Literature No. 03-14-000-6001	
Linear Motion System Catalog on CD ROM	
including 2D DFX CAD Files and Linear Selector* Software	
<b>CD</b> Literature No. 03-00-000-6005	
LINEAR BEARINGS	ΟΤ
Advanced Linear Motion Technology Guide	
CT Literature No. 01-00-000-6001-03	
Advanced Linear Motion Metric Products CT Literature No. 01-50-000-6001-02	
UltraProof* Ball Bushing* bearing	
<b>TB</b> Literature No. 01-01-100-6501	
Smart MultiTrac Ball Bushing* block	
TB Literature No. 01-58-300-6501	
Super Smart Ball Bushing* bearing Rigid Pillow Block	
<b>TB</b> Literature No. 01-01-200-6501	
Miniature Instrument Ball Bushing bearings	
and Matched Sets TB Literature No. 01-03-104-6001	
Metric Miniature Ball Bushing* bearings	
<b>TB</b> Literature No. 01-03-104-6500-01	
Super Smart Ball Bushing* bearings (JIS) <b>TB</b> Literature No. 01-81-100-6001-03	
Super Smart Ball Bushing* bearings	
(6-Track) Inch & ISO	
TB Literature No. 01-01-400-6001 Linear Motion Products Price Book	
PL Literature No. 01-00-000-6901	
Thomson Linear Motion Products Metric	
Interchange Guide MS Literature No. 01-50-000-6003	
60 CASE LINEARRACE shafting	
Genuine 60 Case* LinearRace* shafting	QT
CT Literature No. 02-00-000-6001	
Thomsalloy* 60 Case LinearRace shafting	
TB Literature No. 02-02-006-6002 60 Case Flanged Shaft Support Blocks	
<b>TB</b> Literature No.02-03-103-6001-01	
60 Case LinearRace JIT shafting	
<b>TB</b> Literature No.02-02-005-6001-01	
Linear Motion Products Price Book PL Literature No.01-00-000-6901	
60 Case shafting Poster (Rolled in Tube)	
MS Literature No. 02-02-000-6402	
60 Case shafting Poster (Folded)	
MS Literature No. 02-02-000-6402 60 Case shafting & Super Smart	
Ball Bushing* bearing Poster	
MS Literature No. 99-00-000-6424	

#### **LINEAR GUIDES**

LINEAR GUIDES	Q
Linear Motion & Control Solutions Catalog CT Literature No. 99-40-000-6100	
Maintenance-Free Linear Guides TB Literature No. 14-00-000-6800	
AccuGlide* Miniature R-Series Linear Guides TB Literature No. 14-03-100-6001	
AccuGlide Protective Bellows TB Literature No. 05-02-100-6001	
AccuGlide Scraper Option TB Literature No. 14-50-100-6001	
Linear Guides Price Book PL Literature No. 14-00-000-6901	
Linear Guides Interchange Guide (THK/STAR to Thomson) MS Literature No. 05-02-000-6014	
Choosing Linear Guides for Smooth Moves (MD Article 5/98) MS Literature No. 14-00-000-6200	
Linear Guide CAD (.dxf) files CD Literature No. 14-00-000-6301	
AccuMax* Linear Guide Video VO Literature No. 05-03-000-6800	
SAGINAW* BALL SCREWS	QI
Advanced Linear Actuator Guide	
CT Literature No. 06-00-000-6001-02 Expert Ball Screw Reconditioning for	
any Design or Make CT Literature No. 06-16-000-6400-01	
Performance Pak* Actuators/	
Engineering and Selection Guide CT Literature No. 09-00-000-6001-01	
Ball Screw Alignment Procedures CT Literature No. 06-00-000-6403	
High Capacity Miniature Ball Screws TB Literature No. 06-01-005-6001-02	
Ball Screw Inspection Kit TB Literature No. 06-16-000-6001	
Quick Mount* V-Series Bearing Support Blocks TB Literature No: 06-21-100-6001	
Thomson T/K Modified Acme Assemblies Literature No. 06-30-000-6001-01	
Telescoping Ball Screws TB Literature No. 06-35-000-6001	
Precision Gear Drive Units TB Literature No. 06-36-000-6001	
Class 5 Metric Precision Ball Screw Assembly TB Literature No. 06-51-000-6001-01	
Class 3 Metric Precision Ball Screw Assembly TB Literature No. 06-52-000-6001	
High-Speed HPD In-Line Ball Screw Actuator TB Literature No. 09-11-100-6001	

Ball Screw and PPA Price List PL Literature No. 06-00-000-6900-1	
Actuators for All-Weather Antenna Positioning	
<b>MS</b> Literature No. 09-10-000-6400	
MOLDED PRODUCTS	ΟΤΥ
Nyliner* Bearing Designer's Guide	
CT Literature No. 04-00-000-6001-03	
Nyliner Plus* Bearing Test & Evaluation Kit	
<b>TB</b> Literature No. 04-01-100-6001-02	
Nyliner Bushing Bearings TB Literature No. 04-02-000-6501	
Repair Tool Kit	
MS Literature No 04-02-100-6001	
FluoroNyliner* Bushing Bearings TB Literature No. 04-03-000-6001-3	
Zero Clearance Bearings	
<b>TB</b> Literature No. 04-04-000-6001	
Nyliner, Nylined*, & Nyliner Plus Engineered	
Polymer Bearings - Complete Price Guide PL Literature No. 04-00-000-6902	
Nyliner Bushing Bearings/FluoroNyliner	
Bushing Bearings - Complete Price Guide	
PL Literature No. 04-00-000-6903	
FluoroNyliner Bushing Bearings Complete	
Interchange List	
PL Literature No. 04-03-000-6003	
MICRON* TRUE PLANETARY* GEARHEADS	QTY
Micron Consolidated Catalog CT Literature No. 10-00-000-6001	
Gearhead Express Brochure	
<b>CT</b> Literature No. 10-008-000-6001	
Programmable Limit Switches	
TB Literature No. 10-05-000-6001	
THOMSON AIRPAX MECHATRONICS	ΟΤΥ
Airpax Consolidated Catalog	
TB Literature No. 12-00-000-6001	
THOMSON PRECISION BALL	ΟΤΥ
Thomson Precision Ball Catalog	
CT Literature No. 07-00-000-6001-02	
CORPORATE CATALOGS & BROCHURES	ΟΤΥ
Why You Should Specify Thomson	
Linear Motion Products	
<b>CT</b> Literature No. 199-00-000-6416-01	
LinearFax* Technical Data TB Literature No. 99-00-000-6401	
The World's Most Complete	
Linear Bearing Line	
<b>TB</b> Literature No. 99-00-000-6430	
Thomson 2000 VO Literature No. 99-00-000-6301	
IBL BALL SCREWS	ΟΤΥ
CT LITERATURE NO. 08-00-000-6002	<b>u</b>
· · · · · · · · · · · · · · · · · · ·	

Code: CT-Catalog/Brochure; TB-Technical Bulletin; PL-Price List; CD-CD ROM; MS-Miscellaneous; VO-Video

COMPANY NAME		
NAME		
ADDRESS		
CITY		STATE ZIP
COUNTRY		
PHONE	FAX	E-MAIL



\*Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.

# **ENGINEERING CONVERSION FACTORS**

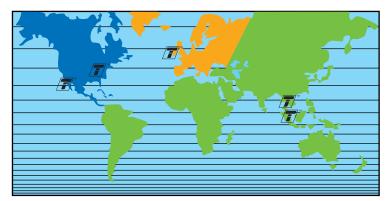
QUANTITY		SI UNIT	CONVERSION FACTORS	
QUANTITY	Inch Unit			CONVERSION FACTORS
LENGTH	Inch in.	Meter m	Metre m	1 in. = 25.4 mm 1 mm = 0.03937 in. 1 m = 3.2808 ft. 1 ft. = 0.3048 m
AREA	Square Inch in.²	Square Meter m²	Square Metre m <sup>2</sup>	$\begin{array}{rrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrr$
MASS	Pound <sup>Ib</sup> m	Kilogram <b>kg</b>	Kilogram <b>kg</b>	1 lb <sub>m</sub> = 0.45359237 kg 1 kg = 2.2046 lb
FORCE	Pound Force Ib <sub>f</sub>	Kilogram Force kg <sub>f</sub>	Newton N	$\begin{array}{llllllllllllllllllllllllllllllllllll$
STRESS or PRESSURE	Pounds per square inch <b>Ib<sub>f</sub>/in.</b> ²	Kilograms per square meter kg <sub>f</sub> /m <sup>2</sup>	Pascal Pa	$\begin{array}{llllllllllllllllllllllllllllllllllll$
TORQUE or WORK	Inch Pounds <b>Ib<sub>f</sub>-in</b> .	Kilogram Meters <b>kg<sub>f</sub>-m</b>	Newton- Metres <b>Nm</b>	$\begin{array}{llllllllllllllllllllllllllllllllllll$
POWER	Foot pound per minute Ib <sub>f</sub> -ft./min.	Force per second kg <sub>f</sub> -m/s	Newton Metre per second <b>Nm/s</b>	$\begin{array}{llllllllllllllllllllllllllllllllllll$
VELOCITY	Feet per second ft./s	Meters per second <b>m/s</b>	Meters per second <b>m/s</b>	1 ft./sec. = 0.3048 m/s 1 in./sec. = 2.54 cm/s 1 ft./sec. = 0.00508 m/s 1 mile/hr. = 0.44704 m/s 1 km/hr. = 0.27777 m/s 1 mile/hr = 1.609344 km/hr.
ACCELERA- TION	Feet per second squared ft./s <sup>2</sup>	Meters per second squared <b>m/s</b> <sup>2</sup>	Metres per second squared <b>m/s</b> <sup>2</sup>	1 ft./s² = 0.3048 m/s²



For Application Engineering assistance contact the Thomson Technical HelpLine at 1-800-554-8466. \* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries.



# Worldwide Manufacturing, Service & Sales



- USA HEADQUARTERS: Port Washington, NY
  - Farmingdale, NY Ronkonkoma, NY
  - Lancaster, PA
  - Bristol, CT Unionville, CT Cheshire, CT
  - Saginaw, MI 
     Bay City, MI
- **Mexico** Tijuana
- To United Kingdom Barnstaple Farnborough
- Malaysia Kluang
- **Singapore**

# **1800 DISTRIBUTORS WORLD WIDE!**

In North America: 1-800-554-THOMSON Europe: (44) 1271 334 500 Elsewhere: 516-883-8000

# ONE SOURCE FOR ALL LINEAR MOTION AND CONTROL APPLICATIONS



All Thomson Industries Manufacturing Locations are ISO 9000 Certified and Automotive Facilities Operate to QS-9000 Standards Three-time winner General Motors Supplier of the Year

ISO 9000

# www.thomsonindustries.com

\* Trademark of Thomson Industries, Inc. THOMSON is registered in the U.S. Patent and Trademark Office and in other countries. The specifications in this publication are believed to be accurate and reliable. However, it is the responsibility of the product user to determine the suitability of Thomson products for a specific application. While defective products will be replaced without charge if promptly returned, no liability is assumed beyond such replacement. ©1999 Thomson Industries, Inc. Printed in the U.S.A. RIPON 250K HAP/CP 12-14-99 9808-16.qxd 99-40-000-6100

FOR IMMEDI	ATE ASSISTANCE:	Europe:	<b>a</b> :	(44) 1271 334 500	
USA, Canada or Mexico:	Free 🕿: 1 (800) 554-8466 Free Fax: 1 (800) 445-0329	UK	Sales Fax: Free 🕿: Free Fax:	(44) 1271 334 502 0800 9751000 0800 9751001	Elsewhere: 🕿: 1 (516) 883-8937 Fax: 1 (516) 883-7109
Internet: E-mail:	www.thomsonindustries.com thomson@thomsonmail.com	France	Free 🕿: Free Fax:	0800 90 5721 0800 91 6315	or write: Thomson Industries, Inc. 2 Channel Drive
Literature: LinearFax*:	litrequest@thomsonmail.com 1 (800) 55-4-THOMSON	Germany	Free 🕿: Free Fax:	0130 816 553 0130 816 552	Port Washington, NY 11050 USA



2 Channel Drive Port Washington, NY 11050 USA PRESORTED STANDARD U.S. POSTAGE PAID THOMSON INDUSTRIES, INC.